

Design Patterns
→ Creation of

Case Study

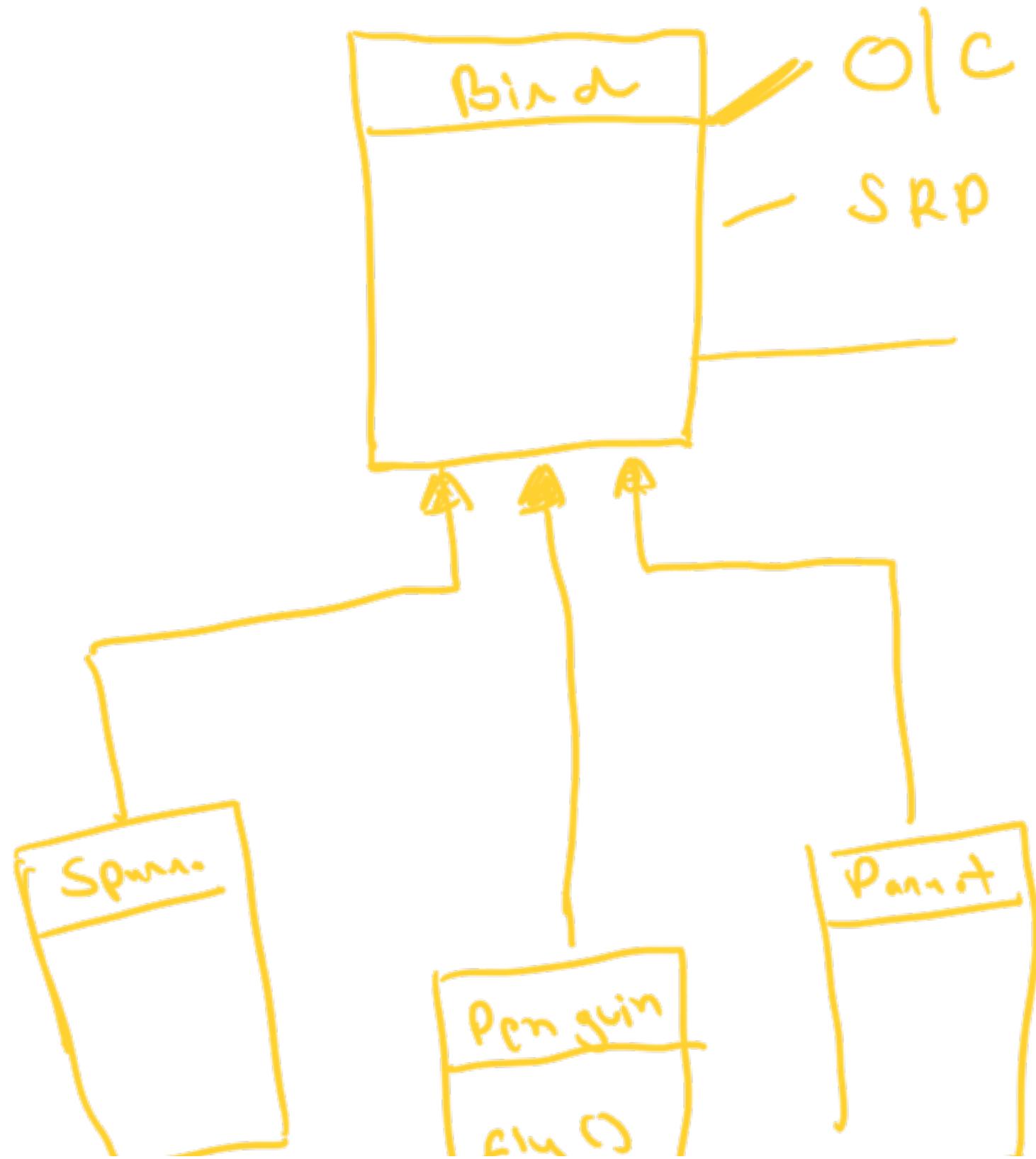
→ Bird

VO



| fly() {

✓



Flyc)

if C + ypc ==

else if C Parrot

...

SRP, OIC



Solution 5

- * dummy ↴ ↴ ↴
- * return / not null ↴ ↴ ↴
- * throw an exception ↴ ↴ ↴

List < Bird > = List . of (

) → Some ()



For each bird:

⇒ Bird, fly()

if bird is flying
do this()

if bird is Penguin()
do this

Lesson on Substitution principle

→ in order to handle any sub classes, I should not have to do any special handling

Fennel

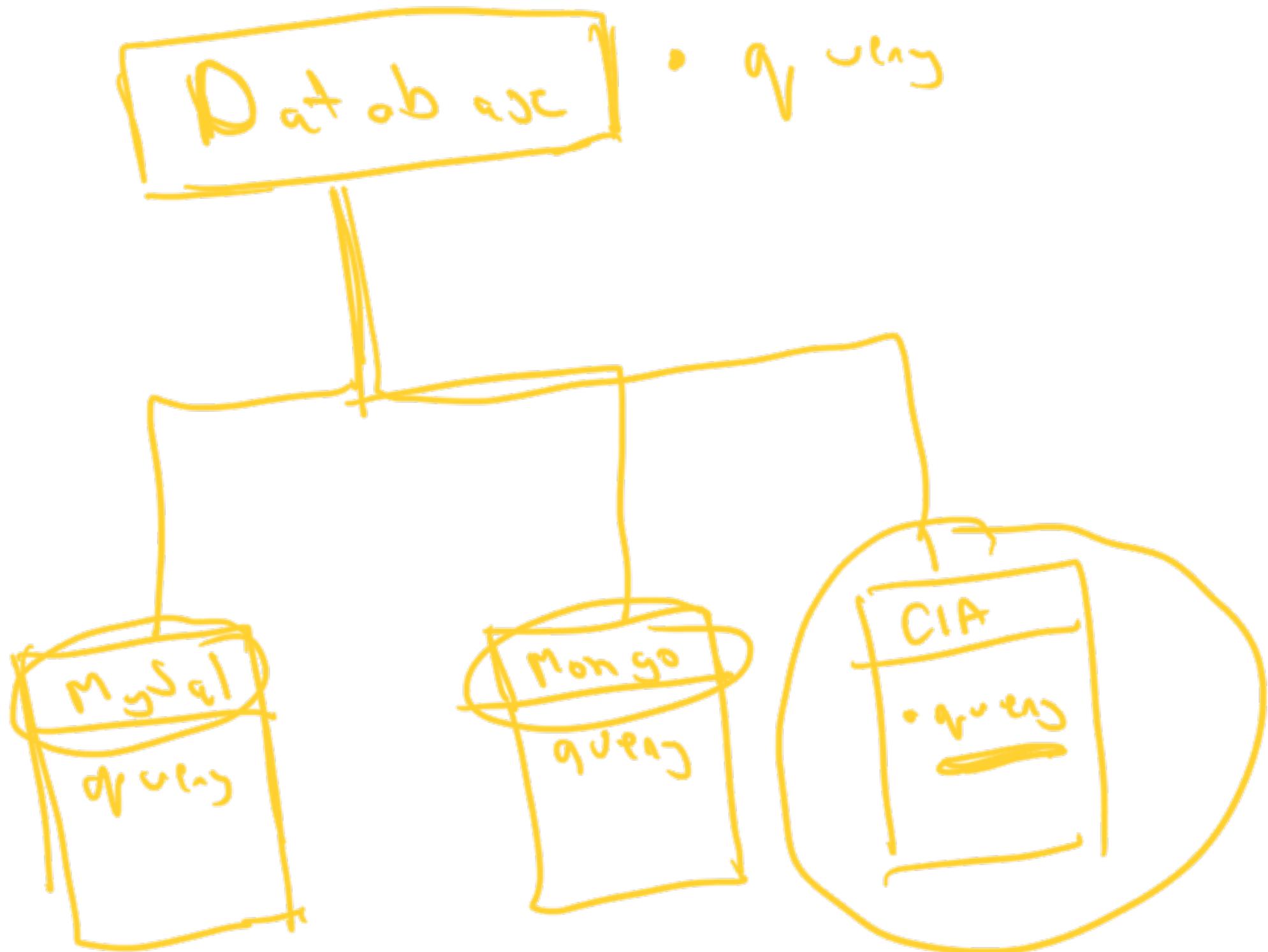
→ Penguin p = new Penguin()

Bird  = (Bird) p;

