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# Part 1A: Distance Weighted KNN Regression

## Checklist

### Final r2 Value:

For k=3, the final r2 value is: 0.8287402327561264  
This was achieved, when the weight used was (1/distance)3 .

The plot below illustrated how the r2 error varies as the power in the weight is changed for k=3:

The global best value was achieved for k=10 and power=5. The r2 value was 0.8610154123824508.

For k=10, this is how the r2 values varies with the power.

We shall see that feature selection led to much better r2 values. Spefically, when forward selection was employed to select the 5 best features, and Mahalanobis distance was used, the model was able to achieve an r2 value of 0.9691290819198476.

### Implementation of calculate\_distances

def calculate\_distances(allvalues:np.ndarray, row:np.ndarray)->np.ndarray:

"""

Calculate the distance between all the training samples, and one

point.

If there are m training examples, and N features, then the shapes are as follows

allvalues m x N

row N x 1

diff2 m x N

np.sum(diff2) m x 1

Return m x 1

"""

diff2 = np.square(allvalues - row)

"""

diff2 is m x N, summing it along axis 1 will give an m x 1 array

"""

return np.sqrt(np.sum(diff2, axis=1))

### Implementation of *predict*

def predict(train\_features:np.ndarray, train\_values:np.ndarray, test\_features:np.ndarray, k:int, p:int)->np.ndarray:

global g\_normalize\_to\_zero\_mean\_and\_unit\_variance, g\_scale\_between\_zero\_and\_one

if g\_normalize\_to\_zero\_mean\_and\_unit\_variance:

"""

If normalization is required, normalize to zero mean and unit

standard deviation.

"""

stddvarr = np.std(train\_features, axis=0)

meanarr = np.mean(train\_features, axis=0)

train\_norm = normalize(train\_features, stddvarr, meanarr) *# Normalize*

else:

"""

If normalization is not required do nothing

"""

train\_norm = train\_features

if g\_scale\_between\_zero\_and\_one:

"""

If scaling is required scale to a range in [0, 1]

"""

amin, amax = get\_min\_max(train\_norm)

train\_norm = scale(train\_norm, amin, amax) *# Scale*

if g\_normalize\_to\_zero\_mean\_and\_unit\_variance:

"""

Normalize the test values by the same amount we had normalized the

training features.

It is important to use the values of stddvarr and meanarr exactly

as we had used in the training normalization

"""

test\_norm = normalize(test\_features, stddvarr, meanarr)

else:

test\_norm = test\_features

if g\_scale\_between\_zero\_and\_one:

"""

Scale the test features exactly as we had scaled the train features

Again, it is important to use the same values of amin and amax that we

had used in the training scaling

"""

test\_norm = scale(test\_norm, amin, amax) *# Normalize*

all\_predictions = []

"""

This version uses np.argsort(), and then chooses k values out of it

The best case complexity of np.argsort() is O(n log(n))

A better complexity can be achieved by using heapify.

Heapify operation can run in O(n), and removing something from a heap is

O(log(n))

The algorithm can be as follows:

1. Create a heap using the distances as the sort index in O(n) complexity

2. Remove k elements from the heap, each in log(n) complexity

The total complexity of the above is O(n + k\*log(n))

However, this scheme has not been implemented. For this size of data,

the overheads might actually be higher than the speedup achieved.

For larger data sets, this might be more efficient.

"""

for i in test\_norm:

"""

For each data point in the test data, categorize it

"""

"""

Calculate the idstance between this point, and all other points

"""

distances = calculate\_distances(train\_norm, i)

"""

Sort based on the distance, and get the k smallest indices

"""

sorted\_indices = np.argsort(distances)[0:k]

"""

Get the nearest distances, this will be used in the weighted average

"""

nearest\_distances = distances[sorted\_indices]

"""

Avoid division by zero

"""

nearest\_distances = nearest\_distances + 0.0000000001

"""

Get the y for the nearest k points

"""

nearest\_values = train\_values[sorted\_indices]

"""

Weight is inverse of distance

"""

nearest\_weights = 1 / nearest\_distances

"""

The power used in calculating the weight is a parameter

weight = (1/distance) ^ p

"""

nearest\_weights = nearest\_weights \*\* p

"""

Multiply each of the nearest weights with the nearest y values

and sum it up

"""

prediction = np.sum(np.multiply(nearest\_weights, nearest\_values))

"""

Divide by the sum of the weights so that everything adds up and the

weighted average is proper

"""

prediction = prediction / np.sum(nearest\_weights)

"""

