

# Assignment 4 Report

Name: Bhavesh Sood

Roll No: 2019355

Branch: CSAI

Q1)

1. Generated data from multivariate gaussian with the given mean and covariance.

```
import numpy as np
np.random.seed(43)
import matplotlib.pyplot as plt
mean1=[0,0,0]
cov1 = [[1, 0.8, 0.8], [0.8, 1, 0.8],[0.8, 0.8, 1]]
X= np.random.multivariate_normal(mean1, cov1, 1000)
print(X)
```

```
[[-0.37783608  0.11676566 -0.45780845]
 [ 0.3471694   0.30203767  0.8447309 ]
 [-0.0026565  -1.33003507 -0.05867343]
 ...
 [ 0.59601504  0.73963566  0.50036625]
 [-0.00954922  0.69076099 -0.27270638]
 [-1.55886924 -1.23020385 -1.11034104]]
```

Then Normalized the data so that value in each dimension lies in [0,1]

```
X_min=np.min(X)
X_max=np.max(X)
X = (X - X_min)/(X_max - X_min)
X

array([[0.46034139, 0.53913369, 0.44760142],
       [0.57583806, 0.56864837, 0.65510187],
       [0.5201092 , 0.30865175, 0.51118545],
       ...,
       [0.6154803 , 0.63835972, 0.60024302],
       [0.51901116, 0.63057376, 0.47708902],
       [0.27219743, 0.32455532, 0.34365001]])
```

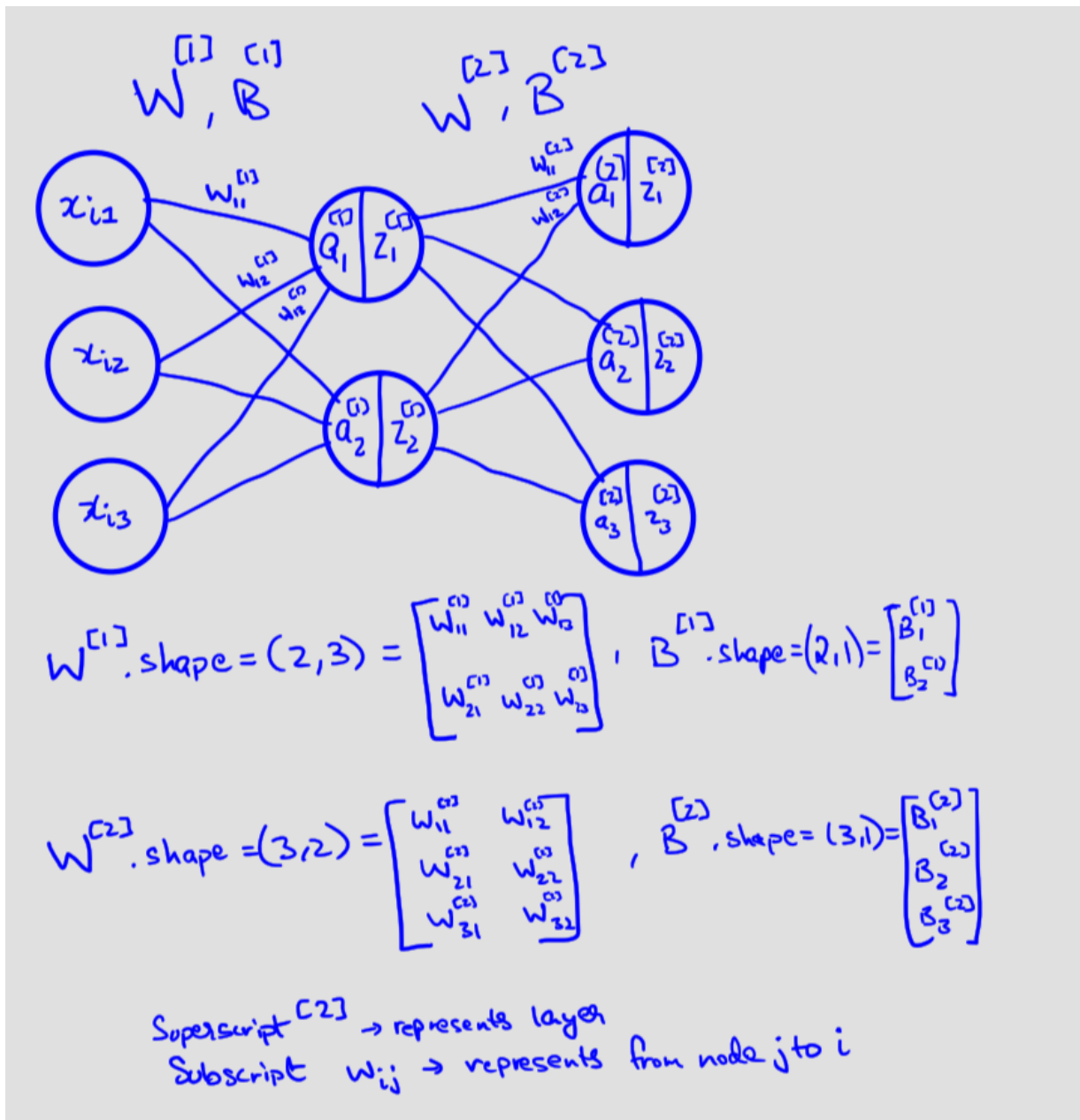
Finally divided the data into training and test-set.

```
X_train=X[:, :800]
X_test=X[:, 800:]
print(X_train.shape,X_test.shape)
```

```
(3, 800) (3, 200)
```