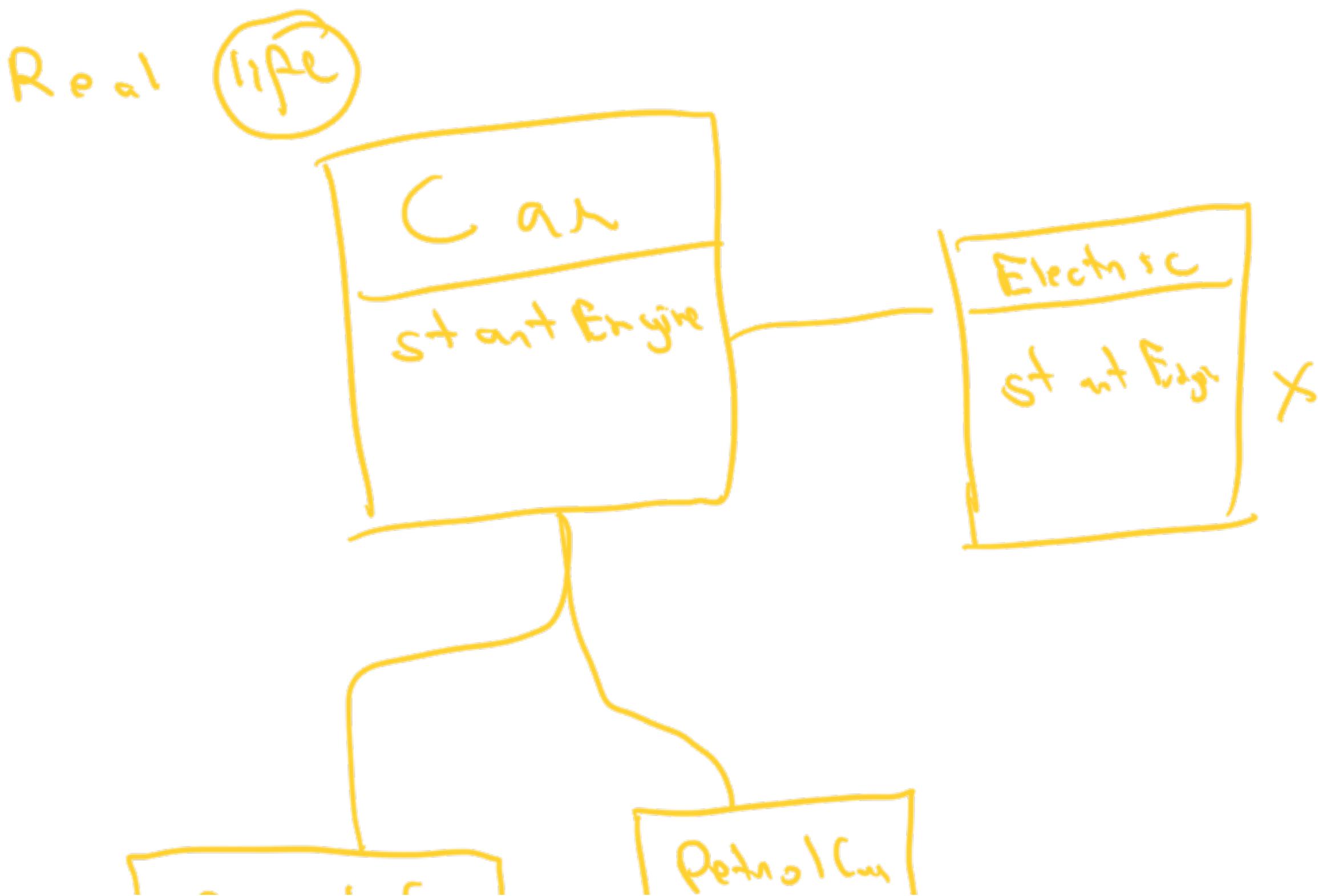


??

Pl. MySQL vs Sparrow, Flyt



→ new → the novelty or exception





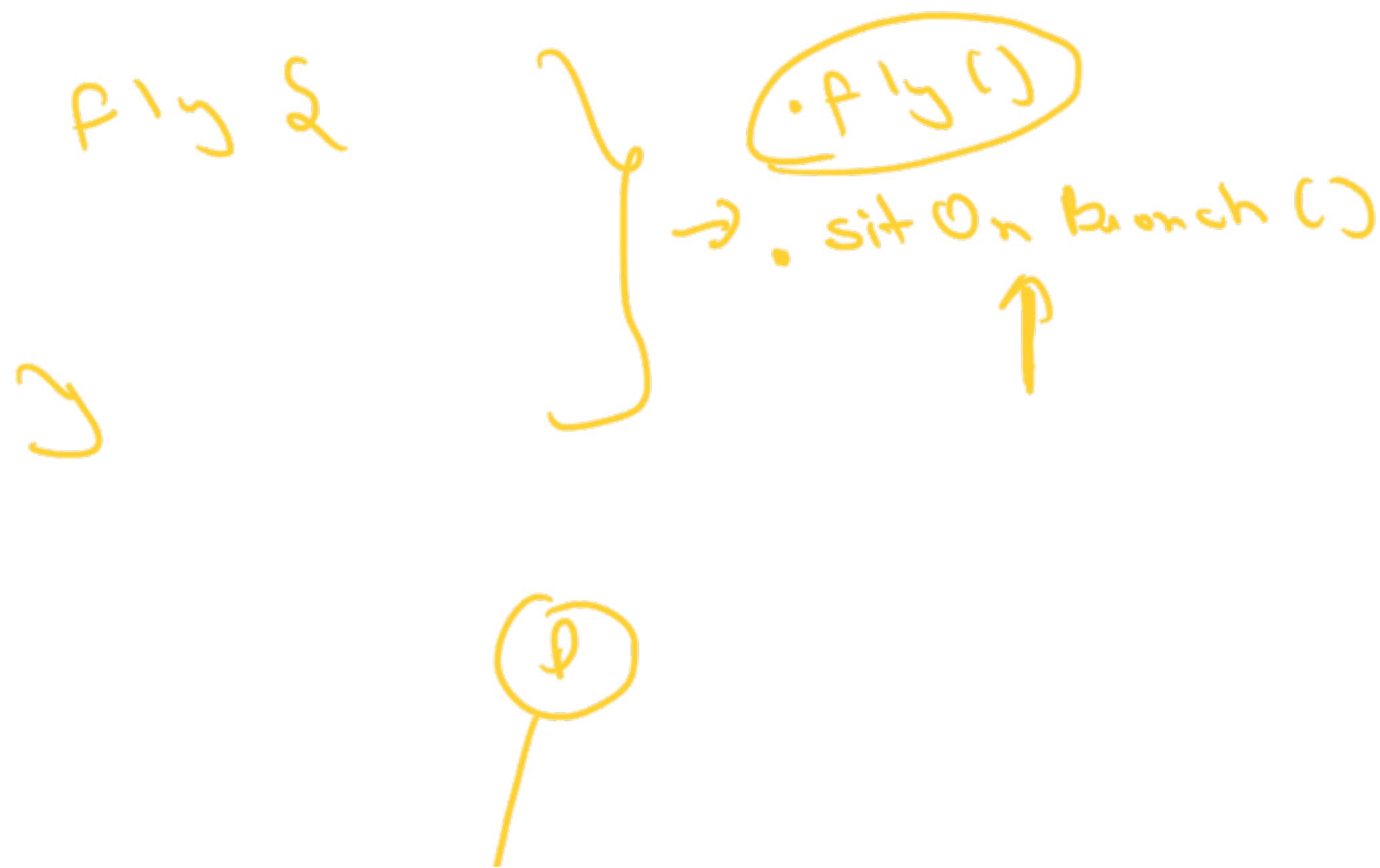
Start situation

→ Start engine

Electric car → Gas

Gas. Start Engine

if I sub situte Electric \rightarrow Car
then it should become running
special handling

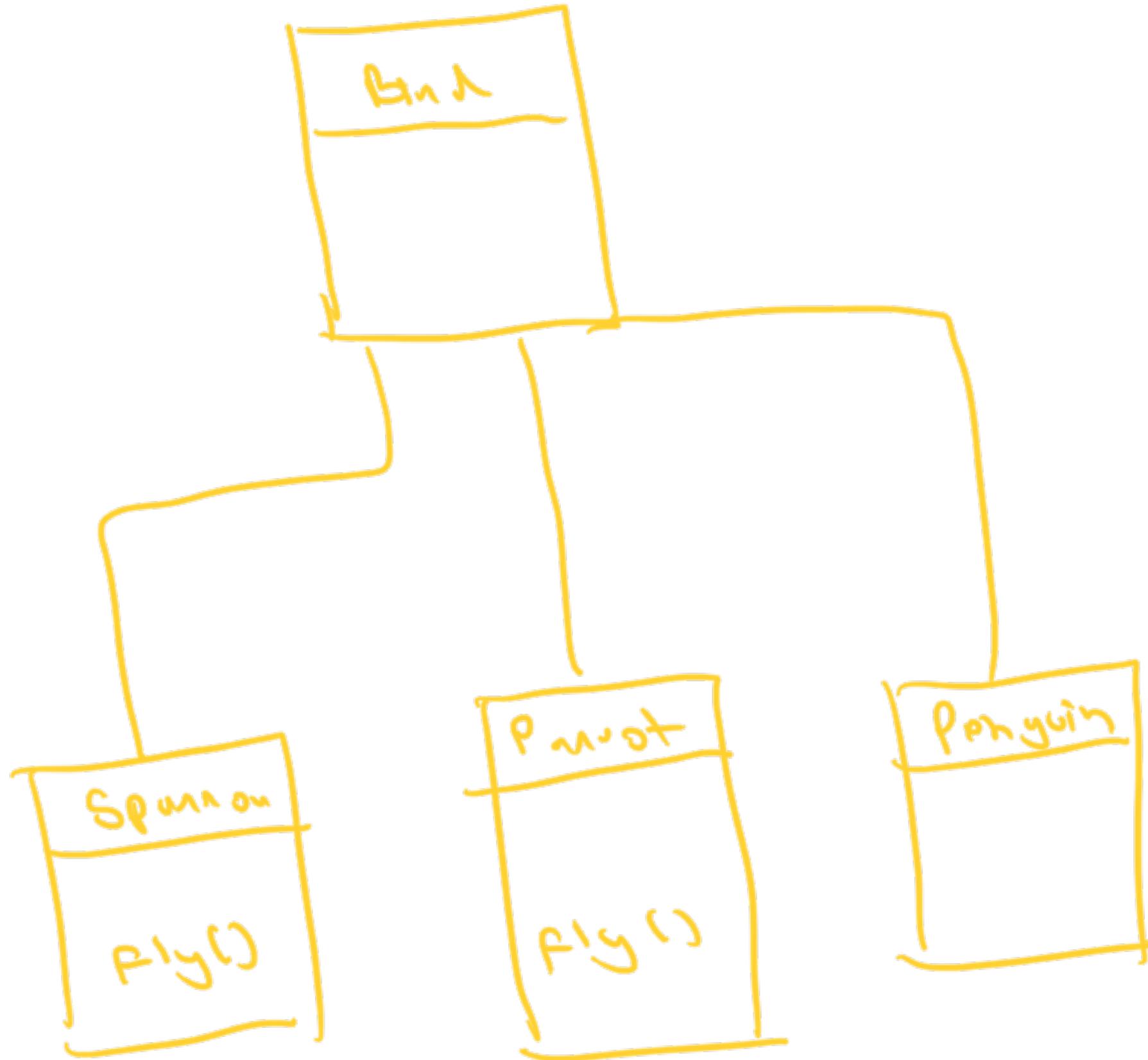




choose one approach

Build → program = new Program()
build. fly() →

Fix LSP



What is the base class?

