Light shift and effective B field

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1 Goal

Derive and clarify some effects related to vector and tensor light shifts as well as a few different places they may appear in an experiment. Most, if not all of the discussion will be limited to E1 transitions. I'm not really looking for the most mathematically straight forward derivation, rather trying to see this from different angle for better understanding.

2 Summary of main results¹

See the linked sections for the quantitative results.

- 1. Section 4.1.1 checks the Stark shift's dependency on m_F by explicitly compute it using the Clebsch-Gordan coefficients. It confirms that the dependency of the Stark shift on m_F is at most a second order polynomial and it has the expected symmetry when driven with linear or circular polarized light.
- 2. Section 4.1.2 proves that the second order coupling between to states F and F' is proportional to the Clebsch-Gordan coefficients $\langle F', m'_F | F, k; m_F, p \rangle$ where k = 0, 1, 2 denotes scalar, vector and tensor coupling.

3 Some useful formulas

3.1 Spherical component of vector

Similar to the decomposition of light polarization into σ^{\pm} and π , every 3D vector (operator) can be equivalently expressed as a rank-1 spherical tensor,

$$V_0 = V_z$$

$$V_{\pm 1} = \mp \frac{1}{\sqrt{2}} (V_x \pm iV_y)$$
(1)

In particular, when applied to the angular momentum operator,

$$J_0 = J_z$$

$$J_{\pm 1} = \mp \frac{1}{\sqrt{2}} (J_x \pm iJ_y)$$

$$= \mp \frac{J_{\pm}}{\sqrt{2}}$$
(2)

¹ "Results" as in ones that are hard to find elsewhere in a form that I like. I'm sure many people have derived/used these before. This does not include standard ones like Wigner-Eckart theorem since it's easy to find reference for it.

where J_{\pm} are the angular momentum raising and lowering operators.

For the complex conjugate of the vector V^* , defined as

$$(V^*)_{x,y,z} = V^*_{x,y,z} \tag{3}$$

The spherical components are

$$(V^*)_0 = V_z^*$$

$$(V^*)_{\pm 1} = \mp \frac{1}{\sqrt{2}} (V_x^* \pm i V_y^*)$$
(4)

Note that in general $(V^*)_{\pm 1} \neq V^*_{\pm 1}$. In fact,

$$V_{\pm 1}^* = \mp \frac{1}{\sqrt{2}} (V_x^* \mp i V_y^*)$$

= $- (V^*)_{\mp 1}$ (5)

$$V_q^* = (-1)^q (V^*)_{-q} \tag{6}$$

i.e. the +1 component of V^* is related to the -1 component of V, and the -1 component of V^* is related to the +1 component of V.

Dot product of two vector

$$\vec{A} \cdot \vec{B} = \sum_{i=x,y,z} A_i B_i$$

$$= -A_{-1}B_{+1} - A_{+1}B_{-1} + A_0 B_0$$

$$= \sum_{q=-1,0,1} (-1)^q A_q B_{-q}$$

$$= \sum_{q=-1,0,1} \sqrt{3} \langle 0, 0 | 1, 1; q, -q \rangle A_q B_{-q}$$
(7)

3.2 Wigner-Eckart theorem

This describes the relation between matrix elements of a vector/tensor operator in the angular momentum basis. The matrix element for different angular momentum states are related to each other with Clebsch-Gordan coefficients.

$$\langle j, m | T_q^{(k)} | j', m' \rangle = \langle j', k; m', q | j, m \rangle \langle j | | T^{(k)} | | j' \rangle$$

$$\tag{8}$$

where $T_q^{(k)}$ is the q-th component of the spherical tensor operator $T^{(k)}$ of rank k. This is the result of rotation symmetry between all the matrix elements.

