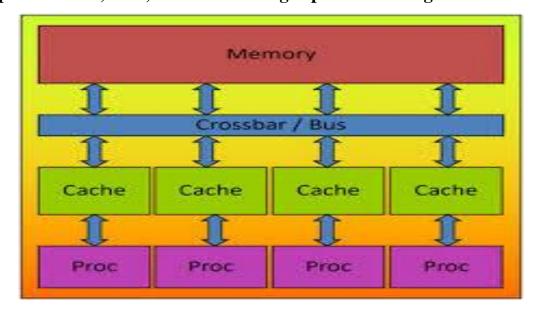
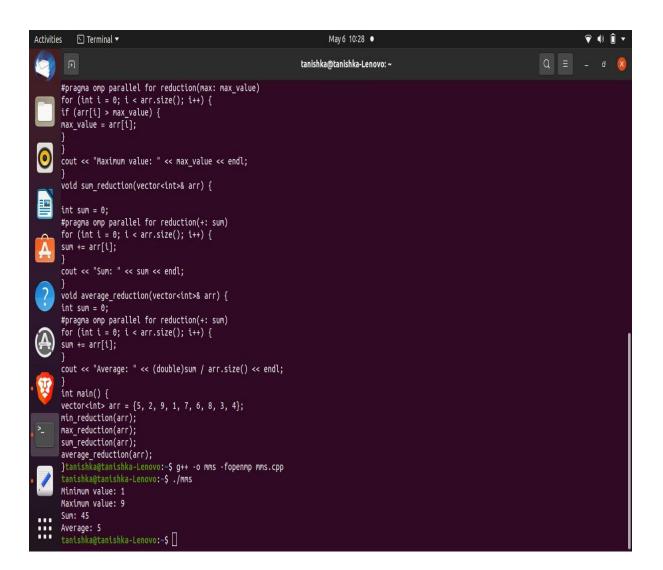
Aim: Implement Min, Max, Sum and Average operations using Parallel Reduction

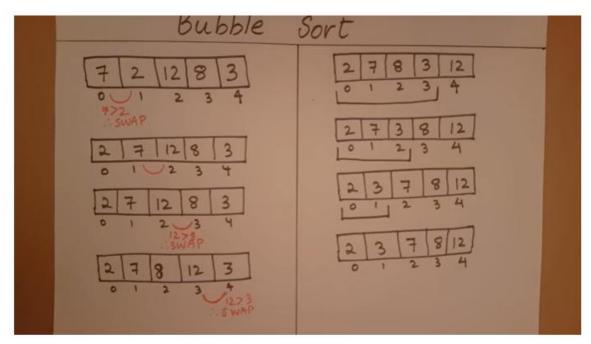


```
#include <iostream>
#include <vector>
#include <omp.h>
#include <climits>
using namespace std;
void min_reduction(vector<int>& arr) {
int min_value = INT_MAX;
#pragma omp parallel for reduction(min: min_value)
for (int i = 0; i < arr.size(); i++) {
if (arr[i] < min_value) {</pre>
min_value = arr[i];
cout << "Minimum value: " << min_value << endl;</pre>
void max_reduction(vector<int>& arr) {
int max_value = INT_MIN;
#pragma omp parallel for reduction(max: max_value)
for (int i = 0; i < arr.size(); i++) {
if (arr[i] > max_value) {
max_value = arr[i];
```

```
}
cout << "Maximum value: " << max_value << endl;</pre>
void sum_reduction(vector<int>& arr) {
int sum = 0;
#pragma omp parallel for reduction(+: sum)
for (int i = 0; i < arr.size(); i++) {
sum += arr[i];
cout << "Sum: " << sum << endl;
void average_reduction(vector<int>& arr) {
int sum = 0;
#pragma omp parallel for reduction(+: sum)
for (int i = 0; i < arr.size(); i++) {
sum += arr[i];
cout << "Average: " << (double)sum / arr.size() << endl;</pre>
int main() {
vector<int> arr = \{5, 2, 9, 1, 7, 6, 8, 3, 4\};
min_reduction(arr);
max_reduction(arr);
sum_reduction(arr);
average_reduction(arr);
}
```



