

Image Enhancement Techniques for PSR regions of the Moon

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Abstract

001 Permanently Shadowed Regions (PSR) of the Moon are
002 located in the poles of the Moon, which are the regions
003 where sunlight does not illuminate the surface. The re-
004 search aims to enhance the imagery in these regions of the
005 moon to aid in mission planning. The research explores
006 techniques which can perform low light image enhance-
007 ment techniques, which can preserve the underlying tex-
008 ture of the image. The preservation of texture is a criti-
009 cal criterion in this regard, as they hold the information
010 about the terrain in the PSR, which is crucial in mission
011 planning. To address this issue, we proposed and ex-
012 perimented with a variety of enhancement algorithms ranging
013 from Dual-Illumination estimation, Controlled Light En-
014 hancement Diffusion (CLED) models, and CNN Based en-
015 hancement models(LoLi-IEA). We also introduced a novel
016 approach utilizing pix-pix SAR colorization to help perform
017 terrain classification. The qualitative and quantitative per-
018 formance of low light enhancement techniques are mea-
019 sured using Lightness order error(LOE) and SPAQ (a per-
020 ceptual image quality measure) respectively to help analyze
021 the best performing technique.

1. Introduction

023 Permanently shadowed regions(PSR) are the regions in lu-
024 nar surface, which are never illuminated by sunlight. These
025 regions occur at the poles of the moon. This phenomenon is
026 a direct effect of the Moon's rotational axis being tilted by
027 only about 1.5° relative to the plane of its orbit around the
028 Sun. This minimal axial tilt means that at the poles, some
029 craters and depressions remain in constant shadow, as sun-
030 light never reaches their floors. But, why are we eager to
031 learn about these poorly illuminated dark abyss?

1.1. Why explore the PSRs?

033 Permanently shadowed regions are one of coldest region in
034 the solar system, with temperatures reaching up to -200 de-
035 gree Celsius (nearly close to absolute zero). The absence
036 of direct sunlight and very low temperatures provide a very

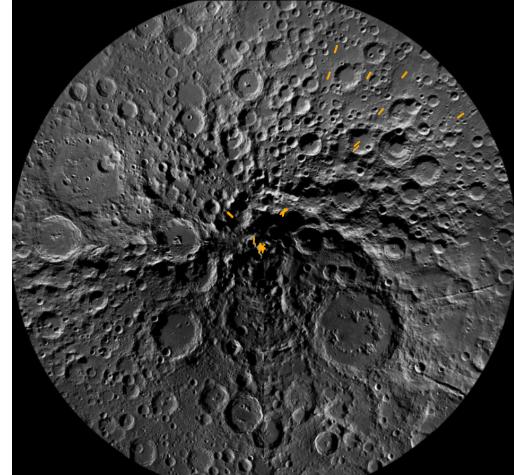


Figure 1. Polar Stereographic image of the South pole of the moon with PSR highlighted.

conducive environment to trap volatile substance such as carbon dioxide and sulfur dioxide alongside water trapped as ice. The potential discovery of water ice is the driving force for space explorations in the enigmatic permanently shadowed regions. In order to aid in mission planning in the permanently shadowed regions we need to have the knowledge about the terrain in those regions. This is usually achieved by sending out exploratory satellites, which will provide us the crucial information to understand the environmental and terrain conditions to perform mission planning for rovers accordingly.

1.2. Problem Formulation

As it turns out the permanently shadowed regions are not completely dark, as shown in Figure 2, whilst they don't receive direct sunlight, they are poorly illuminated by the light scattered by the surrounding craters and mountains. This is the foundational principle to model the problem statement at hand as low light image enhancement problem. We aim to explore existing low-light enhancement methods, and experiment if they are suitable for enhancement of PSR region. The major performance criteria in choosing an algo-