Trade off between

Time complexity

List < Bind > = < ... >

bind. fly()

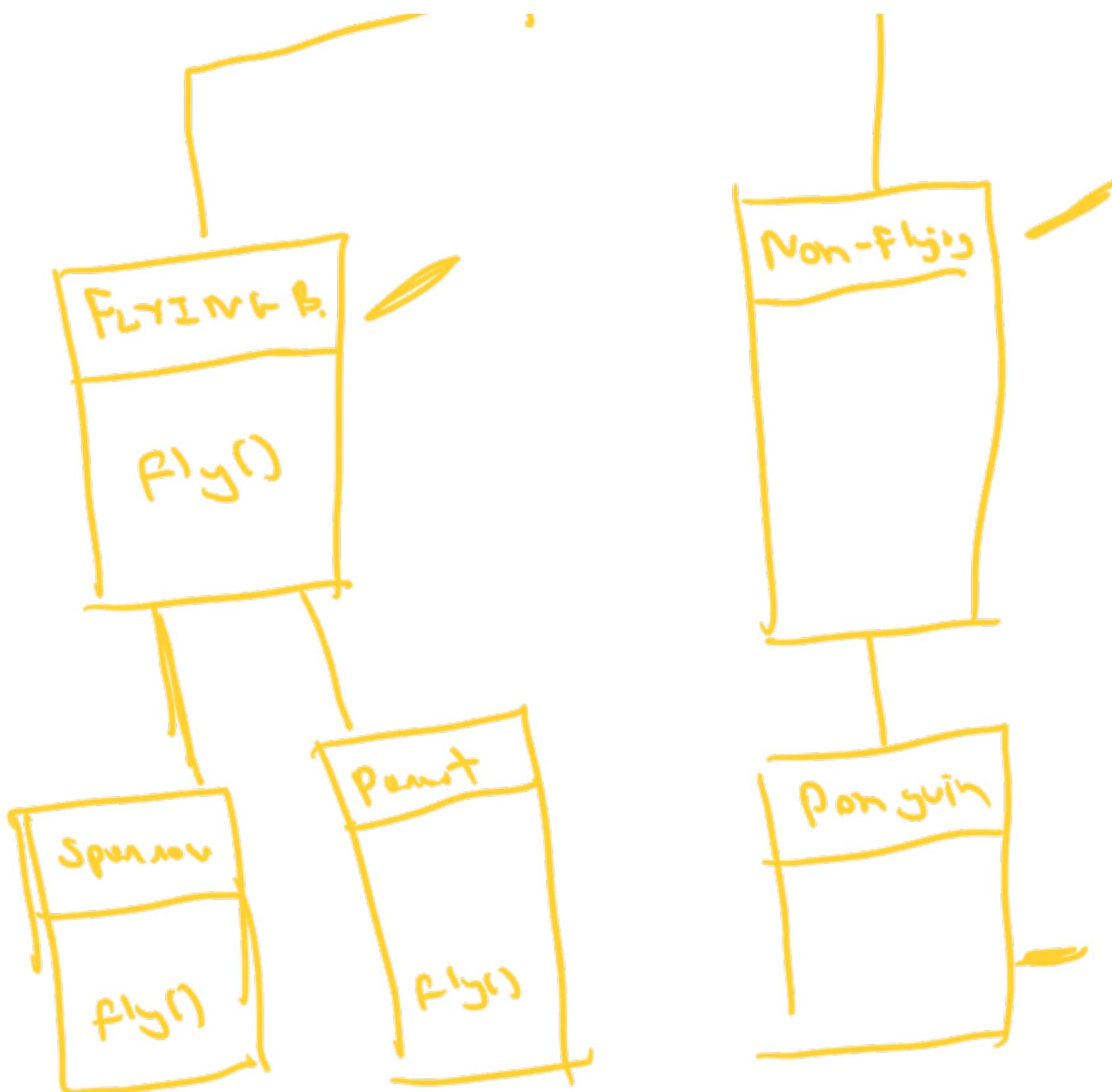
②

Bind

- weight
- book

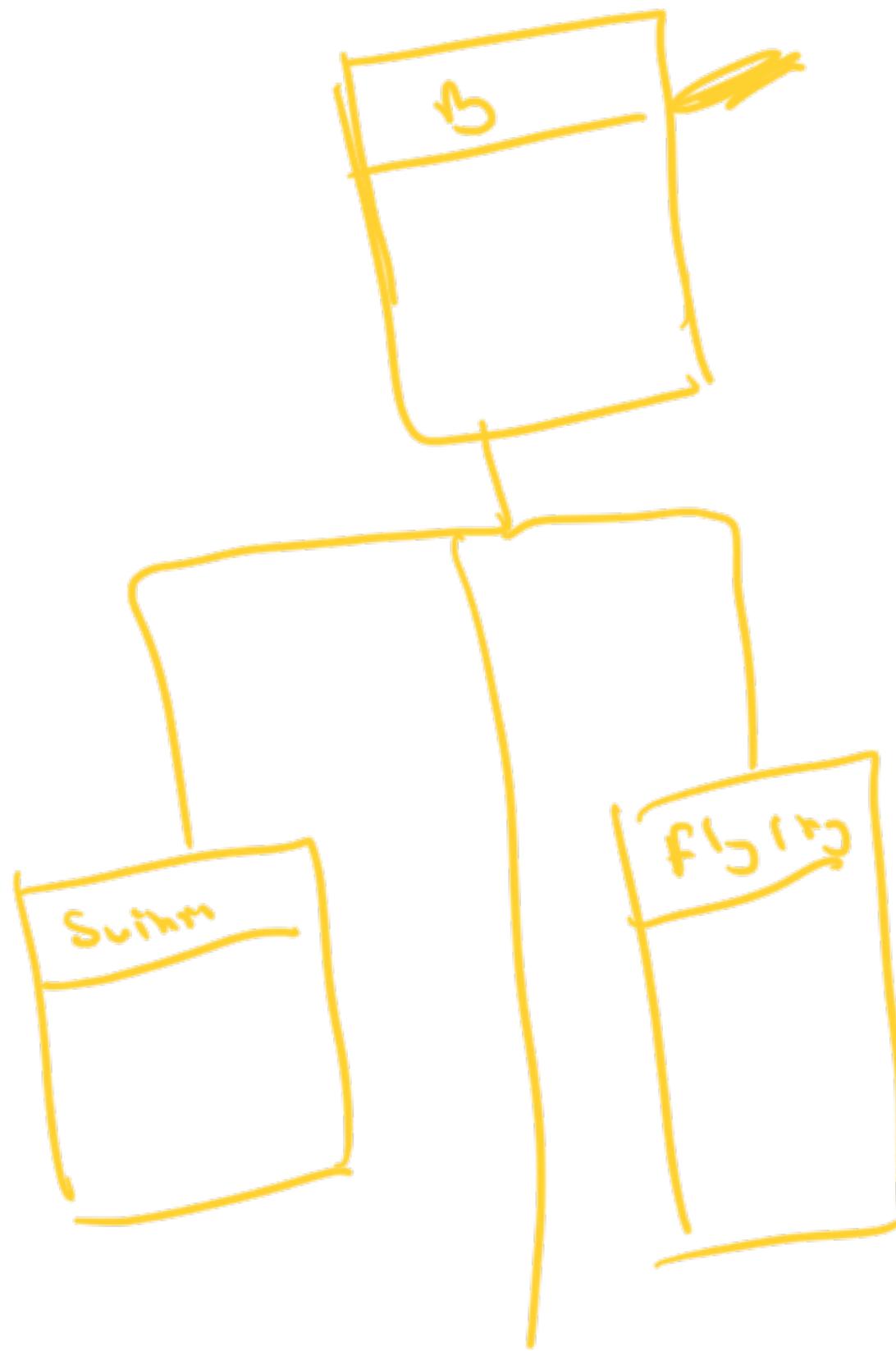
inches

multi-level



→ behavior to classification

→ Supply



P	+	S	R
P	✓	X	✓
D ₉₂	✓	✓	✓

→ Swimmable Flyable Bars

→ Non-swimmable Flyable

→ Class explanation

Tying behaviour
+ O class structure

interface → state X

Java interface

→ blueprint for behavior

→ state +

→ definitions of your
methods

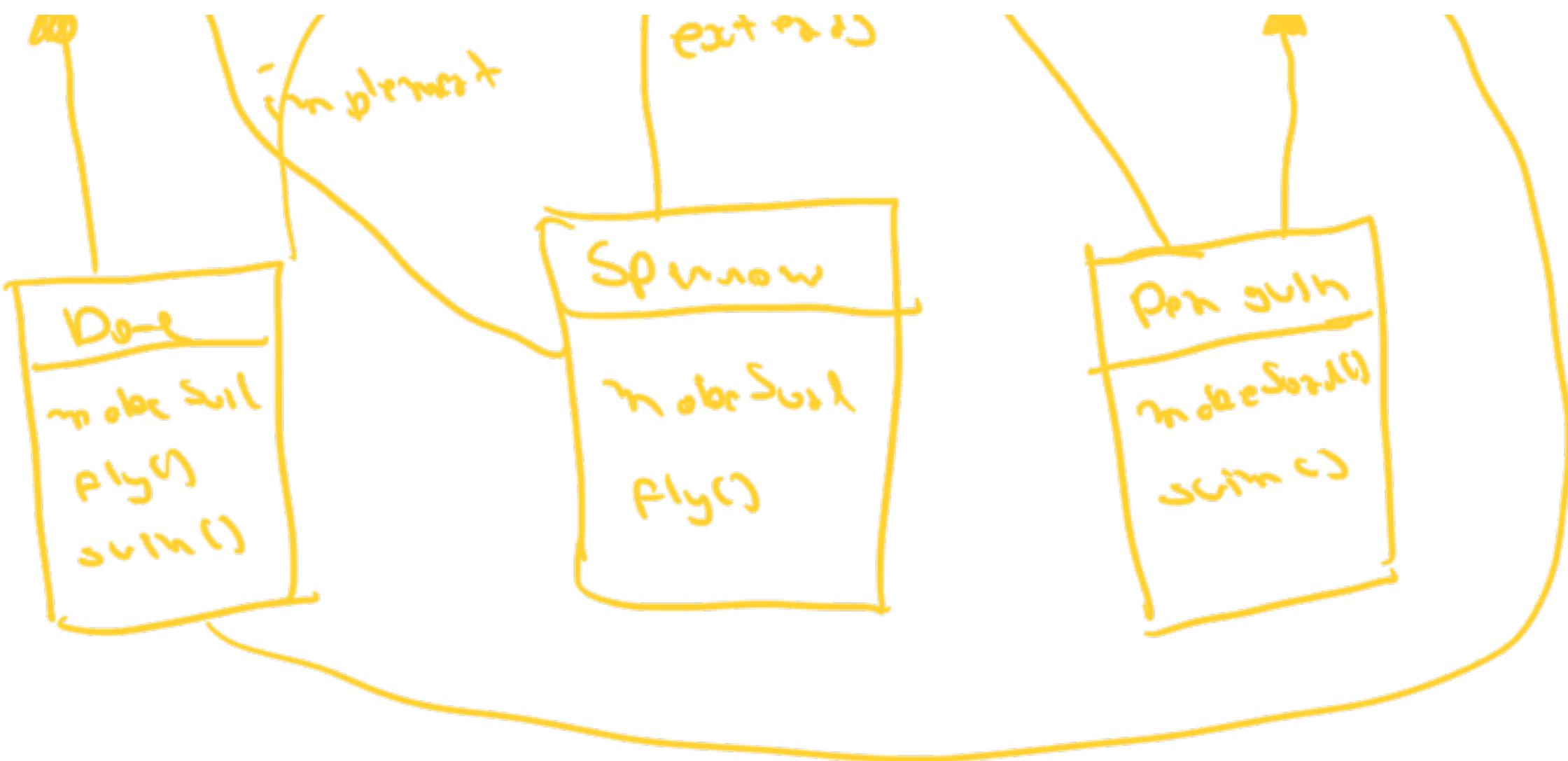
interface

→ tie to class structure

→ multiple classes

Interfaces