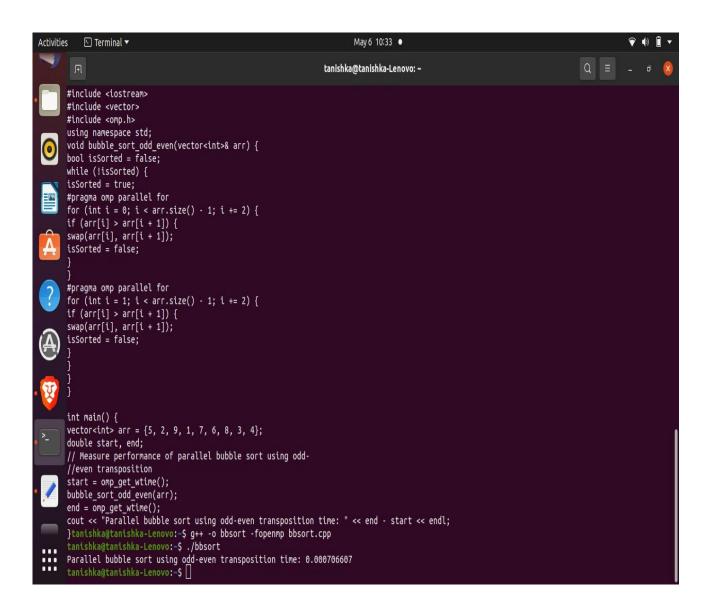
Aim: Write a program to implement Parallel Bubble Sort and Merge sort using OpenMP. Use existing algorithms and measure the performance of sequential and parallel algorithms.



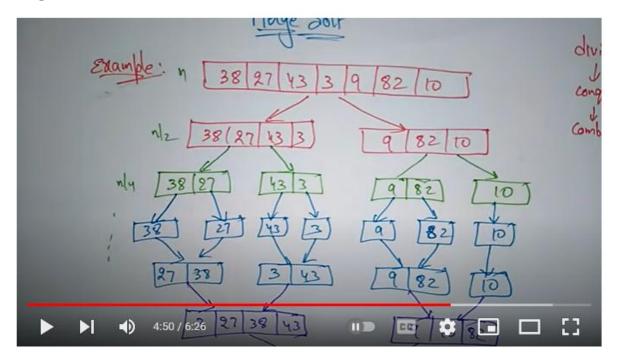
Bubble Sort Code-

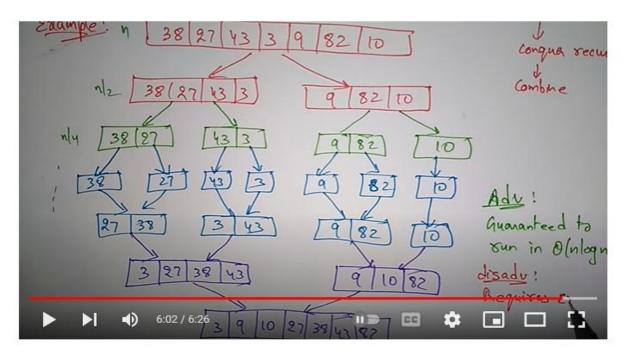
```
#include <iostream>
#include <vector>
#include <omp.h>
using namespace std;
void bubble_sort_odd_even(vector<int>& arr) {
bool isSorted = false;
while (!isSorted) {
isSorted = true;
#pragma omp parallel for
for (int i = 0; i < arr.size() - 1; i += 2) {
if (arr[i] > arr[i + 1]) {
swap(arr[i], arr[i + 1]);
isSorted = false;
}
}
#pragma omp parallel for
```

```
for (int i=1; i < arr.size() - 1; i + = 2) {
    if (arr[i] > arr[i + 1]) {
        swap(arr[i], arr[i + 1]);
        isSorted = false;
    } } } } int main() {
        vector<int> arr = {5, 2, 9, 1, 7, 6, 8, 3, 4};
        double start, end;
    // Measure performance of parallel bubble sort using odd-
    //even transposition
        start = omp_get_wtime();
        bubble_sort_odd_even(arr);
        end = omp_get_wtime();
        cout << "Parallel bubble sort using odd-even transposition time: " << end - start << endl;
    }
```



