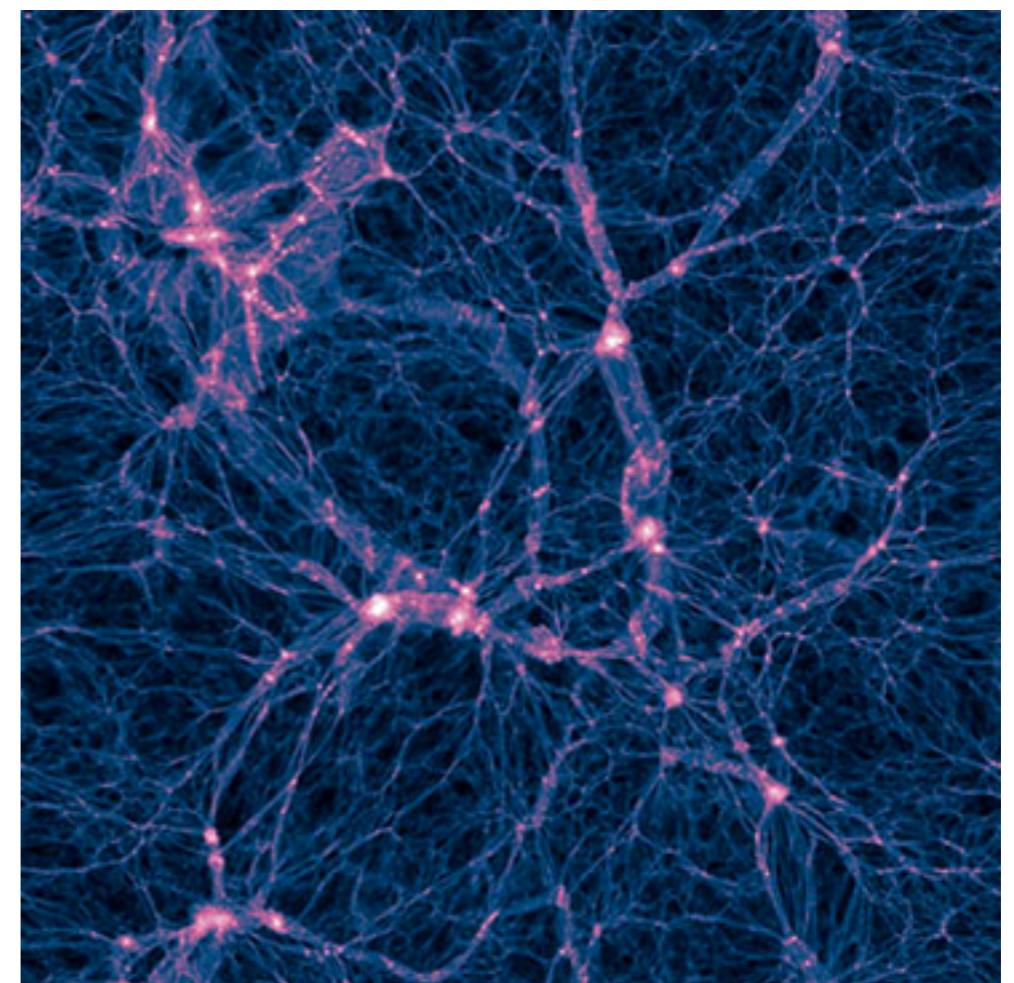
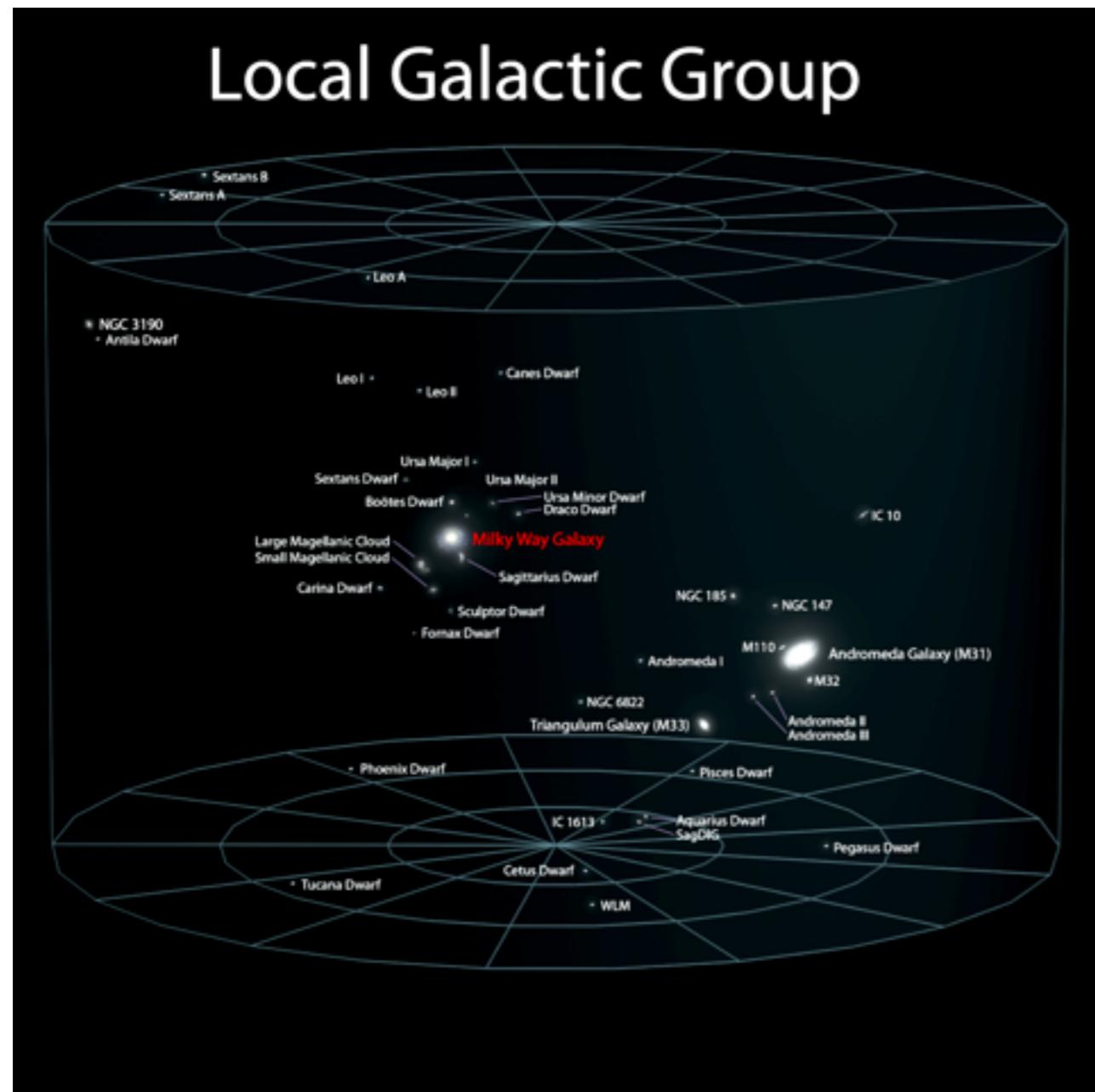


