MLIC: A MaxSAT-Based framework for learning interpretable classification rules

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The Rise of Artificial Intelligence

- "In Phoenix, cars are self-navigating the streets. In many homes, people are barking commands at tiny machines, with the machines responding. On our smartphones, apps can now recognize faces in photos and translate from one language to another." (New York Times, 2018)
- "Al is the new electricity" (Andrew Ng, 2017)

The Need for Interpretable Models

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- The practitioners adopt techniques that can be interpreted and validated by them
- Medical and education domains see usage of techniques such as classification rules, decision rules, and decision lists.

Prior Work

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- The problem of learning optimal interpretable models is computationally intractable
- Prior work, which was mostly rooted in late 1980s and 1990s, focused on greedy approaches

Our Approach

Objective Learn rules that are accurate and interpretable. The learning procedure is offline, so learning does not need to happen in real time.

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- The problem of rule learning is inherently an optimization problem
- The past few years have seen SAT revolution and development of tools that employ SAT as core engine
- Can we take advantage of SAT revolution, in particular progress on MaxSAT solvers?

Key Contributions

- A MaxSAT-based framework, MLIC, that provably trades off accuracy vs interpretability of rules
- The prototype implementation is capable of finding optimal (or high quality near-optimal) classification rules from large data sets

Part I

From Rule Learning to MaxSAT

Binary Classification

- Features: $\mathbf{x} = \{x^1, x^2, \dots, x^m\}$
- Input: Set of training samples $\{X_i, y_i\}$
 - each vector $\mathbf{X}_i \in \mathcal{X}$ contains valuation of the features for sample i,
 - $-y_i \in \{0,1\}$ is the binary label for sample i
- Output: Classifier \mathcal{R} , i.e. $y = \mathcal{R}(\mathbf{x})$
- Our focus: classifiers that can be represented as CNF Formulas $\mathcal{R} := C_1 \wedge C_2 \wedge \cdots \wedge C_k$.
- Size of classifiers: $|\mathcal{R}| = \Sigma_i |C_i|$

Constraint Learning vs Machine Learning

Input Set of training samples $\{X_i, y_i\}$ Output Classifier \mathcal{R}

• Constraint Learning:

$$\min_{\mathcal{R}} |\mathcal{R}|$$
 such that $\mathcal{R}(\mathbf{X}_i) = y_i, \ \forall i$

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Machine Learning:

$$\min_{\mathcal{R}} |\mathcal{R}| + \lambda |\mathcal{E}_{\mathcal{R}}| \quad \text{such that } \mathcal{R}(\mathbf{X}_i) = y_i, \;\; \forall i \notin \mathcal{E}_{\mathcal{R}}$$

MLIC

- Step 1 Discretization of Features
- Step 2 Transformation to MaxSAT Query
- Step 3 Invoke a MaxSAT Solver and extract $\mathcal R$ from MaxSAT solution

Input Features: $\mathbf{x} = \{x^1, x^2, \cdots x^m\}$; Training Data: $\{\mathbf{X}_i, y_i\}$ over m features

Output \mathcal{R} of k clauses

- $k \times m$ binary coefficients, denoted by $\{b_1^1, b_1^2, \cdots b_1^m \cdots b_k^m\}$, such that $\mathcal{R}_i = (b_i^1 x^1 \vee b_i^2 x^2 \ldots \vee b_i^m x^m)$
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Key Ideas

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Construction

Let
$$Q^k = \bigwedge_i D_i \wedge \bigwedge_i N_i \wedge \bigwedge_{i,j} V_i^j$$

 $\sigma^* = \mathsf{MaxSAT}(Q^k, W)$, then $x^j \in \mathcal{R}_i$ iff $\sigma^*(b_i^j) = 1$.

Remember,
$$\mathcal{R}_i = (b_i^1 x^1 \vee b_i^2 x^2 \dots \vee b_i^m x^m)$$

Provable Guarantees

Theorem (Provable trade off of accuracy vs interpretability of rules)

Let $\mathcal{R}_1 \leftarrow \textit{MLIC}(\mathbf{X}, \mathbf{y}, k, \lambda_1)$ and $\mathcal{R}_2 \leftarrow \textit{MLIC}(\mathbf{X}, \mathbf{y}, k, \lambda_2)$, if $\lambda_2 > \lambda_1$ then $|\mathcal{R}_1| \leq |\mathcal{R}_2|$ and $|\mathcal{E}_{\mathcal{R}_1}| \geq |\mathcal{E}_{\mathcal{R}_2}|$.