Equivalently, this also means that no matter what the tensor operator is, it's matrix elements in this (between these) subspace differs from that of a different tensor operator only by a constant factor. (Note that this factor could depend on the j and j' (just not m and m') and it can of course be 0 as well), i.e.

$$\langle j, m | T_1_q^{(k)} | j', m' \rangle \propto \langle j, m | T_2_q^{(k)} | j', m' \rangle \tag{9}$$

3.3 When j = j'

A special case for the Wigner-Echart theorem is when j = j'. In this case we can plug in the angular momentum operator J (this would otherwise result in vanishing matrix elements if $j \neq j'$ since J conserves, well, j).

$$\langle j, m | J_q | j, m' \rangle = \langle j, 1; m', q | j, m \rangle \langle j | |J| | j \rangle$$

$$\propto \langle j, 1; m', q | j, m \rangle$$
(10)

This allow us to replace the CG coefficients with the angular momentum operator, i.e.,

$$\langle j, m | V_q | j, m' \rangle \propto \langle j, m | J_q | j, m' \rangle$$
 (11)

which could make some calculation/expression significantly simpler.

This relation basically states that within the subspace of a single j, we can treat any vector operator as proportional to the angular momentum. The proportionality factor can then be obtained from the dot product with angular momentum, i.e. the projection of the vector onto angular momentum.

3.3.1 m=0 selection rule

The selection rule for m = m' = 0 transition directly follows from this relation since,

$$\langle j, m | V_0 | j, m \rangle \propto \langle j, m | J_0 | j, m \rangle$$

$$= \langle j, m | J_z | j, m \rangle$$

$$= m$$
(12)

which is 0 when m = 0.

3.3.2 Projection theorem

We can use this to derive the projection theorem. Explicitly writing down the proportionality factor in Eq. 11, we have,

$$\langle j, m | V_q | j, m' \rangle = c \langle j, m | J_q | j, m' \rangle \tag{13}$$

Multiply both sides with the angular momentum matrix element and sum over all m' and q

$$\sum_{m',q} \langle j, m | V_q | j, m' \rangle \langle j, m' | J_q^{\dagger} | j, m'' \rangle = c \sum_{m',q} \langle j, m | J_q | j, m' \rangle \langle j, m' | J_q^{\dagger} | j, m'' \rangle$$
(14)

$$\sum_{q} \langle j, m | V_q V_q^{\dagger} | j, m'' \rangle = c \sum_{q} \langle j, m | J_q J_q^{\dagger} | j, m'' \rangle$$
(15)

$$\langle j, m | (\vec{V} \cdot \vec{J}) | j, m'' \rangle = c \langle j, m | J^2 | j, m'' \rangle$$

$$= cj(j+1)$$
(16)

Therefore we have

$$c = \frac{\langle j, m | (\vec{V} \cdot \vec{J}) | j, m'' \rangle}{j(j+1)} \tag{17}$$

$$\langle j, m | V_q | j, m' \rangle = \frac{\langle j, m | (\vec{V} \cdot \vec{J}) | j, m'' \rangle}{j(j+1)} \langle j, m | J_q | j, m' \rangle \tag{18}$$

3.3.3 Explicit calculation

Just for completeness, we can verify this relation between angular momentum and CG coefficients explicitly. This part can be ignored without affecting the understanding of the rest. First the expression using angular momentum operators,

$$\langle j, m|J_{0}|j, m'\rangle = \langle j, m|m'|j, m'\rangle$$

$$= m'\delta_{mm'}$$

$$\langle j, m|J_{\pm 1}|j, m'\rangle = \mp \frac{1}{\sqrt{2}}\langle j, m|J_{\pm}|j, m'\rangle$$

$$= \mp \sqrt{\frac{(j \mp m')(j \pm m' + 1)}{2}}\langle j, m|j, m' \pm 1\rangle$$

$$= \mp \sqrt{\frac{(j \mp m')(j \pm m' + 1)}{2}}\delta_{m,m'\pm 1}$$
(20)

