

HW4B: Stochastic Gradient Descent and Lipschitz Extensions

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I worked with Anthony Rentsch, Lipika Ramaswamy, and Karina Huang on this homework.

My code can be found on my [Github](#)

(https://github.com/bhavenp/cs208/blob/master/homework/HW4b/HW4b_Bhaven_Patel.ipynb).

Problem 1

(a)

$G = \mathbb{R}^n$, $H = [a, b]^n$, $x \sim x'$ differ on one row, $f(x) = \frac{1}{n} \sum_{i=1}^n x_i$

(i)

The global sensitivity $GS_f(x) = \infty$ because we can change any value in the dataset x from to ∞ (or some arbitrarily large number) to get a neighboring dataset x' . Thus, this would change the mean by ∞ .

(ii)

The minimum local sensitivity $\min_{x \in G} LS_f(x) = \infty$ because the best case dataset x would be a one-value dataset/array $x = [x_1]$, where x_1 is any value. The worst case neighboring dataset x' would be a one-value dataset/array $x' = [x'_1]$, where $x'_1 = \infty$ (or some very large number). Thus, the difference between $f(x)$ and $f(x')$ would be infinite like the global sensitivity case.

(iii)

The restricted sensitivity of $RS_f^H = \frac{b-a}{n}$ because in the worst case we have a dataset $x = [a]^n$ and a neighboring dataset $x' = [a, \dots, a, b]$ so the difference between $f(x)$ and $f(x')$ would be $\frac{b-a}{n}$, which is much less than the global sensitivity or the minimum local sensitivity.

Lipschitz extension

A Lipschitz extension of f would be

$$f'(x) = \frac{1}{n} \sum_{i=1}^n [x_i]_a^b$$

where each x_i is clipped to be between a and b .

This obeys the first condition of a Lipschitz extension that $f'(x)$ agrees with $f(x)$ on H because any datasets $x \in H$ are already clipped so the elements x_i are between a and b , so $f'(x) = f(x)$.

$f'(x)$ also obeys the second condition of a Lipschitz extension that $GS_{f'} = RS_{f'}^H$ because the $GS_{f'} = \frac{b-a}{n}$ because all the values in the datasets x and x' will be clipped to be between a and b , so the worst case difference between $f'(x)$ and $f'(x')$ is $\frac{b-a}{n}$. $RS_{f'}^H = \frac{b-a}{n}$ too because $x \in H$ means all the values in the dataset x will be clipped to be between a and b , so the worst case difference between $f'(x)$ and $f'(x')$, where $x, x' \in H$, is also $\frac{b-a}{n}$.

Thus, $f'(x)$ is a Lipschitz extension of f .

(b)

$G = \mathbb{R}^n$, $H = [a, b]^n$, $x \sim x'$ differ on one row, $f(x) = \text{median}(x_1, \dots, x_n)$

(i)

The global sensitivity $GS_f(x) = \infty$ because say the dataset x is composed of 0s and ∞ s (or some arbitrarily large numbers), where there is 1 more 0 than ∞ so $f(x) = 0$. In the worst case, a neighboring dataset x' would have one of the 0s changed to an ∞ , so $f(x') = \infty$. Thus, the median has changed by ∞ , so $GS_f(x) = \infty$.

(ii)

The minimum local sensitivity $\min_{x \in G} LS_f(x) = \infty$ because the best case dataset x would be a one-row dataset $x = [0]$, so $f(x) = 0$. The worst case neighboring dataset x' would be dataset $x' = [\infty]$, and $f(x') = \infty$. Thus, the difference between $f(x)$ and $f(x')$ would be ∞ .

(iii)

The restricted sensitivity of $RS_f^H = b - a$ because in the worst case we have a dataset x composed of a s and b s, where there is 1 more a than b so $f(x) = a$. In the worst case, a neighboring dataset x' would have one of the a s changed to a b , so $f(x') = b$. Thus, the median has changed by $b - a$, so $RS_f^H = b - a$.

(c)

G = the set of undirected graphs,

H = the set of graphs in G in which every vertex has degree at most d , $2 \leq d \leq n - 1$,

$x \sim x'$ differ on one node/vertex, $f(x) = \#$ of isolated vertices

(i)

The global sensitivity $GS_f(x) = n$, where n is the number of nodes/vertices in graph x . In the worst case, the graph $x \in G$ can be composed of n isolated vertices, $f(x) = n$. A neighboring

graph x' is the same as x except for an additional vertex that shares an edge with every other node, making $f(x') = 0$. Thus, difference between $f(x)$ and $f(x')$ is at maximum n .