✓ Create a list of all birds

$\text{List } < \text{bird} \rangle = (\text{new Dove}),$
 $\text{new Pigeon},$
 $\text{Penguin})$

~~per gus . f15~~

Create a list of all binds that
can fly

Set all binds to fly

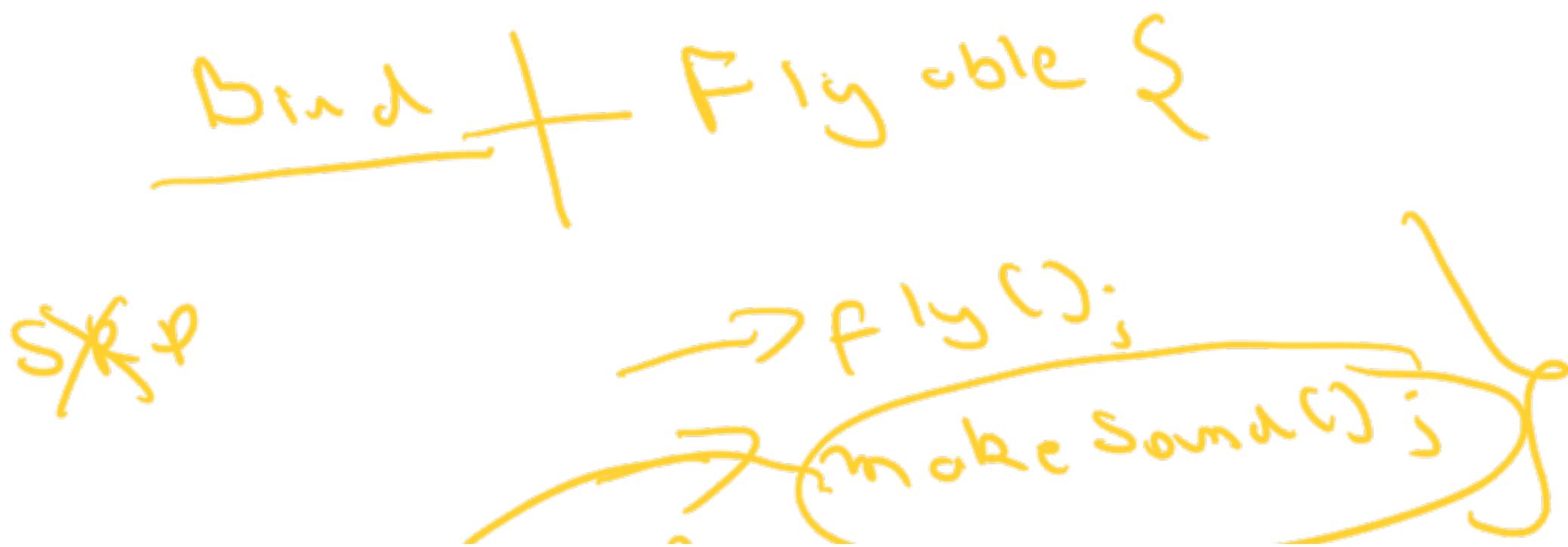


instance of
↓



Interface Segregation

→ no fat interfaces





return null
dummy method

Trick

Interface segregation

Interface segregation

→ SRP compliant



→ Extensibility

Functional interface

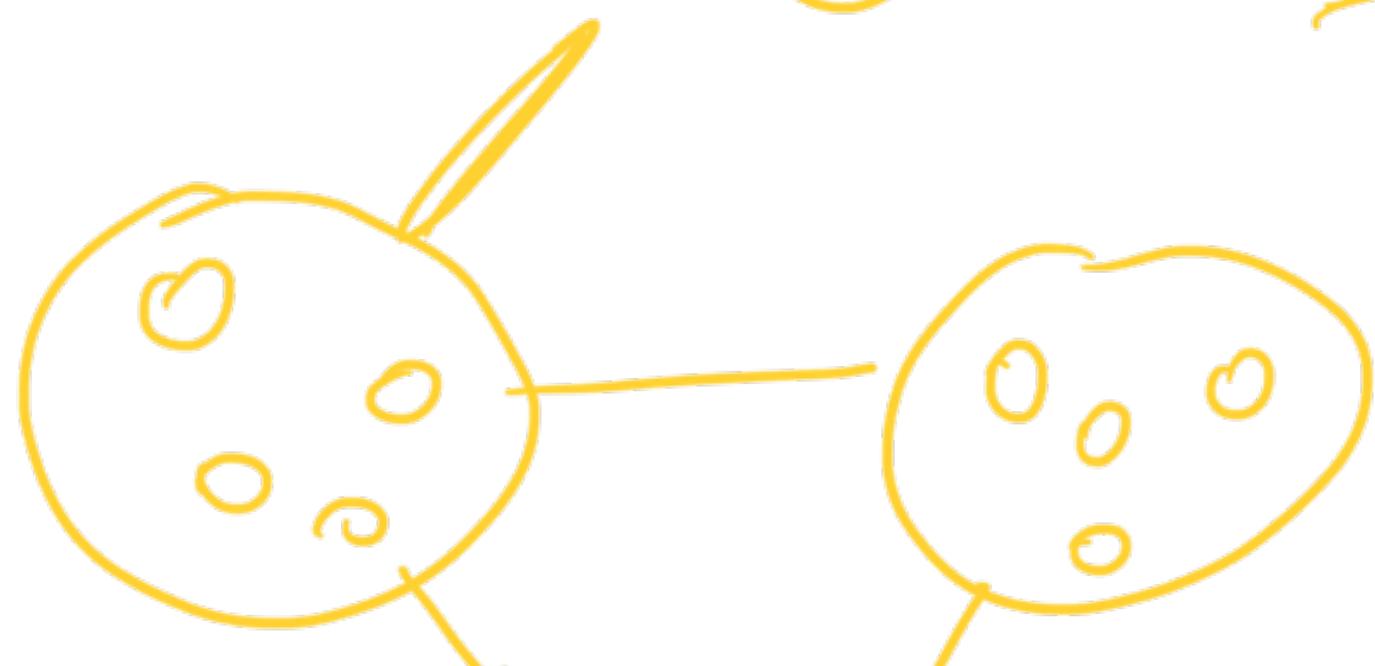
→ Single abstract method
(SAMI)

Keep relevant methods

Iterator ↴

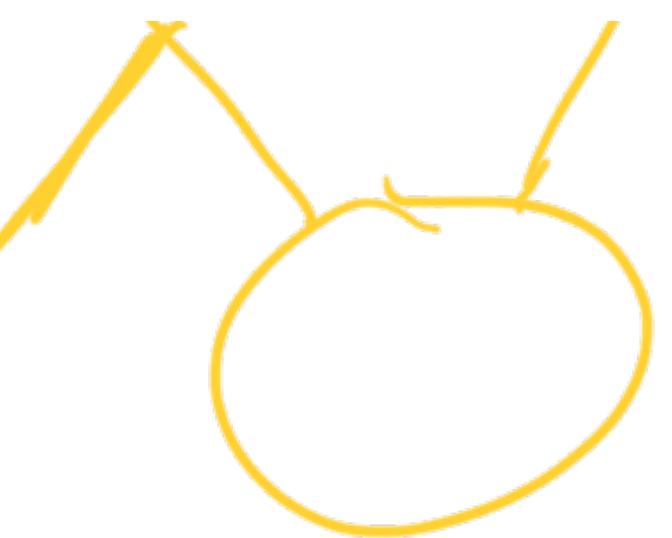
next()