Using the explicit formula for the CG coefficients,

$$\langle j, 1; m', q | j, m \rangle = \delta_{m,m'+q} \sqrt{\frac{(2j+1)(j+j-1)!(j-j+1)!(j+1-j)!}{(j+1+j+1)!}}$$

$$\sqrt{(j+m)!(j-m)!(j-m')!(j+m')!(1-q)!(1+q)!}$$

$$\sum_{k} \frac{(-1)^{k}}{k!(j+1-j-k)!(j-m'-k)!(j+q-k)!(j-1+m+k)!(j-j-q+k)!}$$

$$= \delta_{m,m'+q} \frac{\sqrt{(j+m)!(j-m)!(j-m')!(j+m')!(1-q)!(1+q)!}}{2\sqrt{(j+1)j}}$$

$$\sum_{k} \frac{(-1)^{k}}{k!(1-k)!(j-m'-k)!(1+q-k)!(j-1+m'+k)!(-q+k)!}$$
(21)

For q = 0

$$\langle j, 1; m', 0 | j, m \rangle = \delta_{mm'} \frac{\sqrt{(j+m)!(j-m)!(j-m)!(j+m)!}}{2\sqrt{(j+1)j}}$$

$$\sum_{k=0,1} \frac{(-1)^k}{k!(1-k)!(j-m-k)!(1-k)!(j-1+m+k)!k!}$$

$$= \delta_{mm'} \frac{(j-m)!(j+m)!}{2\sqrt{(j+1)j}} \left(\frac{1}{(j-m)!(j-1+m)!} - \frac{1}{(j-m-1)!(j+m)!} \right)$$

$$= m \frac{\delta_{mm'}}{\sqrt{j(j+1)}}$$
(22)

For $q = \pm 1$

$$\langle j, 1; m', \pm 1 | j, m \rangle = \delta_{m,m'\pm 1} \frac{\sqrt{(j+m)!(j-m)!(j-m')!(j+m')!(1\mp 1)!(1\pm 1)!}}{2\sqrt{(j+1)j}}$$

$$\sum_{k} \frac{(-1)^{k}}{k!(1-k)!(j-m'-k)!(1\pm 1-k)!(j-1+m+k)!(\mp 1+k)!}$$

$$= \frac{\delta_{m,m'\pm 1}}{\sqrt{(j+1)j}} \sqrt{\frac{(j+m'\pm 1)!(j-m'\mp 1)!(j-m')!(j+m')!}{2}}$$

$$\sum_{k} \frac{(-1)^{k}}{k!(1-k)!(j-m'-k)!(1\pm 1-k)!(j-1+m'+k)!(\mp 1+k)!}$$
(23)

For q = 1

$$\langle j, 1; m', 1 | j, m \rangle = \frac{\delta_{m,m'+1}}{\sqrt{(j+1)j}} \sqrt{\frac{(j+m'+1)!(j-m'-1)!(j-m')!(j+m')!}{2}}$$

$$\sum_{k} \frac{(-1)^{k}}{k!(1-k)!(j-m'-k)!(1+1-k)!(j-1+m'+k)!(-1+k)!}$$

$$= -\frac{\delta_{m,m'+1}}{\sqrt{(j+1)j}} \sqrt{\frac{(j+m'+1)!(j-m'-1)!(j-m')!(j+m')!}{2(j-m'-1)!(j-m'-1)!(j+m')!}}$$

$$= -\sqrt{\frac{(j+m'+1)(j-m')}{2}} \frac{\delta_{m,m'+1}}{\sqrt{(j+1)j}}$$
(24)

For q = -1

$$\langle j, 1; m', -1 | j, m \rangle = \frac{\delta_{m,m'-1}}{\sqrt{(j+1)j}} \sqrt{\frac{(j+m'-1)!(j-m'+1)!(j-m')!(j+m')!}{2}}$$

$$\sum_{k} \frac{(-1)^{k}}{k!(1-k)!(j-m'-k)!(-k)!(j-1+m'+k)!(1+k)!}$$

$$= \frac{\delta_{m,m'-1}}{\sqrt{(j+1)j}} \sqrt{\frac{(j+m'-1)!(j-m'+1)!(j-m')!(j+m')!}{2(j-m')!(j-m')!(j+m'-1)!(j+m'-1)!}}$$

$$= \sqrt{\frac{(j-m'+1)(j+m')}{2}} \frac{\delta_{m,m'-1}}{\sqrt{(j+1)j}}$$
(25)