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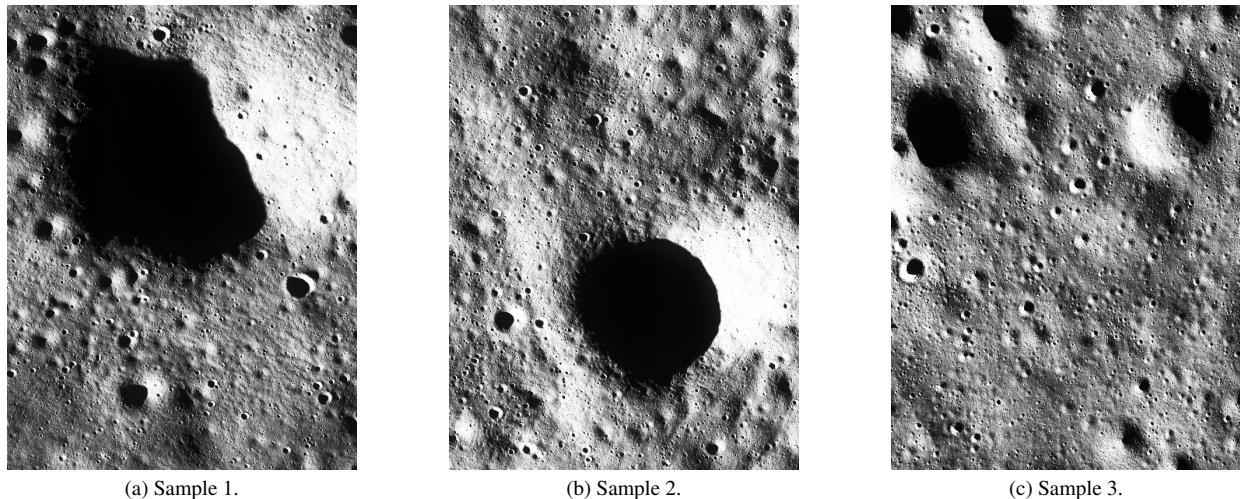


Figure 2. Samples of Permanently Shadowed Region as observed by Chandrayan-2 Orbiter High Resolution Camera

058 rithm is that it should preserve the texture even when
059 enhanced, as the texture in the image contains the information
060 about the terrain. Another major criteria for the any
061 learning based algorithm we develop should be capable of
062 one-shot / few shot learning methodology, due to the lack
063 of extensively labeled and annotated dataset for the perma-
064 ntly shadowed region. It is because of the above reason
065 we are evaluating our methodologies utilizing no reference
066 based image quality assurance metrics such as, Lightness
067 Order Error and SPAQ[4].

068 2. Literature Review and Previous Methods

069 2.1. Traditional Methods

070 Low-light imaging has been a long standing problem and
071 has to be handled on a case to case basis, due to the nature
072 of the problem itself. Exposure correction is a traditional
073 approach utilized in low light image enhancement.
074 A rudimentary approach to exposure correction is performing
075 local and/or global histogram equalization[1] on the input
076 image provide an enhanced output. One of the popular
077 approach is utilizing LIME[5], which optimizes the illumina-
078 tion map of an image to produce an enhanced image by
079 enforcing structure priors. Retinex theory [8] is a widely
080 pursued research direction that builds upon the foundational
081 model of Dual Illumination Estimation[16], a methodology
082 we have implemented for PSR enhancement . These tech-
083 niques require compute extensive parameter tuning for the
084 algorithm to produce the best possible enhancement, which
085 is elucidated in the findings of this research

086 2.2. Learning Based Techniques

087 With the rapid development in Artificial Intelligence and
088 Machine Learning, researchers have explored in its appli-

089 cation in low-light imaging enhancement techniques. Kin
090 Gwn Lore et al[9]. proposed a deep auto encoder based
091 learning method for low light image enhancement, they
092 intelligently brightened an image without over sampling
093 lighter portion of the image with high dynamic range. Deep
094 neural networks[2] are utilized to develop noise source ag-
095 nnostic de noising frameworks, which eliminates the need for
096 knowing about the noise statistics and behavior before de-
097 noising the images. These techniques are employed to per-
098 form low light image enhancement alongside with noise re-
099 duction. Convolution neural networks and diffusion models
100 are the forerunners in low light image enhancements. Con-
101 trollable Light Enhancement Diffusion (CLED) [15]model
102 is a state of the art model, upon which we built our method-
103 ology enhance PSRs. ReCoRo, a GAN based light enhance-
104 ment model which allowed spatial/regional control over the
105 measure of enhancement the model introduced. This is the
106 baseline model which was used as the guideline to building
107 our CLED based PSR enhancement model. LoLi-IEA[10]
108 is CNN based model which adaptively performs both global
109 and local enhancement.