(ii)

The minimum local sensitivity $\min_{x \in G} LS_f(x) = 1$ because the best case graph x would have 0 isolated vertices, so $f(x) = 0$. The worst case neighboring graph x' would be x plus an isolated vertex, so $f(x') = 1$. Thus, difference between $f(x)$ and $f(x')$ is at maximum 1, which is the same for the global sensitivity.

(iii)

The restricted sensitivity of $RS_f^H = d$ because in the worst case, a graph $x \in H$ consists of n vertices where all the vertices are unconnected. For the graph x , $f(x) = n$. Then, we could have a neighboring graph x' in which the single vertex with d edges is added to x . Thus, $f(x') = n - d$, so the difference between $f(x)$ and $f(x')$ is d .

Problem 2

Local model for DP-SGD

Below is my implementation of the local model for DP-SGD. I changed it from the centralized model for DP-SGD because for every subject i in my batch S_t , I compute a noisy gradient for the current θ s/parameters by calculating the actual gradient and then adding noise sampled from the Gaussian distribution $N(0, \tau^2 I)$, where

$$\tau = \left(\frac{C}{\epsilon_0/2} \right) \cdot \sqrt{T \cdot \frac{L}{n} \cdot \log\left(\frac{1}{\delta}\right)}$$

C is the clipping parameter. ϵ_0 is our total privacy-loss parameter specified by the user; we divide it by two because we are releasing two θ s/parameters. δ is our also our user-specified parameter for (ϵ, δ) -DP. T is the number of steps, L is the batch size, and n is the number of training points.

```

In [1]: ## Here is the likelihood function for a Logit. 'b' is array of betas
        calcllik<-function(b,data){
          y<-data[,1]
          x<-data[,2]

          pi<- 1/(1+exp(-b[1] - b[2]*x)) # Here is the systematic component
          if(pi == 1.0){ #probability of 1.0 causes NaNs, so change to 0.99999
            pi <- 0.99999;
          }
          if(pi == 0.0){ #probability of 0.0 causes NaNs and infinities, so change to 0.00001
            pi <- 0.00001;
          }

          llik <- y * log(pi) + (1-y) * log(1-pi) # Here is the stochastic component

          return(-llik)
        }

        ## Bound/Censor/Clip a variable to a range
        clip <- function(x, lower, upper){
          x.clipped <- x
          x.clipped[x.clipped<lower] <- lower
          x.clipped[x.clipped>upper] <- upper
          return(x.clipped)
        }

```

```

In [2]: #load the Massachusetts PUMS data
        library("foreign");
        PUMSdata <- read.csv(file="https://raw.githubusercontent.com/privacytoolspr/privacytoolspr/master/data/mass_pums.csv");

        marg_educ_data <- PUMSdata[c("married","educ")]; #get married and education data

        #predict are you married {0,1} based on education
        output <- glm(married ~ educ, family="binomial", data=marg_educ_data)