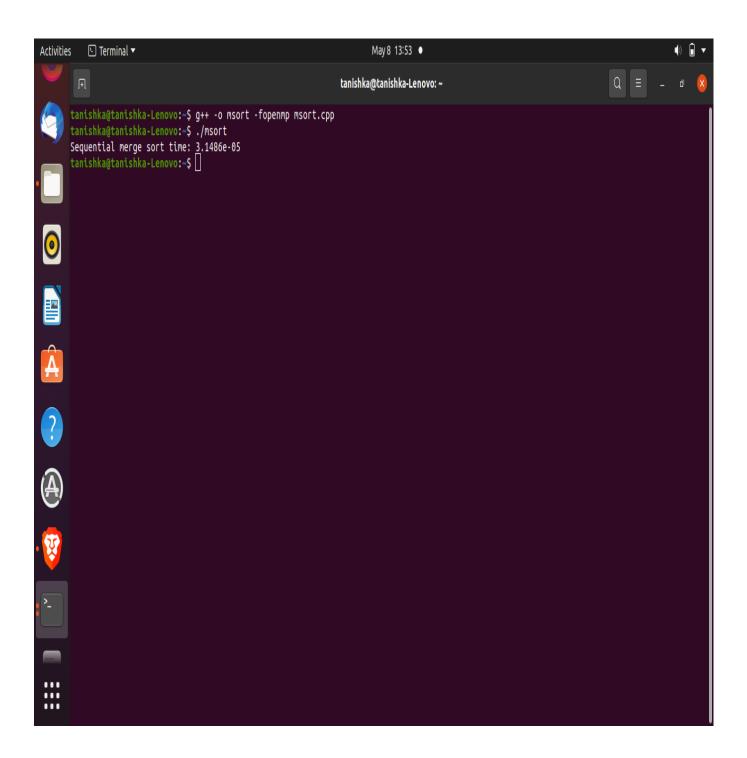
Merge Sort





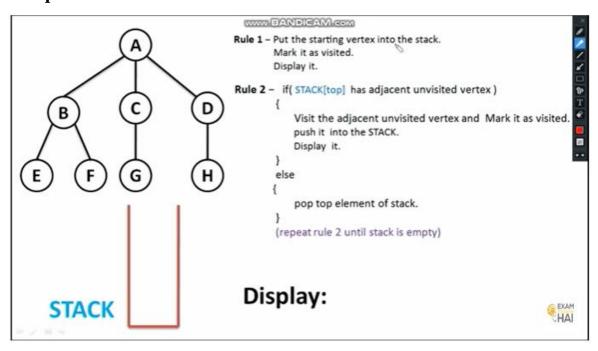
```
#include <iostream>
#include <vector>
#include <omp.h>
using namespace std;
void merge(vector<int>& arr, int l, int m, int r) {
     int i, j, k;
     int n1 = m - 1 + 1;
     int n2 = r - m;
     vector<int> L(n1), R(n2);
     for (i = 0; i < n1; i++) {
          L[i] = arr[1 + i];
     }
     for (j = 0; j < n2; j++) {
          R[j] = arr[m + 1 + j];
     }
     i = 0;
     j = 0;
     k = 1;
     while (i < n1 \&\& j < n2) {
          if (L[i] <= R[j]) {
               arr[k++] = L[i++];
          } else {
               arr[k++] = R[j++];
          }
     }
}
void merge_sort(vector<int>& arr, int l, int r) {
     if (1 < r) {
          int m = 1 + (r - 1) / 2;
#pragma omp task
          merge_sort(arr, 1, m);
#pragma omp task
          merge\_sort(arr, m + 1, r);
          merge(arr, l, m, r);
```

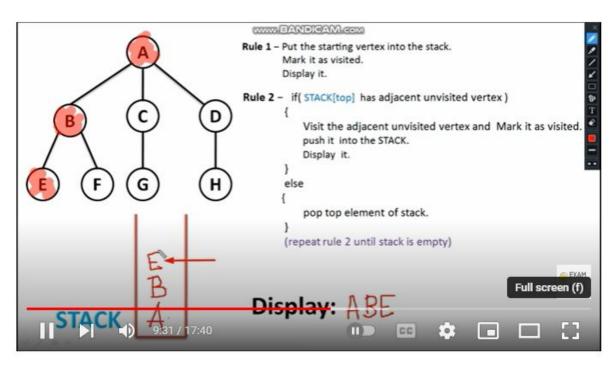
```
}
}
void parallel_merge_sort(vector<int>& arr) {
#pragma omp parallel
     {
#pragma omp single
          merge_sort(arr, 0, arr.size() - 1);
     }
}
int main() {
     vector<int> arr = \{5, 2, 9, 1, 7, 6, 8, 3, 4\};
     double start, end;
     // Measure performance of sequential merge sort
     start = omp_get_wtime();
     merge_sort(arr, 0, arr.size() - 1);
     end = omp_get_wtime();
     cout << "Sequential merge sort time: " << end - start <<endl;</pre>
     // Measure performance of parallel merge sort
     arr = \{5, 2, 9, 1, 7, 6, 8, 3, 4\};
     start = omp_get_wtime();
     parallel_merge_sort(arr);
     end = omp_get_wtime();
     return 0;
     }
```

