

Project Report

1. Read the entire paper thoroughly. Understood most of the part and did a dry run of the algorithms that need to be implemented. Code needs to be implemented yet.

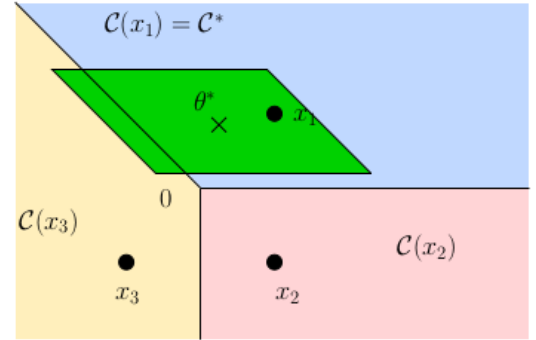
To be implemented in the paper.

1. Illustration of confidence set converging into the cone

Need to write a program that,

1) Compute the confidence set {a set which encapsulates the predicted theta and original theta with a given regret bound} at each phase of the algorithm .

2) And therefore show as a result how the confidence set changes and converges into the cone of the optimal arm.



2. XY - static algorithm.

Min-max optimization problem.

Let f be,

$$x'^T (A + xx^T)^{-1} x'$$

then as shown in the RHS, to implement G-allocation strategy, we need to min-max f. This can be implemented as shown below

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Input: decision space  $\mathcal{X} \in \mathbb{R}^d$ , confidence  $\delta > 0$ 
Set:  $t = 0$ ;  $Y = \{y = (x - x'); x \neq x' \in \mathcal{X}\}$ ;
while Eq. 11 is not true do
  if G-allocation then
     $x_t = \arg \min_{x \in \mathcal{X}} \max_{x' \in \mathcal{X}} x'^T (A + xx^T)^{-1} x'$ 
  else if  $\mathcal{XY}$ -allocation then
     $x_t = \arg \min_{x \in \mathcal{X}} \max_{y \in Y} y^T (A + xx^T)^{-1} y$ 
  end if
  Update  $\hat{\theta}_t = A_t^{-1} b_t$ ,  $t = t + 1$ 
end while
Return arm  $\Pi(\hat{\theta}_t)$ 

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Figure 2: Static allocation algorithms

Let X_1, X_2, X_3 be the arms given.

X_1	<table><tr><td>X_2 => f_12</td></tr><tr><td>X_3 => f_13</td></tr></table>	X_2 => f_12	X_3 => f_13	T1 =Max { f_12, f_13 }	Min { T1, T2, T3 }
X_2 => f_12					
X_3 => f_13					
X_2	<table><tr><td>X_1 => f_21</td></tr><tr><td>X_3 => f_23</td></tr></table>	X_1 => f_21	X_3 => f_23	T1 =Max { f_21, f_23 }	
X_1 => f_21					
X_3 => f_23					
X_3	<table><tr><td>X_1 => f_31</td></tr><tr><td>X_2 => f_32</td></tr></table>	X_1 => f_31	X_2 => f_32	T2 =Max { f_31, f_32 }	
X_1 => f_31					
X_2 => f_32					

3. XY – adaptive algorithm

Let X_hat_j => Set of potentially optimal arms in phase j

Algorithm:

1. In each phase we implement XY iterative algo.
2. The phase length is determined by the uncertainty present in estimating the active directions between successive phases.
3. Once a phase ends then we compute theta_hat using OLS method.
4. We then use the sub-optimal condition to remove the arms from X_hat_j.
5. And loop over the above steps until | X_hat_j | = 1