```

```
In [3]: # Calculate the gradient at a point in the parameter space
calcgradient_localRelease <- function(row, C, thetas, fun, noise_sigma){
  dx <- 0.0001
  #using numerical approximation of gradient for each theta. Assuming two
  out1 <- eval(fun(b=tetas, data=row))
  out2 <- eval(fun(b=tetas + c(0,dx), data=row))
  out3 <- eval(fun(b=tetas + c(dx,0), data=row))

  #calculate clipped gradient for theta1
  theta1_grad <- (out3 - out1) / dx;
  theta1_grad <- clip(theta1_grad, lower=-C, upper=C);

  #calculate clipped gradient for theta2
  theta2_grad <- (out2 - out1) / dx;
  theta2_grad <- clip(theta2_grad, lower=-C, upper=C);

  #add Gaussian noise to gradients
  thetas_grad <- c(theta1_grad, theta2_grad) + rnorm(n=length(tetas), me

  return(thetas_grad);
}
```

```

In [4]: # ##function to perform local model for SGD
# ##
# ## data: 2-column dataframe where first
# ## N: number of training data points
# ## batch_size: number of training points to be considered in each step
# ## steps: number of iterations to perform local SGD for
# ## C: clipping parameter for gradient
# ## epsilon: privacy-loss parameter
# ## delta: privacy-loss parameter
localSGD <- function(data, N, batch_size, steps, C, epsilon, delta=1e-6){

  thetas <- c(0,0) # Starting parameters
  nu <- c(0.05, 0.01); #c(1,0.01) # Learning speeds for each theta
  history <- matrix(NA, nrow=steps+1, ncol=2);
  history[1,] <- thetas;

  # Iterate one step of SGD
  for(i in 1:steps){

    #Generate our batch for this step
    startB <- ((i-1)*batch_size+1) #beginning index for our batch
    if(i<batch_size){#get end index for our batch
      stopB <- i*batch_size;
    }else{
      stopB <- nrow(data)
    }
    B <- data[startB:stopB, ]; #get rows for this batch

    #calculate gradient separately for each point
    tot_gradient <- c(0,0);
    sigma = C / (epsilon/2) * sqrt( steps*batch_size/N * log(1/delta) )

    for(b in 1:nrow(B)){
      single_row <- B[b, ]; #get row from the data
      #calculate the gradient for this data point
      # 'C' is the clipping parameter. 'thetas' are our parameters to
      # 'noise_sigma' is the standard deviation for the normal with w
      grad_i <- calcgradient_localRelease(single_row, C, thetas, fun=
      tot_gradient <- tot_gradient + grad_i;
    }

    ave_gradient <- tot_gradient / batch_size;
    # cat("Del: ",Del,"\n")
    thetas <- thetas - (nu * ave_gradient); #theta^(l+1) = theta^(l)
    # cat("Theta:",theta, "\n")

    history[i+1,] <- thetas;
  }

  return(history);
}

```

```

In [10]: N <- nrow(marg_educ_data);
L <- round(sqrt(N));      # This is the recommended batch size- sqrt(# of tr
# set.seed(24);
steps <- L; #number of iterations for SGD is same as the number of batches

## Shuffle the data
index <- sample(1:nrow(marg_educ_data), replace=FALSE); #shuffle because we
marg_educ_data <- marg_educ_data[index,];
epsilon = 0.1;
delta = 1e-6;
C <- 10;                # Interval to clip over

history <- localSGD(data=marg_educ_data, N=N, batch_size=L, steps=steps, C=
epsilon=epsilon, delta=1e-6);

