## Question-1

- We incremented  $\theta$  from 0° to 360° in 1° steps and calculated  $\phi$  at each step using Newton's method, with each solution of  $\phi$  using the previous value as an initial guess to improve convergence.
- The first derivative of  $\phi$  with respect to  $\theta$  was computed using both forward and centered difference approximations.
- The forward difference has an error of  $O(\Delta\theta)$ , leading to higher truncation error and less accuracy compared to the centered difference.
- The centered difference has an error of  $O(\Delta\theta^2)$ , providing smoother, more accurate results, as seen in a plot where it yields a more precise derivative approximation than the forward difference.

### Forward Difference First Derivative:

$$f'(x) \approx \frac{f(x+h) - f(x)}{h}$$

#### Central Difference First Derivative:

$$f'(x) \approx \frac{f(x+h) - f(x-h)}{2h}$$

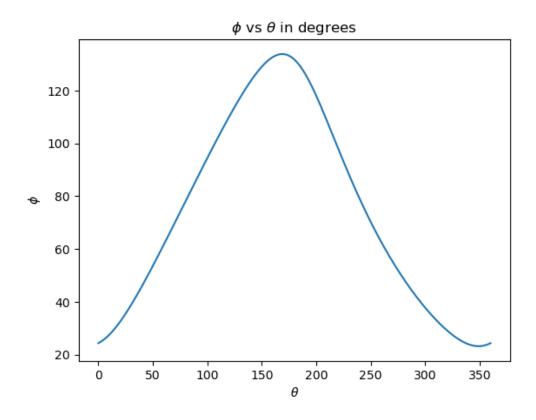


Figure 1:  $\phi$  as a function of  $\theta$ 

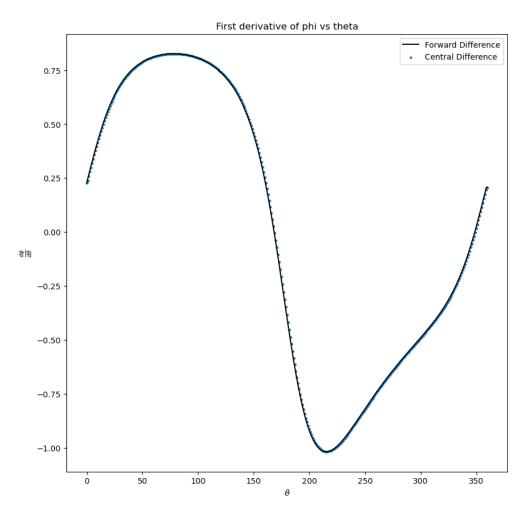


Figure 2:  $\frac{d\phi}{d\theta}$  vs  $\theta$ 

# Question-2

Forward Difference First Derivative:

$$f'(x) \approx \frac{f(x+h) - f(x)}{h}$$

Central Difference First Derivative:

$$f'(x) \approx \frac{f(x+h) - f(x-h)}{2h}$$

Forward Difference Second Derivative:

$$f''(x) \approx \frac{f(x+2h) - 2f(x+h) + f(x)}{h^2}$$

Central Difference Second Derivative:

$$f''(x) \approx \frac{f(x+h) - 2f(x) + f(x-h)}{h^2}$$

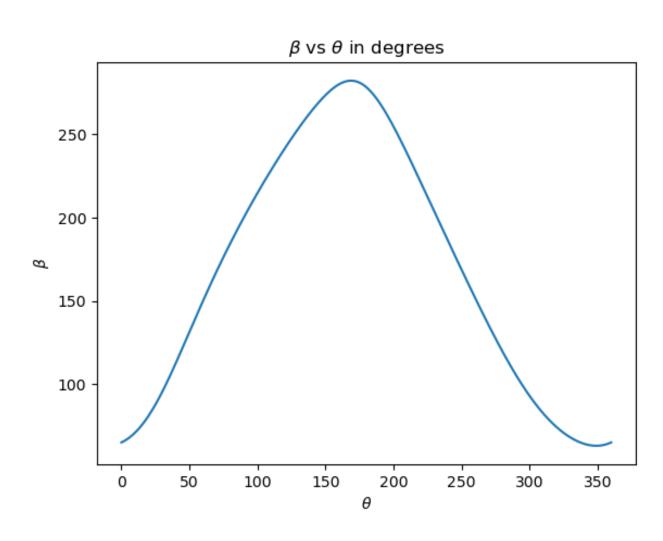


Figure 3:  $\beta$  vs  $\theta$  in degrees.

