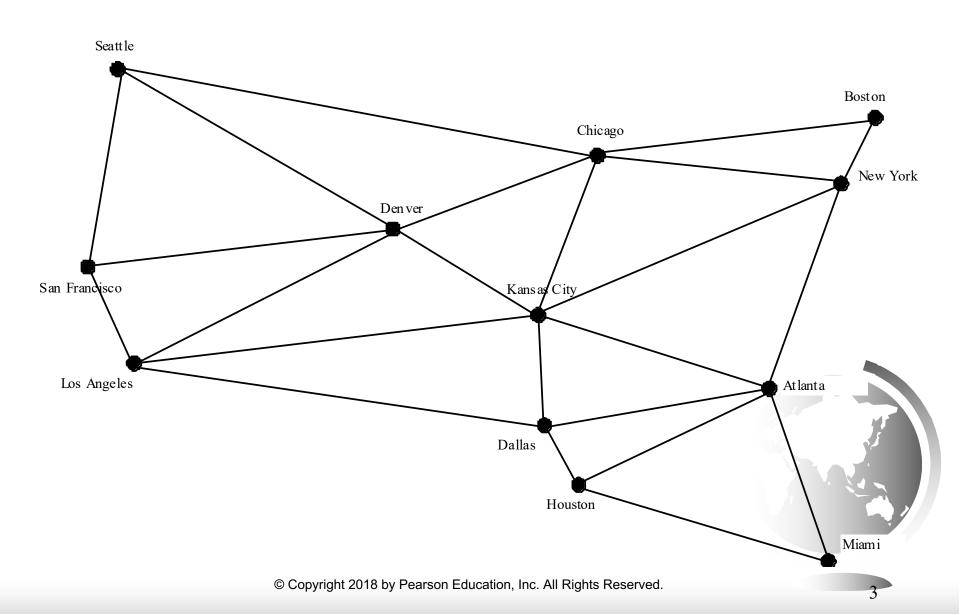
Chapter 22 Graphs and Applications



Objectives

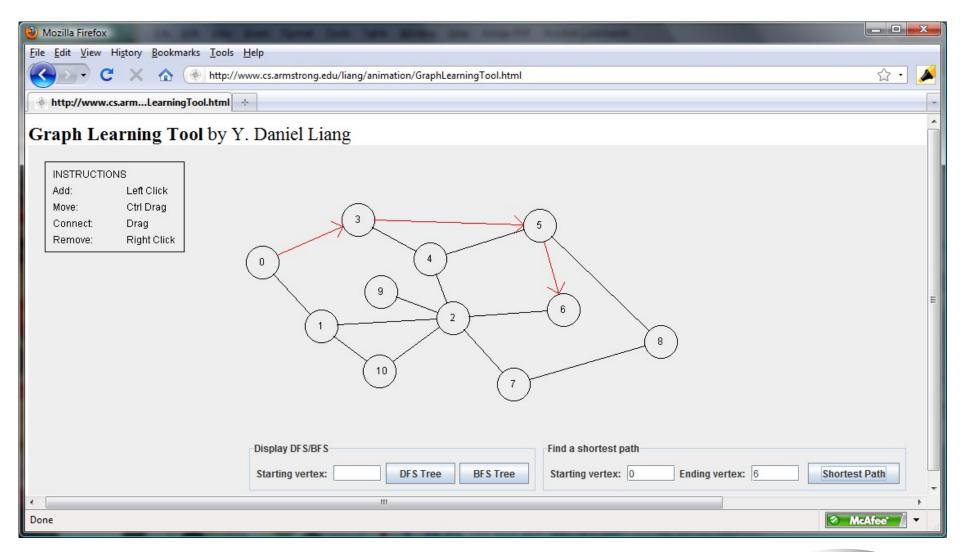
- ◆ To model real-world problems using graphs and explain the Seven Bridges of Königsberg problem (§22.1).
- ◆ To describe the graph terminologies: vertices, edges, simple graphs, weighted/unweighted graphs, and directed/undirected graphs (§22.2).
- → To represent vertices and edges using lists, adjacent matrices, and adjacent lists (§22.3).
- → To model graphs using the Graph class (§22.4).
- ◆ To display graphs visually (§22.5).
- → To represent the traversal of a graph using the Tree class (§22.6).
- → To design and implement depth-first search (§22.7).
- → To solve the connected-circle problem using depth-first search (§22.8)
- → To design and implement breadth-first search (§22.9).
- → To solve the nine-tail problem using breadth-first search (§22.10).