```

history

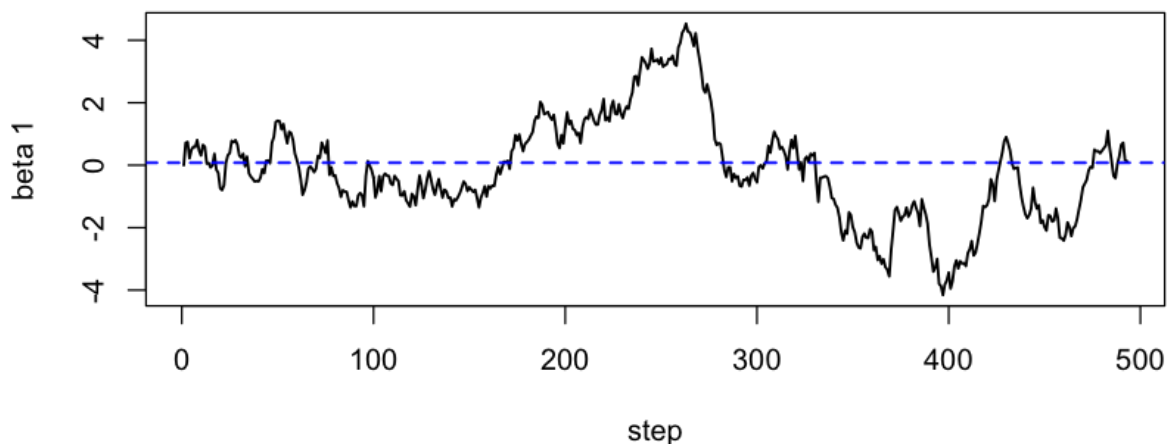
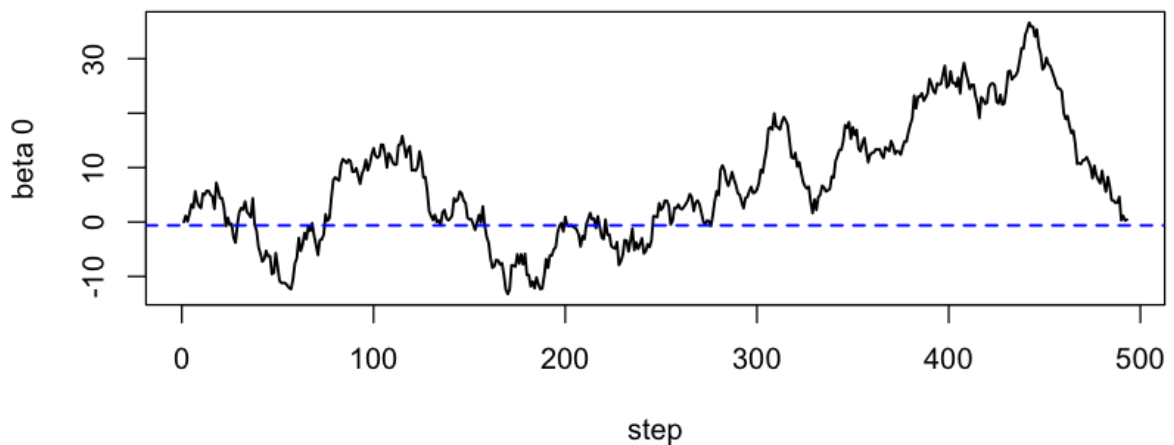
0.00000000	0.000000000
1.14315834	0.714910003
0.09071891	0.745191032
1.53889885	0.224617753
3.24127378	0.492825849
2.62331115	0.591141451
5.64571983	0.580655562
3.75142509	0.804210150
2.89119127	0.472479052
2.56410473	0.311100252
5.23543482	0.650424595
5.00780169	0.590312072
5.74613548	0.052310917

```
In [11]: par(mfcol=c(2,1))

all.ylim<-c( min(c(history[,1],output$coef[1] )), max(c(history[,1],output$
plot(history[,1], type="l", ylim=all.ylim, ylab="beta 0", xlab="step", lwd=
abline(h=output$coef[1], lty=2, col="blue", lwd=1.5)

all.ylim<-c( min(c(history[,2],output$coef[2] )), max(c(history[,2],output$
plot(history[,2], type="l", ylim=all.ylim, ylab="beta 1", xlab="step", lwd=
abline(h=output$coef[2], lty=2, col="blue", lwd=1.5)

# dev.copy2pdf(file="./dpSGD.pdf")
```



As the plots above show, my `localSGD` function provides a DP-release of θ_0 and θ_1 that are close to true, non-DP θ values when I use an $\epsilon = 1$. We observe much more jitteriness in the values of the θ s because we are adding much more noise in the local model. I tuned my learning rate parameters until I got good results using an $\epsilon = 1$.

Evaluate performance of the local model of DP-SGD

Below, I evaluate the performance of the local model of DP-SGD by performing DP-releases for θ_0 and θ_1 for ϵ s in ranging from 0.1 to 10. For each ϵ , I perform 5 DP-releases, so that I can calculate a range of classification errors for each ϵ and calculate the RMSE of the DP-released parameters compared to the non-DP released parameters.

```
In [3]: #function to calculate the classification error given the data and thetas f
calc_classf_error <- function(data, thetas){
  preds <- 1 / (1+ exp(-thetas[1] - thetas[2] * data[,2])) ); #perform lin
  preds[preds >= 0.5] <- 1; #convert probabilities >= 0.5 to 1s
  preds[preds < 0.5] <- 0; #convert probabilities < 0.5 to 0s
  #   cat(sum(preds))

  y_true = data[[1]]; #get the true classifications
  comparison <- (preds == y_true); #compare the predictions to true label
  error <- 1 - mean(comparison); #mean of comparison vector is accuracy.
  return(error);
}
```

```

In [13]: ### SET-UP PARAMETERS
eps_vals <- c(0.1, 0.25, 0.5, 0.75, 1.0, 2.0, 5.0, 10.0);
num_sims <- 5;
N <- nrow(marg_educ_data);
L <- round(sqrt(N)); # This is the recommended batch size- sqrt(# of tr
steps <- L; #number of iterations for SGD is same as the number of batches
delta = 1e-6;
C <- 10; # Interval to clip over

#shuffle because we worry the data may have been sorted in some way
index <- sample(1:nrow(marg_educ_data), replace=FALSE);
marg_educ_data <- marg_educ_data[index,];

thetas_history <- matrix(0, nrow=length(eps_vals)*num_sims, ncol=4);

row = 1;
for(eps in eps_vals){
  #printing for diagnostic purposes
  cat("Beginning simulations for epsilon= ", eps, '\n');
  cat(format(Sys.time(), "%a %b %d %X %Y"), '\n')

  for(l in 1:num_sims){
    #get a DP release of the thetas for the given epsilon
    history <- localSGD(data=marg_educ_data, N=N, batch_size=L, steps=s
    dp_thetas <- history[L+1, ];
    #calculate classificaiton error for this DP-release of thetas
    clsf_error <- calc_classf_error(data = marg_educ_data, thetas=dp_th
    #save the thetas and classification error
    thetas_history[row, ] <- c(eps, dp_thetas, clsf_error);
    row <- row + 1;
  }
}