Comparing the result from the two methods, we can see that the proportionality factor is $\sqrt{(j+1)j}$, or

$$\langle j, m | J_q | j, m' \rangle = \sqrt{(j+1)j} \langle j, 1; m', q | j, m \rangle \tag{26}$$

4 Vector and tensor light shift

4.1 Direct derivation

The coupling between state $|F, m_F\rangle$ and $|F', m_F'\rangle$

$$\langle F, m_F | d_{-q} | F', m_F' \rangle = \langle F | | \mathbf{d} | | F' \rangle \langle F, m_F | F', 1; m_F', -q \rangle$$

$$(27)$$

$$= \langle F||\mathbf{d}||F'\rangle(-1)^{F'-1+m_F}\sqrt{2F+1}\begin{pmatrix} F' & 1 & F\\ m_F' & -q & m_F \end{pmatrix}$$
(28)

where F and m_F (F' and m_F') are the total angular momentum and its projection for the initial (final) state. d is the dipole operator and q is the label for the spherical harmonic component (-1, 0, or 1). $q = \pm 1$ corresponds to the σ^{\pm} polarization/transition and q = 0 corresponds to the π polarization/transition.

4.1.1 Diagonal terms (Stark shifts) only

We can first calculate the Stark shift for a pure $(\sigma^+, \pi \text{ or } \sigma^-)$ polarization. This is the case that contains no non-diagonal terms. We should be able to use this to verify the m_F dependency of the final effect. (Scalar, vector and tensor shift should corresponds to 0, 1 and 2 order terms of m_F respectively).

Since we only care about the m_F dependency, we can ignore everything that's m_F independent.

The Stark shift.

$$\Delta E \propto \langle F, m_{F} | d_{-q} | F', m'_{F} \rangle \langle F', m'_{F} | d_{q} | F, m_{F} \rangle$$

$$\propto |\langle F, m_{F} | F', 1; m'_{F}, -q \rangle|^{2}$$

$$\propto (F + m_{F})! (F - m_{F})! (F' - m_{F} - q)! (F' + m_{F} + q)!$$

$$\left| \sum_{k} \frac{(-1)^{k}}{k! (1 - q - k)! (F' - F + 1 - k)! (F - F' + q + k)! (F' - q - k - m_{F})! (F - 1 + q + k + m_{F})!} \right|^{2}$$
(29)

The last proportionality relation uses the generic explicit expression for the Clebsch-Gordan coefficients (ignoring m_F independent factors). The sum is over all the k's where the factorials are non-negative. We'll call the last expression $\Delta'(m_F, q)$ in the following part for simplicity. For q = -1

$$\Delta'(m_F, -1) = (F + m_F)!(F - m_F)!(F' - m_F + 1)!(F' + m_F - 1)!$$

$$\left| \sum_{k} \frac{(-1)^k}{k!(2-k)!(F' - F + 1 - k)!(F - F' - 1 + k)!(F' + 1 - k - m_F)!(F - 2 + k + m_F)!} \right|^2$$
(30)

Since we have $F'-F+1-k \ge 0$ and $F-F'-1+k \ge 0$, we have k=F'-F+1, (with the explicit condition to make sure $F'+m_F-1 \ge 0$)

$$\Delta'(m_F, -1) = \begin{cases}
\frac{(F + m_F)!(F' - m_F + 1)!}{((F' - F + 1)!(F - F' + 1)!)^2(F - m_F)!(F' + m_F - 1)!} & (m_F \geqslant 1 - F') \\
0 & (m_F < 1 - F')
\end{cases}$$
(31)

To simplify this further, we used the fact that F' = F - 1, F, F + 1

$$\Delta'(m_F, -1) = \begin{cases} \frac{(F + m_F)!(F - m_F)!}{4(F - m_F)!(F + m_F - 2)!} & (m_F \ge 2 - F, F' = F - 1) \\ 0 & (m_F < 2 - F, F' = F - 1) \\ \frac{(F + m_F)!(F - m_F + 1)!}{(F - m_F)!(F + m_F - 1)!} & (m_F \ge 1 - F, F' = F) \\ 0 & (m_F < 1 - F, F' = F) \\ \frac{(F + m_F)!(F - m_F + 2)!}{4(F - m_F)!(F + m_F)!} & (m_F \ge 1 - (F + 1), F' = F + 1) \\ 0 & (m_F < 1 - (F + 1), F' = F + 1) \end{cases}$$