2. We have to encode a autoencoder with one input layer which would be having 3 nodes as it's a 3 dimensional data , then one hidden layer with 2 nodes, and finally output layer with 3 nodes.

Setup



Forward Propagation:

The activation function used for output and hidden layer is sigmoid.

Forward Propagation:

Firstly we define Matrices  $A_1, Z_1, A_2, Z_2$  as follows:

Let  $X_i = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$  be the input vector.

Then

$$1) A_1 = W^{[1]} X_i + B^{[1]} = \begin{bmatrix} a_1^{[1]} \\ a_2^{[1]} \end{bmatrix}$$

$$2) Z_1 = \sigma(A_1) = \begin{bmatrix} \sigma(a_1) \\ \sigma(a_2) \end{bmatrix} = \begin{bmatrix} z_1^{[1]} \\ z_2^{[1]} \end{bmatrix}, \quad \sigma(x) \rightarrow \text{sigmoid of } x$$

$$3) A_2 = W^{[2]} Z_1 + B^{[2]} = \begin{bmatrix} a_1^{[2]} \\ a_2^{[2]} \\ a_3^{[2]} \end{bmatrix}$$

$$4) Z_2 = \sigma(A_2) = \begin{bmatrix} z_1^{[2]} \\ z_2^{[2]} \\ z_3^{[2]} \end{bmatrix}$$

$Z_2$  gives us the final layer output.

Backpropagation:

Backpropagation:

$$\text{Error } E = \sum_{j=1}^3 (x_{ij} - \hat{x}_{ij})^2 = \sum_{j=1}^3 (x_{ij} - z_j^{[2]})^2$$

$$"dz_j^{[2]}" = \frac{dE}{dz_j^{[2]}} = -2(x_{ij} - z_j^{[2]}) \quad , \text{ we do this for } 1 \leq j \leq 3$$

$$\text{We define "dZ2" = } \begin{bmatrix} dz_1^{[2]} \\ dz_2^{[2]} \\ dz_3^{[2]} \end{bmatrix}$$

$$\sigma'(x) = \sigma(x)(1 - \sigma(x))$$

Now

$$"da_j^{[2]}" = \frac{dE}{da_j^{[2]}} = \frac{dE}{dz_j^{[2]}} \cdot \frac{dz_j^{[2]}}{da_j^{[2]}} = -2(x_{ij} - z_j^{[2]}) \cdot (z_j^{[2]}(1 - z_j^{[2]}))$$

$$\text{We define this as "dA2" = } \begin{bmatrix} da_1^{[2]} \\ da_2^{[2]} \\ da_3^{[2]} \end{bmatrix}$$

$$\text{For } w^{[2]}, \quad \frac{dE}{dw_{ji}^{[2]}} = \frac{dE}{da_j^{[2]}} \cdot \frac{da_j^{[2]}}{dw_{ji}^{[2]}} = "da_j^{[2]}" \times z_i^{[1]} \quad ; \text{ as } a_j^{[2]} = w_{j1}z_1^{[1]} + w_{j2}z_2^{[1]} + B_j^{[2]}$$

$$\text{We can represent it in matrix form "dW2" = dA2} \cdot Z_1^T$$

$$\text{For } B^{[2]}, \quad \frac{dE}{dB_j^{[2]}} = \frac{dE}{da_j^{[2]}} \cdot \frac{da_j^{[2]}}{dB_j^{[2]}} = \frac{dE}{da_j^{[2]}} \cdot 1$$

$$\therefore "dB2" = "dA2"$$

For Z1

$$"dz_i^{c1}" = \frac{dE}{dz_i^{c1}} = \sum_{j=1}^3 \frac{dE}{da_j^{c2}} \frac{da_j^{c2}}{dz_i^{c1}} = \sum_{j=1}^3 \frac{dE}{da_j^{c2}} \cdot W_{ji}^{c2} = \sum_{j=1}^3 "da_j^{c2}" \cdot W_{ji}^{c2}$$

