



Required Software

Download **NoMachine Enterprise Client** on your laptop



NOMACHINE

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Enterprise Client Products
Install just the bare minimum to get access



Get access to all your remote PCs and desktop computers where you have provided a NoMachine server product. Do that with a minimal install, including only the client-side components of the NoMachine software suite.

NoMachine Enterprise Client

- NoMachine Enterprise Client for Windows
- NoMachine Enterprise Client for Mac
- NoMachine Enterprise Client for Linux
- NoMachine Enterprise Client for Raspberry Pi
- NoMachine Enterprise Client for ARM

Features and support



Design Your Own CPU

Session 1 – Intro to SystemVerilog



Session 1 – Intro to SystemVerilog

Session 2 – The single-cycle CPU

Session 3 – Optimisation and bare-metal programming



About Me

- Part IV Electronic Engineering with Computer Systems
- IP: *A Universal Superscalar Processor Design for MIPS and RISC-V*
- GDP: *Verify a RISC-V Core in 10 Weeks*
- R&D Intern at Codasip (Fabless RISC-V IP firm)



Reasons for Attending These Workshops

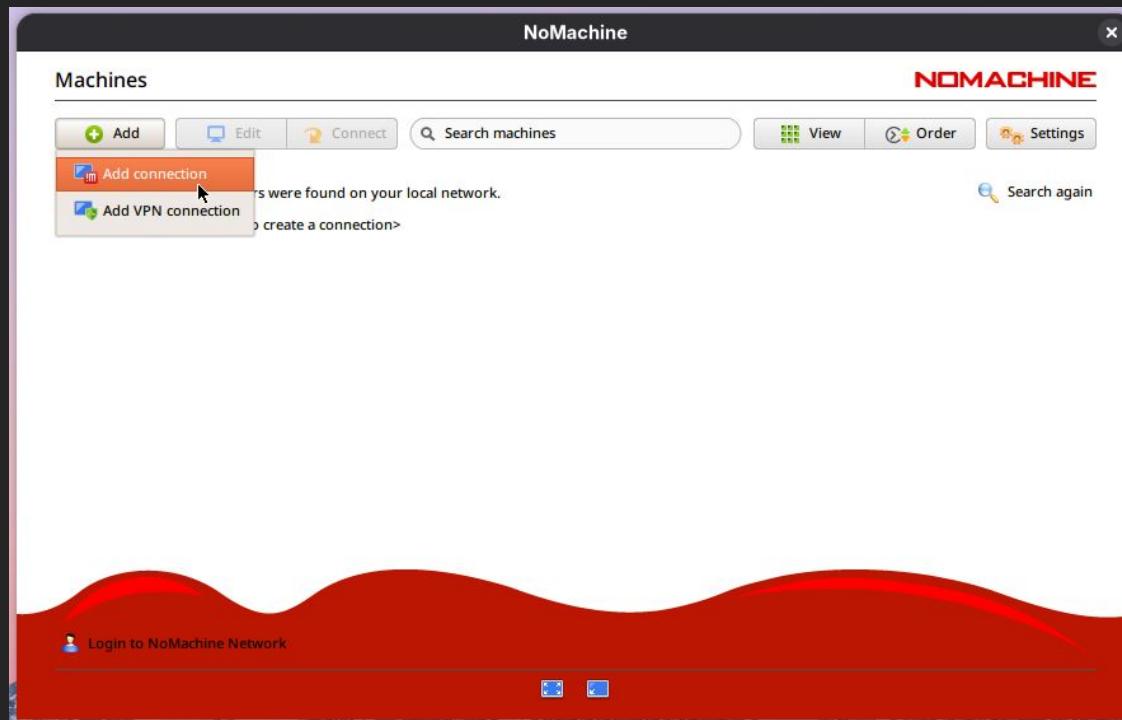
- You're interested in doing a digital design focused IP or GDP
- You want an internship in digital design
- You want to learn or have a refresher on SystemVerilog
- You want to know how digital systems are designed
- For fun