$$\Delta'(m_F, -1) = \begin{cases} \frac{(F + m_F)(F + m_F - 1)}{4} & (F' = F - 1) \\ \frac{(F + m_F)(F - m_F + 1)}{4} & (F' = F) \\ \frac{(F - m_F + 2)(F - m_F + 1)}{4} & (F' = F + 1) \end{cases}$$

$$(32)$$

The final simplification uses the fact that $m_F \geqslant F$ and that the expression produces the right value (i.e. 0) even for out-of-bound m_F . For q = 0,

$$\Delta'(m_F, 0) = (F + m_F)!(F - m_F)!(F' - m_F)!(F' + m_F)!$$

$$\left| \sum_{k} \frac{(-1)^k}{k!(1-k)!(F' - F + 1 - k)!(F - F' + k)!(F' - k - m_F)!(F - 1 + k + m_F)!} \right|^2$$
(34)

Conditional on the value of F'

$$\Delta'(m_F, 0) = \begin{cases}
(F + m_F)!(F - m_F)!(F - 1 - m_F)!(F - 1 + m_F)! \\
\left| \sum_{k} \frac{(-1)^k}{k!(1-k)!(-k)!(1+k)!(F - 1 - k - m_F)!(F - 1 + k + m_F)!} \right|^2 & (F' = F - 1) \\
(F + m_F)!(F - m_F)!(F - m_F)!(F + m_F)! \\
\left| \sum_{k} \frac{(-1)^k}{k!(1-k)!(1-k)!k!(F - k - m_F)!(F - 1 + k + m_F)!} \right|^2 & (F' = F) \\
(F + m_F)!(F - m_F)!(F' - m_F)!(F' + m_F)! \\
\left| \sum_{k} \frac{(-1)^k}{k!(1-k)!(2-k)!(-1+k)!(F + 1 - k - m_F)!(F - 1 + k + m_F)!} \right|^2 & (F' = F + 1)
\end{cases}$$

For the first and third case, k can only be 0 and 1 respectively. For the second case, k can be either

0 or 1 and we need to sum over both

$$\Delta'(m_F, 0) = \begin{cases}
\frac{(F + m_F)!(F - m_F)!(F - 1 - m_F)!(F - 1 + m_F)!}{((F - 1 - m_F)!(F - 1 + m_F)!)^2} & (F' = F - 1) \\
\frac{(F + m_F)!(F - m_F)!(F - 1 + m_F)!}{(F - m_F)!(F - m_F)!(F + m_F)!} & (F' = F)
\end{cases}$$

$$\Delta'(m_F, 0) = \begin{cases}
\frac{1}{(F - m_F)!(F - 1 + m_F)!} - \frac{1}{(F - 1 - m_F)!(F + m_F)!} \\
\frac{(F + m_F)!(F - 1 + m_F)!(F + 1 - m_F)!(F + 1 + m_F)!}{((F - m_F)!(F + m_F)!)^2}
\end{cases}$$

$$(F' = F - 1)$$

$$(F' = F - 1)$$

$$(F' = F + 1)$$

$$\Delta'(m_F, 0) = \begin{cases} F^2 - m_F^2 & (F' = F - 1) \\ 4m_F^2 & (F' = F) \\ (F + 1)^2 - m_F^2 & (F' = F + 1) \end{cases}$$

$$(37)$$

For q = 1,

$$\Delta'(m_F, 1) = (F + m_F)!(F - m_F)!(F' - m_F - 1)!(F' + m_F + 1)!$$

$$\left| \sum_{k} \frac{(-1)^k}{k!(-k)!(F' - F + 1 - k)!(F - F' + 1 + k)!(F' - 1 - k - m_F)!(F + k + m_F)!} \right|^2$$
(38)

which requires k=0,

$$\Delta'(m_F, 1) = \frac{(F + m_F)!(F - m_F)!(F' - m_F - 1)!(F' + m_F + 1)!}{((F' - F + 1)!(F - F' + 1)!(F' - 1 - m_F)!(F + m_F)!)^2}$$

$$= \frac{(F - m_F)!(F' + m_F + 1)!}{((F' - F + 1)!(F - F' + 1)!)^2(F' - m_F - 1)!(F + m_F)!}$$
(39)