Modeling Using Graphs

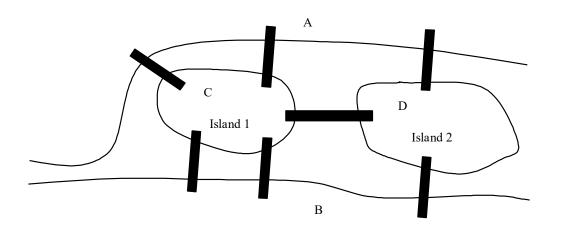


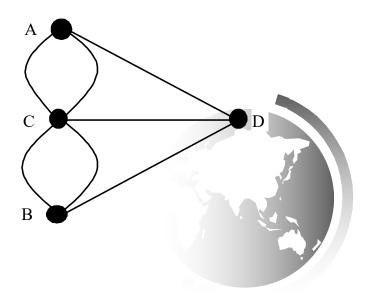
Graph Animation

nttps://liveexample.pearsoncmg.com/dsanimation/GraphLearningTooleBook.html



Seven Bridges of Königsberg





Basic Graph Terminologies

What is a graph?

Define a graph

Directed vs. undirected graphs

Weighted vs. unweighted graphs

Adjacent vertices

Incident

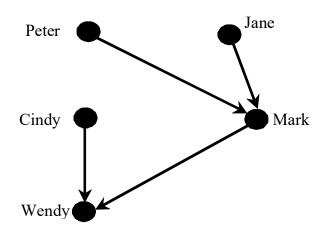
Degree

Neighbor

loop



Directed vs Undirected Graph





Basic Graph Terminologies

Parallel edge

Simple graph

Complete graph

Spanning tree



Representing Graphs

Representing Vertices

Representing Edges: Edge Array

Representing Edges: Edge Objects

Representing Edges: Adjacency Matrices

Representing Edges: Adjacency Lists



Representing Vertices

```
V = ["Seattle", "San Francisco", "Los Angeles",
"Denver", "Kansas City", "Chicago", "Boston", "New York",
"Atlanta", "Miami", "Dallas", "Houston"]
```



Representing Edges: Edge List

```
edges = [
    [0, 1], [0, 3], [0, 5],
    [1, 0], [1, 2], [1, 3],
    [2, 1], [2, 3], [2, 4], [2, 10],
    [3, 0], [3, 1], [3, 2], [3, 4], [3, 5],
    [4, 2], [4, 3], [4, 5], [4, 7], [4, 8], [4, 10],
    [5, 0], [5, 3], [5, 4], [5, 6], [5, 7],
    [6, 5], [6, 7],
    [7, 4], [7, 5], [7, 6], [7, 8],
    [8, 4], [8, 7], [8, 9], [8, 10], [8, 11],
    [9, 8], [9, 11],
    [10, 2], [10, 4], [10, 8], [10, 11],
    [11, 8], [11, 9], [11, 10]
```

Representing Edges: Edge Object

```
class Edge:
    def init (self, u, v):
        self.u = u
        self.v = v
edgeList = []
edgeList.append(Edge(0, 1))
edgeList.append(Edge(0, 3))
edgeList.append(Edge(0, 5))
```