Learning DNF Rules

- $(\mathbf{y} = S(\mathbf{x})) \leftrightarrow \neg (\mathbf{y} = \neg S(\mathbf{x})).$
- And if S is a DNF formula, then $\neg S$ is a CNF formula.
- To learn rule S, we simply call MLIC with $\neg y$ as input and negate the learned rule.

Part II

Experimental Results

Illustrative Example

- Iris Classification:
- Features: sepal length, sepal width, petal length, and petal width
- MLIC learned R:=
 - (sepal length $> 6.3 \lor \text{sepal width} > 3.0 \lor \text{petal width} <= 1.5$) \land
 - 2 (sepal width \leq 2.7 \vee petal length > 4.0 \vee petal width > 1.2) \wedge
 - \odot (petal length ≤ 5.0)

Accuracy

Dataset	Size	# Features	RIPPER	Log Reg	NN	RF	SVM	MLIC
			0.968	0.976	0.977	0.976		0.969
TomsHardware	28170	830	(92.8)	(0.2)	(3.4)	(64.9)	Timeout	(2000)
Tomsitatuware	20170	030	(92.0)	(0.2)	(3.4)	(04.9)	Timeout	(2000)
			0.938	0.963	0.965	0.962	0.962	0.958
Twitter	49990	1050	(187.3)	(0.2)	(6.8)	(250.9)	(1010.0)	(2000)
			-					
			0.852	0.801	0.866	0.844		0.755
adult-data	32560	262	(0.5)	(0.3)	(3.0)	(41.8)	Timeout	(2000)
				. =				
credit-card	20000	224	0.811	0.781	0.822	0.82	T:	0.82
credit-card	30000	334	(0.7)	(0.1)	(3.9)	(25.5)	Timeout	(2000)
			0.886	0.909	0.926	0.909	0.886	0.889
ionosphere	350	564	(0.1)	(0.1)	(1.2)	(1.3)	(0.1)	(15.04)
· · · · · · · · · · · · · · · · · · ·			,	,	,	,	,	, ,
			0.774	0.749	0.764	0.761	0.77	0.736
PIMA	760	134	(0.1)	(0.1)	(1.3)	(1.3)	(21.4)	(2000)
			0.868	0.884	0.921	0.895	0.879	0.895
parkinsons	190	392	(0.1)	(0.1)	(1.2)	(1.1)	(1.6)	(245)
			0.78	0.759	0.788	0.788	0.765	0.797
Trans	740	64	(0.0)	(0.0)	(1.2)	(1.2)	(372.3)	(1177)
ITAIIS	740	04	(0.0)	(0.0)	(1.4)	(1.2)	(312.3)	(1111)
			0.961	0.936	0.961	0.943	0.955	0.946
WDBC	560	540	(0.1)	(0.0)	(1.3)	(1.4)	(3.0)	(911)
			. ,	. ,	. ,	` '	. ,	. ,

Intepretability

Dataset	Size	# Features	RIPPER	MLIC
TomsHardware	28170	830	57.5	4
Twitter	49990	1050	78.5	15
adult-data	32560	262	74.5	51.5
credit-card	30000	334	7.5	4
ionosphere	350	564	3	5.5
PIMA	760	134	5	9
parkinsons	190	392	6.5	6
Trans	740	64	6	4

Learning Rate

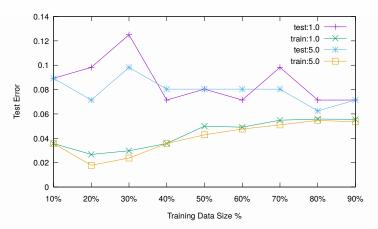


Figure: Plot demonstrating behavior of training and test accuracy vs Size of Training data for WDBC.

Monotonicity

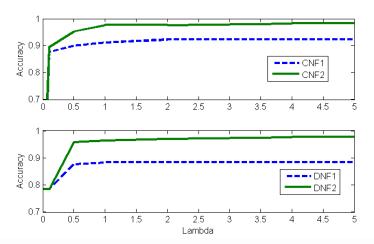


Figure: Plot demonstrating monotone behavior of training accuracy vs λ for CNF and DNF rules with k=1 and 2.

Part III

Conclusion

Summary

- Need for interpretable machine learning systems for usage of AI in core public functions
- The learning task is offline, so allows usage of formal reasoning tools that can provide certificate of correctness
- Long history of prior work: Heuristics to work around combinatorial hardness of optimization problems
- The success of MaxSAT solvers offers opportunity to design techniques with rigorous formal guarantees
- MLIC introduces an approach to use MaxSAT solvers to compute small CNF/DNF rules

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next decade and MaxSAT community can play a central role. Multiple postdoc positions and Ph.D. positions available at the National University of Singapore. Remember, Singapore has been rated as the best city in the world to live in. And of course, you get to see sun everyday!

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