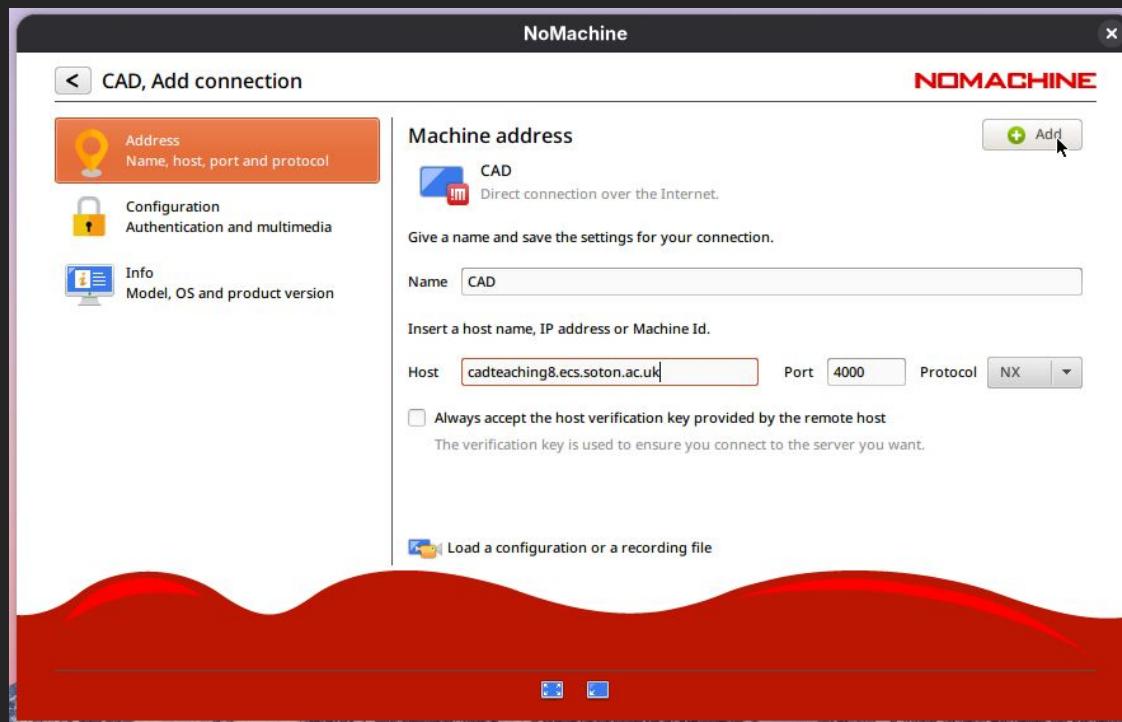
Setup



Setup (1)

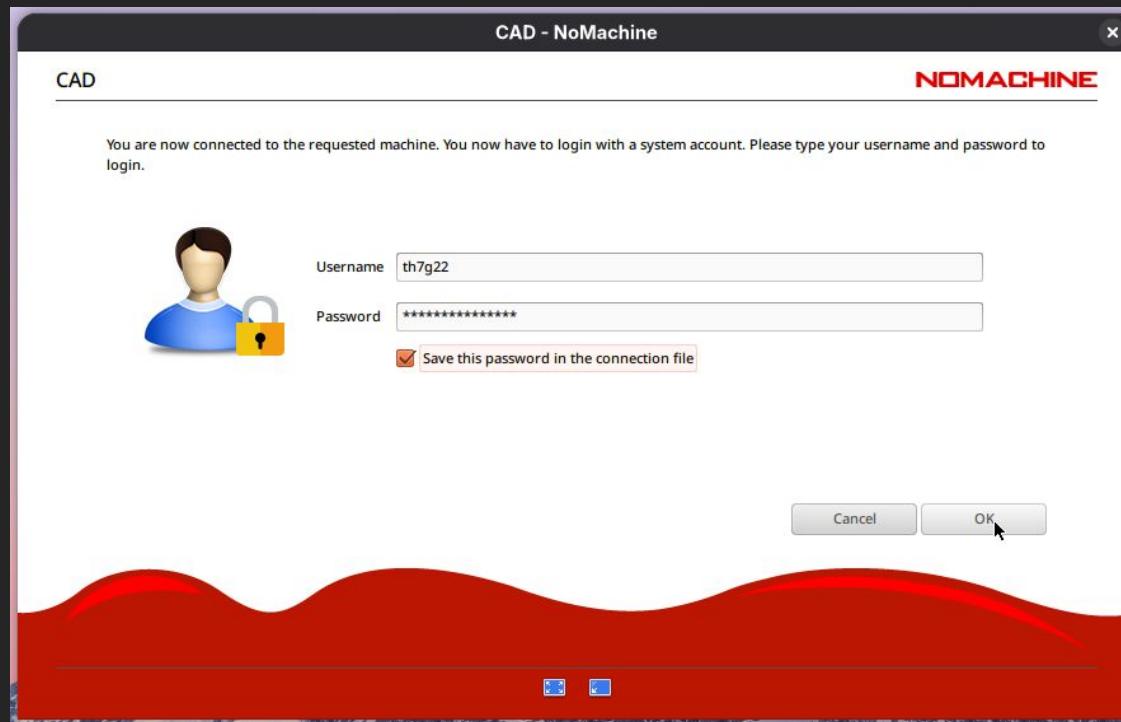


Setup (2)





Setup (3)



Setup (4)





Setup (5)

- In your terminal, clone this Git repository:

<https://github.com/bhart17/design-your-own-cpu>

- `git clone https://github.com/bhart17/design-your-own-cpu.git`
- `cd design-your-own-cpu`



Digital Systems



Digital Systems

- Digital systems are systems that operate on *binary signals*
- An electronic digital system typically uses two different voltages to represent these binary signals (low voltage: '0'; high voltage; '1')
- Not analogue or mixed-signal, though there is an overlap in methodology and technology



Stateful and Stateless Systems (1)

- Stateless system: the output is a function of the inputs

$$Y = f(A)$$

- Stateful system: the output is a function of the inputs *and the current state*

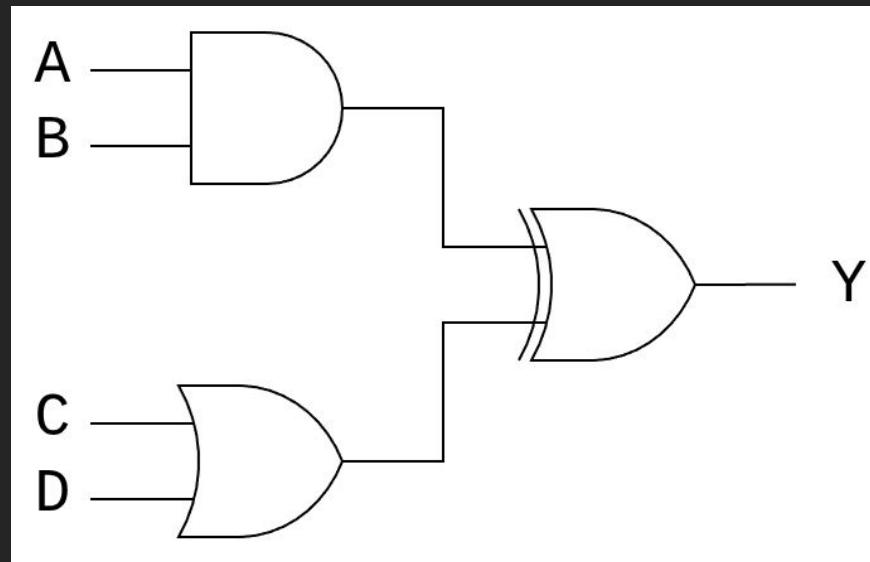
$$Y = f(A, \text{State}_{\text{current}})$$