110 2.3. Adaptive SAR Image Processing

111 Synthetic aperture radar (SAR) is an active imaging tech-
112 nology used by satellites, which transmit microwave pulses
113 and analyze their reflections from Earth's surface, captur-
114 ing data regardless of light conditions or weather. Un-
115 like RGB images, which rely on sunlight and are hin-
116 dered by clouds, SAR can penetrate cloud cover and op-
117 erate at night, ensuring reliable data capture[13]. With
118 multi-polarization techniques, SAR provides unique in-
119 sights into terrain characteristics[7], enabling detailed sur-
120 face analysis that optical imagery cannot achieve. Recent
121 research in synthetic aperture radar (SAR) image process-

ing has increasingly focused on addressing challenges related to image diversity, colorization, and generative techniques, which have improved noise handling, spatial detail preservation, and applicability to PolSAR techniques[3]. Zhang et al.[6] introduced terrain-specific colorization using Multidomain Cycle-Consistency GANs, excelling in simple landscapes like farmlands but struggling with complex textures. Other works using deep neural network-based methods[11] reconstruct fully polarimetric SAR images from single-polarization grayscale data but require extensive data. Similarly, pix2pix models and other cyclic adversarial networks face limitations in handling diverse datasets.

3. Datasets

3.1. Permanently shadowed region Dataset

The dataset of permanently shadowed regions are acquired from the Space Applications Centre (SAC) - ISRO[12]. These are collected utilizing the orbiter high resolution camera onboard the Chandrayan-2 satellite. These data points are packaged in a Planetary Data System Version 4 (PDS4) data format. Each data point contains a radiometrically corrected and calibrated high resolution image of the permanently shadowed region. Each high resolution image is a RGB image of resolution 93,653 x 12,000 pixels.

3.2. SAR Imagery Dataset

The study utilizes the SEN1-2 dataset, a comprehensive collection of 282,384 co-registered image patches from Sentinel-1 (SAR) and Sentinel-2 (optical) satellites, encompassing global land masses across all four meteorological seasons which are available under the open access license CC-BY and available for download provided by the library of the Technical University of Munich: <https://mediatum.ub.tum.de/1436631>. The dataset contains 8-bit single-channel SAR images representing 8-bit color optical images using bands 4, 3, and 2. All images are standardized to a 256×256 pixel resolution. Notably, the SAR images exclusively feature VV polarization data, constraining the analysis to the conversion of VV-polarized SAR images to RGB optical representations. To do the computational processing, the dataset was integrated into a Concatenated-Dataset class, enabling simultaneous access to SAR and optical images. The model was trained using data from the spring season, while testing was conducted with data from the summer season.

4. Methodology

4.1. Dual Illumination estimation for PSR enhancement

The crux of Dual illumination estimation for low light image enhancement is that an image I can be characterized

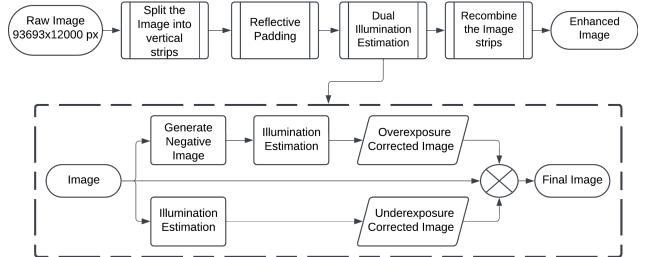


Figure 3. Dual Illumination Estimation Enhancement Framework

as a pixel-wise product of the desired enhanced image I' and a single-channel illumination map L . So, by optimizing the illumination map we can acquire a well enhanced image. The novelty of a Dual illumination estimation framework is that it utilizes a single illumination estimation framework to correct both over and under enhancement in a given image. This is achievable because we process both original image and its negative, the illumination estimation corrects under exposure in original image and over exposure in negative images respectively. This is plausible because over exposure in image presents itself as an under exposed region in negative images. Upon using a vanilla method of dual illumination estimation streaking artifacts were observed, which we had resolved by pre-processing the image by applying reflective padding. The illumination estimation framework is linear estimation process, which has 2 major parameters, lambda (λ) and gamma(γ). The parameter λ controls how similar the new estimate of the illumination(L') is close to original illumination map(L), which is generated by choosing the channel with the highest intensity, removal of optically redundant data. The parameter γ dictates the gamma correction applied to the enhanced image.