Astrostatistics: Sat 17 Feb 2017

<https://github.com/CambridgeAstroStat/PartIII-Astrostatistics>

- Fitting Statistical Models to Astronomical Data
 - Bayesian Computation, Examples, Case Studies
 - Refs: Ivezic, Ch 5, F&B Ch 3 (not much), Gelman BDA
 - Givens & Hoeting “Computational Statistics”
 - Roberts & Casella “Monte Carlo Statistical Methods” (theory)
 - Hogg & DFM, 2017 “Data analysis recipes: Using Markov Chain Monte Carlo.” <https://arxiv.org/abs/1710.06068>

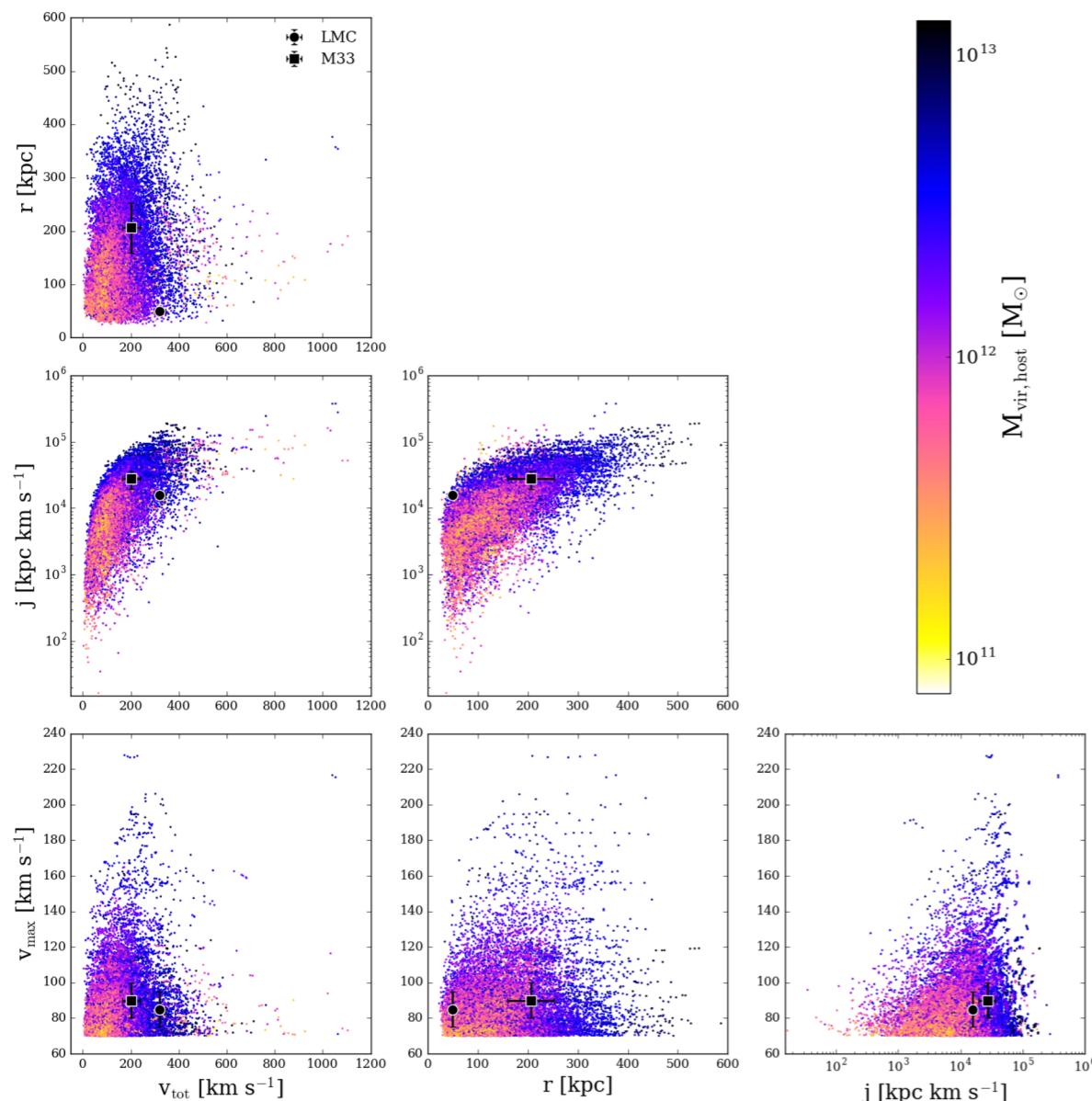
Today: Astrostatistics Case Study 3: Bayesian estimates of the Milky Way and Andromeda masses using high-precision astrometry and cosmological simulations (Patel et al. 2017, arXiv:1703.05767)



