## **DIP ASSIGNMENT - 4**

## Question-1

### Denoising with Bilateral and Gaussian Filters

- Original Noisy Image: Grainy noise reduces detail and edge clarity.
- Bilateral Filtered Image: Smooths noise in flat areas while preserving edges, providing a clearer image with better detail than Gaussian smoothing.
- Gaussian Blurred Image: Reduces noise but blurs edges slightly, leading to a softer appearance compared to the bilateral filter.

### Laplace Filtering on Different Images

- Laplacian on Noisy Image: Enhances edges but amplifies noise, resulting in a grainy edge map.
- Laplacian on Bilateral Filtered Image: Produces sharp edges with minimal noise, showing effective edge preservation after denoising.
- Laplacian on Gaussian Blurred Image: Shows clear but softer edges, as the Gaussian blur slightly reduces edge sharpness.

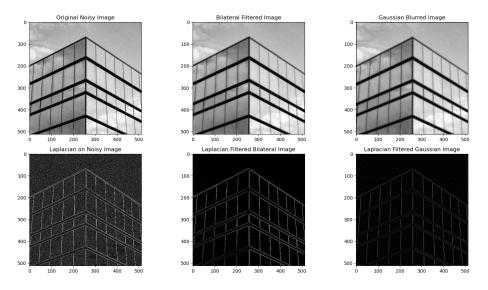


Figure 1: output image under different filter

# Question-2

- Single Circle Detection: The Hough Transform accurately detects a single circle when the radius is known, producing sharp accumulator peaks. Minor radius deviations are tolerated, though peak clarity may reduce as the radius differs.
- Hough Transform with Noise: Noise introduces extra peaks in the accumulator, making it harder to differentiate true circles. Detection is possible if peaks remain distinct, but accuracy drops with higher noise levels.
- Variable Radii Detection: Detection accuracy decreases if the circle radius varies from the expected value. Peak sharpness weakens, especially with large radius differences, highlighting the need for multiple radius checks.
- Detection with Partial Occlusion: Partially occluded circles still produce accumulator peaks, though weaker and less defined. Greater occlusion reduces edge points, weakening accumulator response and reliability.
- Impact of Edge Detectors: The Hough Transform performs best with clean edges. Poor-quality edges, like those from noisy detectors, create cluttered accumulators, reducing detection accuracy.

#### Effect of Threshold and Noise

- Threshold: High thresholds reduce noise but risk missing finer edges; low thresholds capture more details but may introduce noise, cluttering the Hough accumulator.
- **Noise**: Noise creates extra peaks in the accumulator, making it difficult to distinguish true circles and reducing detection accuracy.

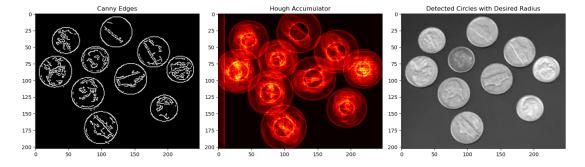


Figure 2: Hough Transform for coins image

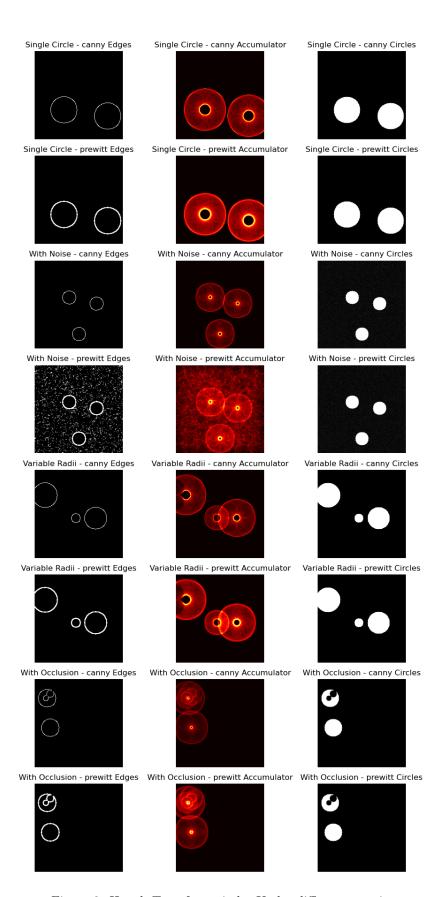


Figure 3: Hough Transform circles Under differnt scenario