$$\text{State}_{\text{next}} = g(A, \text{State}_{\text{current}})$$

- All complex digital systems are stateful

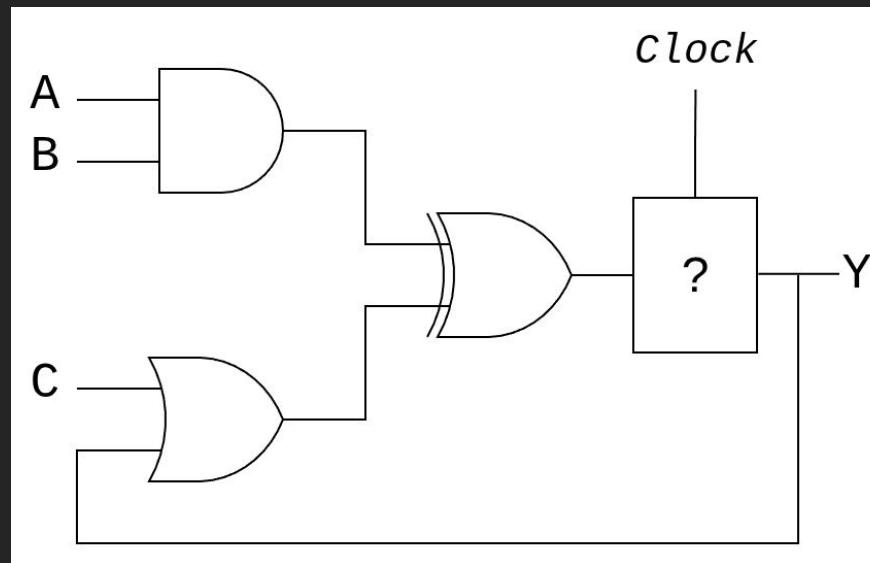
Stateful and Stateless Systems (2)

- A stateless system can be modelled as some set of *combinational* boolean gates



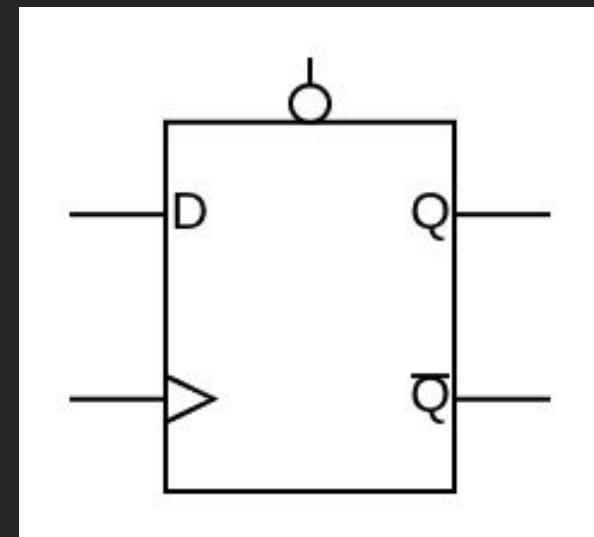
Stateful and Stateless Systems (3)

- A stateful system needs some way of storing state between *cycles*



Flip Flops

- A means of storing digital state
- Has two *stable* states ('1' and '0')
- Takes a new state upon a *clock edge*





Overall: Designing digital systems

- We want to model systems that take in a number of binary inputs
- They compute outputs as a function of these inputs **and** the state of the system using boolean logic
- State is updated on a clock edge



Levels of Abstraction



Abstraction

- A system can be described (or *modelled*) in many ways
- Each is a balance between a high-level description versus a logical or physical description
- We want to *abstract* the physical details of a system away when we are designing it



Levels of Abstraction for a Digital IC (1)