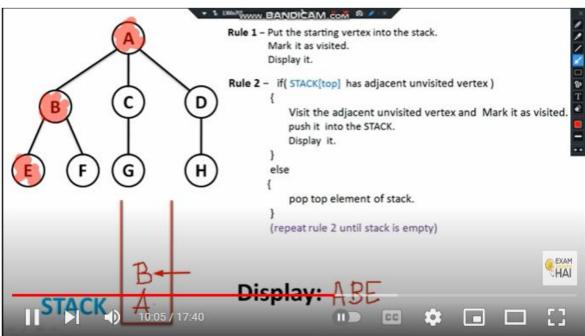


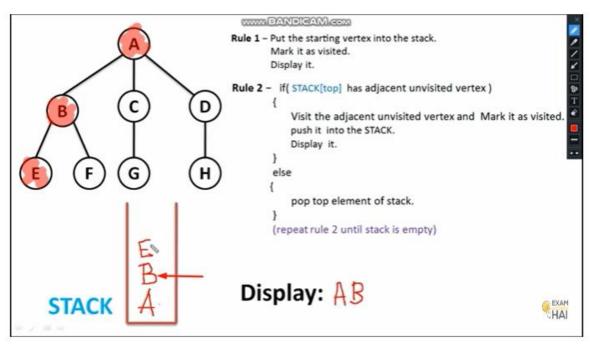
Aim: Design and implement Parallel Breadth First Search and Depth First Search based on existing algorithms using OpenMP. Use a Tree or an undirected graph for BFS and DFS.

