



## eYRC 2021-22: Agri Bot (AB)

## ROS Launch Files

- In the previous sections you must have noticed that we need to use `roscore` command to start ROS Master and Parameter Server, `roslaunch` command to run a ROS Node, `rosparam load` command to load parameters etc.
- This is a tedious process to manually run nodes and load parameters.
- Launch files provides the capability to do all these stuff using a single command.
- The idea is to mention all the nodes that you want to run, all the config file that you want to load etc in a single file which you can run using `roslaunch` command.

## Reading Assignment

1. [ROS Wiki - roslaunch](#)
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