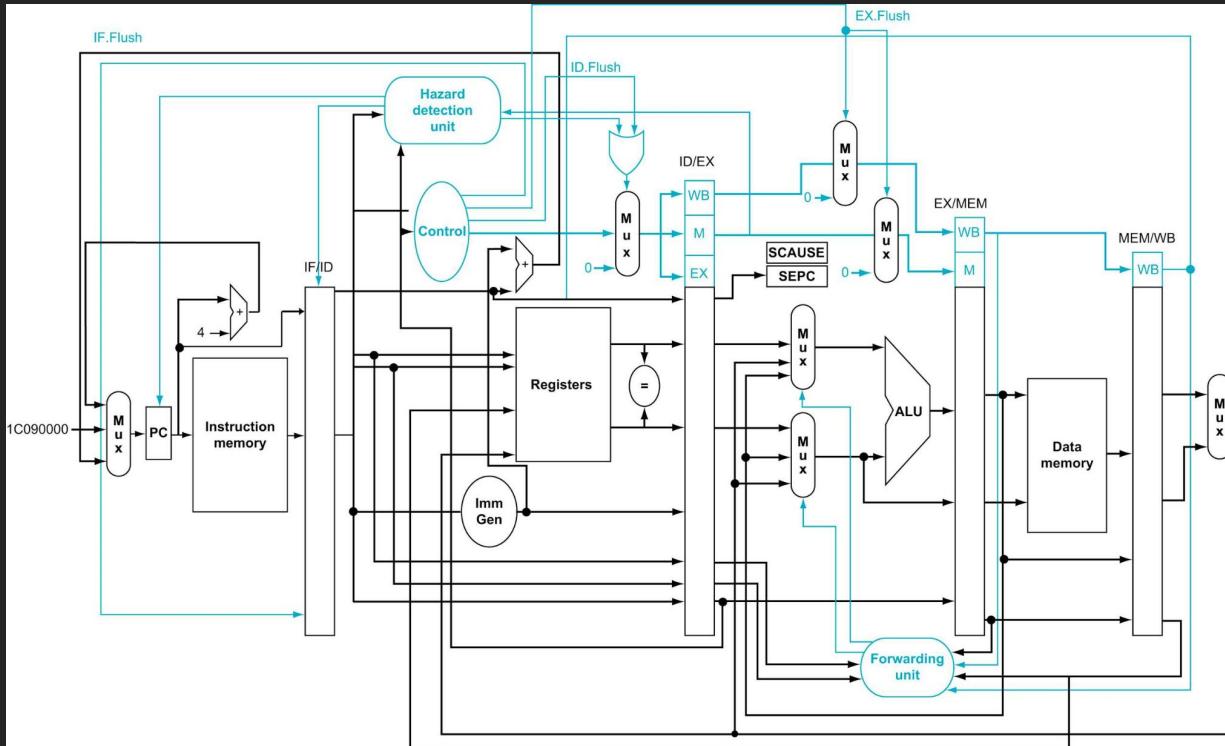
1. Specification
2. Block diagram
3. ???
4. Gate-level circuit (*Generic cells*)
5. Transistor-level circuit (*Specific cells*)
 - 5.1. Transistor circuit diagram
 - 5.2. Stick diagram
 - 5.3. Mask diagram



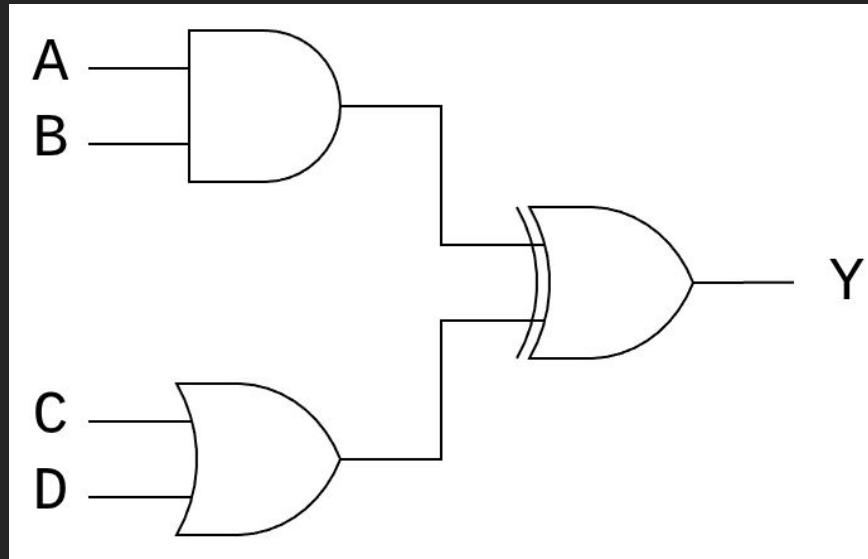
Specification

'The design should do X and Y but not Z.'

Block Diagram

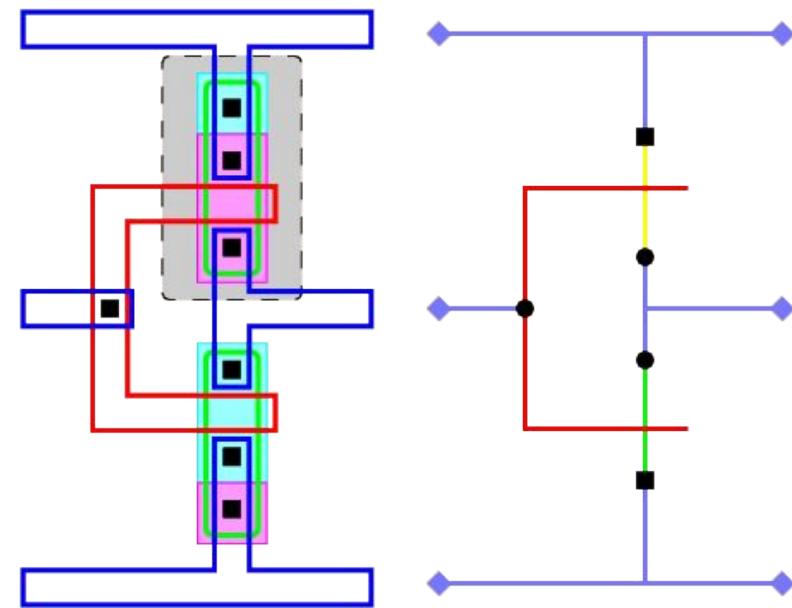
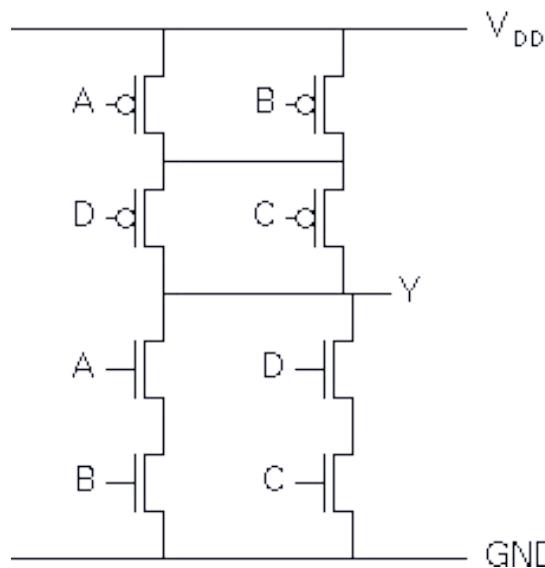


