

Q42. (a) given  $\vec{x}$ ,  $\hat{e}_i$ ,  $[\vec{x}]_F = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \vec{x} \cdot \hat{e}_1 \\ \vec{x} \cdot \hat{e}_2 \\ \vec{x} \cdot \hat{e}_3 \end{bmatrix}$

(b) given:  $R$ ,  $\hat{e}_i$   
 $R_{ij} = \hat{e}_i \cdot \hat{e}_j'$   
 $= \hat{e}_i \cdot R \cdot \hat{e}_j$

(c) given  $\hat{e}_i$ ,  $\hat{e}_i'$  find  $R_{ij}$   
 $R = \hat{e}_i \cdot \hat{e}_i'$   
 $\Rightarrow R_{ij} = \hat{e}_i \cdot \hat{e}_j'$

(d) given  $R_{ij}$ ,  $x_i$ , find  $x_i^*$   
 $\vec{x}^* = R \cdot \vec{x}$   
 $\therefore x_i^* = R_{ij} x_j$

(e) given  $R_{ij}$ ,  $x_i$ , find  $x_{\beta i}^*$   
 $x_{\beta i}^* = x_{\beta i}$   
 $\Rightarrow x_{\beta i}^* = x_i$  (assume fixed frame)

(f) given  $R_{ij}$ ,  $x_i^*$  find  $x_i$   
 $\vec{x}^* = A \cdot \vec{x}$   
 $\Rightarrow \vec{x} = R^{-1} \vec{x}^*$   
 $\Rightarrow \vec{x} = R^T \vec{x}^*$  ( $R^{-1} = R^T$ )  
 $\Rightarrow x_i = R_{ji} x_j^*$

(g) Given  $R_{ij}$ ,  $a_i^*$  find  $a_{\beta i}$

$$a_i = R_{ji} a_j^*$$

~~$$a_i = R_{ji} a_j^*$$~~

$$a_{\beta i} = R^T a_i$$

$$\rightarrow a_{\beta i} = R_{ki} a_k$$

$$= \underline{R_{ki} R_{jk} a_j^*}$$

(h) Given  $R_{ij}$ , find  $R_{\beta ij}$ ,  $R_{ij} = \hat{e}_i \cdot \hat{e}_j'$

$$R_{\beta ij} = \hat{e}_i' \cdot \hat{e}_j'$$

$$(i) \{a^*\}_F = \begin{bmatrix} \vec{a}^* \cdot \hat{e}_1 \\ \vec{a}^* \cdot \hat{e}_2 \\ \vec{a}^* \cdot \hat{e}_3 \end{bmatrix} = R [a]_F = \cancel{R} = R \cdot R \cdot [a]_F$$

(j)  $A = R_{ij} \hat{e}_i' \hat{e}_j'$ ,  $A = A_{ij} \hat{e}_i \hat{e}_j$

$$A_{ij} = \hat{e}_i \cdot A \cdot \hat{e}_j$$

$$= \hat{e}_i \cdot (R_{kl} \hat{e}_k' \hat{e}_l') \cdot \hat{e}_j$$

$$= \hat{e}_i \cdot (\sum_{kl} R_{kl} \hat{e}_k' \hat{e}_l'), \hat{e}_j$$

$$= \sum_{kl} R_{kl} (\hat{e}_i \cdot \hat{e}_k') (\hat{e}_l' \cdot \hat{e}_j)$$

$$= \sum_{kl} R_{kl} \delta_{ki} (\hat{e}_l' \cdot \hat{e}_j)$$

$$= \sum_l R_{li} (\hat{e}_l' \cdot \hat{e}_j)$$

$$= \sum_l R_{li} R_{jl}$$

$$= R_{il} R_{jl}$$

~~$$\Rightarrow A = R R^T = R R^{-1} = I$$~~

$$\rightarrow A_{ij} = \delta_{ij}$$