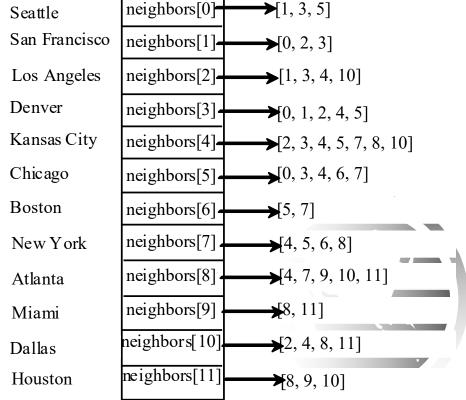


Representing Edges: Adjacency Matrix

```
adjacencyMatrix = [
    [0, 1, 0, 1, 0, 1, 0, 0, 0, 0, 0], # Seattle
    [1, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0], # San Francisco
    [0, 1, 0, 1, 1, 1, 0, 0, 0, 0, 0], # Los Angeles
    [1, 1, 1, 0, 1, 1, 0, 0, 0, 0, 0, 0], # Denver
    [0, 0, 1, 1, 0, 1, 0, 1, 1, 0, 1, 0], # Kansas City
    [1, 0, 0, 1, 1, 0, 1, 1, 0, 0, 0, 0], # Chicago
    [0, 0, 0, 0, 0, 1, 0, 1, 0, 0, 0, 0], # Boston
    [0, 0, 0, 0, 1, 1, 1, 0, 1, 0, 0, 0], # New York
    [0, 0, 0, 1, 1, 0, 0, 1, 0, 1, 1, 1], # Atlanta
    [0, 0, 0, 0, 0, 0, 0, 1, 0, 0, 1], # Miami
    [0, 0, 1, 0, 1, 0, 0, 1, 0, 0, 1], # Dallas
    [0, 0, 0, 0, 0, 0, 0, 1, 1, 1, 0] # Houston
```

Representing Edges: Adjacency List

neighbors = [[1, 3, 5], [0, 2, 3], [1, 3, 4, 10], [0, 1, 2, 4, 5], [2, 3, 4, 5, 7, 8, 10], [0, 3, 4, 6, 7], [5, 7], [4, 5, 6, 8], [4, 7, 9, 10, 11], [8, 11], [2, 4, 8, 11], [8, 9, 10]]



Modeling Graphs

Graph

vertices: list

neighbors: list of adjacency list

Graph(vertexList: list, edgeList: list)

getAdjacencyList(edgeList: list): list

getSize(): int

getVertices(): list

getVertex(index): object

getIndex(v: object): int

getNeighbors(index: int): list

getDegree(v: object): int

printEdges(): None

clear(): None

addVertex(v: object): None

addEdge(u: object, v: object): None

+dfs(index: int): Tree

+bfs(index: int): Tree

Stores vertices.

Stores edges.

Constructs a graph with the specified vertices and edges.

Returns an adjacency list from edgeList.

Returns the number of vertices in the graph.

Returns the vertices in the graph.

Returns the vertex at the specified index.

Returns the index for the specified vertex.

Returns the neighbors of vertex with the specified index.

Returns the degree for a specified vertex.

Prints the edges.

Clears the graph.

Adds a vertex to the graph.

Adds an edge (from u to v) to the graph.

Obtains a depth-first search tree.

Obtains a breadth-first search tree.

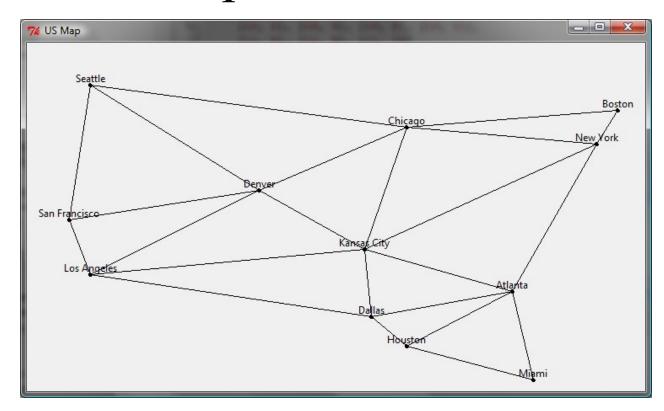


Graph

TestGraph



Graph Visualization



Displayable

Displayable

GraphView

Graph Traversals

Depth-first search and breadth-first search

Both traversals result in a spanning tree, which can be modeled using a class.