Gate-level Circuit



Transistor-level Circuit

AOI22 Schematic

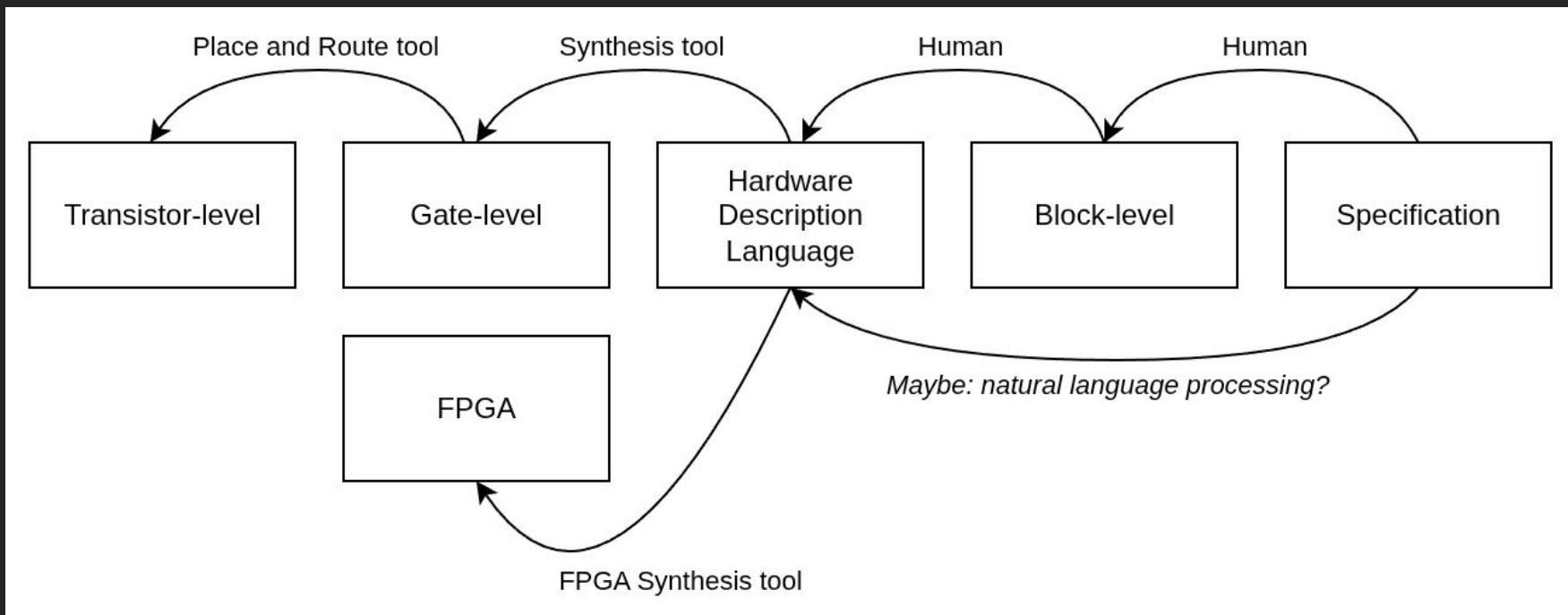




Levels of Abstraction for a Digital IC (2)

1. Specification
2. Block diagram
3. Hardware description language (such as SystemVerilog)
4. Gate-level circuit (*Generic cells*)
5. Transistor-level circuit (*Specific cells*)
 - 5.1. Transistor circuit diagram
 - 5.2. Stick diagram
 - 5.3. Mask diagram

IC Design Flow





SystemVerilog



Hardware Description Languages

- Aiming to describe the logic between an input and output in a formal but high-level way
- Readable by humans but understandable to computers
- Historically called Register Transfer Layer – describing how data flows between *registers*
- Not programming languages!



SystemVerilog

- Defined in IEEE-1800
- Superset of Verilog with the main purpose of adding useful *verification* features
- Most common HDL used today in industry



Purposes of Writing HDL

- When creating an IC: we will want to provide our high-level SystemVerilog to a synthesis tool that will map our design to boolean gates
- However, we want to know if our design works before this stage
- A *simulator* is used to see how it performs under certain inputs
- May seem very close to a programming language – remember, it isn't!