Add this prediction to an array, so that we can get all the predictions

for all the points in one place and return it

"""

all\_predictions.append(prediction)

return all\_predictions

### Implementation of *calculate\_r2*

def calculate\_r2(predicted:np.ndarray, actual:np.ndarray)->float:

"""

Calculate the r2 error and return a float

If there are m examples

predicted mx1

actual mx1

"""

"""

Find the square residuals. This is mx1

SUM((predicted\_i - y\_i) ^ 2)

"""

sum\_square\_residuals = np.sum(np.square(actual - predicted))

"""

Find the mean of the actual values

"""

mean\_actual = np.mean(actual)

"""

Find the sum of squares, this is mx1:

SUM((y\_mean - y\_i) ^ 2)

"""

sum\_squares = np.sum(np.square(actual - mean\_actual))

"""

Return the r2 value

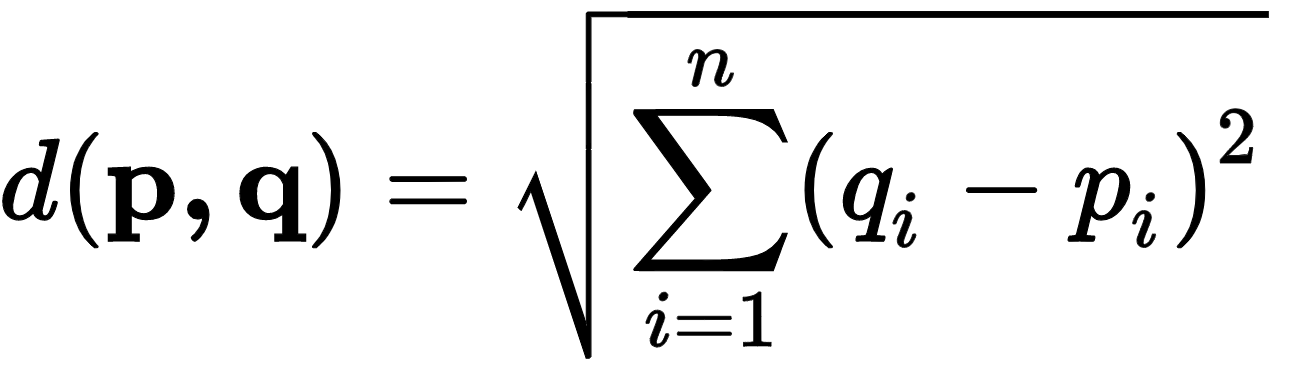
"""

return 1 - (sum\_square\_residuals / sum\_squares)

# Part 1B: Parameters and Techniques for Model Performance

By default, KNN will weigh the contribution of each feature equally when using standard Euclidean distance.

Euclidean distance is given by:



Here, pi and qi are features in the vectors **p, q**. As we can see, here no feature in this metric is given a greater weight than any feature.

Scaling and normalization or standardization must be first performed on each feature so that all the features have values on a similar scale. If that is not done, then one feature might affect the same result too much at the expense of other features – and that might lead to sub-optimal results. One common way to standardize is to ensure that all the features have zero mean and unit standard deviation. Standardization ensures that all the features have a similar range of values. However, standardization does not resolve all problems. This is because:

1. There might be irrelevant features, and those will also be given equal weight, thereby affecting the result.
2. Some features might be correlated, and as such, those features will be counted twice. Again, this might have an effect on the result.
3. Even if all the features are on the same scale, and are all independent of each other, it could just be that some of them are more important than others, and a standard Euclidean distance does not take care of such differences. For example, if age and industry/profession were used to predict the salary of a person, both age and industry/profession may be independent of each other, and may have an effect on the salary, but industry/profession may affect the salary much more than a person’s age. The standard KNN implementation doesn’t not give a higher weightage to a person’s industry/profession after normalization has been performed on it.

With a distance weighted KNN, the above problems still remain the same.

There are several ways to deal with this problem, and they can broadly be categorized as[[1]](#footnote-1) [[2]](#footnote-2):

1. Feature Selection
2. Feature Extraction and/or changing the dimensionality
3. Using a different distance measure (generic)
4. Using different weights for each feature with a custom distance measure. Learning of weights can be employed, and there is a possibility of using a different model to learn the weights.
5. Using different weights for different neighbours

## Feature Selection

In feature selection, one or more features are discarded, and then the KNN is run.

