

MA 232: Introduction to Algebraic Topology

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August 2025

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The Course

Textbook: M. A. Armstrong's *Basic Topology*.
Teams Code: xr80svy

Lecture 1.
Monday
August 4

When are two topological spaces *equivalent*?

The strongest notion of equivalence is homeomorphism. This preserves all properties pertaining to continuity.

However, visually, this is asking for too much. $\mathbb{R}^2 \setminus \{0\}$ and S^1 are not homeomorphic. However, thinking loosely in terms of deformations, both these spaces have one “hole”. If we are allowed to deform space to any extent allowed *without creating or destroying holes*, one can switch between these two spaces.

The goal of algebraic topology is to associate an algebraic object to each topological space such that two topological spaces are equivalent, in the second sense, iff their algebraic structures are isomorphic.

Algebraic topology is thus the study of algebraic invariants under homotopy equivalence of spaces.

Chapter I

The Fundamental Group

Let X, Y be topological spaces. The word “map” without qualification will refer to continuous maps.

Definition I.1 (Homotopy). Maps $f, g: X \rightarrow Y$ are *homotopic* iff there exists a map $F: X \times I \rightarrow Y$ such that $F(\cdot, 0) = f$ and $F(\cdot, 1) = g$. F is called a *homotopy* from f to g and we write $f \sim g$.

For example, the maps $f(s) = e^{2\pi i s}$ and the cardioid $g(s) = 2(1 - \cos(2\pi s))e^{2\pi i s}$ are homotopic.

Remark. If $f \equiv g$ on some subset $A \subseteq X$ and $F(a, \cdot) \equiv f(a) = g(a)$ for all $a \in A$, we say that f and g are homotopic relative to A .

Examples.

- If C is a convex subset of \mathbb{R}^n , then any two maps from any space X are homotopic. A homotopy is given by $F(\cdot, t) = (1 - t)f + tg$. If $f \equiv g$ on $A \subseteq X$, then $F(a, t) = f(a) = g(a)$ on A .
- The other way does not work. The maps $f \equiv 0$ and $g \equiv 1$ from $[0, 1]$ to $\{0, 1\}$ are not homotopic. Any homotopy would have connected domain but disconnected range.

check that
this is con-
tinuous

What if Y were path-connected? Any two maps from a convex set to Y would be homotopic. This follows from the next example.

- Let C be convex and Y be any space. Then any map $f: C \rightarrow Y$ is homotopic to some constant map. To construct a homotopy, pick any point $p \in C$ and define $F(x, t) = f((1 - t)x + tp)$.
- Let $f, g: X \rightarrow S^n \subseteq \mathbb{R}^{n+1}$ such that $f + g$ is never 0. Then $f \sim g$.