```

```

Beginning simulations for epsilon= 0.1
Sun Apr 28 18:36:08 2019
Beginning simulations for epsilon= 0.25
Sun Apr 28 18:38:53 2019
Beginning simulations for epsilon= 0.5
Sun Apr 28 18:41:40 2019
Beginning simulations for epsilon= 0.75
Sun Apr 28 18:44:26 2019
Beginning simulations for epsilon= 1
Sun Apr 28 18:47:12 2019
Beginning simulations for epsilon= 2
Sun Apr 28 18:49:56 2019
Beginning simulations for epsilon= 5
Sun Apr 28 18:52:37 2019
Beginning simulations for epsilon= 10
Sun Apr 28 18:55:21 2019

```

```
In [14]: #create dataframe from history matrix
thetas_history_df <- as.data.frame(thetas_history);
colnames(thetas_history_df) <- c("Epsilon", "Theta0", "Theta1", "Classification_Error")
#save the dataframe to analyze later
write.csv(thetas_history_df, './theta_vals.csv')
```

Below, I load the DP-releases of the theta values for different values of ϵ .

```
In [1]: thetas_history_df <- read.csv("./theta_vals.csv");
thetas_history_df
```

X	Epsilon	Theta0	Theta1	Classification_Error
1	0.10	-1.478539e+01	5.933797e+00	0.4513088
2	0.10	1.164043e+01	1.309560e+00	0.4527602
3	0.10	7.005811e-01	-2.380979e+00	0.5472398
4	0.10	-5.554668e+01	5.776009e+00	0.4538601
5	0.10	6.548709e+00	3.789757e-01	0.4527602
6	0.25	3.355382e+00	-1.911276e-01	0.4527602
7	0.25	-1.403541e+01	2.121839e+00	0.4473639
8	0.25	3.470551e+00	-2.720917e-01	0.5309515
9	0.25	-9.081222e+00	8.912470e-01	0.4562833
10	0.25	3.437159e+00	-2.501663e-01	0.4957946
11	0.50	-5.764790e-01	1.327062e-02	0.5472398
12	0.50	1.322441e+01	-1.041727e+00	0.5309515

Calculate the true values for β_0 and β_1 . Also calculate the classification error for these values.

```
In [4]: #get actual beta0 and beta1
PUMSdata <- read.csv(file="https://raw.githubusercontent.com/privacytoolspr
marg_educ_data <- PUMSdata[c("married","educ")]; #get married and education

#predict are you married {0,1} based on education
output <- glm(married ~ educ, family="binomial", data=marg_educ_data);

#calculate classification error for non-DP thetas
nondp_error <- calc_classf_error(data = marg_educ_data, thetas=output$coefficients)
nondp_error
```