In Matrix form  
 $"dz1" = W^{c2T} \cdot "dA2"$  (dot product)

$$\frac{dE}{da_i^{c1}} = \frac{dE}{dz_i^{c1}} \cdot \frac{dz_i^{c1}}{da_i^{c1}} = "dz_i^{c1}" \cdot \sigma'(a_i^{c1}) (1 - \sigma(a_i^{c1})) , \text{ as } z_i^{c1} = \sigma(a_i^{c1})$$

$$\therefore "dA1" = "dz1" \cdot (z1 (1 - z1))$$

Same as W2, we get "dW1"

$$\frac{dE}{dw_{ji}^{c1}} = \frac{dE}{da_j^{c1}} \frac{da_j^{c1}}{dw_{ji}^{c1}} = "da_j^{c1}" \cdot x_i$$

In Matrix form  
 $"dW1" = "dA1" \cdot X_i^T$

for B1

$$\frac{dE}{db_i^{c1}} = \frac{dE}{da_i^{c1}} \frac{da_i^{c1}}{db_i^{c1}} = \frac{dE}{da_i^{c1}} \cdot 1$$

$$\therefore "dB1" = "dA1"$$

In Concise format forward propagation and backpropagation works like this.

Forward Propagation

```
A1 = np.dot(W1, Xi) + B1
Z1= sigmoid(A1)
A2 = np.dot(W2, Z1) + B2
Z2=sigmoid(A2)
```

Back Propagation:

```
E=(Xi-Z2)**2;
dZ2= -2*(Xi-Z2)
dA2=dZ2*(Z2*(1-Z2))
dW2=np.dot(dA2,Z1.T)
dB2=dA2
dZ1=np.dot(W2.T,dA2)
dA1=dZ1*(Z1*(1-Z1))
dW1=np.dot(dA1,Xi.T)
dB1=dA1
```

Weight Updates are like this:

(Based on matrices defined above)

$$W_2 = W_2 - \alpha "dw_2" \quad ; \text{"dw}_2" \text{ is the matrix as defined above}$$

$$B_2 = B_2 - \alpha "db_2"$$

$$W_1 = W_1 - \alpha "dw_1"$$

$$B_1 = B_1 - \alpha "db_1"$$

This way all the weights are updated in one go, and get stored in matrix form only.

We then run this implementation in python from scratch, and make a loop to run multiple epochs.

```
def runepoch(X_given, parameters):  
    assert (X_given.shape==(3,800))  
    for i in range(800):  
        cur_cache=forwardprop(parameters,X_given[:,i:i+1])  
        cur_grad=backprop(cur_cache,parameters,X_given[:,i:i+1])  
        parameters=updateweights(parameters,cur_grad,.03)  
    return parameters
```

Note we keep the learning rate as 0.03

Using this function we run 100 epochs and plot MSE vs Epoch.