Feature Selection can broadly be categorized into three types:

1. Optimum Methods. This is an exhaustive search where all permutations and combinations of features. However, this quickly becomes intractable as the number of permutations and combinations grows exponentially with the number of features.
2. Heuristic
3. Randomized[[3]](#footnote-3)

The goal of features selection is to do the following:

1. Find uncorrelated features
2. Eliminate irrelevant features

Evaluation of features for feature selection can be grouped into two categories

1. Unsupervised or filter methods  
   In this, training and testing is performed using the training data only. The cross-validation set is never looked at.
2. Supervised or wrapper methods  
   In this method, the features are selected by running over a learning algorithm. Training is done using the training examples, and validation is done over the test data set. A secondary model may be used to predict the best features

Some common methods for feature selection are

1. Forward Search  
   In this method, initially the set of features is empty, and features are added one by one. While adding a feature, all features are evaluated, and the classification error is obtained if the feature is incorporated. The feature that gives the best gain in optimality is chosen. The process is stopped when the improvement in optimality falls below a cutoff.
2. Backward Selection  
   This method begins with all the features in the selected set. Features whose performance that impact the error the smallest adversely are repeatedly removed.
3. Univariate Features Selection  
   In univariate feature selection, each feature is considered independently, and a decision is taken whether to include it for evaluation or not. Common measures used are
   1. Pearson Correlation Coefficient
   2. F-Score
   3. Chi-Square
   4. SNR
   5. Mutual Information

These methods measure correlation between a feature and the target variable.

1. Multivariate Feature Selection

In our case, we implemented forward and backward search, and the model was able to find a set of five features that affect the output the most and produced the best results.

## Feature Extraction

In feature extraction, the current set of features is used to derive a new set of features. This is different from feature selection where features are simply selected, but here, features are combined with each other to form a completely new set of features.

This usually involves projection of a higher dimensional feature space to a lower dimensional feature space. The new features are uncorrelated and cannot be reduced further.

Some common techniques are

1. PCA
2. SVD
3. Fischer Linear Discriminant Analysis
4. PCA with different kernels
   1. Cosine Similarity
   2. Radial Basis Function (RBF)
   3. Polynomial Kernel
   4. Sigmoid Kernel
   5. Laplacian Kernel
   6. Chi-Squared Kernel

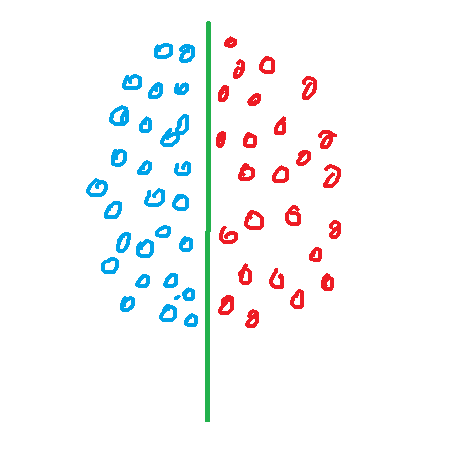
## Principal Component Analysis (PCA)

In PCA, the existing set of features is projected on a new space with fewer dimensions. The axes of the new space are chosen in such a way that it maximizes the variance in the data. Furthermore, the axes are ranked in the order of the most variance (therefore impact), and only the features that contribute most information are chosen.

Apart from the problem with weights of features, PCA is also helpful in dimensionality reduction when there are few samples and a lot of dimensions and helps us mitigate the curse of dimensionality.

PCA was implemented as a step before KNN, however, the results were not encouraging, and the performance was sub-optimal. The results are Presented later.

One problem that PCA runs into is that the new axes chosen in PCA are chosen to maximize variation. However, that might not lead to good class separation. Consider the situation below:



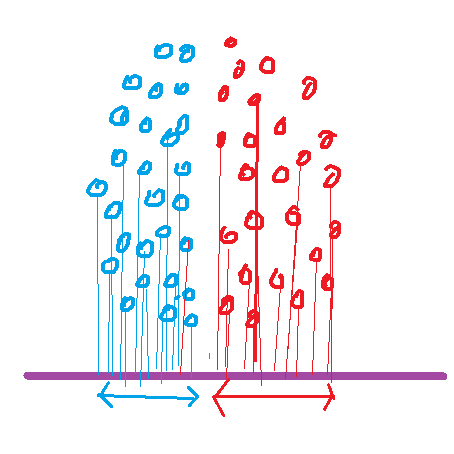
In the diagram above, there are two classes, and the principal axis chosen is shown along the green line. The principal axis is chosen such that the variance in the data is maximized. This does a very good job of describing the data, however, in this case, this principal is not very helpful in helping us categorize the data as both the red and blue categories overlap along the axis.