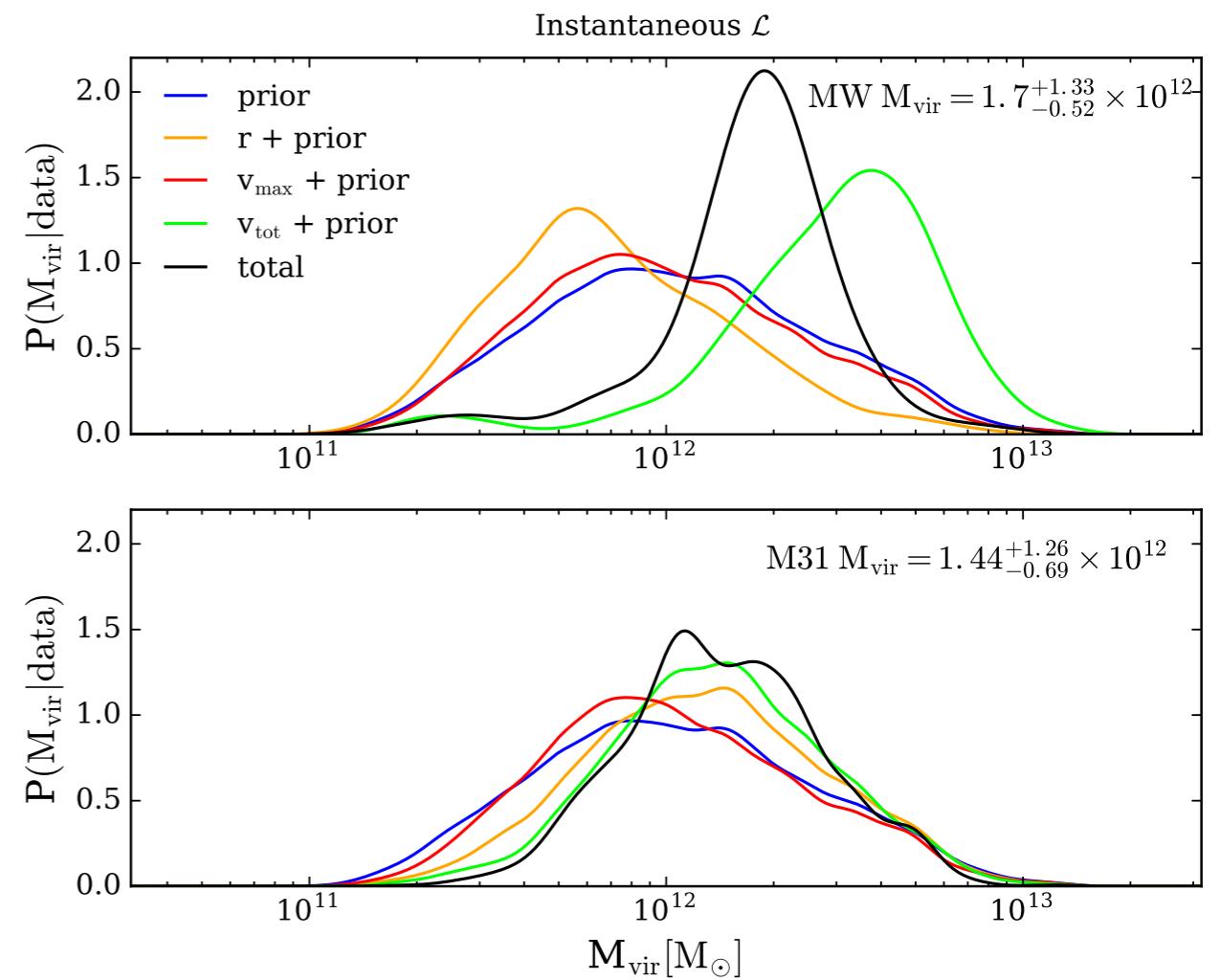
Illustris
Cosmological Simulation of
Galaxy Formation

Today: Astrostatistics Case Study 3:

Bayesian estimates of the Milky Way and Andromeda masses using high-precision astrometry and cosmological simulations (Patel et al. 2017, arXiv:1703.05767)