0.440280362237936

```

In [5]: #function to calculate the RMSE of DP-released thetas compared to true thetas
calc_rmse <- function(theta_preds, true_theta){
  square_sum <- sum( (theta_preds - true_theta)^2 );
  rmse <- sqrt(square_sum);
  return(rmse);
}

#calculate RMSE values for thetas
unq_eps <- unique(thetas_history_df$Epsilon); #get unique epsilon values
rmse_matrix <- matrix(data = 0, nrow = length(unq_eps), ncol = 3);

row_counter = 1;
for(eps in unq_eps){
  eps_thetas <- thetas_history_df[thetas_history_df$Epsilon == eps, ];
  eps_thetas[, 'Theta0']
  theta0_rmse <- calc_rmse(theta_preds = eps_thetas[, 'Theta0'],
                           true_theta = output$coefficients[1]);
  theta1_rmse <- calc_rmse(theta_preds = eps_thetas[, 'Theta1'],
                           true_theta = output$coefficients[2]);

  rmse_matrix[row_counter, ] <- c(eps, theta0_rmse, theta1_rmse);
  row_counter = row_counter + 1;
}

rmse_matrix_df <- as.data.frame(rmse_matrix);
colnames(rmse_matrix_df) <- c("Epsilon", "Theta0_RMSE", "Theta1_RMSE");
rmse_matrix_df

```

Epsilon	Theta0_RMSE	Theta1_RMSE
0.10	58.4897664	8.62586692
0.25	17.3367477	2.26721362
0.50	17.3861059	1.52739047
0.75	5.2143182	0.62752650
1.00	9.2045759	0.87378240
2.00	5.6627062	0.49357280
5.00	2.1886716	0.19687928
10.00	0.8359723	0.07511608

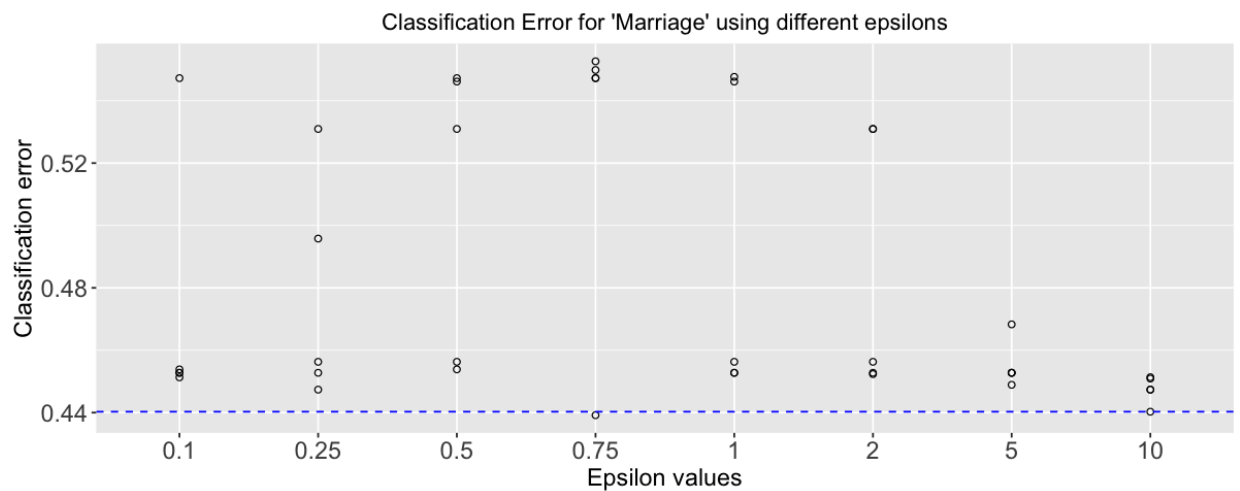
```

In [8]: library(ggplot2)
# plot classification errors for different epsilon values
x_vals <- factor(thetas_history_df$Epsilon);
p1 <- ggplot(thetas_history_df) +
  geom_point(aes(x=x_vals, y=thetas_history_df$Classification_Error), sha
  geom_hline(yintercept=nondp_error, linetype="dashed", color = "blue");

p1 <- p1 + labs(x = "Epsilon values", y = 'Classification error', title =
  'Classification Error for \'Marriage\' using different epsilons') +
  theme(plot.title = element_text(hjust = 0.5),
        axis.text = element_text(size=14), axis.title = element_text(size

options(repr.plot.width=10, repr.plot.height=4); #set plot dimensions
p1 #show plot