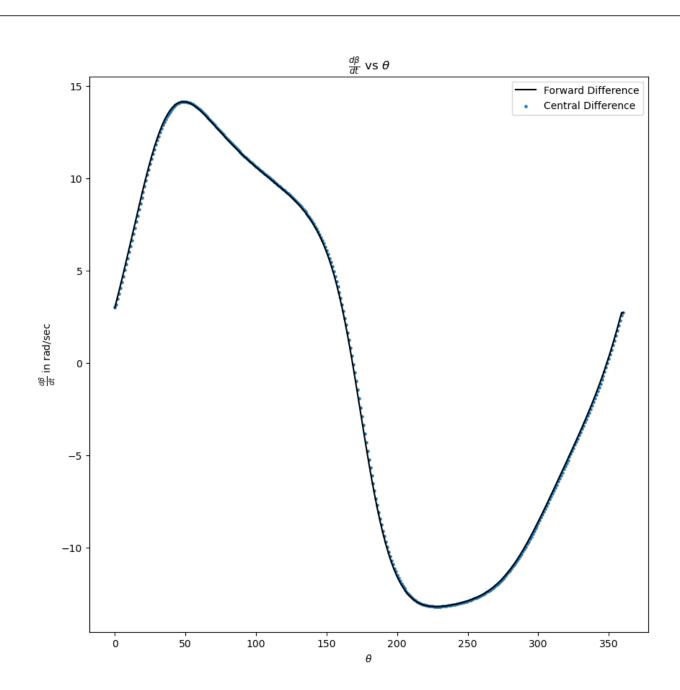


Figure 4: First Derivative of  $\beta$  vs  $\theta$ 

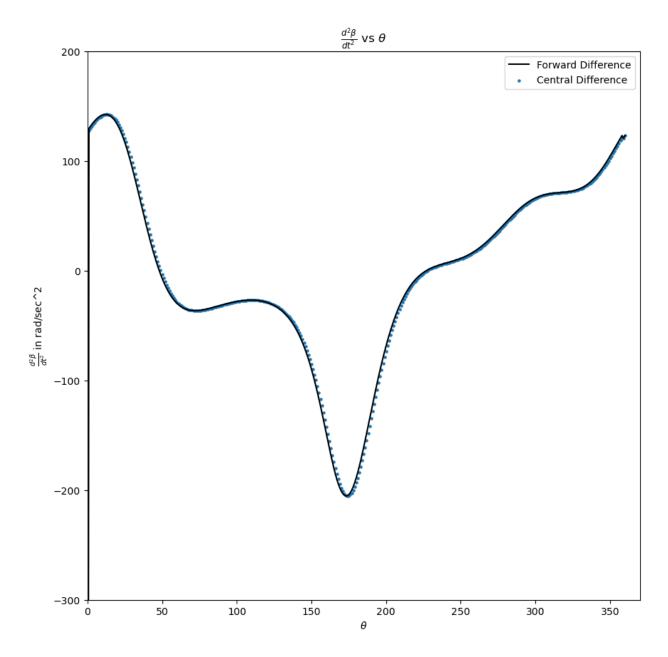


Figure 5: Second Derivative of  $\beta$ 

- Angular velocity at  $\theta = 100^{\circ}$ :  $10.60 \,\mathrm{rad/sec}$
- • Angular acceleration at  $\theta=100^\circ\colon -28.13\,\mathrm{rad/sec}^2$