Support Vector Machines (SVMs)

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Motivaton of Machine Learning

Suppose we have 50 photographs of elephants and 50 photos of tigers.





VS.

We digitize them into 100×100 pixel images, so we have $x \in \mathbb{R}^n$, where n = 10,000.

Now, given a new (different) photograph we want to answer the question: is it an elephant or a tiger? [we assume it is one or the other]

Introduction

What are SVMs?

SVMs are **supervised learning** models with associated learning algorithms that analyze data used for **classification** and **regression analysis**.

Goal of SVM?

To find the **optimal separating hyperplane** which maximizes the margin of the **training data**.

Introduction

Supervised Learning

A machine learning task of inferring a function from labeled training data.

Classification

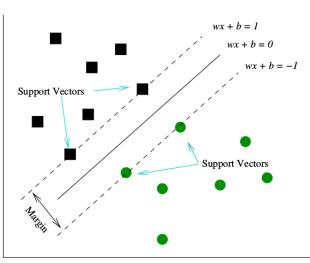
The problem of identifying to which of a set of categories a new observation belongs, on the basis of a training set of data containing observations whose category membership is known.

Regression Analysis

A statistical process for estimating the relationships among variables.

SVM: Idea





WindGustSpeed

Training Data

$$(x_1, y_1), ..., (x_n, y_m) \in \mathcal{X} \times \{\pm 1\}$$

where,

 ${\mathcal X}$ is some non-empty set

 x_i are inputs/patterns/cases

 y_i are outputs/labels/targets

 $\{\pm 1\}$ is binary classification/pattern recognition

Similarity Measure

$$k: \mathcal{X} \times \mathcal{X} \mapsto \mathbb{R}$$

$$(x,x')\mapsto k(x,x')$$

where, k is **kernel** (similarity function) and unless stated, is assumed symmetric, i.e.,

$$k(x, x') = k(x', x) \ \forall x, x' \in \mathcal{X}$$

Kernels are used to calculate dot product in **feature space**, \mathcal{H} .

Types of Kernels

Polynomial kernel

$$k(x, x') = \langle x, x' \rangle^d$$

Gaussian

$$k(x,x') = exp\left(-\frac{\left\|x - x'\right\|^2}{2\sigma^2}\right)$$

Sigmoid

$$k(x, x') = tanh(\kappa \langle x, x' \rangle + \Theta)$$

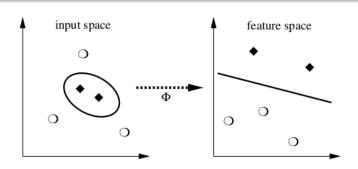
with suitable choices of $d \in \mathbb{N}$ and $\sigma, \kappa, \Theta \in \mathbb{R}$

Feature Space

$$\Phi: \mathcal{X} \mapsto \mathcal{H}$$

$$x \mapsto \mathbf{x} := \Phi(x)$$

where \mathcal{H} is **Feature Space** and **x** is vector representation of x in \mathcal{H} .



Advantages of Feature Space

ullet Easy to define a similarity measure from dot product in ${\cal H}$

$$k(x,x') := \langle \mathbf{x}, \mathbf{x}' \rangle = \langle \Phi(x), \Phi(x') \rangle$$

- Easy to deal with the patterns geometrically.
- Freedom to choose Φ allows us to design a large variety of similarity measures and learning algorithms.

Hyperplane

An hyperplane is a generalization of a plane

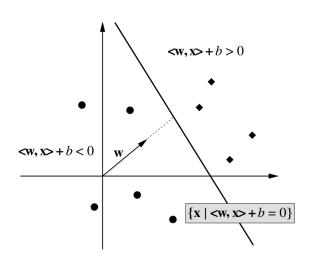
- in one dimension, an hyperplane is called a point
- in two dimensions, it is a line
- in three dimensions, it is a plane
- in more dimensions you can call it an hyperplane

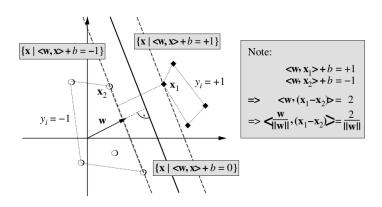


The point L is a separating hyperplane in one dimension

Optimal Separating Hyperplane

- Maximum margin of separation between any training point and hyperplane
- $\bullet \; \max_{\mathbf{w},b} \min \left\{ \|\mathbf{x} \mathbf{x}_i\| : \mathbf{x} \in \mathcal{H}, \langle \mathbf{w}, \mathbf{x} \rangle + b = 0, i = 1,...,m \right\}$
- where $\langle \mathbf{w}, \mathbf{x} \rangle + b = 0$ is the class of hyperplanes in some dot product space \mathcal{H} such that $\mathbf{w} \in \mathcal{H}, b \in \mathbb{R}$.