Testbenches

- We write *synthesisable* modules to describe the hardware we want to fabricate
- Then, we can provide synthetic inputs and test patterns to our design in a *testbench*
- A testbench is *unsynthesisable* – it doesn't map to physical gates; only for the simulator



Demonstration of SystemVerilog Syntax



Practical Work



(0.) Hello World

- Run the simulate script and see the output
- Add your own print message in a loop to understand testbench delays
- Remember – this is unsynthesisable!



1. Modelling Basic Gates

- Design the following boolean logic gates:
 - NOT
 - AND
 - OR
 - XOR



2. Full Adder

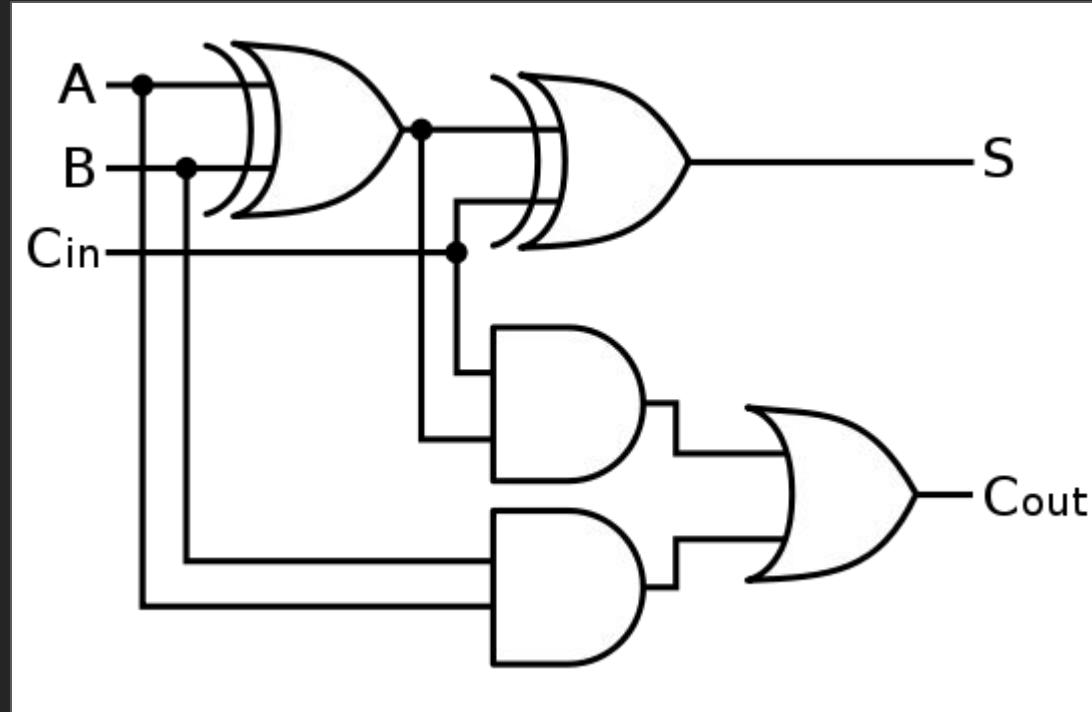
- Create a full adder module
- Three 1-bit inputs: A, B, Cin
- Two 1-bit outputs: Sum, Cout
- We've made some basic gates – should we use them?



Structural versus Behavioural Modelling

- A *structurally* modelled system describes the components and their connections
- A *behaviourally* modelled system describes the high-level behaviour
- You should very rarely write structural HDL – you're just creating a circuit diagram in code
 - High-level meaning is lost: hard to maintain and easy to create bugs
 - The synthesis tool will find a more optimal implementation than you

Structural Full Adder





2. Full Adder

- Create a full adder module
- Three 1-bit inputs: A, B, Cin
- Two 1-bit outputs: Sum, Cout
- We've made some basic gates – should we use them?

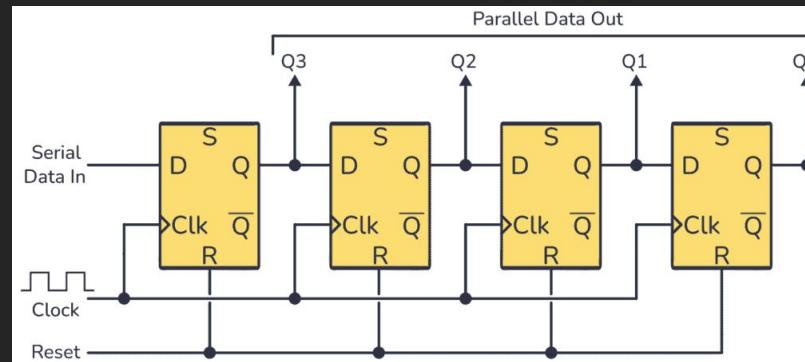


3. Linear-feedback Shift Register

- A crude method for psuedo-random number generation
- First, let's create the shift register
- Then, we can add the linear feedback