## Fischer Linear Discriminant Analysis

In Fischer Linear Discriminant Analysis, the new axis are chosen such that:

1. It maximizes inter-class distance
2. Minimizes intra-class distance

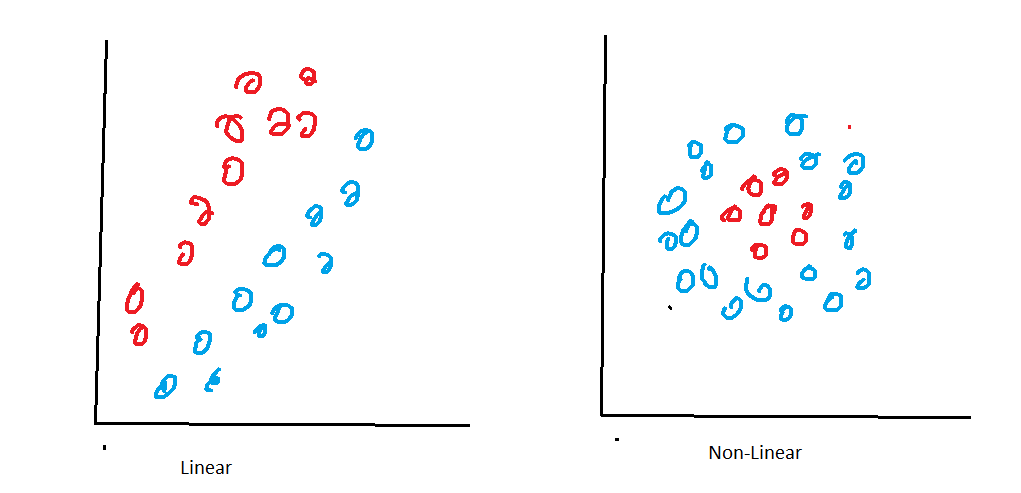
In the previous example, using LDA, the following axis would be chosen, and we will be able to separate the classes easily as they do not overlap over the axis



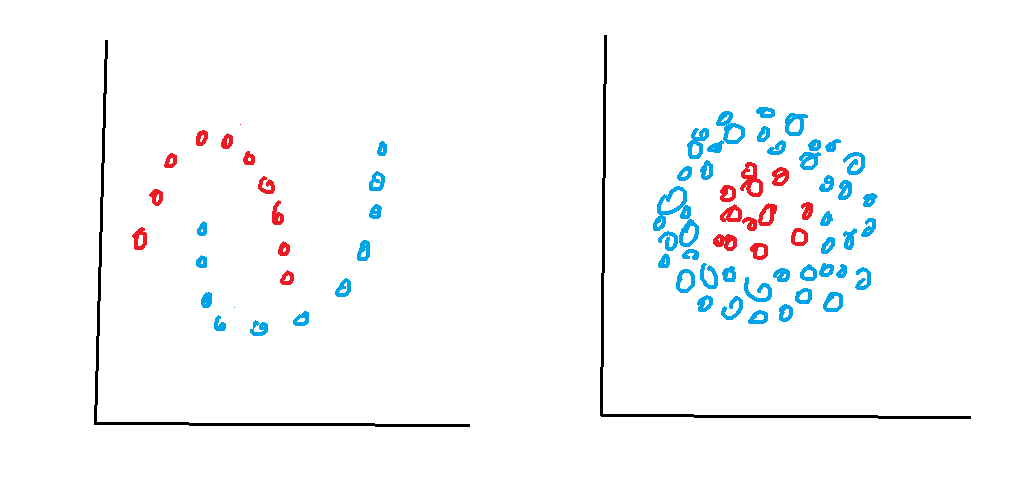
Both PCA and LDA have their uses. PCA does not need class information to work, and can be used to reduce the number of features. LDA needs class information, but can be used to get better class separation.

## PCA with Kernel

Generally, PCA works very well when the data is linearly separable. However, for non-linear separation, PCA does not perform very well. [[4]](#footnote-4)



The RBF Kernel is one such kernel which gives good results for radially separated classes. For example, RBF kernel would give better separation for the following distributions, and regular PCA will give sub-optimal results for these shapes.



