



eYRC 2021-22: Agri Bot (AB)

ROS Package

- ROS Packages according to ROS Wiki

Software in ROS is organized in *packages*. A package might contain ROS [nodes](#), a ROS-independent library, a dataset, configuration files, a third-party piece of software, or anything else that logically constitutes a useful module. The goal of these packages is to provide this useful functionality in an easy-to-consume manner so that software can be easily reused. In general, ROS packages follow a "Goldilocks" principle: enough functionality to be useful, but not too much that the package is heavyweight and difficult to use from other software.

Reference

1. [Packages](#)