→ List ↴



- High cohesion
- has next()
fly()
print()
- SOLID
- ① High cohesion
- ② Low coupling

cohesion



6:01 - 6:05

10:35

2 = 10'

add(*int* α)

add(α)

auto casting

auto boxing

parent child

base derived

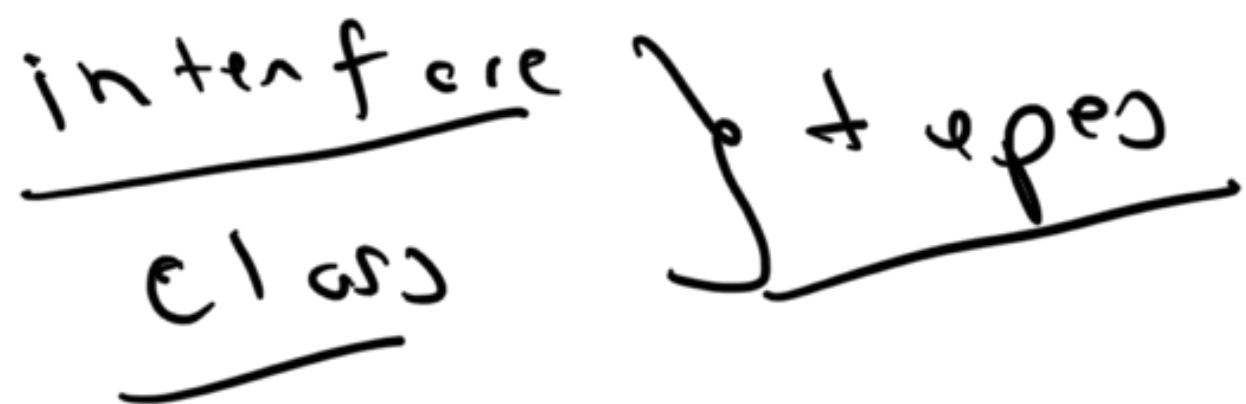
conversion

Super

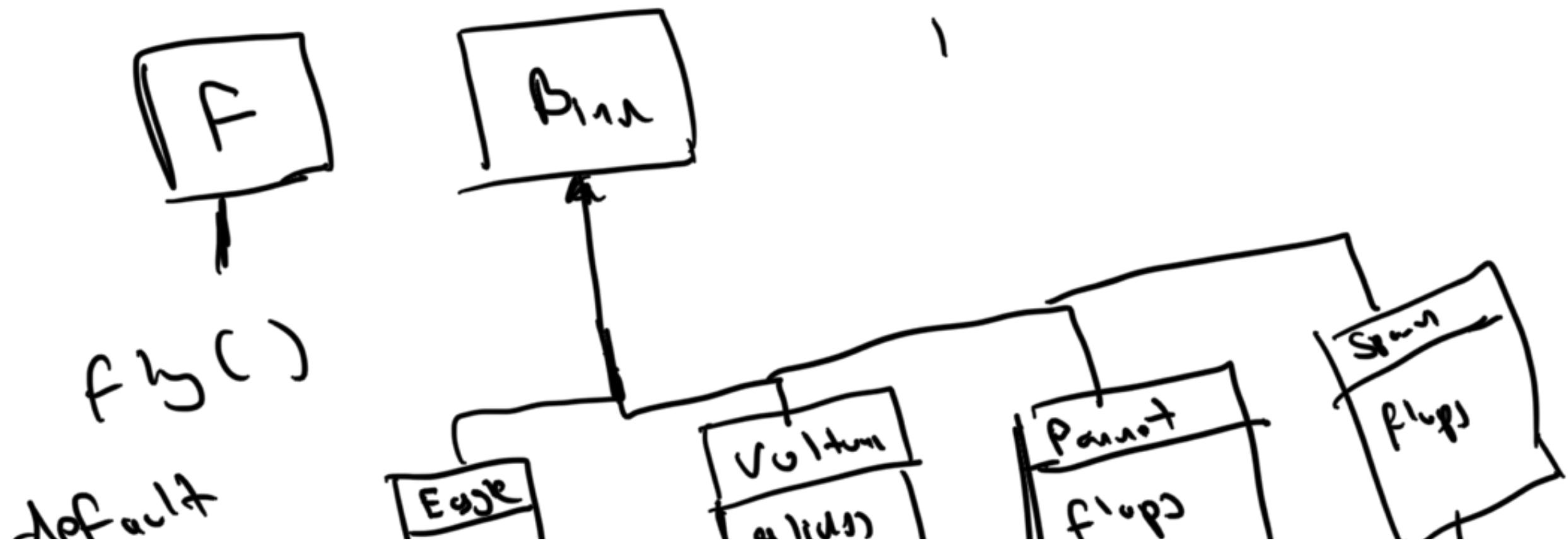
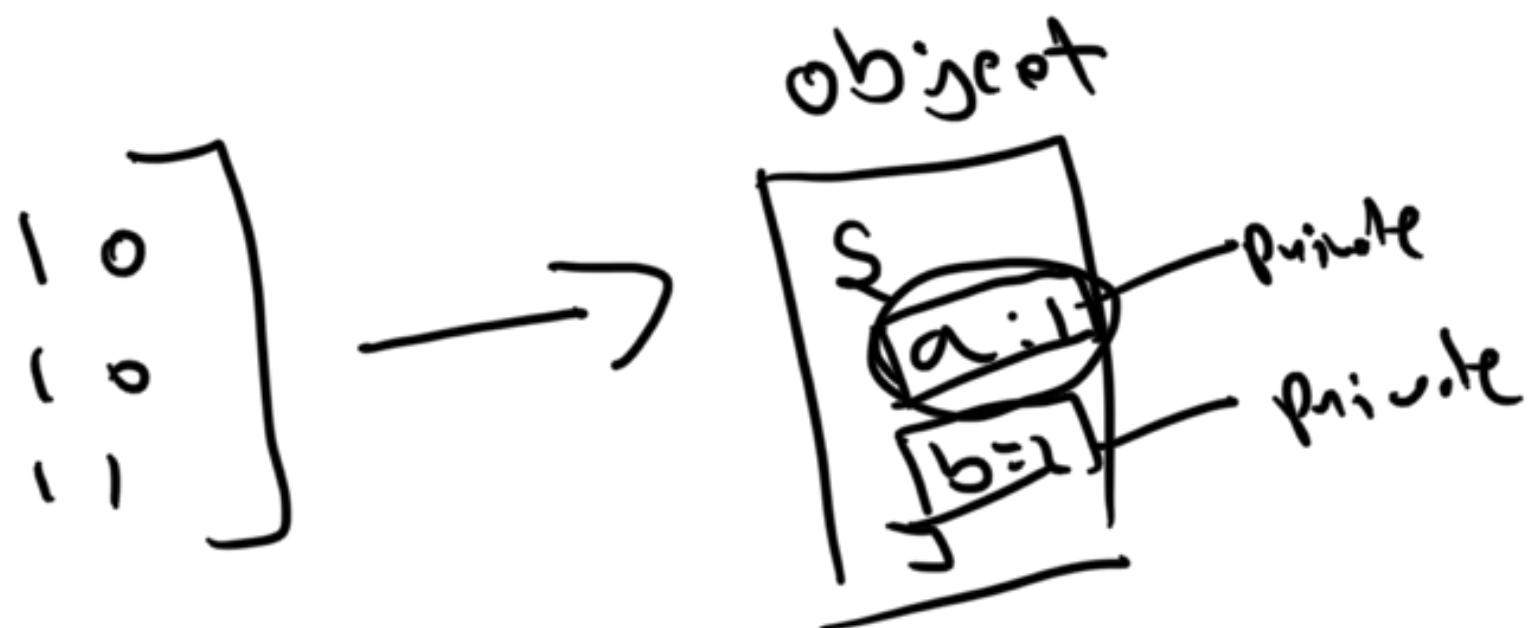
Sub -



Is-A



Temporary allocation





Flying behaviour

1.1.1.1

→ Gliding behaviour

→ Flapping behaviour

Eagle extends tail imp. Flyable

Gliding behaviour
ctrn (Gliding D)

fly() {

 gliding behaviour
 mabfly()



Dependency inversion

- ① High level modules (parent) should not depend on other concrete classes.
Both of them should use abstraction,
tightly coupled