4.2. Mask Based Controllable Light Enhancement Diffusion(Mask-CLED)

Controllable Light Enhancement Diffusion framework employs a conditional diffusion model to enhance regions of images to a desired brightness level. Specifically for low-light enhancement, we are required to generate coherent normal-light images that share the content with the input low-light image. Instead of learning the one-to-one mapping between the two domains, we are interested in approximating the conditional distribution using the available paired image samples from the dataset. We employed a binary masking algorithm which generates a mask highlighting the regions of interest for brightness enhancement. This was just a vanilla binary threshold applied on the image, we thresholded at intensity level of 25. This led to a very crude and noisy mask for regions of interest. Dilation was applied on the image, which helped us expand and feather the edges of the mask. Post dilation, we employed blob de-

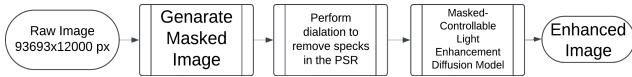


Figure 4. Mask-CLED Model

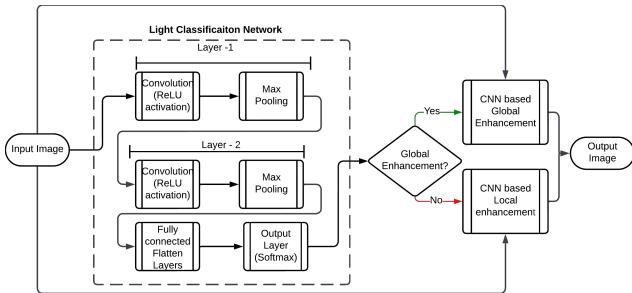


Figure 5. LoLi-IEA Enhancement Framework

212 detection to check for overlapping regions of interest which
 213 were merged to produce a single enhancement region. We
 214 discarded any regions of interest which are smaller than a
 215 user specified pixel size. This is all done to reduce the
 216 computations required for enhancement, and also upon
 217 experimentation we observed bulky and dense masks for region
 218 of interest provided a better enhancement and preservation
 219 of texture in the process. The enhancement is controlled
 220 using a brightness level parameter(λ), this is an embed-
 221 ded parameter in that is embedded into the diffusion model.
 222 The baseline brightness level is extracted by averaging the
 223 pixel values, which is encoded as a discrete nxn embedding
 224 matrix[15] and any intermediate values is filled in using bi-
 225 linear interpolation.

226 4.3. LoLi-IEA - CNN based PSR enhancement

227 This is an extension of the work presented by Ezequiel
 228 Perez-Zaratea et al.[10], we tested the transferability of the
 229 model to permanently shadowed region enhancement. This
 230 is a two stage staggered CNN enhancement methodology.
 231 The first stage CNN model performs light classification, this
 232 determines if local or global enhancement is needed, based
 233 on which it is passed on to a CNN based enhancement net-
 234 work. The second network performs the required light esti-
 235 mation for illumination enhancement. The light classifica-
 236 tion model is trained to detect regions of the images, which
 237 require local or global enhancement. It is a light weight
 238 model with 2 convolution blocks and 2 fully connected lay-
 239 ers. We utilize max pooling in between convolution lay-
 240 ers, alongside with a dropout of 0.5. ReLu is used as the
 241 activation function for the convolution layers and softmax
 242 activation in the last layer. The first stage model takes in
 243 a image and classifies if the image requires global or local
 244 enhancement.

245 The second stage CNN model, performs the illumination
 246 estimation required for enhancement. The network empha-



Figure 6. SAR Colorization Framework

Layer	Input	Output	Kernel Size	Stride
Conv 1	3	32	3x3	1
Pool 1	32	32	2x2	2
Conv 2	32	64	3x3	1
Pool 2	32	32	2x2	2
Flatten 1	64*56*56	128	-	-
Flatten 2	128	2	-	-

Table 1. Light Classification CNN Architecture

247 sizes the repeated application of convolutions and the integration
 248 of features learned at various levels through defined
 249 skip connections. This approach prevents the loss of information
 250 from earlier convolutional layers, making it particularly
 251 effective for image enhancement in low-light conditions
 252 by enabling training based on the image's classification.