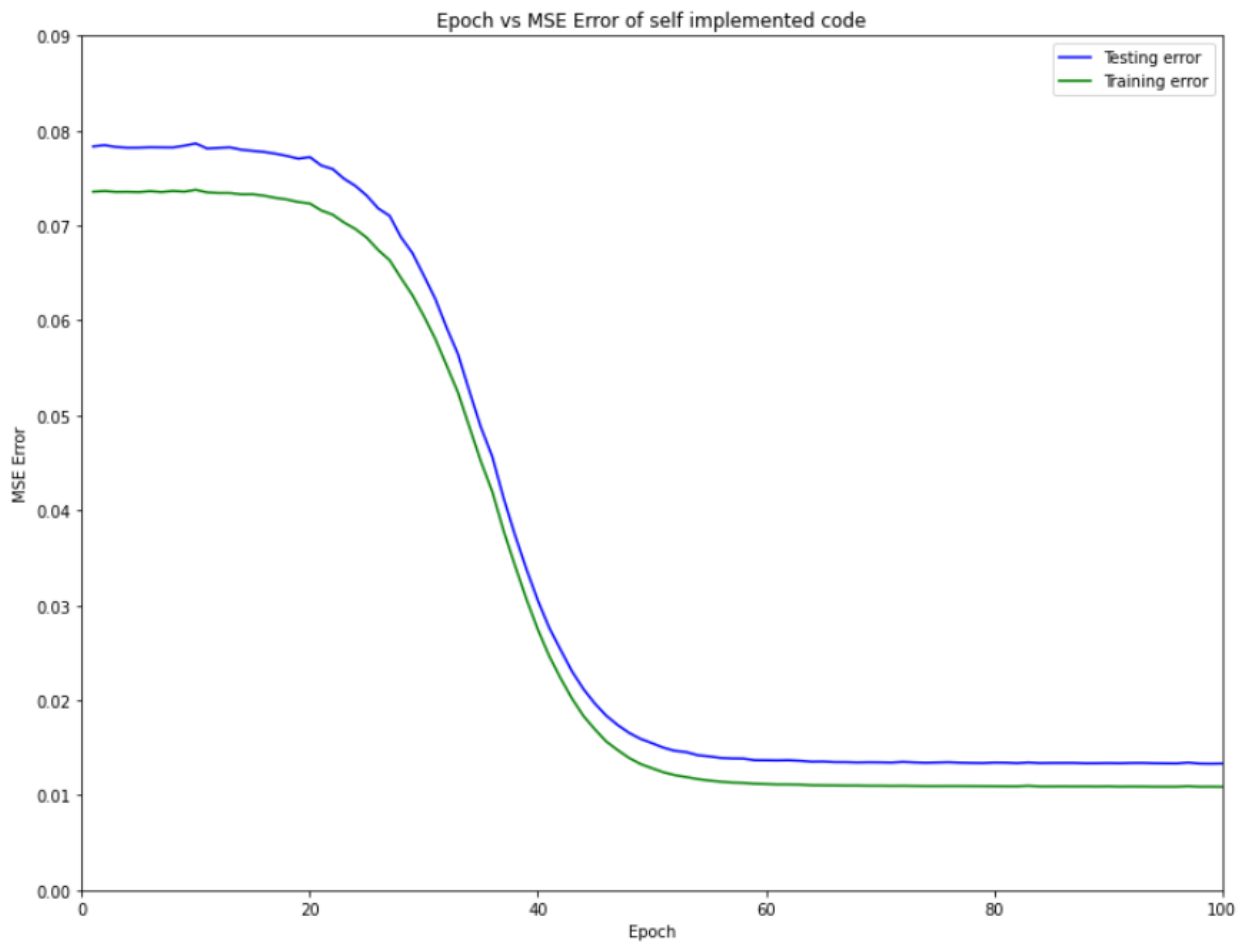
```
parameters=initialize_parameters(3, 2, 3)
testepocherror=[];
trainepocherror=[]
index=np.arange(1,101,1)
for i in range(100):
    p = np.random.permutation(800)
    parameters=runepoch(X_train[:,p],parameters)
    totalerror=0
    totaler2=0
    for i in range(200):
        curans=forwardprop(parameters,X_test[:,i:i+1])
        yhat=curans['Z2']
        Ei=(X_test[:,i:i+1]-yhat)**2;
        totalerror+=Ei
    MSE=totalerror/200
    testepocherror.append(np.sum(MSE))
    for i in range(800):
        curans=forwardprop(parameters,X_train[:,i:i+1])
        yhat=curans['Z2']
        Ei=(X_train[:,i:i+1]-yhat)**2;
        totaler2+=Ei
    MSE=totaler2/800
    trainepocherror.append(np.sum(MSE))
```

I get the following final MSE errors:

```
trainepocherror[-1],testepocherror[-1]
```

```
(0.010873232615716955, 0.013320378386287095)
```

### 3. Final Graph





4. We implement the same neural network but this time using the autograd functionality of pytorch to calculate the gradients.