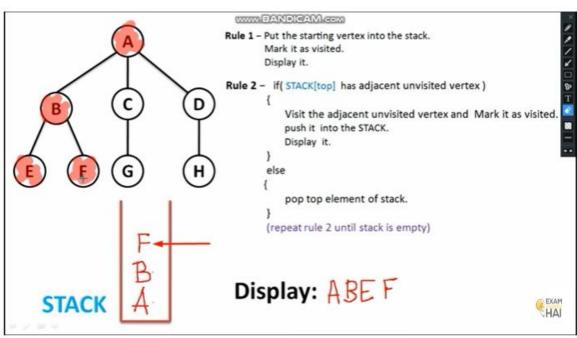
DFS Concept -

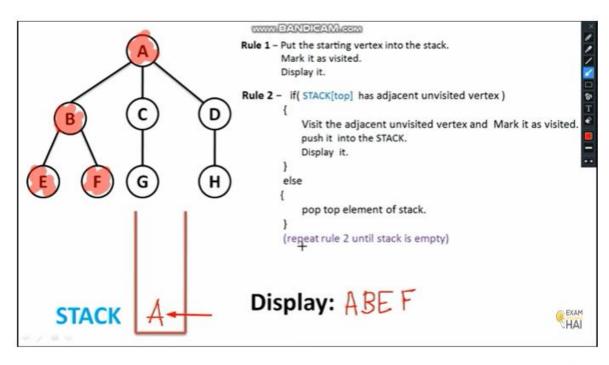


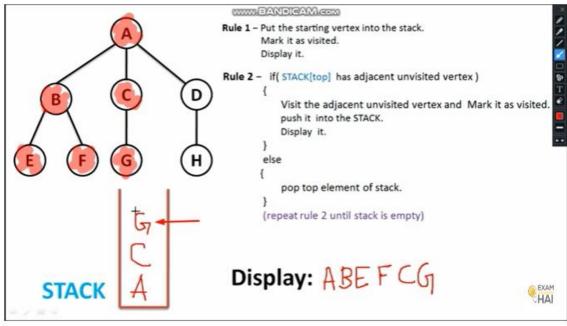


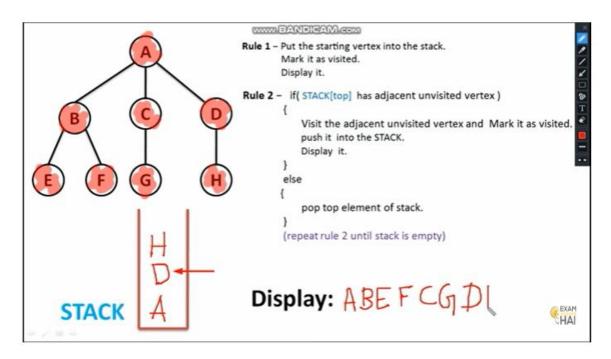


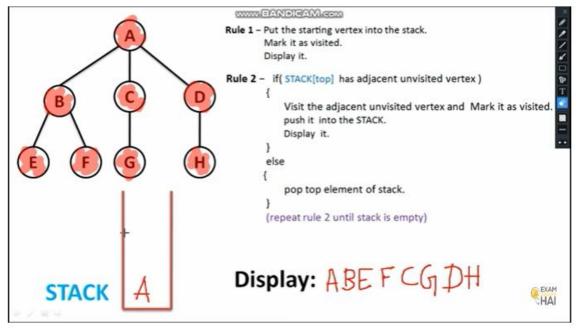


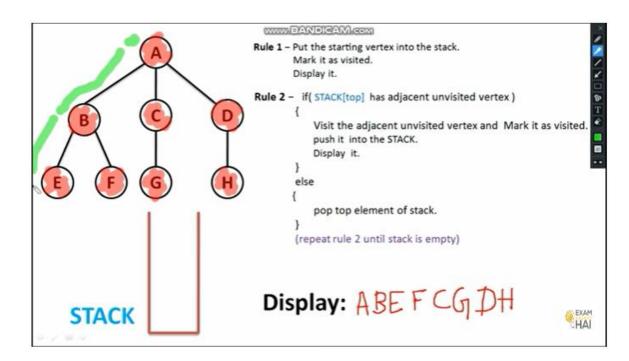












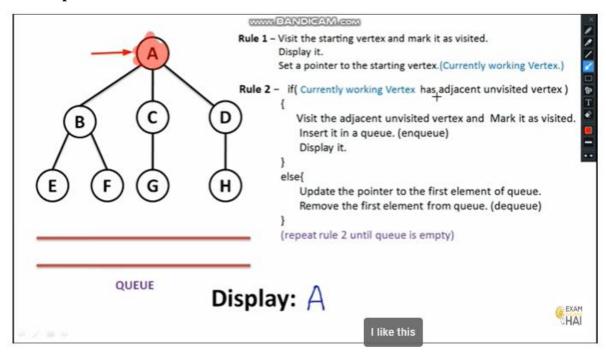
DFS Code-

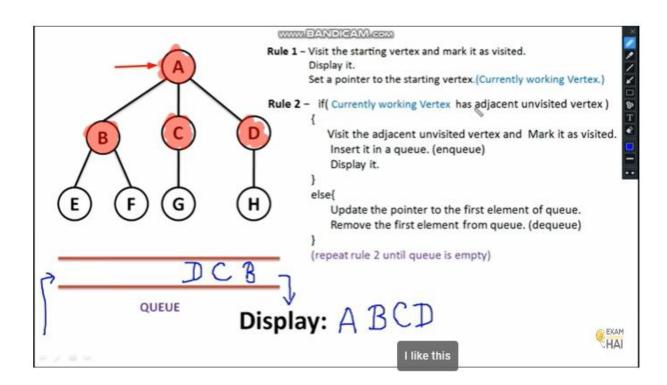
```
#include <iostream>
#include <vector>
#include <omp.h>
using namespace std;
const int MAXN = 1e5;
vector<int> adj[MAXN+5]; // adjacency list
bool visited[MAXN+5]; // mark visited nodes
void dfs(int node) {
  visited[node] = true;
  #pragma omp parallel for
  for (int i = 0; i < adj[node].size(); i++) {
     int next_node = adj[node][i];
    if (!visited[next_node]) {
       dfs(next_node);
     }
int main() {
  cout << "Please enter nodes and edges";</pre>
  int n, m; // number of nodes and edges
  cin >> n >> m;
```

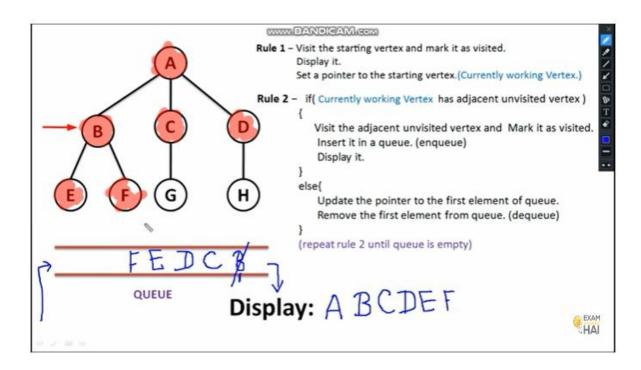
```
for (int i = 1; i \le m; i++) {
  int u, v; // edge between u and v
  cin >> u >> v;
  adj[u].push_back(v);
  adj[v].push_back(u);
}
int start_node; // start node of DFS
cin >> start_node;
dfs(start_node);
// Print visited nodes
for (int i = 1; i \le n; i++) {
  if (visited[i]) {
     cout << i << " ";
  }
cout << endl;</pre>
return 0;
```