254 4.4. SAR Colorization

255 The research employed pix2pix, a Generative Adversarial
 256 Network (GAN) variant, for converting SAR images to optical
 257 images. This approach uses the unique architecture of
 258 GANs, where a generator network creates increasingly realistic
 259 images while a discriminator network attempts to distinguish
 260 between real and generated images, thereby identifying
 261 key regularities and features. Pix2pix distinguishes itself
 262 from traditional GANs by using original images as input
 263 instead of random noise, introducing dropouts for added
 264 variability, and combining U-Net's encoder-decoder struc-
 265 ture with the generator. A critical part is the incorporation
 266 of L1 loss in the generator's loss function, which pre-
 267 vents image blurring and ensures a closer approximation
 268 to the original image. Unlike standard GANs that gen-
 269 erate images from noise through dimension extension and
 270 reduction, pix2pix starts with the original image and uses
 271 dropouts as a noise mechanism. The method was partic-
 272 ularly suited for SAR images, which are characterized by
 273 speckle-like noise and was trained using Sentinel-1 and
 274 Sentinel-2 image pairs that share identical topography—a
 275 dataset challenging to create manually. The training was
 276 conducted with 100 epochs and a mini-batch size of 128,
 277 focusing on transforming SAR and grayscale images into
 278 high-quality RGB optical representations.

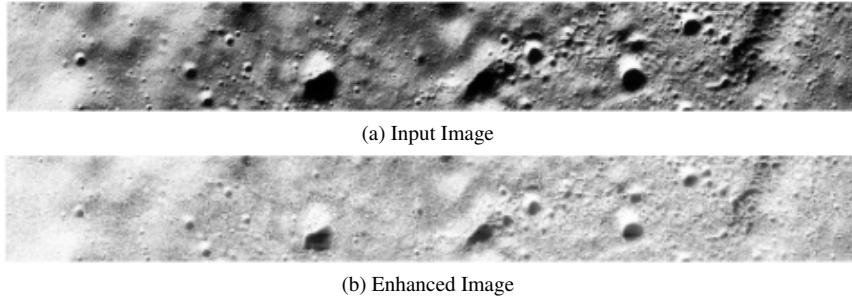


Figure 7. Output from Dual Illumination estimation enhancement

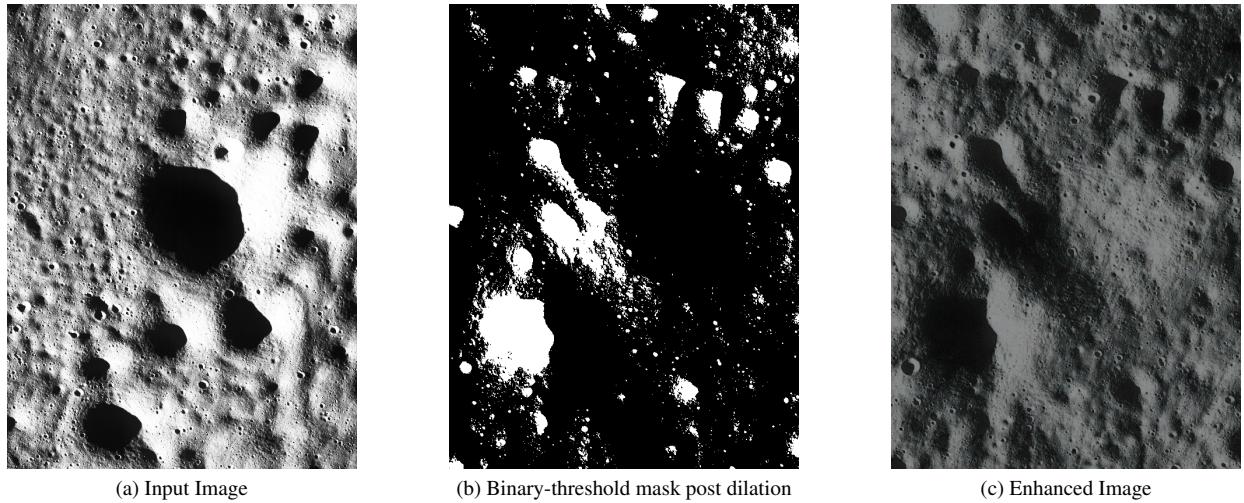


Figure 8. Outputs of CLE Diffusion model enhancement

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5. Simulations and Experiments

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The samples of permanently shadowed regions of the moon were taken and processed through the proposed methodologies and their qualitative and quantitative performance is discussed in this section. We have used the metrics Lightness order Error(LOE)[14] and SPAQ[4]- a perceptual image quality assessment metric, to gauge the performance of our methodologies. The optimal scenario is to have high SPAQ and low LOE scores.

