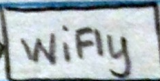
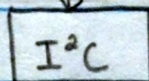


UART



@ 2.4 GHz

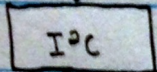
* Communication to/from
WiFly on ARM PIC



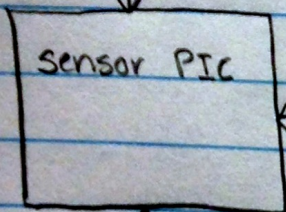
Master

I²C @ 100kbits/sec

Slave
@ 0x9E



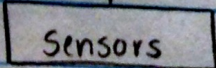
10-bit Sensor Data



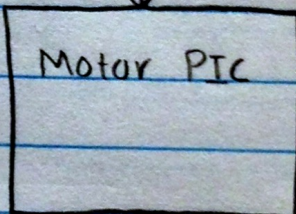
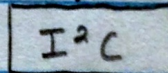
Timer

AND-AN12

1 wire per
sensor



Slave
@ 0x9A



Quadrature
Encoder Left

Quadrature
Encoder Right