Tree

root: int

parent: list

searchOrders: list

vertices: list

Tree(root: int, parent: list,

searchOrders: list, vertices: list)

getRoot(): int

getSearchOrders(): list

getParent(index: int): int

getNumberOfVerticesFound(): int

getPath(index: int): list

print Path(index: int): None

printTree(): None

The root of the tree.

The parents of the vertices in index.

The orders for traversing the vertices in index.

The vertices of the graph.

Constructs a tree with the specified root, parent, search orders, and vertices for the graph.

Returns the root of the tree.

Returns the order of vertices searched.

Returns the parent for the specified vertex index.

Returns the number of vertices searched.

Returns a list of vertices from the specified vertex index

to the root.

Displays a path from the root to the specified vertex.

Displays tree with the root and all edges.



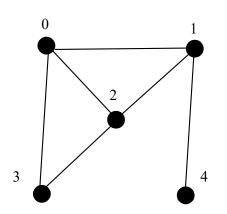
Depth-First Search

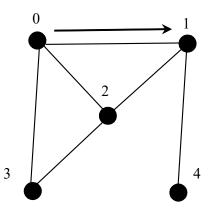
The depth-first search of a graph is like the depth-first search of a tree discussed in §19.2.3, "Tree Traversal." In the case of a tree, the search starts from the root. In a graph, the search can start from any vertex.

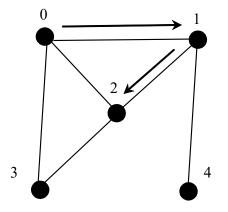
dfs(vertex v):
 visit v
 for each neighbor w of v:
 if w has not been visited:
 dfs(w)

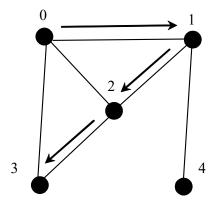


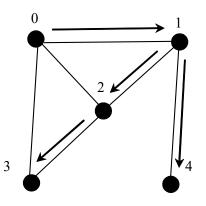
Depth-First Search Example





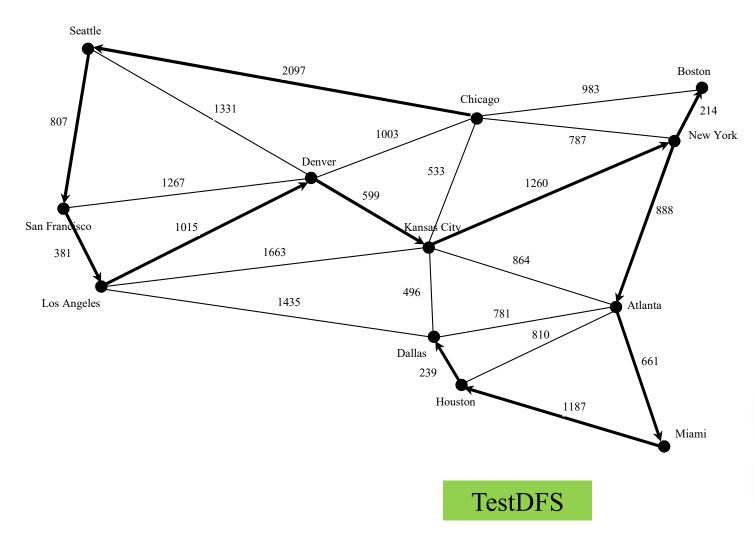








Depth-First Search Example





Applications of the DFS

Detecting whether a graph is connected. Search the graph starting from any vertex. If the number of vertices searched is the same as the number of vertices in the graph, the graph is connected. Otherwise, the graph is not connected (See Exercise 22.2.)