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As discussed previously, we observed streaking artifacts in the enhanced images when we used Dual illumination estimation techniques which we had resolved using reflective padding. Furthermore, we ran experiments to understand the influence the parameter lambda and gamma had on the enhanced image. The experiment results are plotted in Figure 11 & 12, from which we can conclude that we need to choose the lowest viable γ value for any given λ to achieve the lowest possible lightness order error. Also, γ is independent of the parameter λ , which is apparent from the constant lightness order error we achieve when we vary λ for a given γ . So we can empirically choose γ value in accordance

with our use case.

The Mask-Controllable light diffusion model gave qualitatively better result than dual diffusion illumination esti-

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mation model, as indicated by the Figure 14, which was the virtue of the regional enhancement control capabilities of the diffusion model. We ran experiments to understand how the brightness level parameter influences the quality of the enhanced image, this is plotted as a SPAQ score versus

brightness level plot in Figure 13. It is quite evident that the score peaked at brightness level 6 from the plot.

We then shifted our focus to our Convolutional Neural Network-based enhancement technique for enhancement of

permanently shadowed region of the moon. The reason of

experimenting with LoLi-IEA was to alleviate the overhead

of region of interest mask generation used in Mask-CLE

diffusion model. Our hunch paid off, as we got a better

SPAQ score in comparison to dual illumination estimation

enhancement and Mask-CLED model as shown in Figure

14.

The SAR Colorization uses Cyclic Generative Adversarial

Networks (GAN) to develop terrain mapping and coloriza-

tion techniques. By analyzing SAR imagery across differ-



Figure 9. Output from LoLi-IEA model



Figure 10. SAR colorization outputs at using model trained upto different epochs

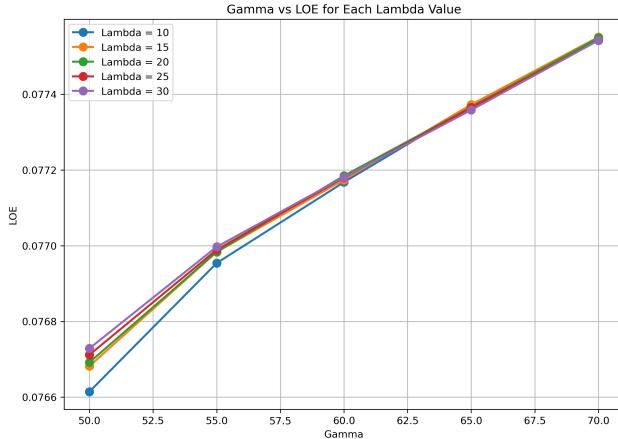


Figure 11. A plot showing Gamma Vs. LOE variation in Dual Illumination Estimation Enhancement

322 ent seasonal contexts, the research demonstrated a notable
323 learning progression, with the most substantial improvements
324 around the 40th training epoch. After this critical

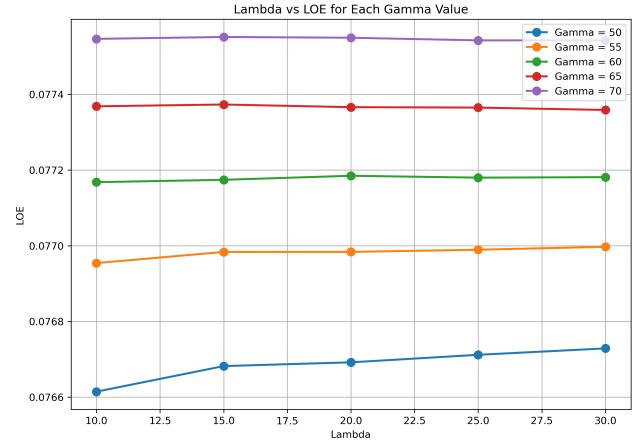


Figure 12. A plot showing Lambda Vs. LOE variation in Dual Illumination Estimation Enhancement

325 point, while the colorization enhancements became incrementally subtle, the results maintained consistent stability.
326 The research methodology strategically employed a training approach that utilized spring season datasets for model development, with subsequent testing and analysis conducted
327 using summer season data, thereby ensuring a comprehensive evaluation of the GAN model's performance across seasonal variations. The generated color images successfully captured broad landscape features like rivers but notably struggled to render precise building details, resulting in blurry architectural representations when converting SAR images to RGB optical-like imagery.

