Object SSA for Body.walkSubTree(DLNode$HG;)LNode$HG;

```
BB0 (en)
```

```
BB1
2  GetOSSAInstruction: O1_1= O2_1< pskip>
```

```
BB2
3    conditional branch(eq) v1,v5
```

```
BB3
6   v7 = invokevirtual < Application, LBody, gravSub(LNode$HG;)LNode$HG; > v1,v3 @10 exception:v6
```

```
BB4
```

```
BB5
       O3_1 = diff-Object-Phi(O2_1, nullobject_7 )
              v8 = phi  v3,v7
9    return v8
```

```
BB6 (ex)
```