Open for extension



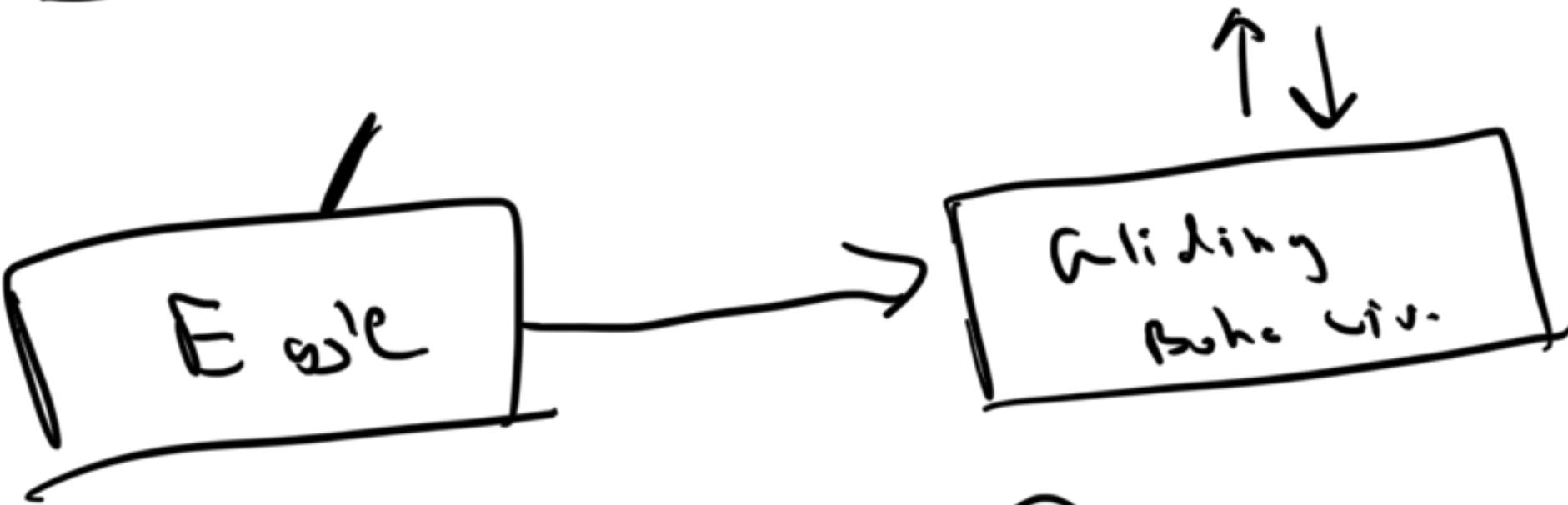
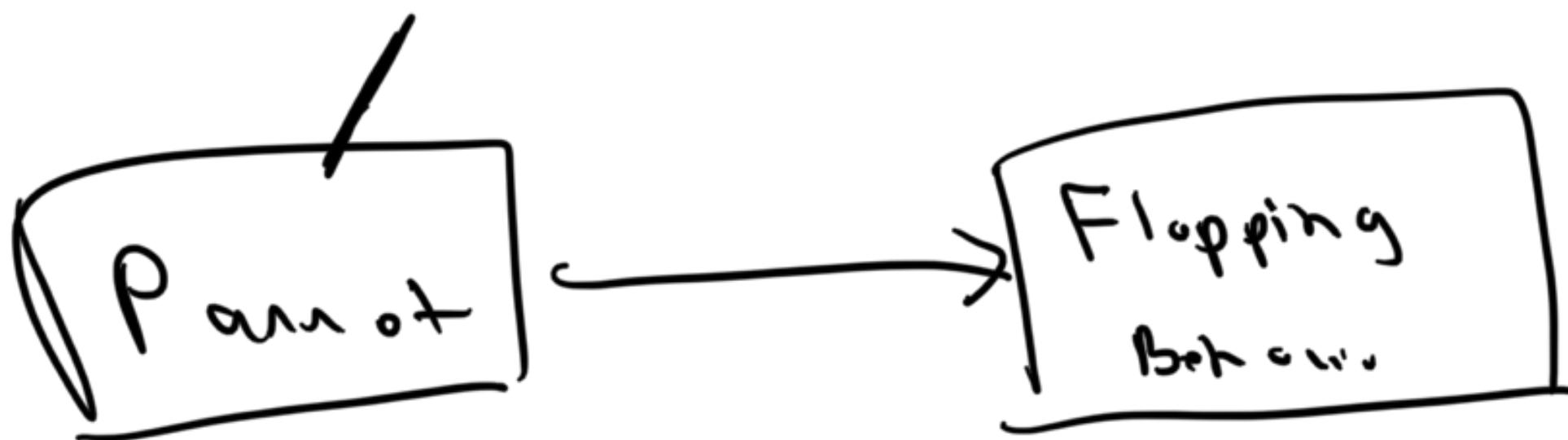
Close for modification