## Using a different Distance Metric

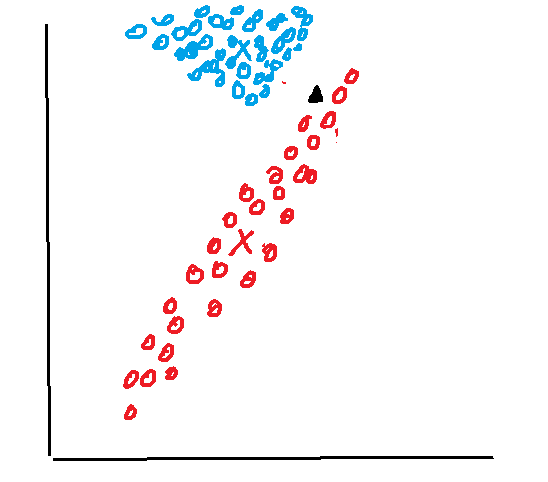
A host of other distance metrics can be used to ameliorate some of the problems with Euclidean distance. Minkowski’s distance is a popular choice, but it also assigns equal weight to all features.

Some other choices for distance functions can be categorized as suitable for[[5]](#footnote-5)

1. Real Valued Vector Spaces – Euclidean, Mahalnobis, Chebyshev, Minkowski etc.
2. Latitude and Longitude form – havershine
3. Integer Valued Vector – Hamming, Canberra, Bray Curtis
4. Boolean – Jaccard, Matching, Dice, Kulinski, Rogers-Tanimoto, Russel-Rao, Sokal-Michener, etc.
5. Strings – Cosine distance is a popular choice

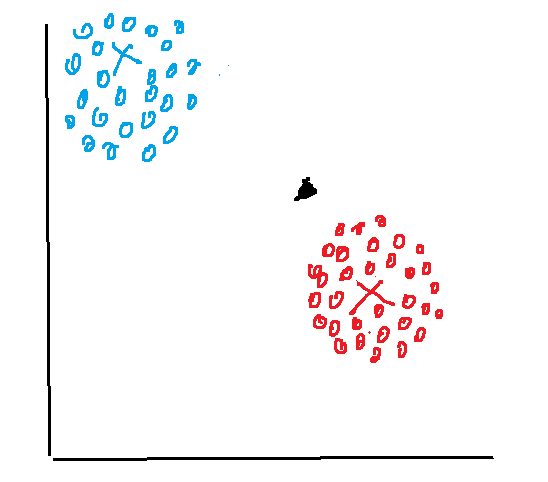
### Mahalnobis Distance

Consider a distribution that looks like this.

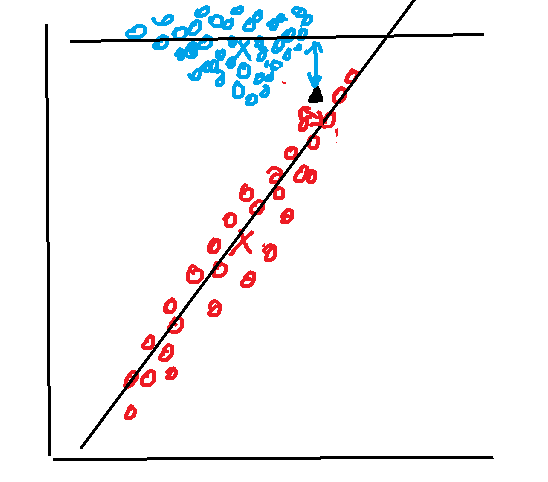


Here there are two classes, red, and blue, and the centroids are marked with ‘x’. If we are to evaluate the point marked by the black triangle, and its distance from the centroid is measured, then it is closer to the blue centroid than the red centroid, and might be categorized as blue. However, the distribution of red items is not a sphere, and elongated.

In general, k-NN works well when the distribution of the classes is spherical like below:



Mahalanobis distance is one which takes care of correlations between the data, and the shapes of the distributions. Mahalanobis distances uses the correlation covariance matrix to calculate the distance from an axis that describes the similarity rather than the Euclidean distance.



Mahalanobis distance measure was implemented and gave slightly better results than standard Euclidean distance. The results are presented later.

1. Sudeshna Sarkar, <https://www.youtube.com/watch?v=KTzXVnRlnw4> [↑](#footnote-ref-1)
2. He et. al., Attribute Value Weighting in K-Modes Clustering, <https://arxiv.org/ftp/cs/papers/0701/0701013.pdf> [↑](#footnote-ref-2)
3. Boutsidis, et.al., Unsupervised Feature Selection for the k-Means Clustering Problem, <https://www.stat.berkeley.edu/~mmahoney/pubs/NIPS09.pdf> [↑](#footnote-ref-3)
4. <http://rasbt.github.io/mlxtend/user_guide/feature_extraction/RBFKernelPCA/> [↑](#footnote-ref-4)
5. <https://scikit-learn.org/stable/modules/generated/sklearn.neighbors.DistanceMetric.html> [↑](#footnote-ref-5)