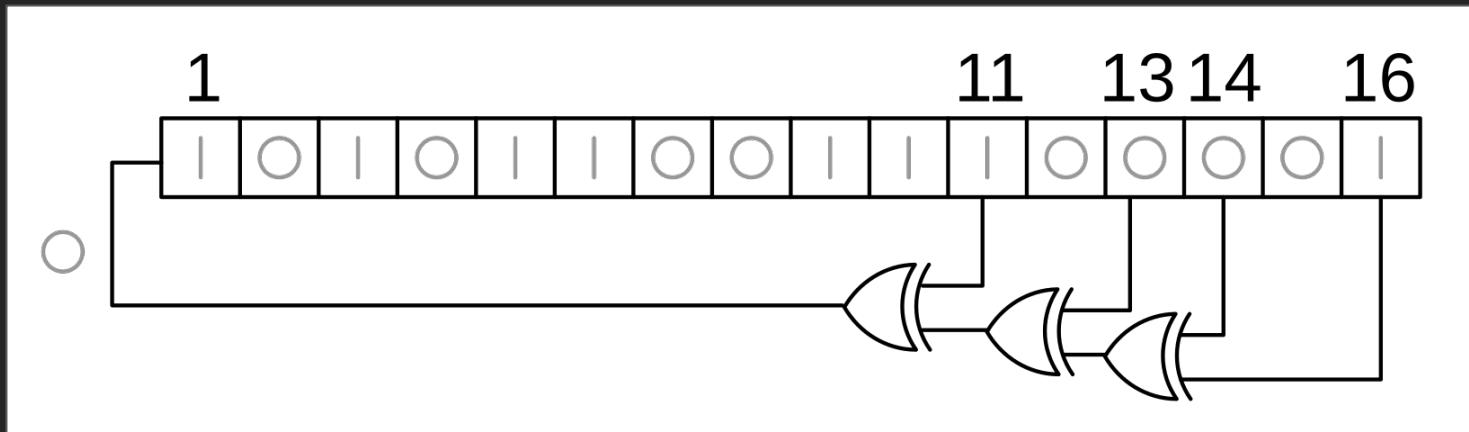
Shift Registers

- Upon a clock cycle, the bits in the register are 'shifted' by one place
- The top bit is removed from the register
- A new bit is stored as the bottom bit



Linear-feedback

- The new bottom bit is some function of the current state of the register
- XOR gates are usually used





3. Linear-feedback Shift Register

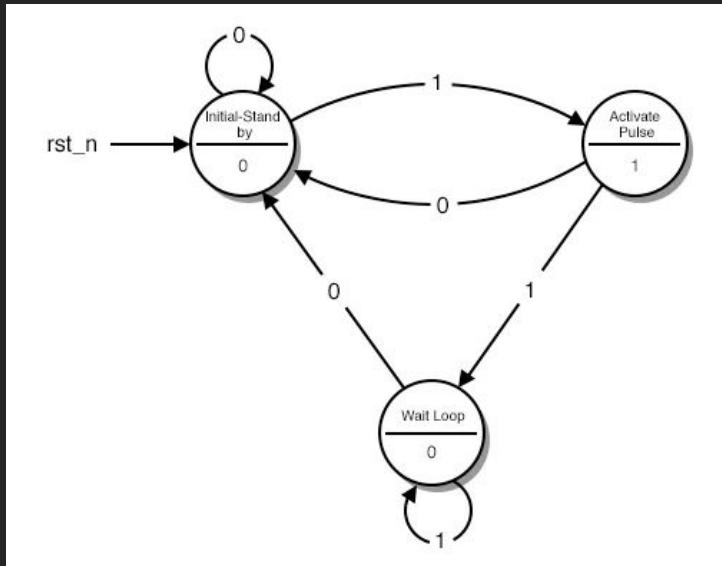
- A crude method for psuedo-random number generation
- First, let's create the shift register
- Then, we can add the linear feedback
- How “random” are the numbers?



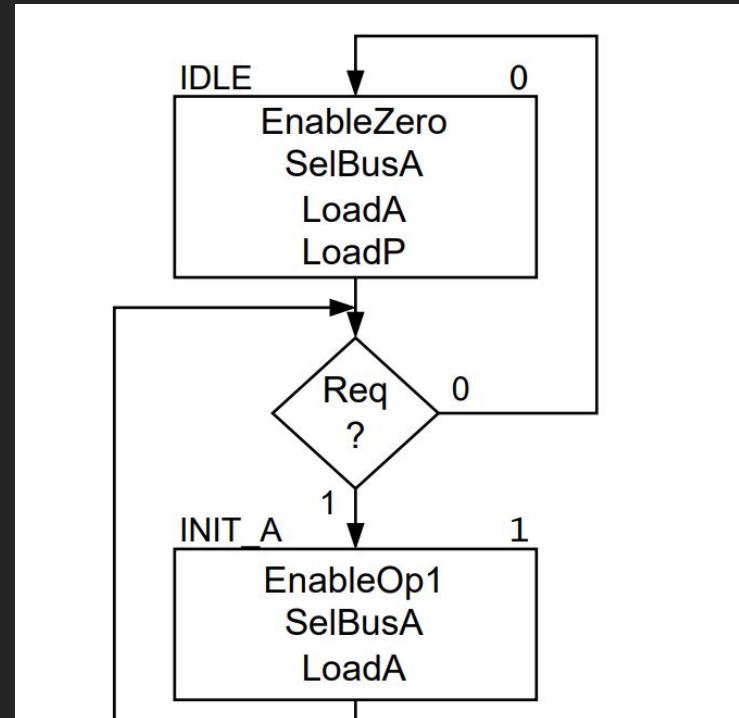
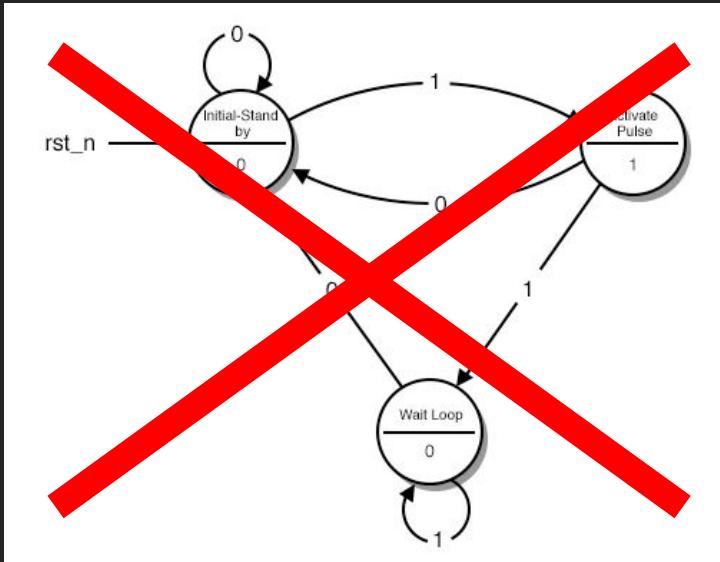
4. Algorithmic State Machine