Here we omitted the check for $F' - m_F - 1 \ge 0$ since the final expression would not depend on it. Conditional on the F' values

$$\Delta'(m_F, 1) = \begin{cases}
\frac{(F - m_F)!(F + m_F)!}{4(F - m_F - 2)!(F + m_F)!} & (F' = F - 1) \\
\frac{(F - m_F)!(F + m_F + 1)!}{(F - m_F)!(F + m_F)!} & (F' = F) \\
\frac{(F - m_F)!(F + m_F + 2)!}{4(F - m_F)!(F + m_F)!} & (F' = F + 1)
\end{cases}$$

$$\Delta'(m_F, 1) = \begin{cases}
\frac{(F - m_F)(F - m_F - 1)}{4} & (F' = F - 1) \\
\frac{(F - m_F)(F + m_F + 1)}{4} & (F' = F) \\
\frac{(F - m_F)(F + m_F + 1)}{4} & (F' = F + 1)
\end{cases}$$
(41)

$$\Delta'(m_F, 1) = \begin{cases} \frac{(F - m_F)(F - m_F - 1)}{4} & (F' = F - 1)\\ (F - m_F)(F + m_F + 1) & (F' = F)\\ \frac{(F + m_F + 2)(F + m_F + 1)}{4} & (F' = F + 1) \end{cases}$$
(41)

We can see that the expressions for $\Delta'(m_F,q)$ are all second order polynomials of m_F . We can also verify that $\Delta'(-m_F, 1) = \Delta'(m_F, -1)$ as required by symmetry.

We can also see that for circular polarization $(q = \pm 1)$ the resulting shift always have a non-zero linear term. The slope of this term is $\frac{1-2F}{4}$, -1, and $\frac{2F+3}{4}$ for σ^+ polarization (q=1) and F' = F - 1, F, F + 1 respectively². On the other hand, the expressions for π polarization never have

²For the F' = F - 1 expression, 1 - 2F may be 0 for $F = \frac{1}{2}$ but this cannot happen for F' = F - 1.

any linear m_F term which is also consistent with symmetry.

It is somewhat interesting that the coefficient for the second order terms are never zero, even for $F=0,\frac{1}{2}$ cases where tensor shift does not exist. Of course since there are not enough "sampling points" on the polynomial the m_F^2 term would just appear at most as a global energy shift in such cases.

4.1.2 Full generic effective Hamiltonian for a single excited state

When the polarization of the light is not one of the pure polarizations, the effect of the second order perturbation would contain off-diagonal terms in addition to the diagonal ones. In such cases, we would need to calculate the full effective Hamiltonian matrix instead of only the Stark shifts.

Let the amplitude of the light be A_q , where q = -1, 0, 1 corresponds to the σ^- , π and σ^+ polarizations. The matrix element for the effective Hamiltonian is,

$$\langle F, m_{F} | H_{\text{eff}} | F', m_{F}' \rangle$$

$$= \frac{1}{4\Delta} \sum_{m_{F}'', q, q'} \langle F, m_{F} | (-1)^{q} A_{q} d_{-q} | F'', m_{F}'' \rangle \langle F'', m_{F}'' | ((-1)^{q'} A_{q'} d_{-q'})^{\dagger} | F', m_{F}' \rangle$$

$$= \frac{1}{4\Delta} \sum_{m_{F}'', q, q'} (-1)^{q} \langle F, m_{F} | A_{q} d_{-q} | F'', m_{F}'' \rangle \langle F'', m_{F}'' | (A^{*})_{q'} d_{-q'} | F', m_{F}' \rangle$$
(42)

where $(A^*)_q$ is the spherical component of the complex conjugate of A (ref Eq. 4). Using Wigner-Echart and the spherical decomposition of rank-2 tensor.