Detecting whether there is a path between two vertices. (See Exercise 22.3)

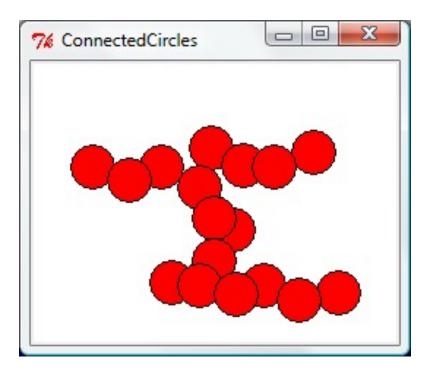
Finding a path between two vertices. (See Exercise 22.3)

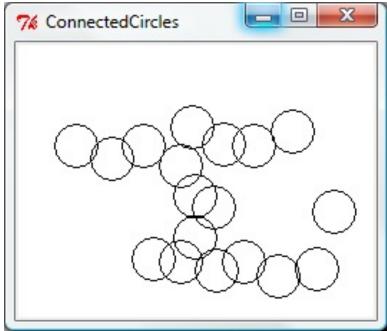
Finding all connected components. A connected component is a maximal connected subgraph in which every pair of vertices are connected by a path. (See Exercise 22.2)

Detecting whether there is a cycle in the graph. (See Exercise 22.4)

Finding a cycle in the graph. (See Exercise 22.5)

The Connected Circles Problem





ConnectedCircles

Breadth-First Search

The breadth-first traversal of a graph is like the breadth-first traversal of a tree discussed in §22.2.3, "Tree Traversal." With breadth-first traversal of a tree, the nodes are visited level by level. First the root is visited, then all the children of the root, then the grandchildren of the root from left to right, and so on.

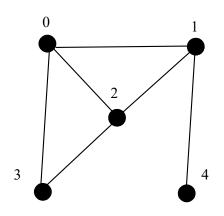


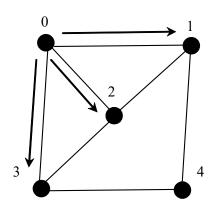
Breadth-First Search Algorithm

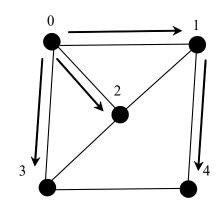
```
bfs(vertex v):
  create an empty queue for storing vertices to be visited
  add v into the queue
  mark v visited
  while the queue is not empty:
     dequeue a vertex, say u, from the queue
     add u into a list of traversed vertices
     for each neighbor w of u
       if w has not been visited:
          add w into the queue
          mark w visited
```



Breadth-First Search Example







Queue: 0

Queue: 1 2 3

Queue: 2 3 4

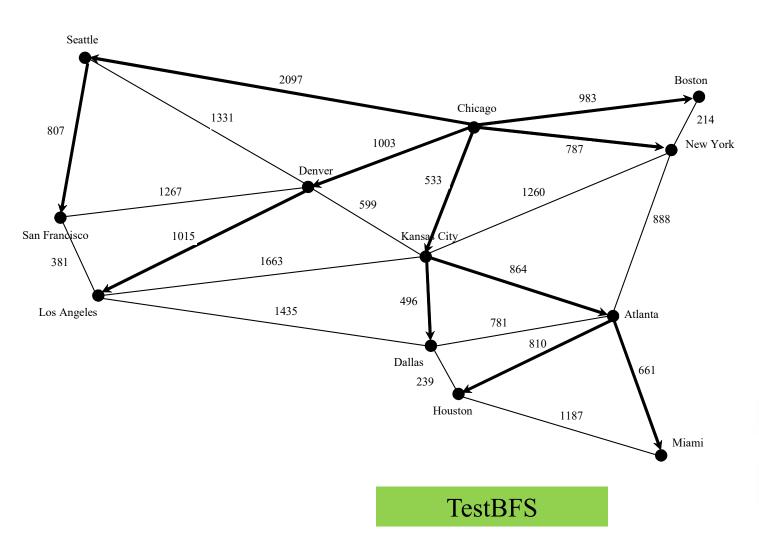
isVisited[0] = True

isVisited[1] = True, isVisited[2] = True,

isVisited[3] = True

isVisited[4] = True

Breadth-First Search Example





Applications of the BFS

Detecting whether a graph is connected. A graph is connected if there is a path between any two vertices in the graph.