- Create a state machine representing a traffic light controller at a pedestrian crossing
- Then, create a testbench to make sure the design works properly

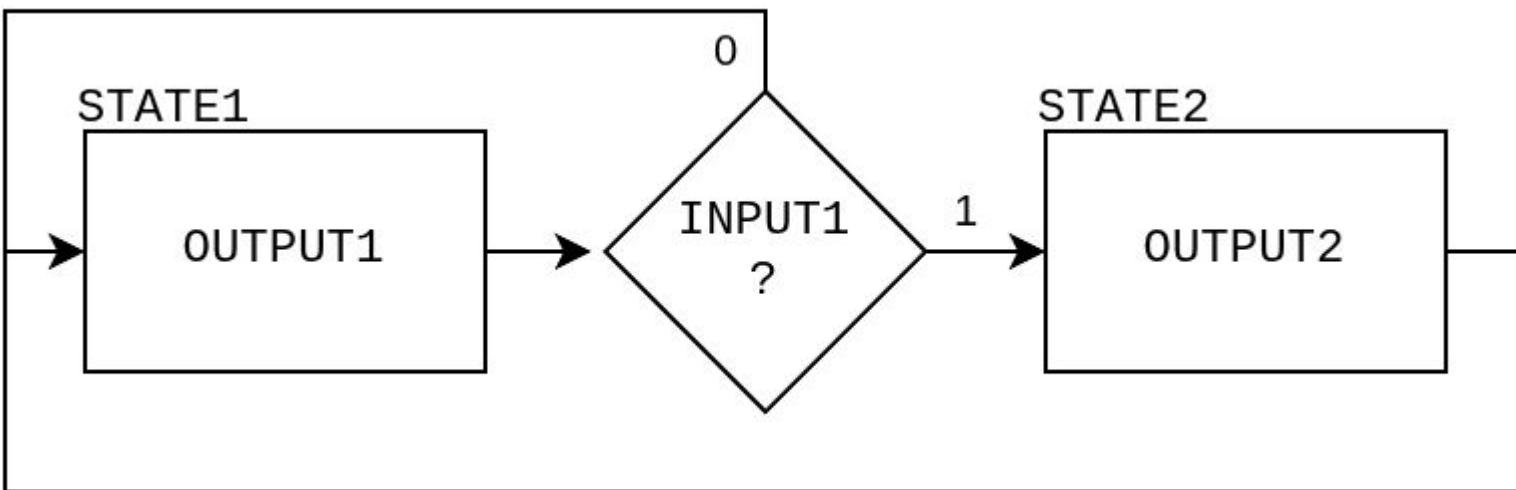
State Machines (1)



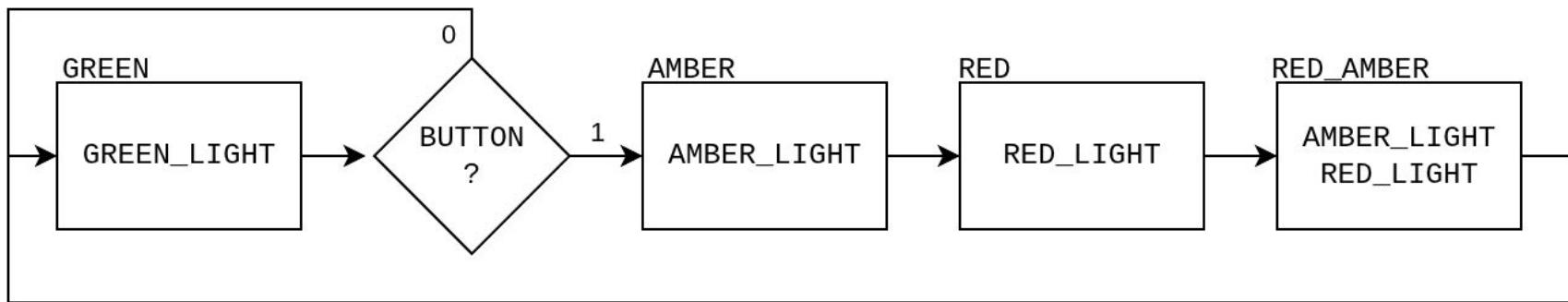
State Machines (2)



Example State Machine in SystemVerilog



Traffic Light Controller





4. Algorithmic State Machine

- Create a state machine representing a traffic light controller at a pedestrian crossing
- Then, create a testbench to make sure the design works properly



Next Week

- Learn about how CPUs are designed
- Implement some blocks in your own RISC-V CPU
- Run a handwritten machine code program

*Some materials and inspiration in this presentation sourced from Iain McNally's notes
(<https://www.southampton.ac.uk/~bim/>)*