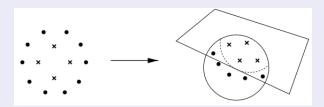
SVM: Non-linear case

- Map data into a richer feature space including nonlinear features
- construct a hyperplane in that space so all other equations are the same
- Formally, pre-process the data with:

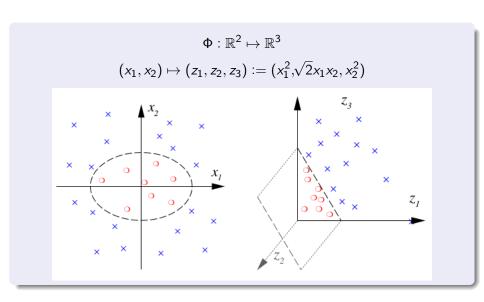
$$x \mapsto \Phi(x)$$

• then learn the map from $\Phi(x)$ to y:

$$f(x) = w.\Phi(x) + b$$



SVM: Polynomial mapping



SVM: Kernel trick

- Problem: dimensionality of $\Phi(x)$ can be very large, making w hard to represent explicitly in memory.
- The Representer theorem (Kimeldorf and Wahba, 1971) shows that (for SVMs as a special case):

$$w = \sum_{i=1}^{m} \alpha_i \Phi(x_i)$$

• for some α , instead of optimizing w directly we can optimize α .

$$f(x) = \sum_{i=1}^{m} \alpha_i \Phi(x_i) \cdot \Phi(x) + b$$

• Where $K(x_i, x) = \Phi(x_i) \cdot \Phi(x)$ is the kernel function.

Selected Observations

Two input variables (i.e.,two-dimensional space):Pressure3pm and Sunshine

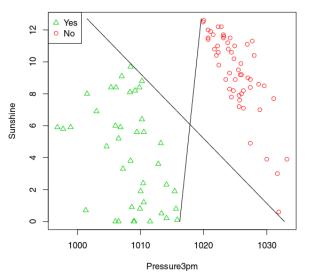


Figure: A simple and easily linearly separable collection of observations

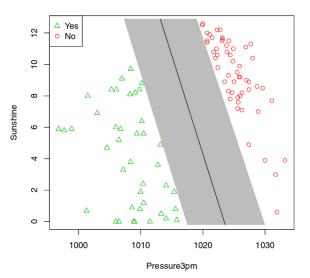


Figure: Maximal region or margin between the two classes of observations

Algorithm(Original Observations)

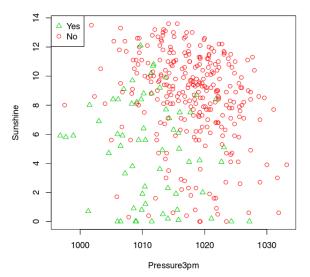


Figure: A nonlinearly separable collection of observations

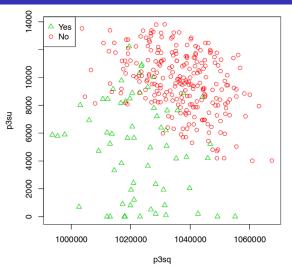


Figure: Nonlinearly transformed observations showing Pressure3pm squared (x-axis) against Pressure3pm multiplied by Sunshine, artificially

SVM: Overview

SVM: Advantages

- Performs well on problems that are nonlinear, sparse, and high-dimensional.
- Modeling only deals with support vectors instead of whole training data set(training-set size independent).
- The model is less affected by outliers.

SVM: Overview

SVM: Disadvantages

- Sensitive to the choice of tuning option (e.g., the type of transformations to perform), making it harder to use and timeconsuming to identify the best model.
- Transformations performed can be computationally expensive and are performed both whilst building the model and when scoring new data.

References

- Data Mining with Rattle and R: Graham Williams.
- Tutorial learning-with-kernels: Schölkopf.
- Support Vector Machine Tutorial: Jason Weston: NEC Labs America, 4 Independence Way, Princeton, USA.
- 4 http://www.svm-tutorial.com

Thank you for your attention.