#### Forward and back Prop

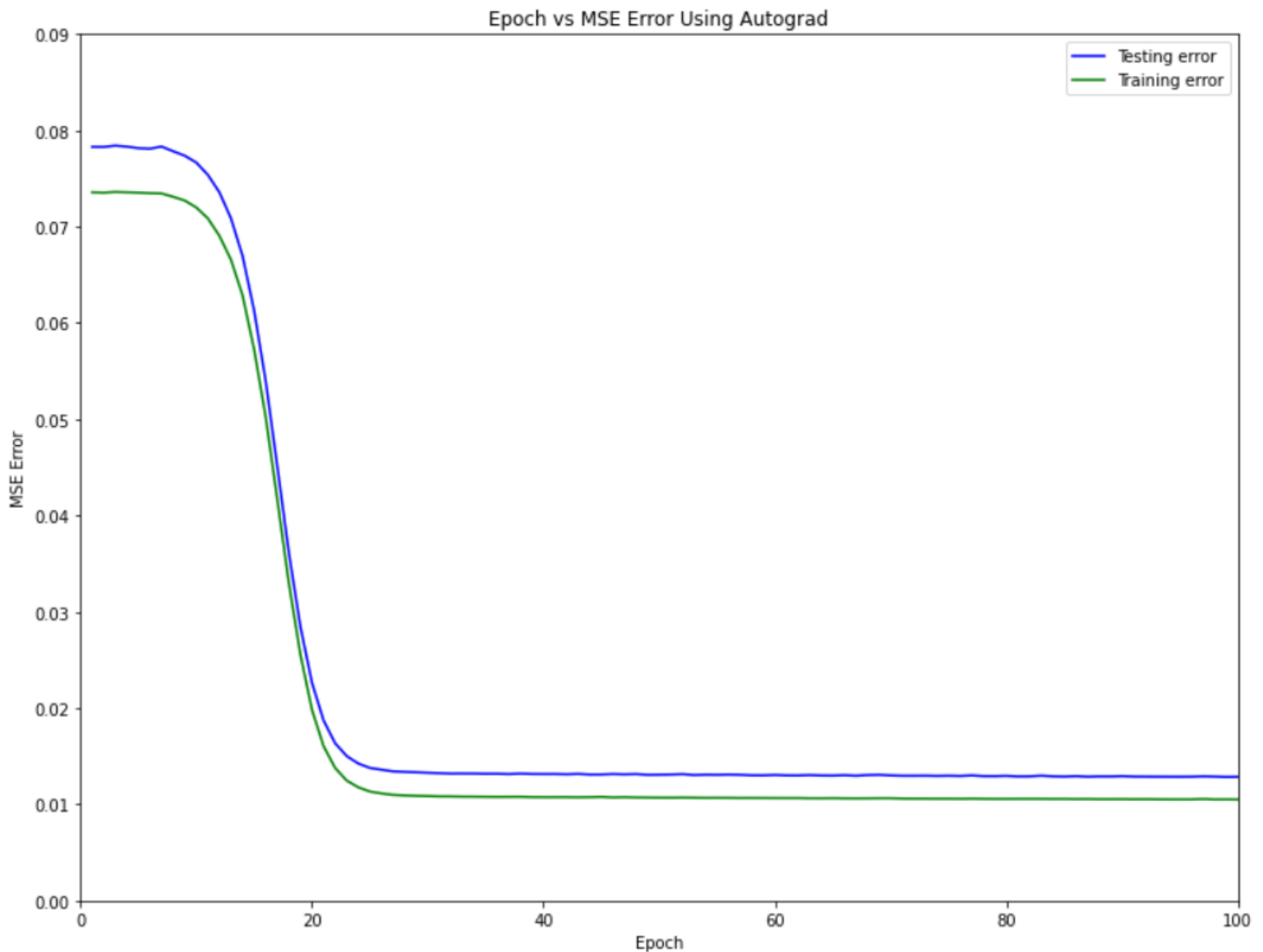
```
B2=parameters["B2"]
# print(W1.shape,W1.dtype)
A1 = torch.matmul (W1,Xi) + B1
Z1= torch.sigmoid(A1)
A2 = torch.matmul (W2,Z1)+B2
Z2=torch.sigmoid(A2)
E=(Xi-Z2)**2;
# print(E)
E.retain_grad()
Z2.retain_grad()
A2.retain_grad()
Z1.retain_grad()
A1.retain_grad()
W2.retain_grad()
W1.retain_grad()
B2.retain_grad()
B1.retain_grad()

E.sum().backward(retain_graph=True)
```

#### Weight Update

```
with torch.no_grad():
    # print("GRADIENT ",W2,W2.grad)
    W2-=learningrate*W2.grad
    W1-=learningrate*W1.grad
    B2-=learningrate*B2.grad
    B1-=learningrate*B1.grad
W2.grad.zero_()
W1.grad.zero_()
B1.grad.zero_()
B2.grad.zero_()
```

## Graph with autograd



```
| trainepocherror[-1],testepocherror[-1]
```

```
(tensor(0.0105, dtype=torch.float64, grad_fn=<SumBackward0>),  
 tensor(0.0129, dtype=torch.float64, grad_fn=<SumBackward0>))
```

Inference :

We notice that we get the exact shape curve of the graph and even the final values of the MSE error are pretty much the same. ( Slight difference being in that torch uses float64 dtype so handles higher precision much better)