Interactive Illustration of the Sampling Properties of Estimators

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August 7, 2023

Abstract

This is the documentation of the implementation of a learning module for an interactive illustration of the sampling properties of estimators

1 Introduction

This repository contains the implementation of a learning module with interactive and animated illustrations of fundamental statistical concepts and properties.

2 Goal of the learning module (Why?)

Understanding the concept and properties of sampling distributions of estimators is one of the most important concepts of statistical inference, i.e, of learning from data about the underlying data generating process (DGP) formalized in probabilistic (population) model of interest, and thus, a fundamental part of empirical studies in social science in general and econometrics in particular. Practice, however, has shown that students often have difficulty understanding the concept of sampling distributions and their properties. One potential reason for this is that the sampling properties of estimators are often formulated and analyzed in an abstract way only. The goal of this learning module is to give a more intuitive understanding of the sampling properties of estimators using interactive and animated illustrations of simulation results.

One example is to understand the effect of increasing the sample size n on the sampling properties of the sample average \overline{X} as an estimator for the mean μ of a random variable of interest as stated in the law of large numbers (LLN) and the central limit theorem (CLT). Using interactive illustrations of simulation results the students can increase the sample size and observe how the sample average gets closer to the mean (LLN) and how the sampling distribution of the standardized statistic of the sample average gets closer to the standard normal distribution (CLT).

The topics, i.e. the sample distribution of estimators, is part of every statistics and econometrics course and can be found in any introductory textbook for this field. However, by using interactive and animated illustrations the results we aim to provide a deeper and more intuitive understanding of these concepts. We believe that this kind of understanding is hard to achieve by just attending a *lecture*, reading a *textbook*, or, by chatting with *ChatGPT* about this topic. Certainly, another way to achieve this is to provide the implementation of the simulation studies or to let the students to implement the simulation studies themselves. However, this is often too big a hurdle, especially for undergraduate students.

3 Subject of the learning module (What?)

3.1 General

Subject of this learning module are the sampling properties of estimators for different data generating processes (DGPs). The DGPs are based on a statistical model with a particular parameter of interest, e.g., the mean of a Bernoulli random variable. The parameter(s) of interest of the DGPs are estimated using a particular estimator, e.g., the sample average. This learning module shows the effect of changes in the DGP, e.g., increasing the sample size n, on the sampling distribution of an estimator.

Note, the interactive illustration of the sampling properties of the sample average for increasing the sample size n, i.e., the large sample properties of the sample mean,

is only one subject of interest. Other subjects are to understand the effect of omitted variable bias (OVB) and heteroskedasticity on the sampling distribution of the OLS estimator in a simple linear regression model.

3.2 Univariate random variables and sample average

Bernoulli distribution and sample average

This illustration shows the effect of changing the sample size n and the probability of success p of the Bernoulli distribution on the sampling distribution of the sample average as estimator for mean of the Bernoulli distribution.

. . .

Continuous uniform distribution and sample average

This illustration shows the effect of changing the sample size n and the lower bound a and the upper bound b of the continuous uniform distribution on the sampling distribution of the sample average as estimator for mean of the continuous uniform distribution.

...

3.3 Linear regression model and ordinary least squares

Illustration of the properties of the OLS estimator to estimate the slope coefficient β_1 of a linear regression model, i.e.,

$$Y_i = \beta_0 + \beta_1 X_i + u_i \tag{1}$$

Sampling distribution and sample size

This illustration shows the effect of increasing the sample size n on the sampling distribution of the OLS estimator for the slope coefficient of a simple linear regression model.

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Sample Size and parameterization of the DGP

This illustration shows the effect of changing the parameters of the DFP, i.e.,

- 1. changing the sample size n,
- 2. changing the variance of u_i , i.e., $\sigma_{u_i}^2$, and,
- 3. changing the variance of X_i , i.e., σ_X^2 ,

on the sampling distribution of the OLS estimator for the slope coefficient of a simple linear regression model.

. . .

Effect of Heteroskedasticity

. . .

Effect of Omitted Variable Bias

...