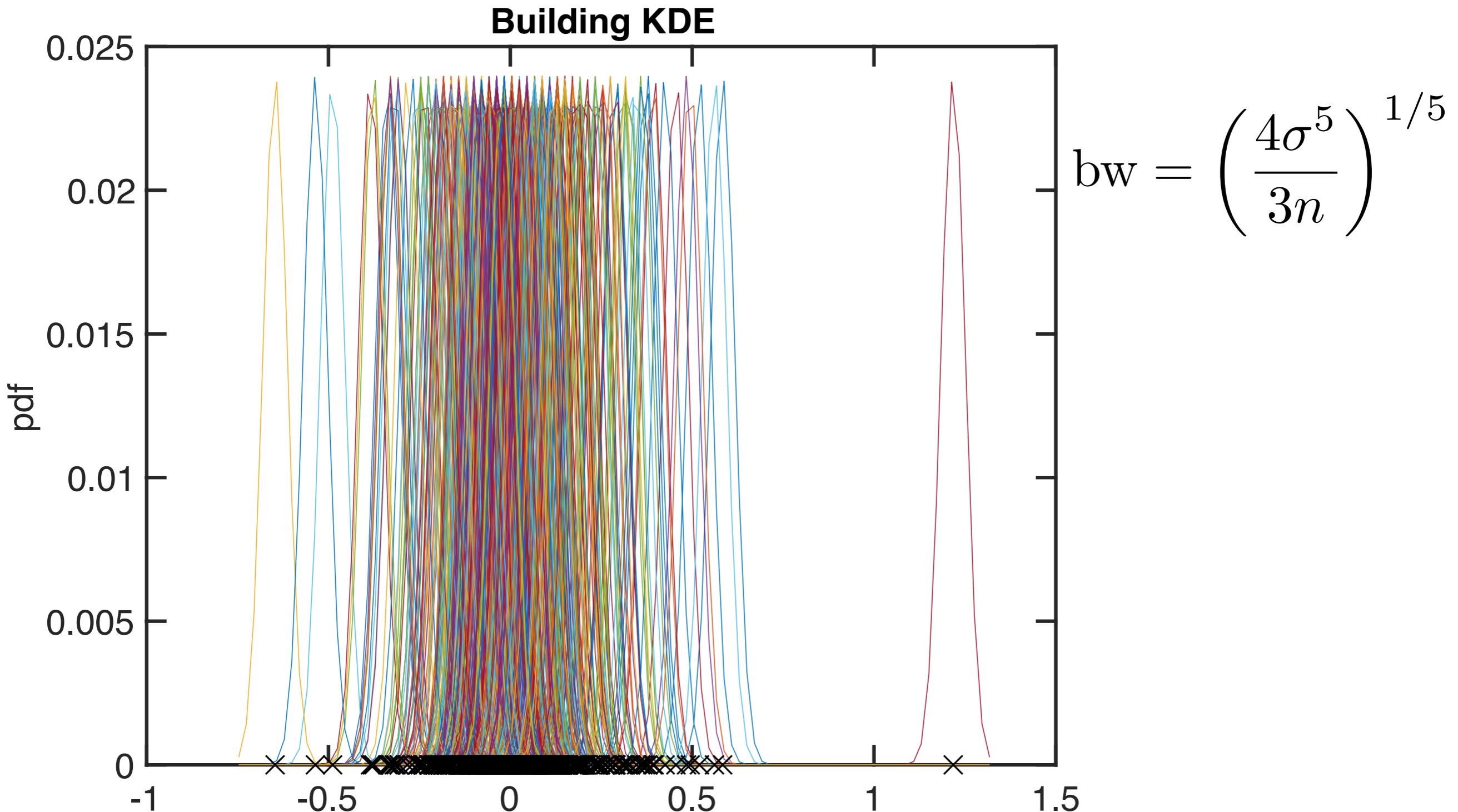
Simulation \rightarrow Prior



- Bayesian Inference
- Importance Sampling
- Kernel Density Estimation

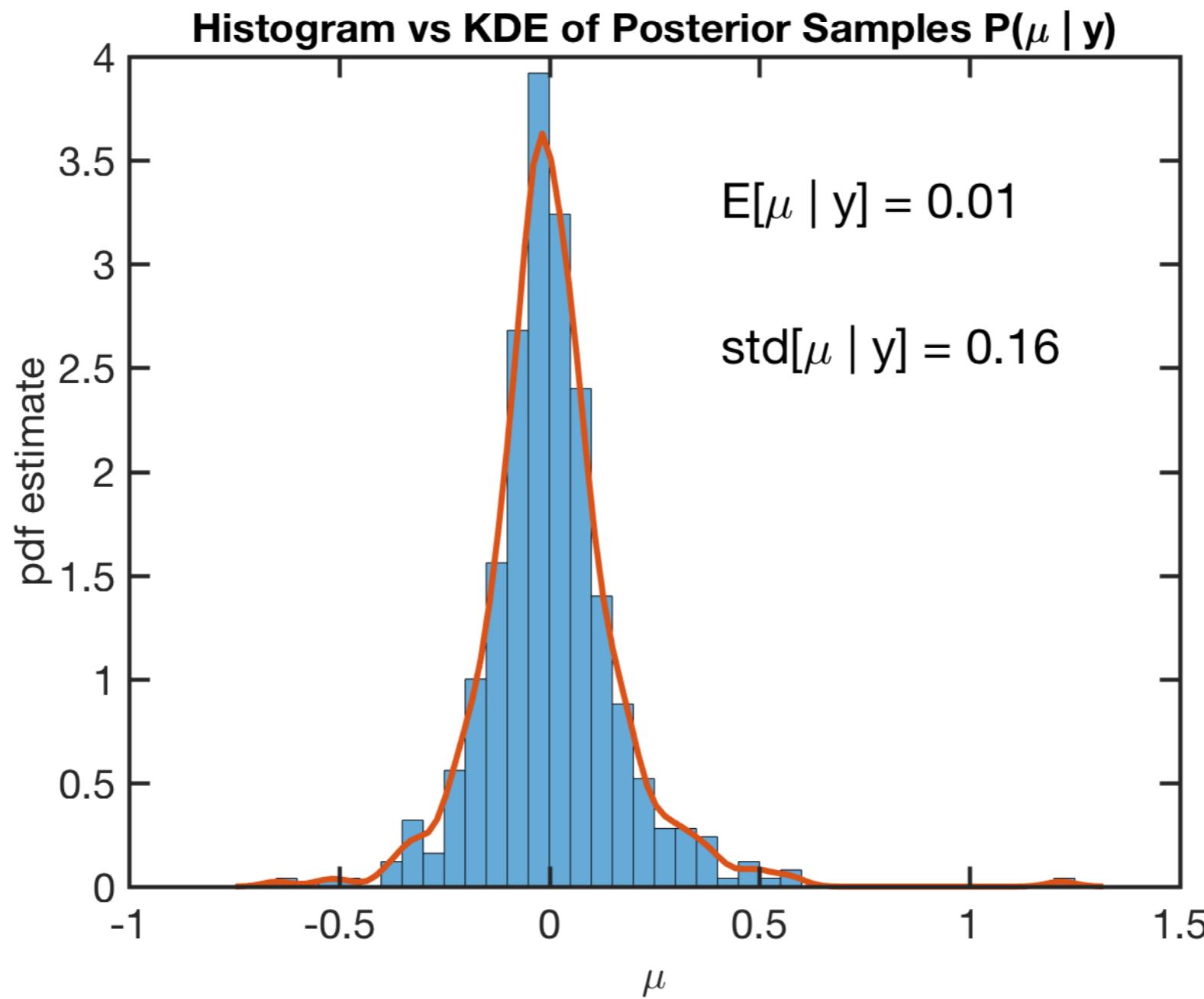
Kernel Density Estimation (KDE) (Smooth Histogram)

Each sample gets a Gaussian at the sample point
with an “optimal” bandwidth bw (rule of thumb)



Kernel Density Estimation (KDE) (Smooth Histogram)

Then add them up and normalise pdf to 1



Weighted KDE

$$\text{wkde}(\theta) = \sum_{s=1}^m w_s \times N(\theta | \theta_s, \text{bw})$$

Silverman's Rule of Thumb: $\text{bw} = \left(\frac{4\sigma^5}{3n} \right)^{1/5}$

if equal weights: $w_i = 1/m$

$$\text{kde}(\theta) = \frac{1}{m} \sum_{s=1}^m N(\theta | \theta_s, \text{bw})$$

What if you can't directly sample the posterior: $\theta_i \sim P(\theta | D)$?

$$\mathbb{E}[f(\theta) | D] = \int f(\theta) P(\theta | D) d\theta \approx \frac{1}{m} \sum_{i=1}^m f(\theta_i)$$

