

# Utility Maximization in Cognitive Radio Networks using POMDP Approximate Value Iteration methods

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**Abstract**—This document is a model and instructions for  $\text{\LaTeX}$ . This and the `IEEEtran.cls` file define the components of your paper [title, text, heads, etc.]. **\*CRITICAL: Do Not Use Symbols, Special Characters, Footnotes, or Math in Paper Title or Abstract.**

**Index Terms**—Hidden Markov Model, Viterbi Algorithm, Expectation-Maximization, Belief Space, POMDP, Value Iteration, and the PERSEUS Algorithm

## I. INTRODUCTION

This document is a model and instructions for  $\text{\LaTeX}$ . Please observe the conference page limits.

## II. SYSTEM MODEL

### A. Observation Model

$$y(n) = \sum_{m=0}^{M-1} h(m)x(n-m) + v(n) \quad (1)$$

Here,  $y(n)$  is the wideband signal observed at the SU receiver expressed as a convolution of the PU signal  $x(n)$  with the channel impulse response  $h(n)$ , added with a noise term  $v(n)$ . Equation (1) can be written in the frequency domain by taking a K-point DFT which decomposes the observed wideband signal into K discrete narrow-band components as shown below,

$$Y_k(i) = H_k X_k(i) + V_k(i) \quad (2)$$

where,

$i \in \{1, 2, 3, \dots, T\}$  represents the index of the observation  
 $k \in \{1, 2, 3, \dots, K\}$  represents the index of the channel  
 $V_k(i) \sim \mathcal{CN}(0, \sigma_V^2)$  represents the circular symmetric additive complex Gaussian noise sample i.i.d across channel indices and across time indices. These noise samples are assumed to be independent of the occupancy state of the channels.  
 $H_k \sim \mathcal{CN}(0, \sigma_H^2)$  represents the  $k^{th}$  DFT coefficient of the impulse response  $h(n)$  of the channel in between the PU and the SU receiver - another circular symmetric complex Gaussian random variable i.i.d across channel indices with variance  $\sigma_H^2$ . These impulse response samples are also assumed to be independent of the occupancy state of the channels. We define the set  $B$  as the set of channels obtained by discretizing the spectrum of interest, i.e.  $B = \{b_1, b_2, b_3, \dots, b_K\}$ . The PU

occupancy behavior in each sub-band  $b_k \in B$  is modelled as  $X_k$  taking two possible values 0 (*Idle*) and 1 (*Occupied*). Therefore, the PU occupancy behavior in the entire wideband spectrum of interest discretized into narrow-band frequency components can be modelled as a vector of size  $|B| = K$  such that,

$$\vec{X} = [X_1, X_2, X_3, \dots, X_K]^T \in \{0, 1\}^K \quad (3)$$

### B. Correlation Model

The true states encapsulate the actual occupancy behavior of the PU and the measurements at the SU are noisy observations of these true states which are modelled to be the observed states of a Hidden Markov Model. For some sub-band  $j \in \{2, 3, 4, \dots, K\}$  and time index  $i \in \{1, 2, 3, \dots, T\}$ , the system is assumed to satisfy the Markov property as shown below,

$$\mathbb{P}(X_j(i)|X_{j-1}(i), X_{j-2}(i), \dots, X_1(i)) = \mathbb{P}(X_j(i)|X_{j-1}(i))$$

And, we will use  $\mathbb{P}(X_1(i))$  for  $j = 1$ . Now, let's expand on the previously discussed observation model. Taking the expectation operator on both sides of equation (2) given  $X_k$  has realized as  $x_k$ , we have,

$$\mathbb{E}[Y_k(i)|X_k(i) = x_k] = \mathbb{E}[H_k x_k] + \mathbb{E}[V_k(i)]$$

$$\mathbb{E}[Y_k(i)|X_k(i) = x_k] = \mathbb{E}[H_k] \mathbb{E}[x_k] + \mathbb{E}[V_k(i)]$$

$$\mathbb{E}[Y_k(i)|X_k(i) = x_k] = 0 \quad (4)$$

because,  $V_k(i) \sim \mathcal{CN}(0, \sigma_V^2)$  and  $H_k \sim \mathcal{CN}(0, \sigma_H^2)$ .