$$\frac{\langle F, m_{F} | H_{\text{eff}} | F', m_{F}' \rangle}{4\Delta} = \frac{\langle F | | d | | F'' \rangle^{*}}{4\Delta} \sum_{m_{F}', q, q'} (-1)^{q} A_{q}(A^{*})_{-q'} \langle F, m_{F} | F'', 1; m_{F}'', -q \rangle \langle F'', 1; m_{F}'', -q' | F', m_{F}' \rangle
= \frac{\langle F | | d | | F'' \rangle \langle F' | | d | | F'' \rangle^{*}}{4\Delta} \sum_{k,p} T_{p}^{k}
\sum_{m_{F}', q, q'} (-1)^{q} \langle k, p | 1, 1; q, -q' \rangle \langle F, m_{F} | F'', 1; m_{F}'', -q \rangle \langle F'', 1; m_{F}'', -q' | F', m_{F}' \rangle
(43)$$

Rewriting in 3 - j symbol,

$$\sum_{m_F'',q,q'} (-1)^q \langle k,p|1,1;q,-q'\rangle \langle F,m_F|F'',1;m_F'',-q\rangle \langle F'',1;m_F'',-q'|F',m_F'\rangle$$

$$=(-1)^{2F''+p-m_F-m_F'} \sqrt{(2k+1)(2F+1)(2F'+1)}$$

$$\sum_{m_F'',q,q'} (-1)^q \begin{pmatrix} 1 & 1 & k \\ q & -q' & -p \end{pmatrix} \begin{pmatrix} F'' & 1 & F \\ m_F'' & -q & -m_F \end{pmatrix} \begin{pmatrix} F'' & 1 & F' \\ m_F'' & -q' & -m_F' \end{pmatrix}$$

$$=(-1)^{2F''+p-m_F-m_F'} \sqrt{(2k+1)(2F+1)(2F'+1)}$$

$$\sum_{m_F'',q,q'} (-1)^q \begin{pmatrix} 1 & k & 1 \\ q' & -p & -q \end{pmatrix} \begin{pmatrix} 1 & F & F'' \\ q & -m_F & -m_F'' \end{pmatrix} \begin{pmatrix} F'' & F' & 1 \\ m_F'' & m_F' & -q' \end{pmatrix}$$

$$=(-1)^{F''+m_F-p} \sqrt{(2k+1)(2F+1)(2F'+1)}$$

$$\sum_{m_F'',q,q'} (-1)^{1+1+F''-q-q'-m_F''} \begin{pmatrix} 1 & k & 1 \\ q' & -p & -q \end{pmatrix} \begin{pmatrix} 1 & F & F'' \\ q & -m_F & -m_F'' \end{pmatrix} \begin{pmatrix} F'' & F' & 1 \\ m_F'' & m_F'' & -q' \end{pmatrix}$$

$$=(-1)^{F''+m_F-p} \sqrt{(2k+1)(2F+1)(2F'+1)} \begin{pmatrix} k & F & F' \\ p & m_F & -m_F' \end{pmatrix} \begin{pmatrix} k & F & F' \\ F'' & 1 & 1 \end{pmatrix}$$

$$=(-1)^{F''-F+k+2m_F} \sqrt{(2k+1)(2F+1)(k,F;p,m_F|F',m_F')} \begin{pmatrix} k & F & F' \\ F'' & 1 & 1 \end{pmatrix}$$

For F' = F,

$$\sum_{m''_{F},q,q'} (-1)^{q} \langle k,p|1,1;q,-q' \rangle \langle F,m_{F}|F'',1;m''_{F},-q \rangle \langle F'',1;m''_{F},-q'|F,m'_{F} \rangle
= (-1)^{F''-F+k+2m_{F}} \sqrt{(2k+1)(2F+1)} \langle k,F;p,m_{F}|F,m'_{F} \rangle \begin{cases} k & F & F \\ F'' & 1 & 1 \end{cases}$$
(45)

- 5 Vector light shift as effective magnetic field
- 6 Mitigating the effect of transverse circular polarization in optical tweezers