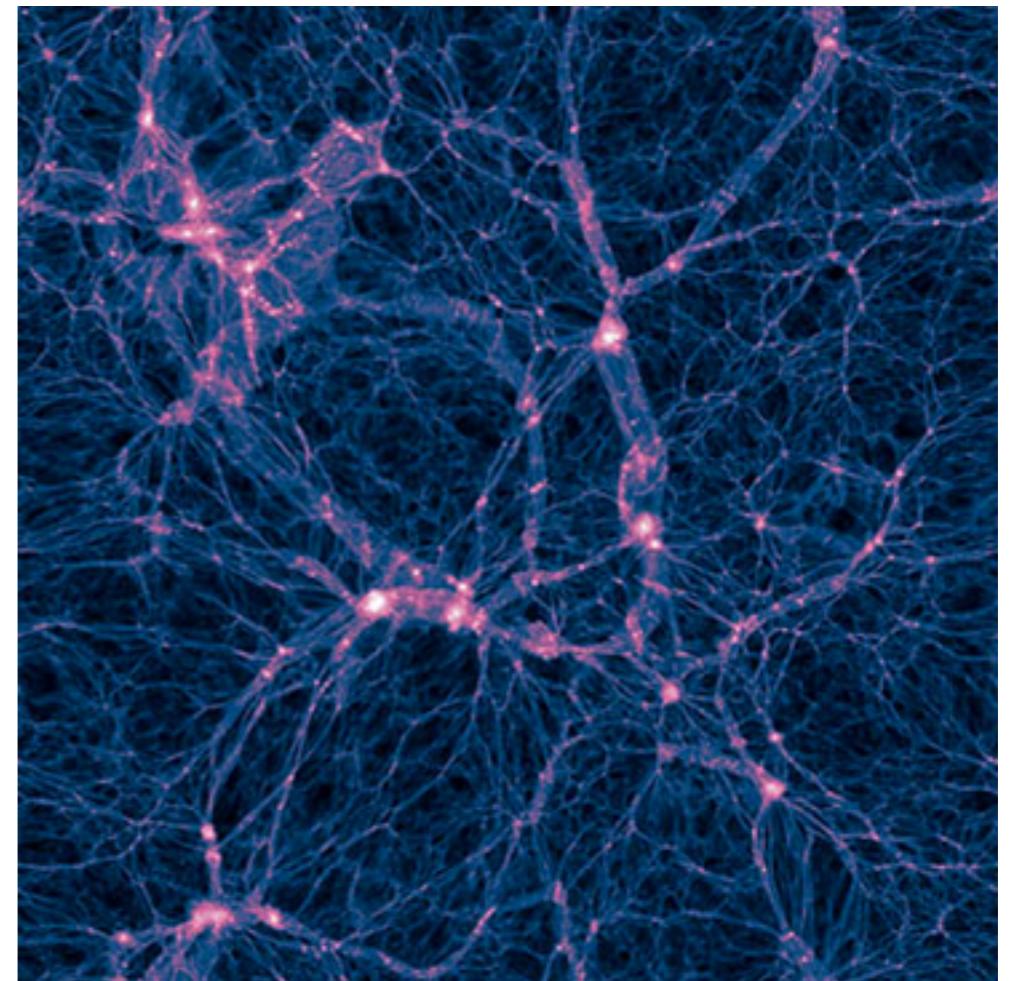
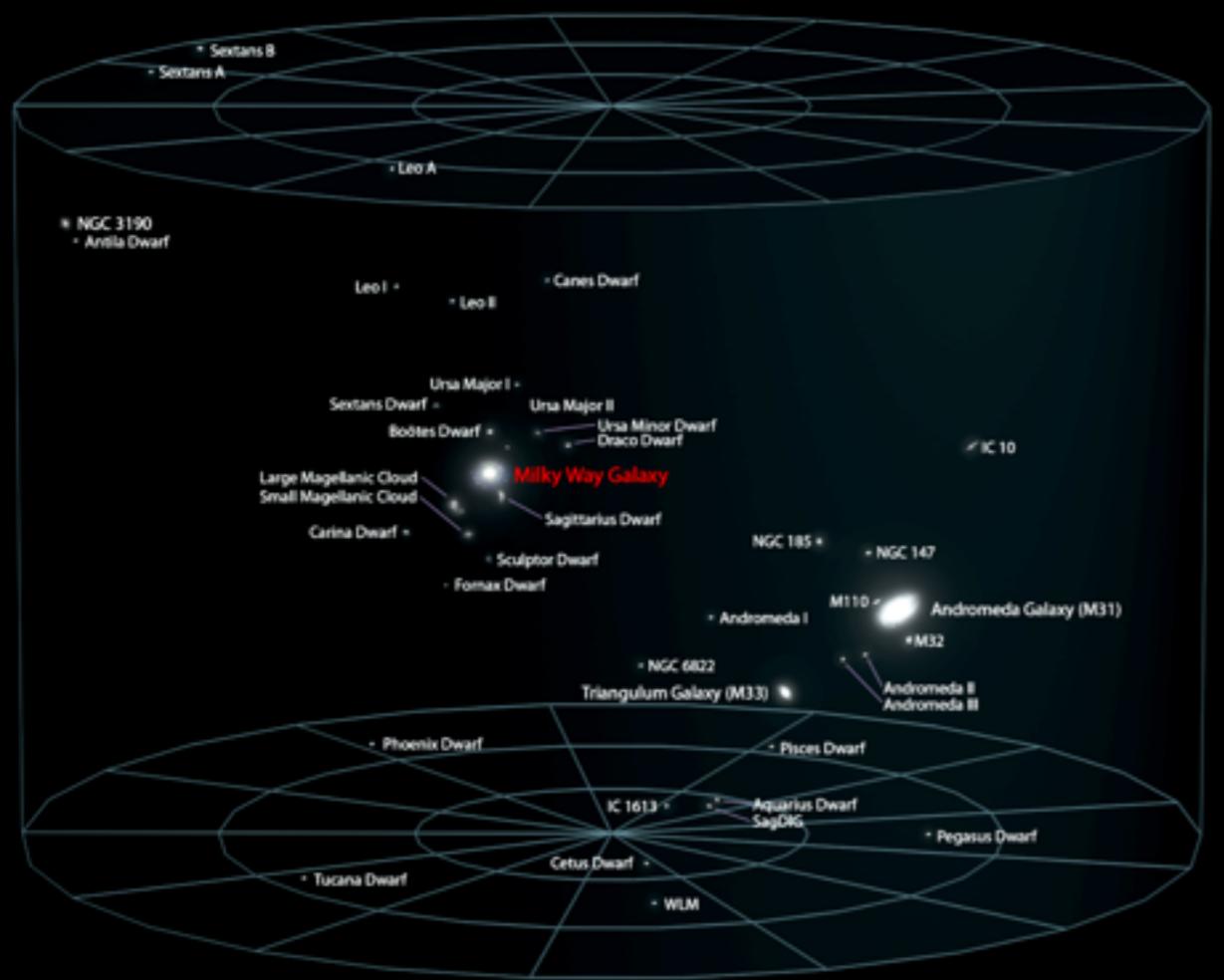
- Posterior simulation - Markov Chain Monte Carlo, Nested Sampling, etc. generates draws
- Importance Sampling - draw from an easier (“tractable”) distribution $\theta_i \sim Q(\theta)$ and weight the samples by $w_i = P(\theta_i | D) / Q(\theta_i)$

$$\int f(\theta) P(\theta | D) d\theta = \int f(\theta) \frac{P(\theta | D)}{Q(\theta)} Q(\theta) d\theta \approx \frac{1}{m} \sum_{i=1}^m f(\theta_i) w_i$$

Now: Astrostatistics Case Study 3:

Bayesian estimates of the Milky Way and Andromeda masses using high-precision astrometry and cosmological simulations
(Patel, Besla & Mandel, MNRAS 468, 3428, arXiv:1703.05767)