Furthermore, the variance of  $Y_k(i)$  given  $X_k$  at observation cycle  $i$  has realized as  $x_k$ , is calculated to be,

$$Var(Y_k(i)|X_k(i) = x_k) = \mathbb{E}[|H_k X_k(i) + V_k(i)|^2 | X_k(i) = x_k]$$

$$Var(Y_k(i)|X_k(i) = x_k) = \mathbb{E}[|H_k X_k(i)|^2 + |V_k(i)|^2 + 2\Re(H_k X_k(i) V_k^*(i)) | X_k(i) = x_k]$$

$$Var(Y_k(i)|X_k(i) = x_k) = \sigma_H^2 x_k + \sigma_V^2 \quad (5)$$

For the first part of our paper, we assume that the temporal dynamics of the PU Occupancy are slower than the SU's process times. In other words, for the first part of our paper, we assume that the PU is static during our evaluation period.

We can incorporate the above assumption into our correlation model as shown below by eliminating the time dependence.

$$\mathbb{P}(X_j|X_{j-1}, X_{j-2}, \dots, X_1) = \mathbb{P}(X_j|X_{j-1}), \text{ for } j > 1,$$

And, we will continue to use  $\mathbb{P}(X_1)$  for  $j = 1$ . Now, we know that,

$$\vec{X} = [X_1, X_2, X_3, \dots, X_K]^T$$

which realizes as  $\vec{x} = [x_1, x_2, x_3, \dots, x_K]^T$ , so,

$$\mathbb{P}(\vec{X} = \vec{x}) = \mathbb{P}(X_1 = x_1) \prod_{k=2}^K \mathbb{P}(X_k = x_k | X_{k-1} = x_{k-1}) \quad (6)$$

Since  $x_k \in \{0, 1\}$ , for  $k \in \{1, 2, 3, \dots, K\}$ , let,

$$\mathbb{P}(X_k = 1) \triangleq \Pi, \forall k$$

Furthermore, let,

$$\mathbb{P}(X_k = 1 | X_{k-1} = 0) \triangleq p, \forall k$$

And,

$$\mathbb{P}(X_k = 0 | X_{k-1} = 1) \triangleq q, \forall k$$

From the above definitions, we have,

$$\mathbb{P}(X_k = 1) = \Pi = \frac{p}{p+q}, \forall k$$

Moreover, we also assume that the Markov Property is satisfied when we traverse the spectrum in the descending order of the channel indices, i.e, the reverse direction. Mathematically,

$$\mathbb{P}(\vec{X} = \vec{x}) = \mathbb{P}(X_K = x_K) \prod_{k=1}^{K-1} \mathbb{P}(X_k = x_k | X_{k+1} = x_{k+1})$$

We now proceed with our discussions assuming that there is only one Primary User (PU), i.e. licensed incumbent in the wideband spectrum of interest and that there is only one Secondary User (SU) learning to intelligently access the *spectrum holes* or *white spaces* both spatially and temporally. In the next section of our paper, assuming a static PU, model knowledge, and complete observations, we discuss an algorithm to estimate the PU occupancy behavior. Later, we methodically relax these assumptions and detail occupancy behavior estimation results and optimal POMDP policy search methods for cases where we have incomplete observations, dynamic PU occupancy behavior, and no model information.

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Before you begin to format your paper, first write and save the content as a separate text file. Complete all content and organizational editing before formatting. Please note sections III-A–III-E below for more information on proofreading, spelling and grammar.

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Define abbreviations and acronyms the first time they are used in the text, even after they have been defined in the abstract. Abbreviations such as IEEE, SI, MKS, CGS, ac, dc, and rms do not have to be defined. Do not use abbreviations in the title or heads unless they are unavoidable.

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Be sure that the symbols in your equation have been defined before or immediately following the equation. Use “(7)”, not “Eq. (7)” or “equation (7)”, except at the beginning of a sentence: “Equation (7) is . . .”

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- The word "data" is plural, not singular.
- The subscript for the permeability of vacuum  $\mu_0$ , and other common scientific constants, is zero with subscript formatting, not a lowercase letter "o".
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- In your paper title, if the words "that uses" can accurately replace the word "using", capitalize the "u"; if not, keep using lower-cased.
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copy	More table copy <sup>a</sup>		

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#### ACKNOWLEDGMENT

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