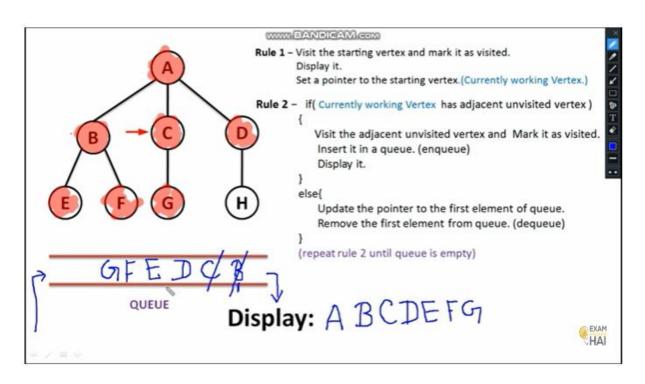
}

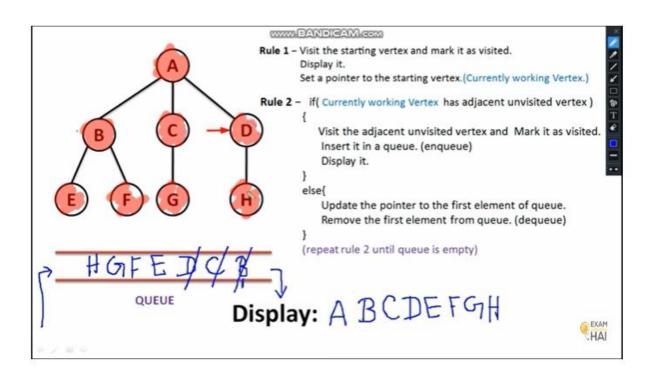
BFS Concept:

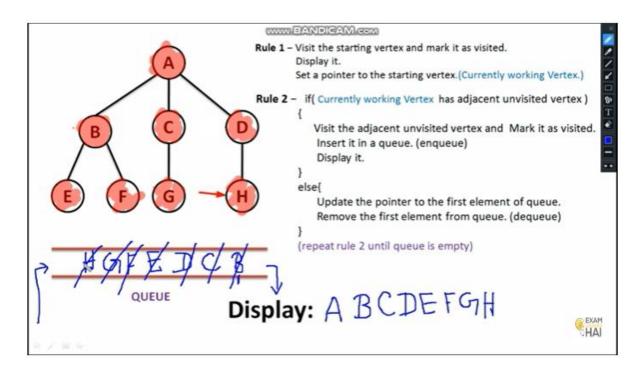


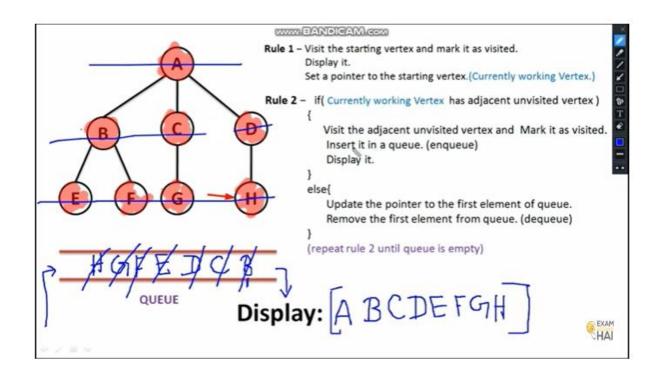












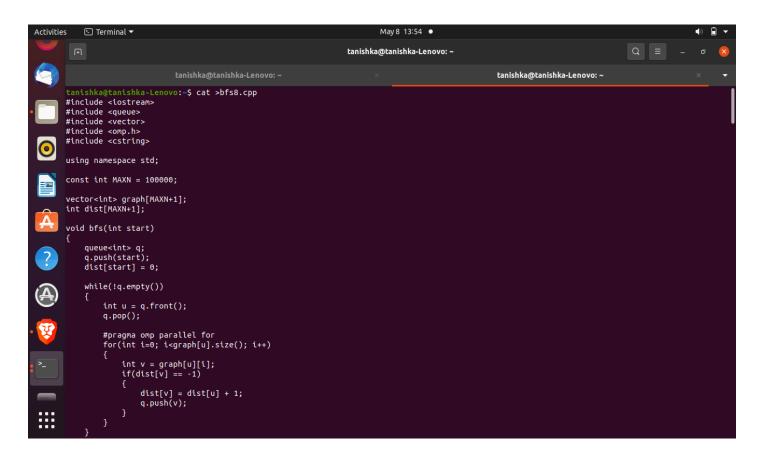
BFS Code-

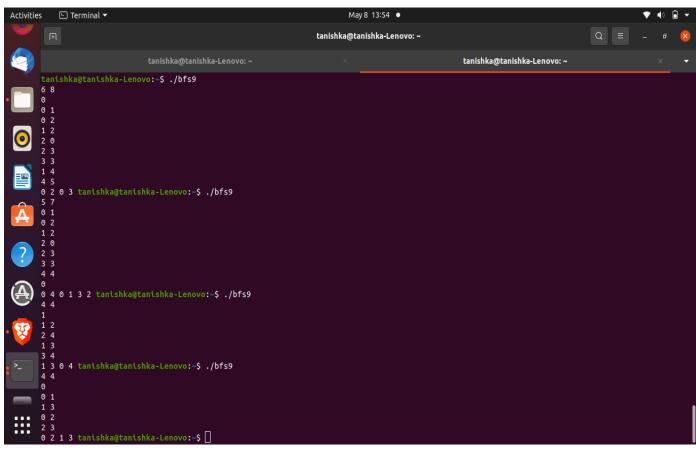
```
#include <iostream>
#include <queue>
#include <vector>
#include <omp.h>
using namespace std;
int main() {
  int num_vertices, num_edges, source;
  cin >> num_vertices >> num_edges >> source;
  vector<vector<int>> adi_list(num_vertices + 1);
  for (int i = 0; i < num\_edges; i++) {
    int u, v;
    cin >> u >> v;
     adj_list[u].push_back(v);
     adj_list[v].push_back(u);
```

queue<int> q;

```
vector<bool> visited(num_vertices + 1, false);
q.push(source);
visited[source] = true;
while (!q.empty()) {
  int curr_vertex = q.front();
  q.pop();
  cout << curr_vertex << " ";</pre>
  #pragma omp parallel for shared(adj_list, visited, q) schedule(dynamic)
  for (int i = 0; i < adj_list[curr_vertex].size(); i++) {
     int neighbour = adj_list[curr_vertex][i];
     if (!visited[neighbour]) {
       visited[neighbour] = true;
       q.push(neighbour);
     }
return 0;
```

}





Aim: Write a CUDA Program for:

- 1. Addition of two large vectors
- 2. Matrix Multiplication using CUDA C

1. Vector Addition Program

```
nvcc --version
!pip install git+https://github.com/afnan47/cuda.git
%load_ext nvcc_plugin
%%cu
#include <iostream>
using namespace std;
__global__
void add(int* A, int* B, int* C, int size) {
  int tid = blockIdx.x * blockDim.x + threadIdx.x;
  if (tid < size) {</pre>
     C[tid] = A[tid] + B[tid];
  }
void initialize(int* vector, int size) {
  for (int i = 0; i < size; i++) {
     vector[i] = rand() \% 10;
  }
void print(int* vector, int size) {
  for (int i = 0; i < size; i++) {
     cout << vector[i] << " ";
  cout << endl;
int main() {
  int N = 4;
```

```
int* A, * B, * C;
 int vectorSize = N;
 size_t vectorBytes = vectorSize * sizeof(int);
 A = new int[vectorSize];
 B = new int[vectorSize];
 C = new int[vectorSize];
initialize(A, vectorSize);
 initialize(B, vectorSize);
 cout << "Vector A: ";
 print(A, N);
 cout << "Vector B: ";</pre>
 print(B, N);
 int* X, * Y, * Z;
 cudaMalloc(&X, vectorBytes);
 cudaMalloc(&Y, vectorBytes);
 cudaMalloc(&Z, vectorBytes);
 cudaMemcpy(X, A, vectorBytes, cudaMemcpyHostToDevice);
 cudaMemcpy(Y, B, vectorBytes, cudaMemcpyHostToDevice);
 int threadsPerBlock = 256;
 int blocksPerGrid = (N + threadsPerBlock - 1) / threadsPerBlock;
 add<<<br/>blocksPerGrid, threadsPerBlock>>>(X, Y, Z, N);
 cudaMemcpy(C, Z, vectorBytes, cudaMemcpyDeviceToHost);
 cout << "Addition: ";</pre>
 print(C, N);
 delete[] A;
 delete[] B;
 delete[] C;
 cudaFree(X);
 cudaFree(Y);
 cudaFree(Z);
 return 0;
```