```

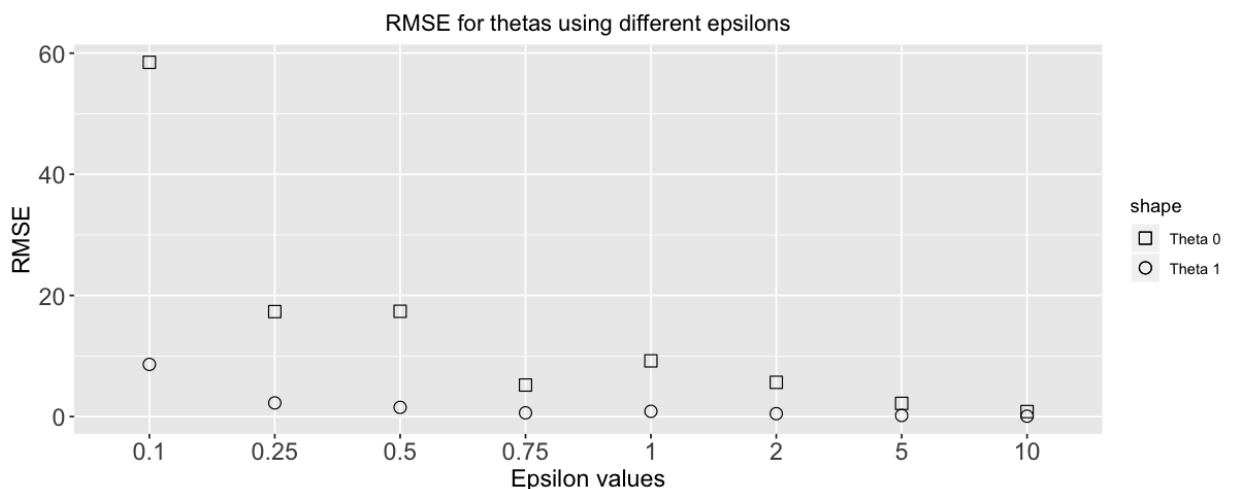


The dashed blue line represents the classification error of the non-DP released θ_0 and θ_1 when used to predict "Marriage" based on "Education".

```
In [7]: library(ggplot2)
# plot classification errors for different epsilon values
x_vals <- factor(rmse_matrix_df$Epsilon);
p1 <- ggplot(rmse_matrix_df) +
  geom_point(aes(x=x_vals, y=rmse_matrix_df$Theta0_RMSE, shape='Theta 0')) +
  geom_point(aes(x=x_vals, y=rmse_matrix_df$Theta1_RMSE, shape='Theta 1'))

p1 <- p1 + scale_shape_manual(values = c("Theta 0"=0, "Theta 1"=1));

p1 <- p1 + labs(x = "Epsilon values", y = 'RMSE', title =
  'RMSE for thetas using different epsilons') +
  theme(plot.title = element_text(hjust = 0.5),
    axis.text = element_text(size=14), axis.title = element_text(size=
options(repr.plot.width=10, repr.plot.height=4); #set plot dimensions
p1 #show plot
```



The first graph shows the relationship between ϵ and classification error rate. For the most part, lower values of ϵ lead to higher classification error rate, as can be seen with $\epsilon = 0.25, 0.5$, and 0.75 . Unexpectedly, the classification error for $\epsilon = 0.1$ is near the true classification error rate for most of the 5 trials, which could be due to the low number of simulations (5) run or possibly the regularization effect of performing a differentially-private release of the θ s; the noise added at $\epsilon = 0.1$ may help the model better predict on points that the non-DP model misclassifies. When $\epsilon > 1$, the classification error for most trials shrinks toward the classification error observed with the non-DP θ s (blue line), which is expected because we add less noise to the gradients with greater values of ϵ .

The second graph displays the RMSE between the DP-released θ s for a given value of ϵ and the non-DP released θ s. Overall, as ϵ increases, we observe that the RMSE of the θ s decreases, and at $\epsilon = 10$, the RMSEs are almost 0. Although the classification error rate for $\epsilon = 0.1$ was closer to baseline, the RMSE for the θ s is the highest for $\epsilon = 0.1$, which is expected because an $\epsilon = 0.1$ causes a larger standard deviation for the Normal distribution from which we draw noise. As stated above, the noisier θ s must be better at classifying some of the points that are misclassified as the θ es approach the non-DP θ s. For all values of ϵ , θ_1 has a lower RMSE than θ_0 , which might be due to the larger learning rate for θ_1 , causing it to jump around much more with each update to it.