4 Method of the learning module (How?)

4.1 General

For an interactive and immediate user experience it is useful to separate the simulation study and the presentation of the results. This two-step procedure allows also a flexible implementation, i.e., the simulation studies can be conducted with any suitable software, e.g., R, python, etc. and the results can be presented interactively using basic web development languages, i.e., html, css and javascript.

Appealing, flexible, interactive and animated presentation using html, css and javascript

While the setup and the implementation of the simulation or other studies depends on the topic of the learning module, the presentation of the results should be based on core web development tools. The content of each learning module is presented using *html*, the most popular language to build web pages.¹ This allows a very flexible presentation of the results. The styling of the learning module is based on *css*, a popular language for styling web pages, and on *bootstrap*, a popular *css* framework. The interactive and animated feature of the learning module is based on *javascript*, a popular language for programming web pages. The *bootstrap* framework with its grid system allows the development of responsive, mobile-first websites with an appealing design. This enables an appealing experience of the learning also on mobile devices.

Structure of the html, css and javascript files

What follows in Section 4.3 to 4.3 is an explanation of the structure of the html, css and javascript files. The explanations are based on the illustration of the properties of the sample average as estimator for the mean of a Bernoulli random variable, i.e., based on module ber-dis-sam-ave which has two parameters (the sample size n and the probability of success p) and three figures (the bar plot of number of ones and zero, the histogram of sample average and the histogram of the standardized sample average). Note, the implementation is flexible in the sense that it can be used for any learning module with two parameters and three figures.

4.2 Structure of the file with the simulation study

Depending on the subject of the learning module the number of interactive parameters and the number of figures and/or tables for the illustration of the results are chosen. For the learning module ber-dis-sam-ave there are two interactive parameters, i,e, sample size n and probability of success p, and three figures, i.e., the bar plot of number of ones and zero, the histogram of sample average and the histogram of the standardized sample average. In this setup the variable and fixed inputs of the simulation study can be defined as in R Code Snippet 1. The simulation study is based on a loop which runs over the variable inputs (here n.vec and p.vec). For each variable input combination

 $^{^1\}mathrm{An}$ introduction to the most important web page development languages can be found here: https://www.w3schools.com/

RR=10000 realizations of the DGP are simulated and RR=10000 estimates are calculated. Based on the simulation results for RR=10000 realizations the illustration of interest is stored as figure_01_y_z.svg, where 0x indicates the 0xth figure, y indicates the yth index value of the first parameter and z indicates the zth index value of the second parameter. E.g. for ii = 1 and jj = 1 the results for the parameters n = 5 and p = 0.2 are stored in figure_01_1_1.svg (see also R Code Snippet 2 below). Note, for the integration into the html file and the animation using javascirpit file later the naming of the figure and/or tables is important (see Section 4.3).

4.3 Structure of the *html* file

The interactive and animated illustration of the learning module is based on six components introduced below.

1) Integrate of the illustrations

The illustrations are integrated using img tags. The src attributes of the img tags point to a particular figure, i.e., the illustration of a particular simulation results. The class attributes of all img tags are set to figureCl and the id attributes of the img tags are based on the following naming convention: figure1Id, figure2Id, The naming convention of the id attribute are used to refer to the src attribute of the img tag, i.e., to show the illustration of the simulation results of a particular DGP using javascript. Code snippet 3 below shows the integration of figure 1 for the illustration of the simulation results based on a DGP with two interactive parameters.

2) Distribution of the illustrations across tabs

The *img* tags above are embedded into *div* tags to distribute the illustrations across tabs, i.e., one tab for each figure. The content of the *div* tags, i.e., the tabs, can be displayed or not using the *display* attribute of the *div* tags. The *class* attributes of all *div* tags for the tabs are set to tabContentL1Cl and the *id* attributes of the *div* tags for the tabs are based on the following naming convention: tabContentL1N1Id,

Code Snippet 1: R code snippet simulation setup

```
# inputs (variable)
n.vec <- c(5, 10, 25, 50, 100)
p.vec <- c(0.2, 0.4, 0.6, 0.8)
# inputs (fixed)
RR <- 10000</pre>
```