Output:

Vector A: 3 6 7 5

Vector B: 3 5 6 2

Addition: 6 11 13 7

2. Matrix multiplication

```
nvcc --version
!pip install git+https://github.com/afnan47/cuda.git
%load_ext nvcc_plugin
%%cu
#include <iostream>
#include <cuda.h>
using namespace std;
#define BLOCK_SIZE 2
__global__ void gpuMM(float *A, float *B, float *C, int N)
  // Matrix multiplication for NxN matrices C=A*B
  // Each thread computes a single element of C
  int row = blockIdx.y*blockDim.y + threadIdx.y;
  int col = blockIdx.x*blockDim.x + threadIdx.x;
  float sum = 0.f;
```

```
for (int n = 0; n < N; ++n)
     sum += A[row*N+n]*B[n*N+col];
  C[row*N+col] = sum;
int main(int argc, char *argv[])
{int N;float K;
  // Perform matrix multiplication C = A*B
  // where A, B and C are NxN matrices
  // Restricted to matrices where N = K*BLOCK_SIZE;
 cout<<"Enter a Value for Size/2 of matrix";</pre>
 cin>>K;
  K = 1;
  N = K*BLOCK\_SIZE;
  cout << "\n Executing Matrix Multiplcation" << endl;</pre>
  cout << "\n Matrix size: " << N << "x" << N << endl;
  // Allocate memory on the host
  float *hA,*hB,*hC;
  hA = new float[N*N];
  hB = new float[N*N];
  hC = new float[N*N];
  // Initialize matrices on the host
  for (int j=0; j<N; j++){
    for (int i=0; i<N; i++){
      hA[j*N+i] = 2;
      hB[j*N+i] = 4;
     }
```

```
// Allocate memory on the device
int size = N*N*sizeof(float); // Size of the memory in bytes
float *dA,*dB,*dC;
cudaMalloc(&dA,size);
cudaMalloc(&dB,size);
cudaMalloc(&dC,size);
dim3 threadBlock(BLOCK_SIZE,BLOCK_SIZE);
dim3 grid(K,K);
cout<<"\n Input Matrix 1 \n";</pre>
for (int row=0; row<N; row++){</pre>
    for (int col=0; col<N; col++){
        cout<<hA[row*col]<<" ";
     }
    cout<<endl;
cout<<"\n Input Matrix 2 \n";</pre>
for (int row=0; row<N; row++){</pre>
    for (int col=0; col<N; col++){
        cout<<hB[row*col]<<" ";
    }
    cout<<endl;
  }
// Copy matrices from the host to device
cudaMemcpy(dA,hA,size,cudaMemcpyHostToDevice);
cudaMemcpy(dB,hB,size,cudaMemcpyHostToDevice);
//Execute the matrix multiplication kernel
gpuMM<<<grid,threadBlock>>>(dA,dB,dC,N);
```

```
// Now do the matrix multiplication on the CPU
 /*float sum;
 for (int row=0; row<N; row++){</pre>
    for (int col=0; col<N; col++){
      sum = 0.f;
      for (int n=0; n<N; n++){
         sum += hA[row*N+n]*hB[n*N+col];
      }
      hC[row*N+col] = sum;
      cout << sum <<" ";
    }
    cout<<endl;
 }*/
// Allocate memory to store the GPU answer on the host
 float *C;
 C = new float[N*N];
 // Now copy the GPU result back to CPU
 cudaMemcpy(C,dC,size,cudaMemcpyDeviceToHost);
 // Check the result and make sure it is correct
 cout <<"\n\n\n\n Resultant matrix\n\n";</pre>
 for (int row=0; row<N; row++){</pre>
    for (int col=0; col<N; col++){
        cout << C[row*col] << " ";
    }
    cout<<endl;
 cout << "Finished." << endl;</pre>
```

Output-

Matrix size: 2x2

Input Matrix 1

22

22

Input Matrix 2

44

44

Resultant matrix

16 16

16 16

Finished.