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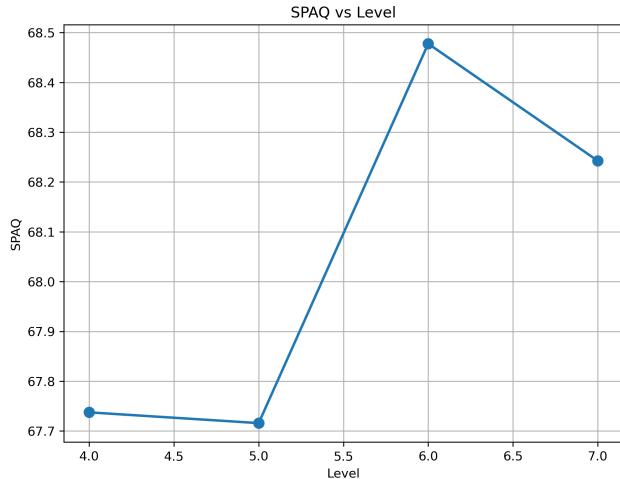


Figure 13. A plot showing variation of SPAQ over different brightness levels in Mask-CLE Diffusion model

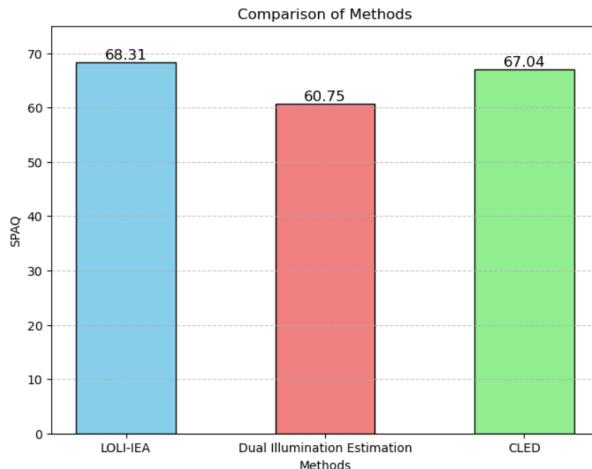


Figure 14. SPAQ Score comparison across different methodologies

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6. Conclusion

In conclusion, the results of our enhancement strategies highlight the need for a context-aware and adaptable approach to reveal hidden details in Permanently Shadowed Regions. Among the low-light enhancement techniques, both CLED and LoLi-IEA performed similarly, with LoLi-IEA being preferred due to its reduced overhead from not requiring explicit ROI mask generation. However, these methods did not improve near-zero regions of the images. Our hypothesis of colorizing SAR images to better understand terrain texture was supported by the results, demonstrating the effectiveness of texture mapping in semantically similar regions. This approach holds promise not only for Earth's terrain but could also be applied to lunar surfaces

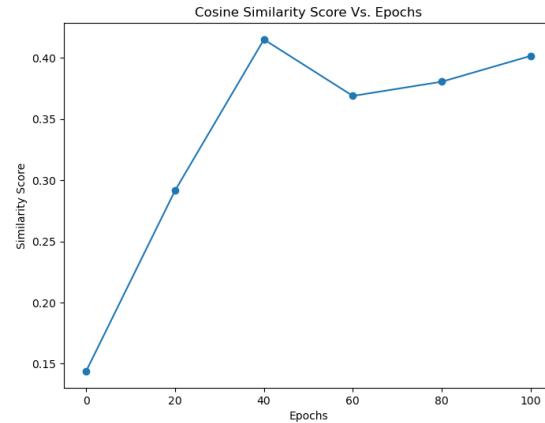


Figure 15. A plot of Cosine similarity score vs Epochs for the Pix-Pix SAR colorization model

once labeled data and SAR images of the moon are available, offering potential for future research.

7. Contribution

Bharath Raam Radhakrishnan, worked on setting up the experimental framework, including problem formulation and data collection for Dual Illumination estimation, CLE Diffusion models and LoLi-IEA models. Aneesh Ojha, worked on the development and fine tuning of SAR Colorization pix-pix cyclic gan model. The contribution percentage of the authors towards the research presented in the paper is as follows

- Bharath Raam Radhakrishnan - 50%
- Aneesh Ojha - 50%

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