Code Snippet 2: R code snippet simulation and illustration implementation

```
# simulation/illustration
for (ii in 1:length(n.vec)) {
    for (jj in 1:length(p.vec)) {
        NN <- n.vec[ii]
        p <- p.vec[jj]
        # simulation
        tmp.sim <- Y_bar_ber_sim_fun(RR = RR, NN = NN, p = p)

        # plot no 01
        plt.nam <- paste(fig.dir, "figure_01_", ii, "_", jj, ".svg", sep = "")
        svg(plt.nam)
        ...
        dev.off()
        ...
}</pre>
```

Code Snippet 3: Html code snippet for the integration of a figure

```
<img src="./figures/figure_01_1_1.svg" alt=""
class="figureCl" id="figure1Id" style="max-width: 75%;">
```

tabContentL1N1Id, The naming convention of the *id* attributes are used to change the *display* property of the *style* attribute of the *div* tags for the tabs, i.e, to display or not the content of the tab based on *buttons* using *javascript*.

3) Interaction with the illustrations with sliders

The parametrization of the DGP can be changed using *input* tags². The values of the *input* tags will be used to change the *src* attribute of the *img* tags, i.e., to change to the illustration of a particular simulation result. The *class* attribute of all *input* tags are set to sliderCl and the *id* attribute of the *input* tags are based on the following naming convention: slider1Id, slider2Id, The naming convention of the *id* attribute are used to interact with a particular slider using *javascript*. Code snippet 5 below shows the integration of slider 1.

```
Code Snippet 5: Html code snippet for integration of a slider

aufrufen

<input class="sliderCl" id="slider1Id" type="text"

data-slider-min="0" data-slider-max="4" data-slider-step="1"

data-slider-value="2"/>
```

4) Displaying the specification of the DGP selected with sliders

The underlying specification of the DGP is displayed using p tags. The class attribute of all p tags to display the slider values are set to sliderValueCl and the id attribute of the p tags to display the slider values are based on the following naming convention: sliderValue1Id, sliderValue2Id, The naming convention of the id attribute are used to address the .innerHTML property of the p tags to display the

²The bootstrap-slider library (see https://github.com/seiyria/bootstrap-slider) is used to display and interact with the learning module using sliders

slider values using *javascript*. Code snippet 6 below shows the integration to display the slider value of slider 1.

Code Snippet 6: Html code snippet for integration of a slider value

```
Sample Size \(n\)
```

5) Explaining the figures and the effect of the parametrization

For each figure an overall explanation can be added. Furthermore, for each figure and each slider, i.e., each interactive parameter, a explanation of the effect of the parametrization can be added. All explanations are collected in div tags with the class attribute audioTextCl and the id attributes of the div tags are based on the following naming convention: audioTextFigure10verallId, audioTextFigure20verallId, ... for the explanations of the figures and audioTextFigure1Slider1Id, audioTextFigure1Slider2Id, ..., for the explanations of the effects of different parametrization of the DGP. Again, the naming convention of the id attributes of the div tags are used to refer to specific explanations. Longer explanations can be distributed across multiple span tags inside the div tag. Code snippet 7 below shows the integration of explanation text for figure 1. Code snip-

Code Snippet 7: Html code snippet for adding overall explanation

pet 8 below shows the integration of the explanation of the effect of changing parameter 1, i.e., slider 1, based on the figure 1.

6) Displaying Explanations of the figures and the effects of the parametrization The explanation of the figures or the effects of the parametrization are displayed using p tags.

The class attribute of these p tags are set to audioShowTextC1 and the id attributes of these p tags are based on the following convention: audioShowTextFigure1Id, audioShowTextFigure2Id, The naming convention of the id attributes above are used to refer the .innerHTML property of the p tags using javascript.

Distribution of the content across bootstrap containers

The content of the learning module is divided across *bootstrap containers*. The general scheme of the structure is outlined below.