Detecting whether there is a path between two vertices.

Finding a shortest path between two vertices. You can prove that the path between the root and any node in the BFS tree is the shortest path between the root and the node (see Review Question 22.10).

Finding all connected components. A connected component is a maximal connected subgraph in which every pair of vertices are connected by a path.

Detecting whether there is a cycle in the graph. (See Exercise 22.4) Finding a cycle in the graph. (See Exercise 22.5)

Testing whether a graph is bipartite. A graph is bipartite if the vertices of the graph can be divided into two disjoint sets such that no edges exist between vertices in the same set. (See Exercise 22.8)

The Nine Tail Problem

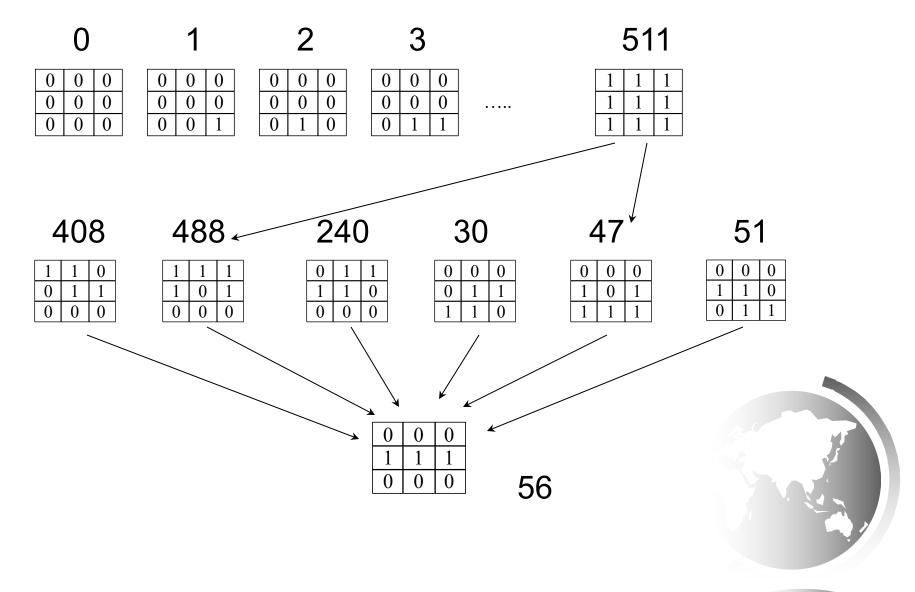
The problem is stated as follows. Nine coins are placed in a three by three matrix with some face up and some face down. A legal move is to take any coin that is face up and reverse it, together with the coins adjacent to it (this does not include coins that are diagonally adjacent). Your task is to find the minimum number of the moves that lead to all coins face down.

Н	Н	Н
Т	Т	Т
Н	H	Н

Н	H	Н
Т	Н	Т
$oxedsymbol{oxedsymbol{oxed}}$	T _	T _

T	Т	Т	
Т	Т	Т	
\Box T_	Τ	T	

Model the Nine Tail Problem



NineTailModel

NineTailModel

tree: Tree

Nine Tai lModel ()

getShortestPath(nodeIndex: int): list

getEdges(): list

getNode(index: int): list

getIndex(node: list): int

getFlippedNode(n ode: list, position:

int): int

flip AC ell(node: list, row: int, column:

int): None

print Node (n od e: li st): None

A tree rooted at node 511.

Constructs a model for the nine tail problem and obtains the tree.

Returns a path from the specified node to the root. The path returned consists of the node labels in a list.

Returns an edge list for the graph.

Returns a node consisting of nine characters of H's and T's.

Returns the index of the specified node.

Flips the node at the specified position and returns the index of the flipped node.

Flips the node at the specified row and column.

Displays the node to the console.

NineTailModel

NineTail