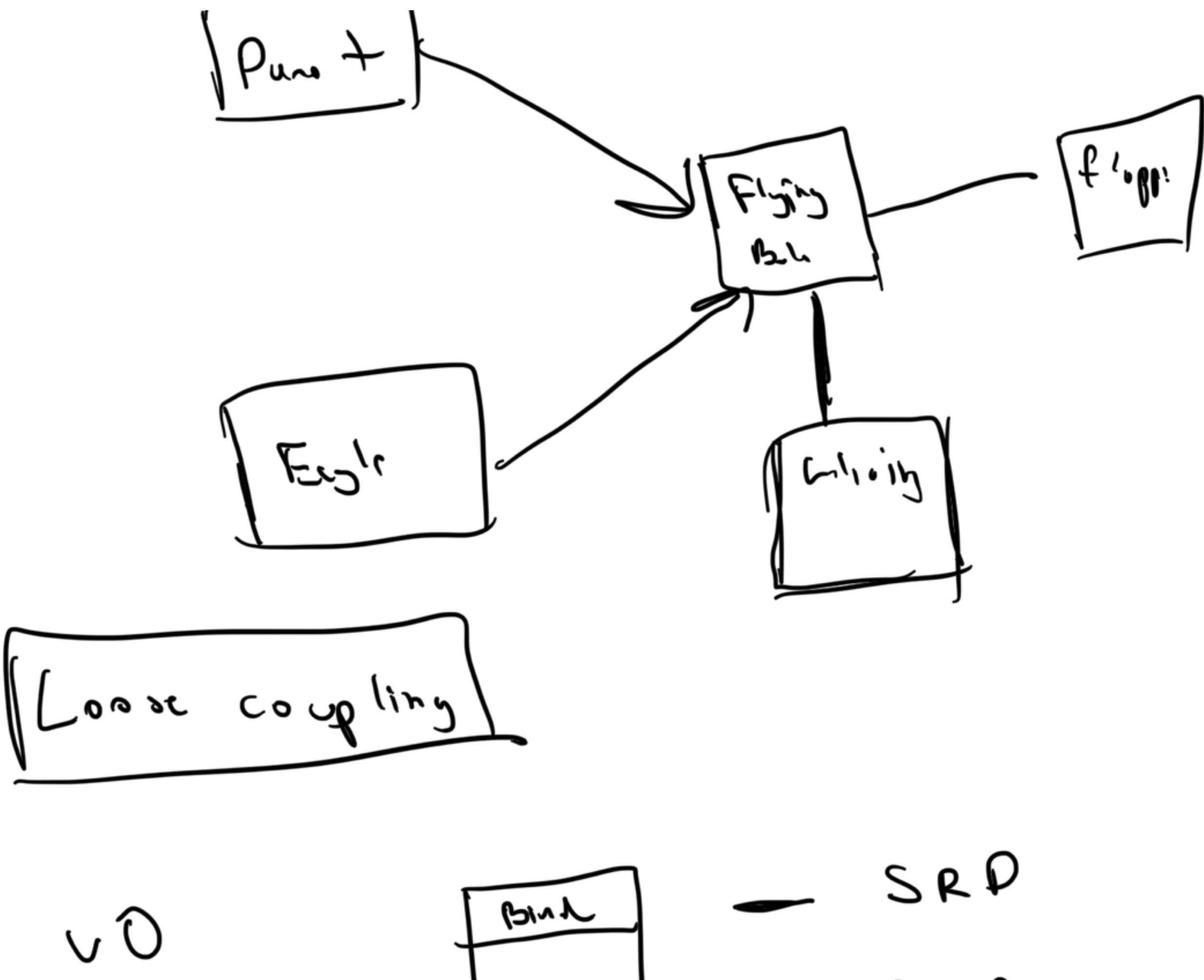


Solder to



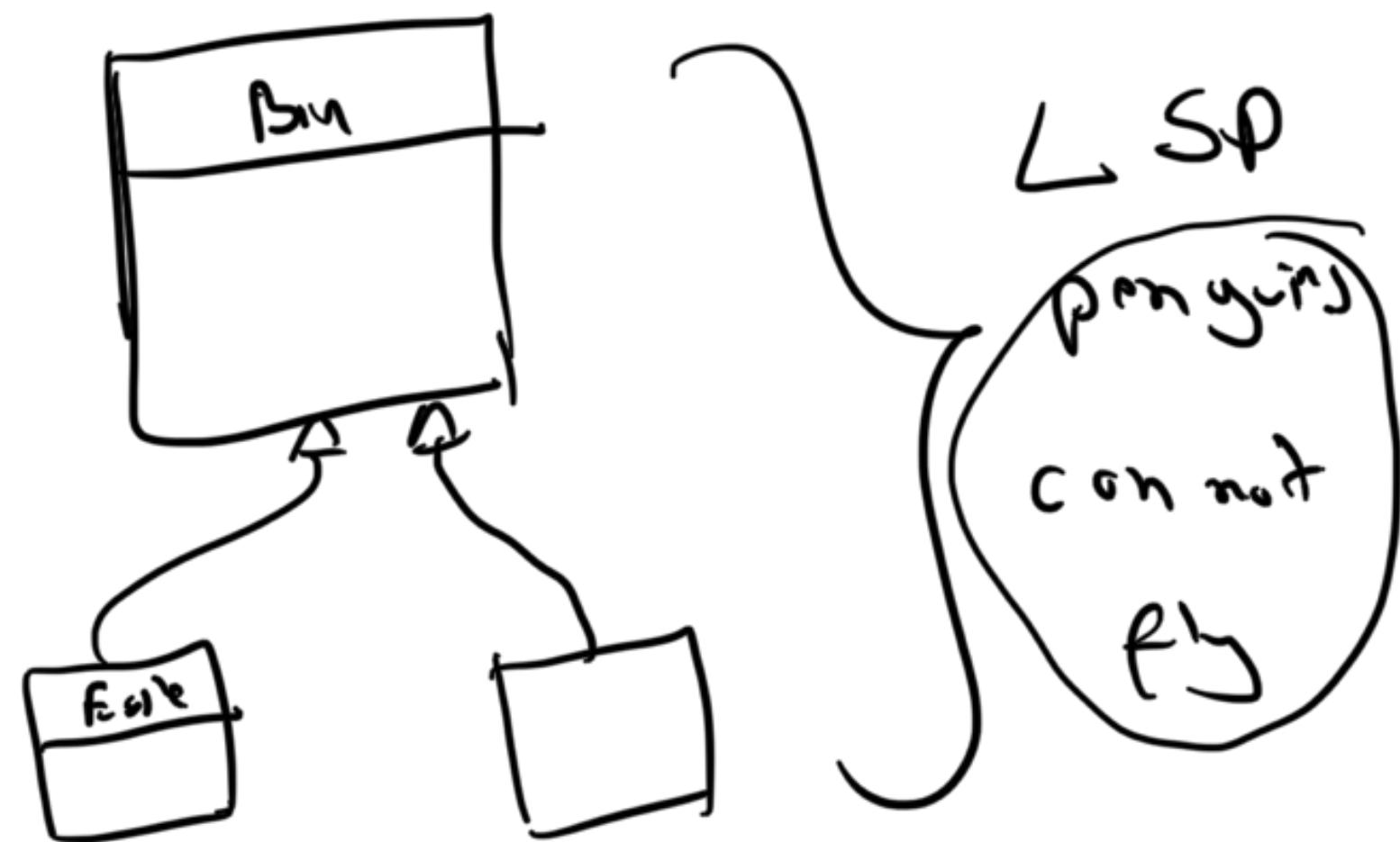
middle in



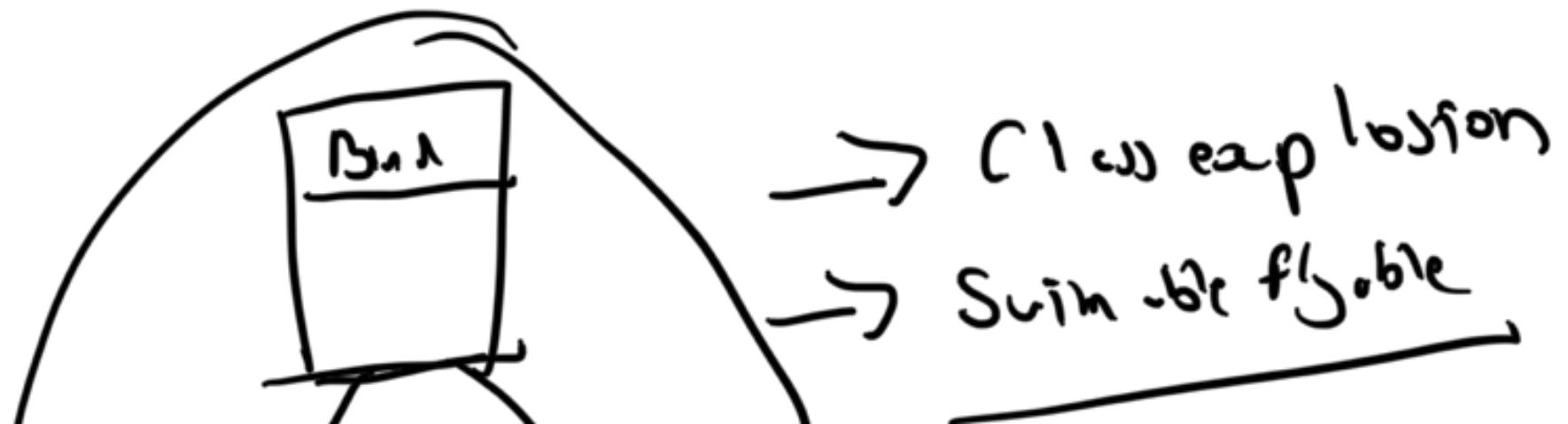


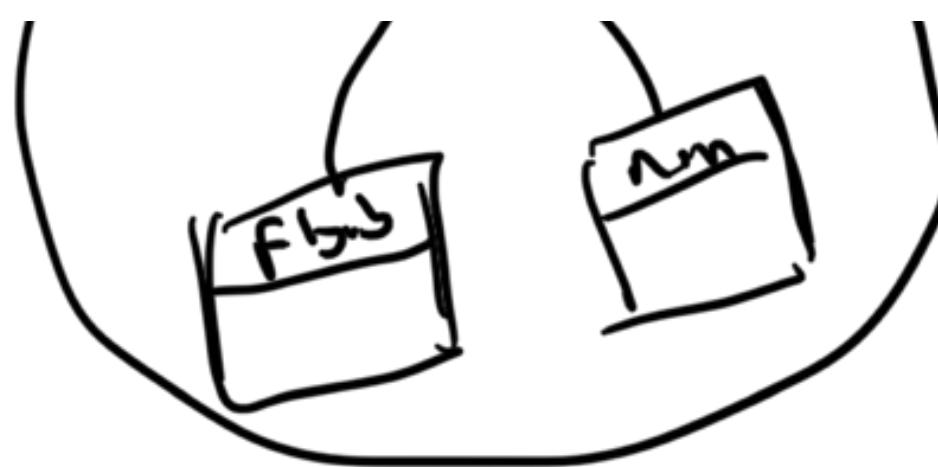


V1

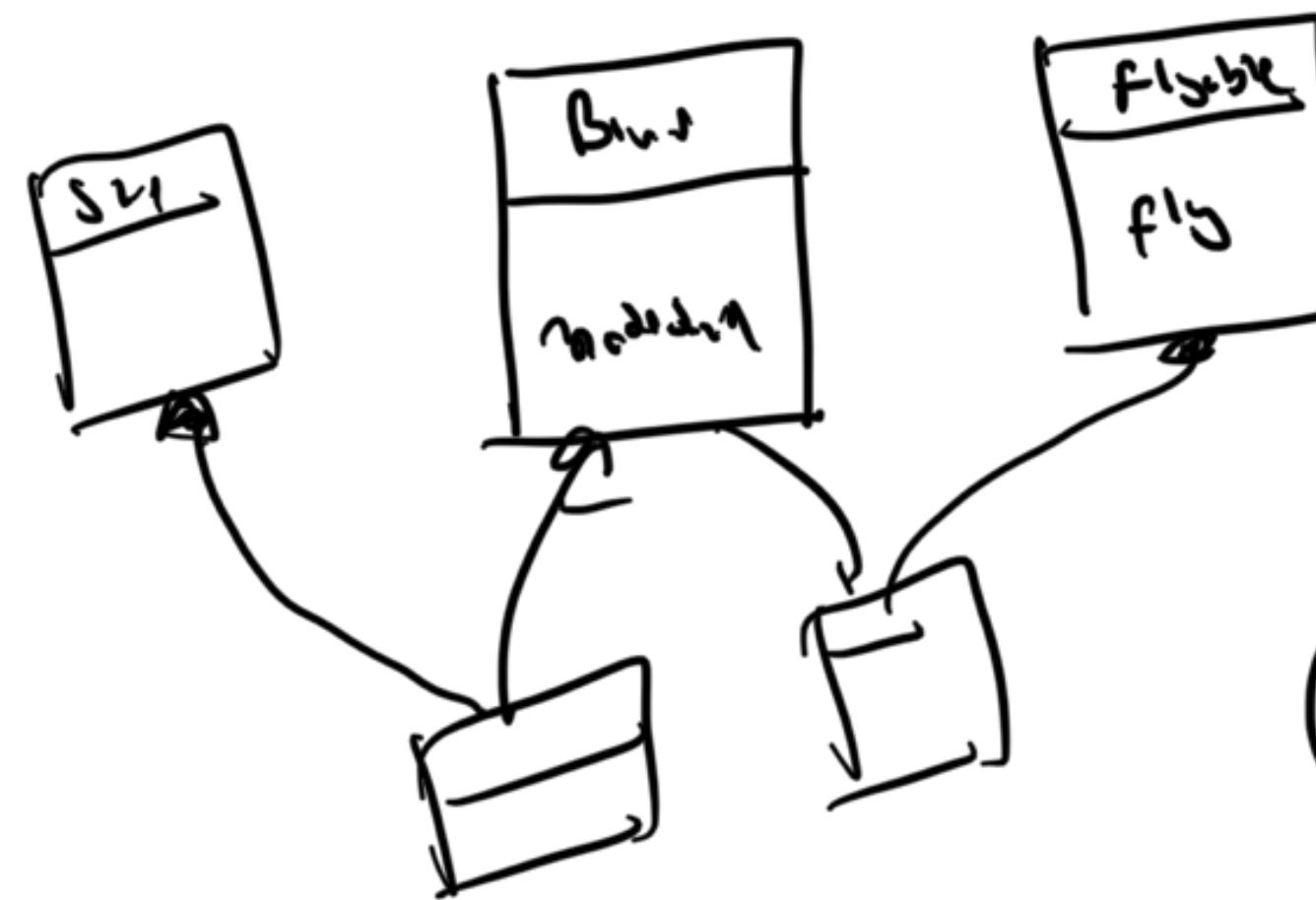


V2





✓3



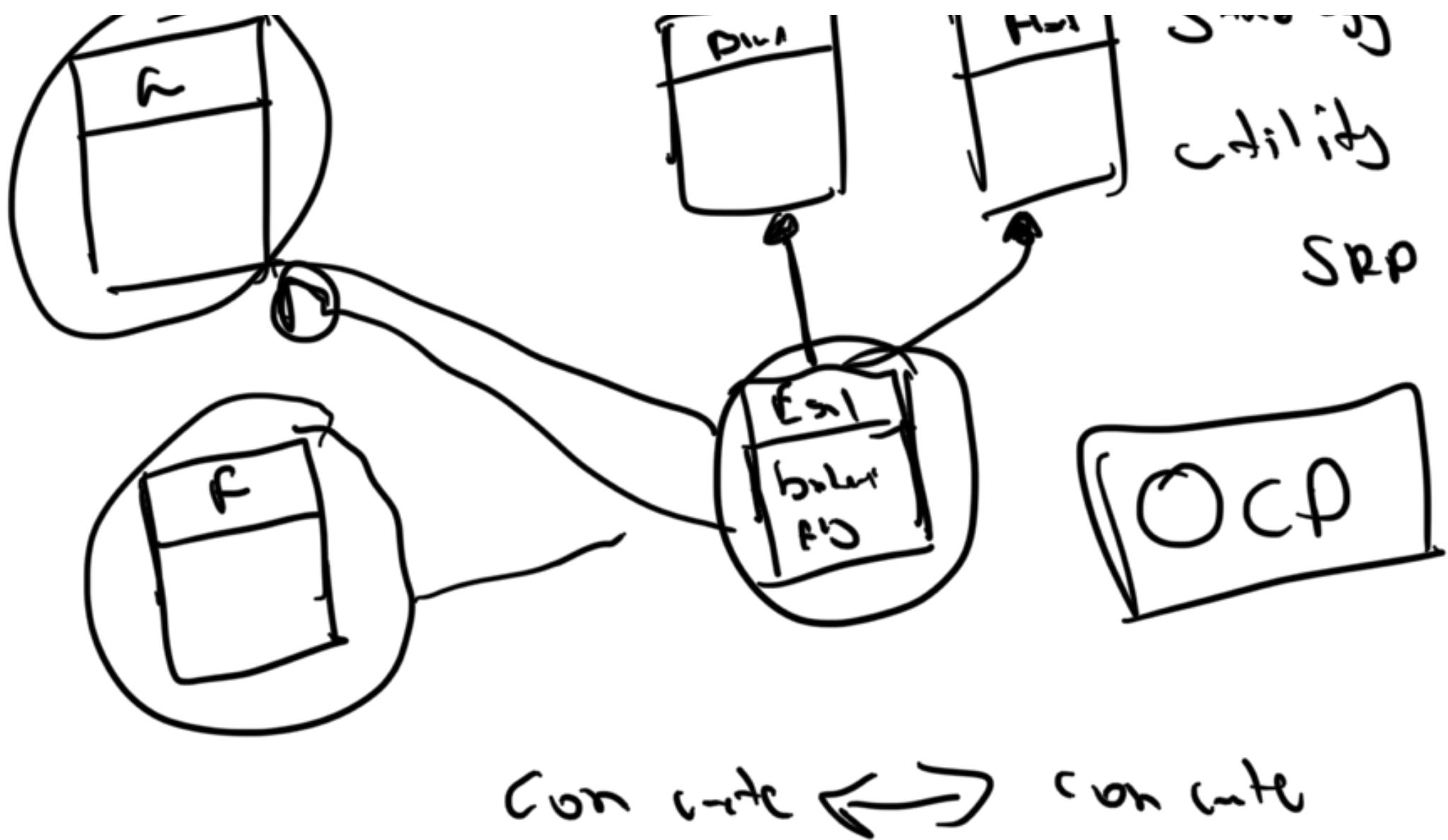
SRP ✓
O/C ✓
~~ESP ✓~~

$f'(y)$
+ in abs.

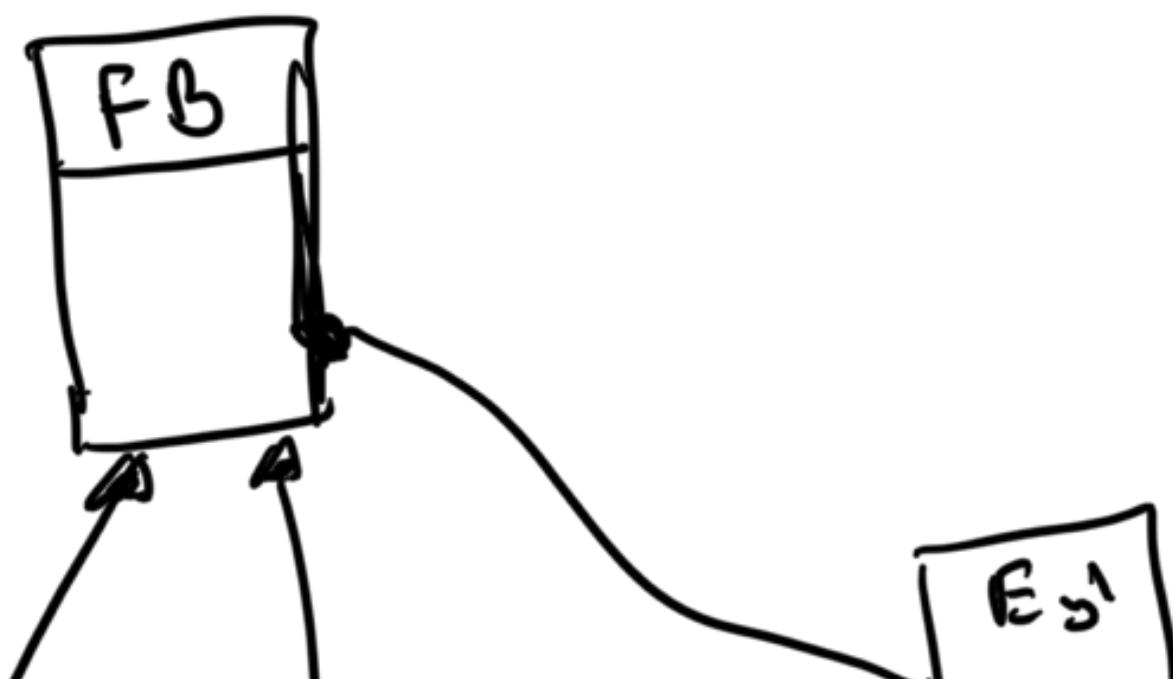
Code duplication

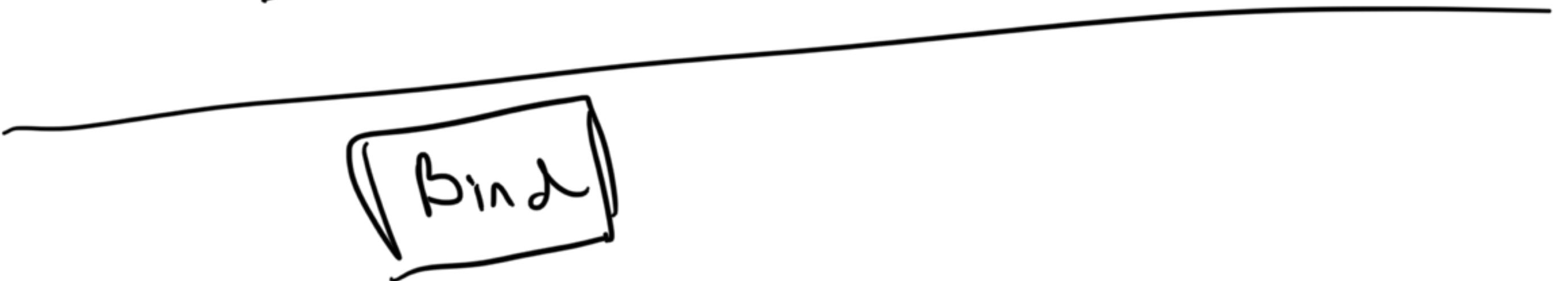
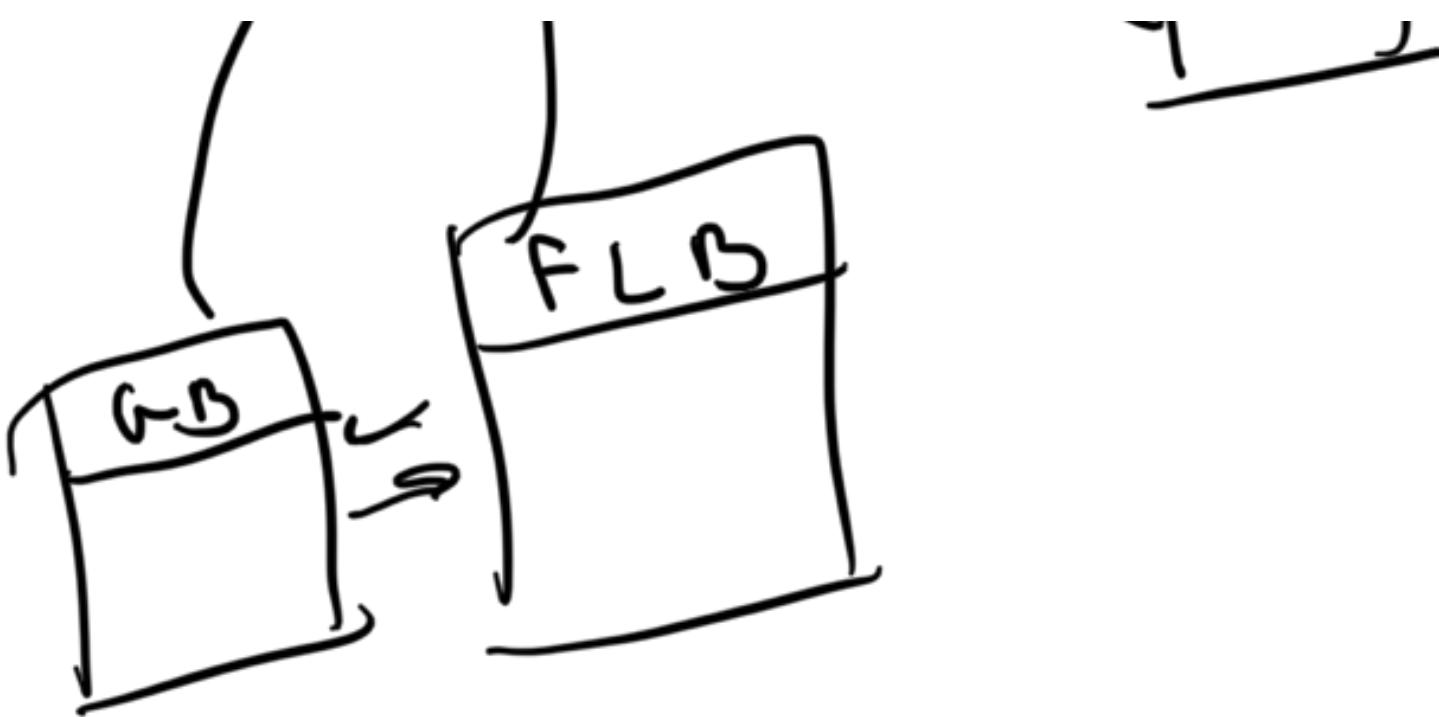
fat interfaces

$\sqrt{4}$



✓6





SOLID \rightarrow loose coupling

\rightarrow SRP

\rightarrow OCP

\rightarrow TSP

$\rightarrow \underline{TI} J$

high cohesion

$\rightarrow ISP$

SOLID

\rightarrow SRP - only one reason to change

\rightarrow OCP - open for extension

— closest for no difficulties

↳ LSP = no special handling
for any sub class

→ ISP — loose interfaces

→ DI — concrete classes should
not depend on
each other

✓ ✓ ✓ ✓ ✓ ✓