- 1st Container: Header of the module
- 2nd Container with three sections
 - Topic of the module
 - Data generating process (DGP)
 - Estimator and parameter of interest
- 3rd Container:
 - Parameter panel with the slider to change the parameter of interest
 - Illustration panel with four tabs for the illustration of
 - * Sample draw: Particular outcome
 - * Residual: Particular diagnostic
 - * Estimates: Histogram of parameter estimates
 - * Std. Estimates: Histogram of standardized parameter etimates
- 4th Container: More Details
 - Simulation Exercise:

Other content such as explanations as plain text or formula or as audio files can be added and can be manipulated, e.g. made visible/invisible inside tabs or collapsibles using *javascript*.

4.4 Structure of the *javascript* file

The values of the parameters can be changed using bootstrap-slider inputs³ and the javascript par02Fig03Interactivation.js. For example for the input of the sample size the following html code snippet is used.

Changing the slider input values invokes *javascript* function.

The interactive experience of the illustrations is based on three javascript function which are linked to the sliders of the parameters. There is a

4.5 Explained and animated user experience using javascript

The following explanations are based on the illustration of the properties of the sample average as estimator for the mean of a Bernoulli random variable, i.e., based on module ber-dis-sam-ave. The explanation of the figure is based on a simple *javascript* function explainButtoO1Click.

The explained animation of the parameters is based on the <code>javascipt</code> function <code>sliderLoop()</code> and the functions <code>animateButtoO1Click()</code> and <code>animateButtoO2Click()</code>. Note, for each parameter a function <code>animateButtoXXClick()</code> is used, i.e., for the module <code>ber-dis-sam-ave</code> there are two functions, <code>animateButtoO1Click</code> and <code>animateButtoO2Click</code>. Furthermore, the body of both functions, <code>sliderLoop()</code> and <code>animateButtoXXClick()</code> depends on the number of figures (for <code>ber-dis-sam-ave</code> equals three) and the number of parameters (for <code>ber-dis-sam-ave</code> equals two) used in the module.

4.6 Integration in the lecture

- The material of this learning module can be provided on a gradual basis using links to the specific illustrations/sub modules or as a complete course/module with a starting page and links to the sub modules.
- The material can be hosted on GitHub or on a learning platform such as ILIAS.

³See: https://github.com/seiyria/bootstrap-slider

Code Snippet 8: Html code snippet for adding explanation of the effect of a parameter

Code Snippet 9: Html code snippet for bootstrap-slider input

```
Sample size \(n\)<input id="slider01Id" type="text" data-slider-min="0" data-slider-max="4" data-slider-step="1" data-slider-value="2"/>
```

Code Snippet 10: Javascript code snippet for interactive sliders (no 1): Initialize slider values

```
var nVec = [5, 10, 25, 50, 100]

// set initial value for slider 1
document.getElementById("sliderValue01Id").innerHTML = "\\(n = " + nVec
var element = document.getElementById("sliderValue01Id");
MathJax.typeset([element]);
```

Code Snippet 11: Javascript code snippet for interactive sliders (no 2): Update slider values