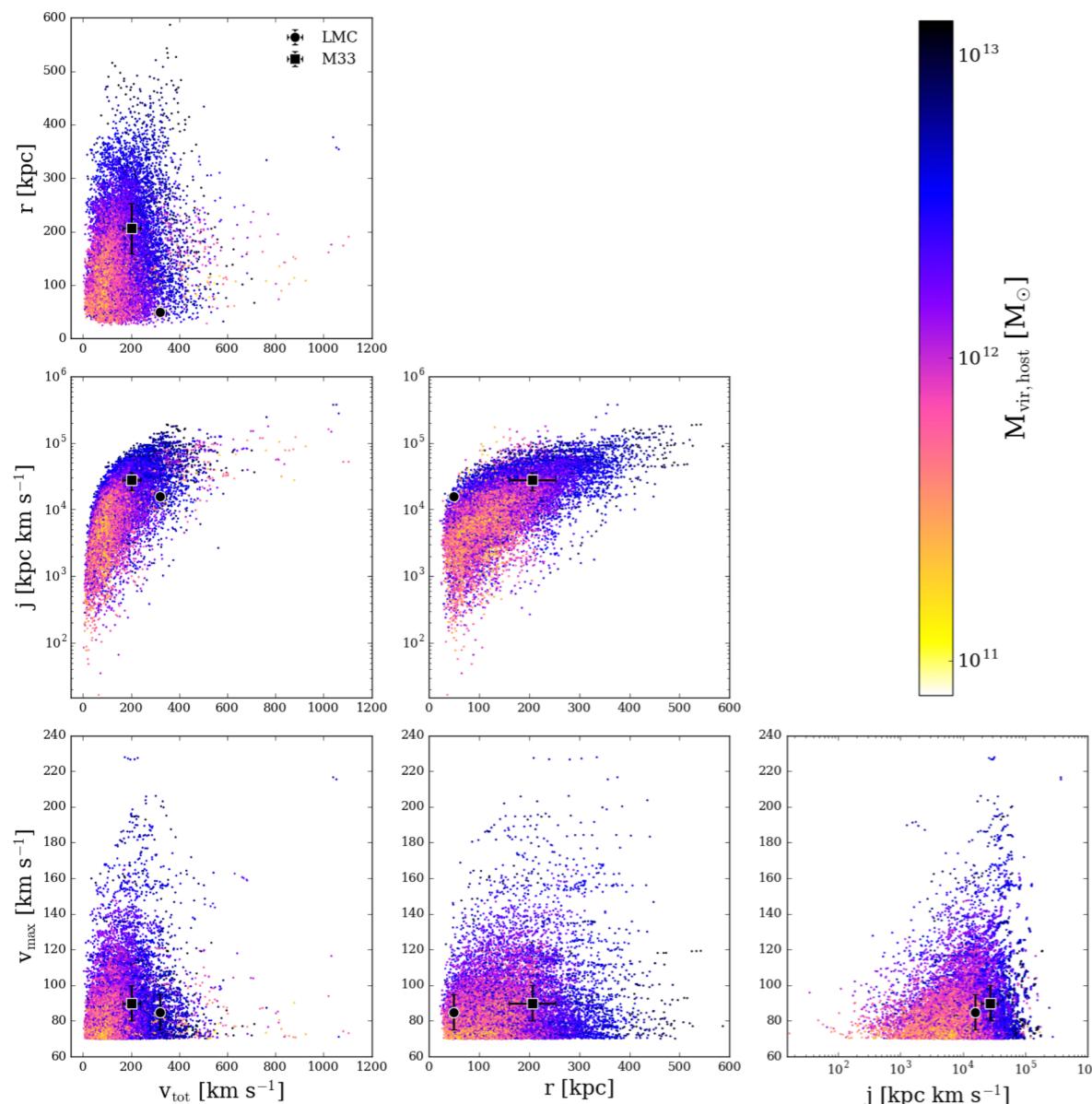
Local Galactic Group



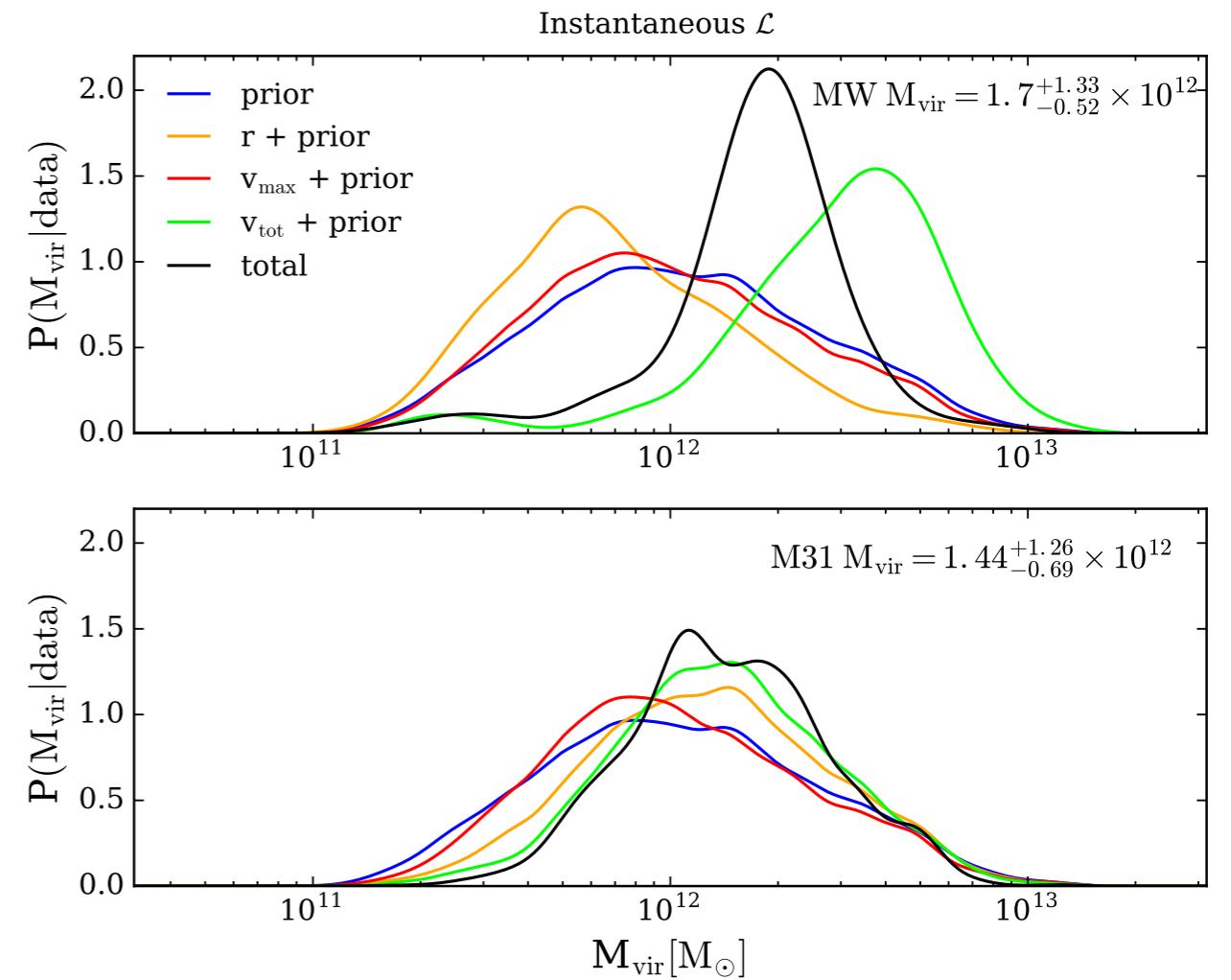
Illustris
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Now: Astrostatistics Case Study 3:

Bayesian estimates of the Milky Way and Andromeda masses using high-precision astrometry and cosmological simulations (Patel et al. 2017, arXiv:1703.05767)

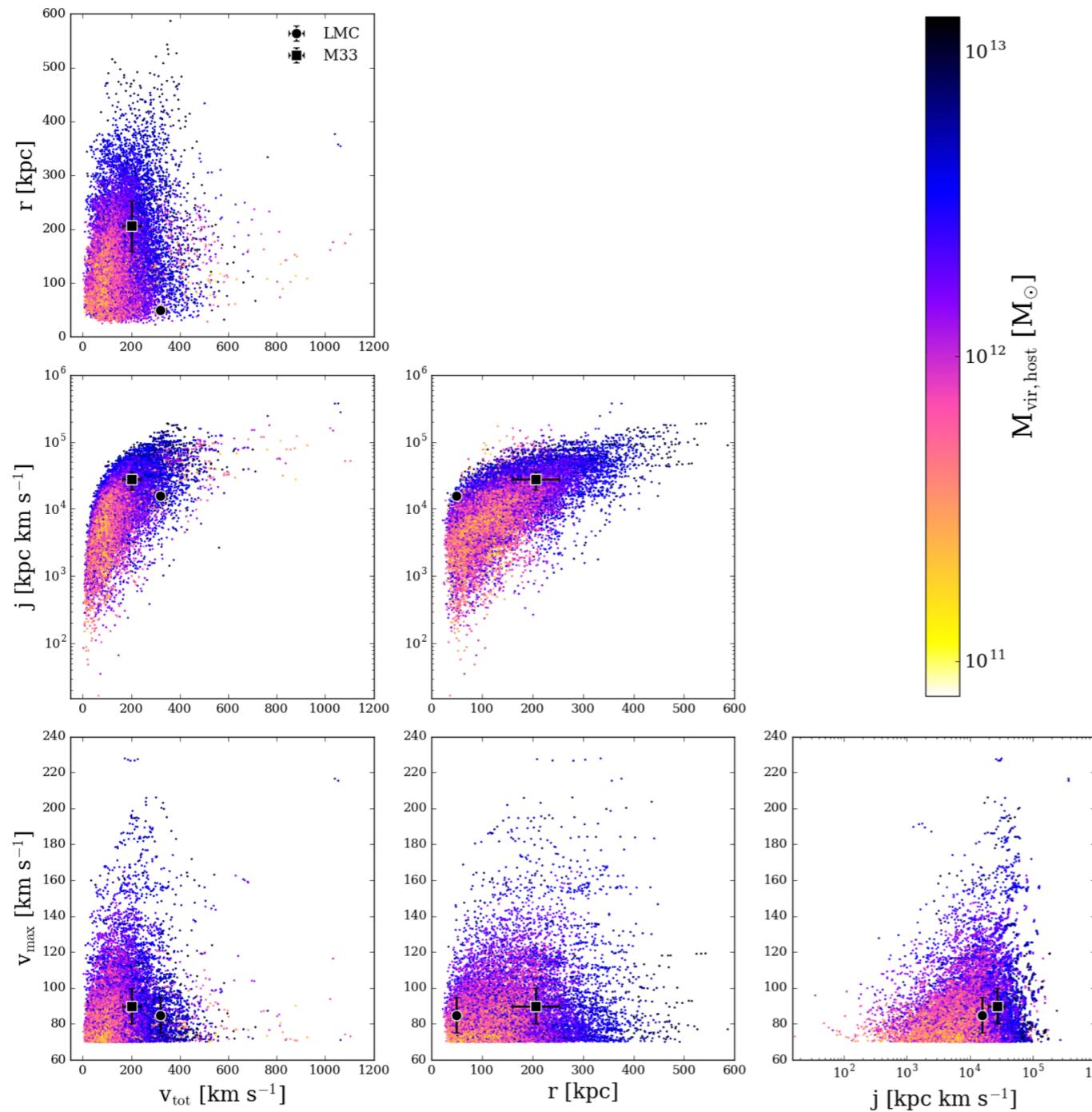


Simulation \rightarrow Prior



- Bayesian Inference
- Importance Sampling
- Kernel Density Estimation

Velocities (v), positions (r), momenta (j),
of satellites are correlated with mass via
galaxy formation physics in simulations (Prior)



x = latent (true) values
of v , r , j

M_{vir} = Mass of Galaxy

Parameters are:
 $\theta = (x, M_{\text{vir}})$

We can measure the (v , r , j) of MW's biggest satellite, Large Magellanic Cloud (LMC)

Table 1. Observational data (\mathbf{d}) for the LMC and M33 used to build likelihoods in the Bayesian inference scheme include the maximum circular velocity, current separation from the host galaxy and total velocity relative to the host galaxy.

	LMC μ	LMC σ	M33 μ	M33 σ
v_{\max}^{obs} (km s $^{-1}$)	85 ^a	10	90 ^b	10
r^{obs} (kpc)	50	5	203	47
$v_{\text{tot}}^{\text{obs}}$ (km s $^{-1}$)	321	24	202	38
j^{obs} (kpc km s $^{-1}$)	15 688	1788	27 656	8219

Notes. ^aThe maximal circular velocity of the LMC's halo rotation curve is adopted from Besla et al. (2012).

^bM33's halo rotation curve maximum is duplicated from van der Marel et al. (2012b).

M33's position, velocity and their errors are adopted from Paper I (table 1), and references within.

$$\mathcal{L}(\mathbf{x}|\mathbf{d}) = N(v_{\max}^{\text{obs}}|v_{\max}, \sigma_v^2) \times N(r^{\text{obs}}|r, \sigma_r^2) \times N(v^{\text{obs}}|v_{\text{tot}}, \sigma_v^2), \quad (8)$$

where

$$N(y|\mu, \sigma) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp \left[\frac{-(y-\mu)^2}{2\sigma^2} \right] \quad (9)$$

How do we combine these measurements (likelihood) with the joint prior on $P(v, r, j, M)$ from the Simulations?