Code Snippet 12: Javascript code snippet for interactive sliders (no 3): Change illustration

```
slider01.on("slide", function() {
    var sliderValue01 = slider01.getValue() + 1;
    var sliderValue02 = slider02.getValue() + 1;

    document.getElementById("imageLiNiId").setAttribute("src", "./figures/figure_01_" + sliderValue01 + "_" + sliderValue02 + ".svg");
    document.getElementById("imageLiNiId").setAttribute("src", "./figures/figure_02_" + sliderValue01 + "_" + sliderValue02 + ".svg");
    document.getElementById("imageLiNiId").setAttribute("src", "./figures/figure_03_" + sliderValue01 + "_" + sliderValue02 + ".svg");
    document.getElementById("sliderValue0IId").innerHTML = "\\((n = " + n\text{Vec}[slider01.getValue()] + "\\)";
    var element = document.getElementById("sliderValue0IId");
    MathJax.typeset([element]);
}

Code Snippet 13: Javascript snippet for explanation

explainButtoO1Click = function(audioId) {
        var audio = document.getElementById(audioId);
        audio.play();
}
```

```
Code Snippet 14: Javascript snippet for explanation and animation (part I)
function sliderLoop(loopSliderValue01, loopSliderValue02) {
        var sliderValue01 = loopSliderValue01 + 1;
        var sliderValue02 = loopSliderValue02 + 1;
        document.getElementById("imageL1N1Id").setAttribute("src", "./figures/figure_0
        document.getElementById("imageL1N2Id").setAttribute("src", "./figures/figure_0
        document.getElementById("imageL1N3Id").setAttribute("src", "./figures/figure_0
        document.getElementById("sliderValue01Id").innerHTML = "\\(n = " + nVec[sliderValue01Id"))
        var element = document.getElementById("sliderValue01Id");
        MathJax.typeset([element]);
        document.getElementById("sliderValue02Id").innerHTML = "\\(p = " + pVec[sliderValue02Id"))
        var element = document.getElementById("sliderValue02Id");
        MathJax.typeset([element]);
        var slider = document.getElementById("slider01Id");
        slider.value = sliderValue01;
        var slider = document.getElementById("slider02Id");
        slider.value = sliderValue02;
};
```

```
Code Snippet 15: Javascript snippet for explanation and animation (part II)
animateButtoO1Click = function(org, start, stop, audioId) {
        var audio = document.getElementById(audioId);
        audio.play();
        var ind = start;
        var loopSliderValue02 = slider02.getValue();
        var outerInterval = setInterval(function() {
                var loopSliderValue01 = ind;
                slider01.setValue(ind);
                sliderLoop(loopSliderValue01, loopSliderValue02);
                ind++;
                if (ind > stop) {
                        var innerInterval = setInterval(function() {
                                 slider01.setValue(ind);
                                 slider01.setValue(org);
                                 sliderLoop(org, loopSliderValue02);
                                 clearInterval(innerInterval);
                         }, 1000);
                         clearInterval(outerInterval);
                }
        }, 1000);
}
  Code Snippet 16: Javascript snippet for explanation and animation (part III)
animateButtoO2Click = function(org, start, stop, audioId) {
        var audio = document.getElementById(audioId);
        audio.play();
        var ind = start;
        var loopSliderValue01 = slider01.getValue();
        var outerInterval = setInterval(function() {
                var loopSliderValue02 = ind;
                slider02.setValue(ind);
                sliderLoop(loopSliderValue01, loopSliderValue02);
                ind++;
                if (ind > stop) {
                         var innerInterval = setInterval(function() {
                                 slider02.setValue(ind);
                                 slider02.setValue(org);
                                 sliderLoop(loopSliderValue01, org);
                                 clearInterval(innerInterval);
                         }, 1000);
                         clearInterval(outerInterval);
        }, 1000);
}
```

The easiest way to host the material on a learning platform such as ILIAS is using a import interface for .html structures. In the case of the learning platform ILIAS this procedure is quite easy and flexible.

4.7 Structure of the learning module

- The learning module contains different sub modules where each sub module has a specific learning goal, e.g., "understand the effect of the sample size on the sample properties of the sample average to estimate the mean of a Bernoulli distribution".
- The material of a sub module is collected in a sub folder, e.g., ber-dis-sam-ave.
- The sub folder contains:
 - .R file, e.g., ber_dis_sam_ave.R, with the simulation study and the results stored in the figures and/or tables subdirectory
 - figures subdirectory with the illustrations of the simulation results
 - audios subdirectory with the audio text and files for the explanations using interactive animations
 - tables subdirectory with the reports of the simulation results (optional)
 - .html file, e.g., ber_dis_sam_ave.html, with the interactive representation
 of the illustrations
 - myScript. js with the javascript for the interactive illustrations
 - myStyle.css with the css styles for the interactive illustrations
 - Additional assets, e.g.,:
 - * .png file with a logo for the header of the .html file

* ...

References

 $[{\rm SW19}]$ James H. Stock and Mark W. Watson. Introduction to Econometrics. Pearson, 2019.