d = measurements
 x = latent (true) values
 M_{vir} = Mass of Galaxy

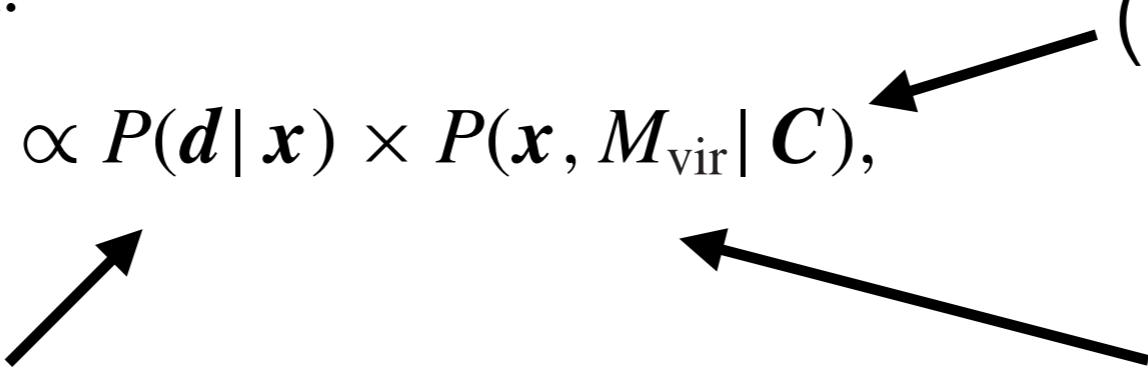
3.2.3 *Importance sampling*

Now that the prior and likelihood have been defined, we return to Bayes' theorem:

$$P(x, M_{\text{vir}} | d, C) \propto P(d | x) \times P(x, M_{\text{vir}} | C), \quad (11)$$

(Ignore C)

Likelihood (observations) Prior (samples from Simulation)



Importance Sampling

Parameters are: $\theta = (\mathbf{x}, M_{\text{vir}})$

measured data are: \mathbf{d}

Expectations of functions of the physical parameters under the posterior PDF are approximated as sums over the n samples as follows:

$$\begin{aligned} \int f(\boldsymbol{\theta}) P(\mathbf{x}, M_{\text{vir}} | \mathbf{d}, \mathbf{C}) d\boldsymbol{\theta} &= \frac{\int f(\boldsymbol{\theta}) P(\mathbf{d} | \mathbf{x}) P(\mathbf{x}, \underline{M}_{\text{vir}} | \mathbf{C}) d\boldsymbol{\theta}}{\int P(\mathbf{d} | \mathbf{x}) P(\mathbf{x}, M_{\text{vir}} | \mathbf{C}) d\boldsymbol{\theta}} \\ &\approx \frac{\sum_j^n f(\boldsymbol{\theta}_j) P(\mathbf{d} | \mathbf{x}_j)}{\sum_j^n P(\mathbf{d} | \mathbf{x}_j)}. \end{aligned} \quad (12)$$

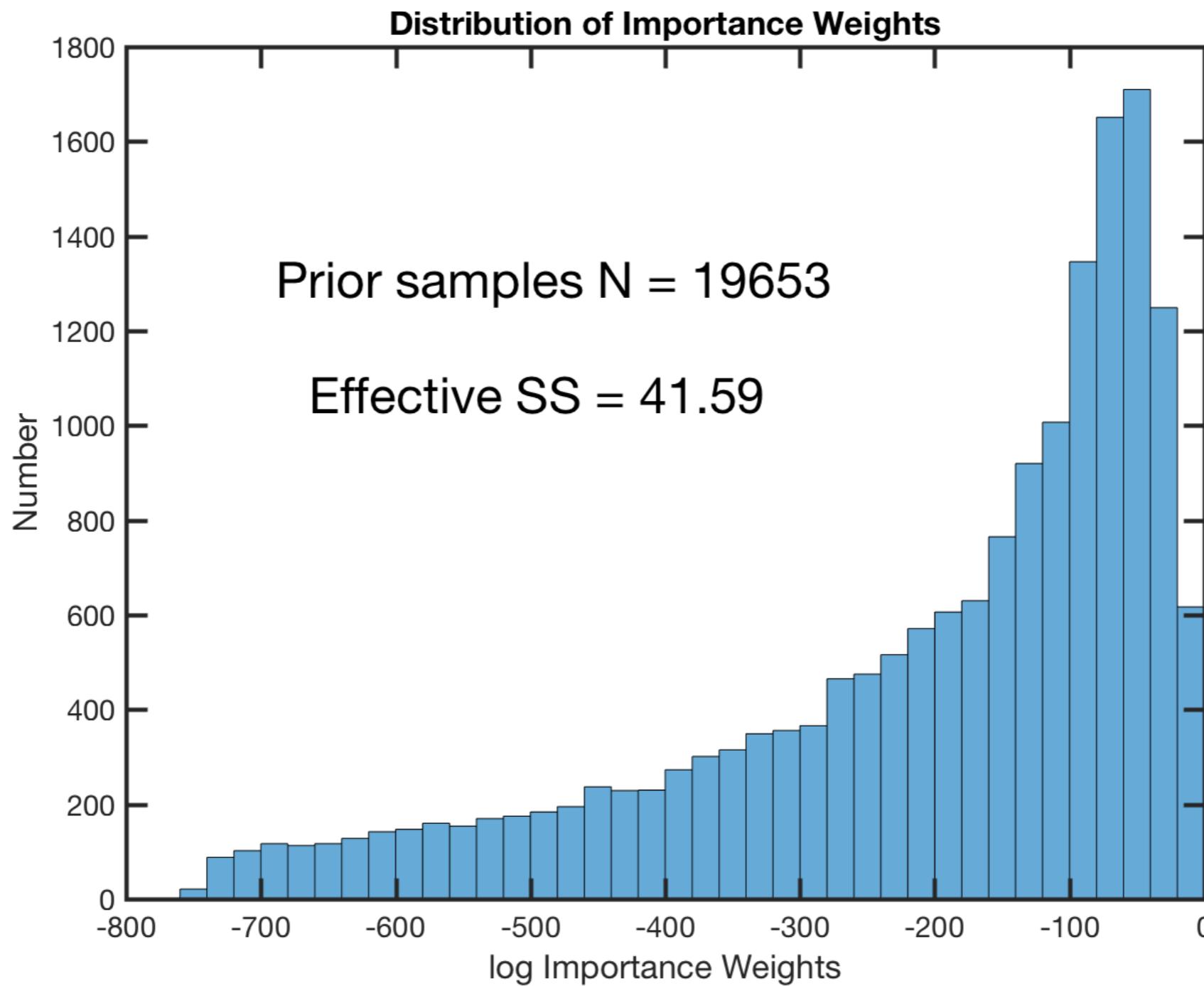
The denominator of this equation is the normalization constant. If

Importance Sampling

$$\begin{aligned} & \int f(M_{\text{vir}}) P(M_{\text{vir}} | \mathbf{d}, \mathbf{C}) dM_{\text{vir}} \\ &= \int f(M_{\text{vir}}) P(\mathbf{x}, M_{\text{vir}} | \mathbf{d}, \mathbf{C}) d\mathbf{x} dM_{\text{vir}} \\ &\approx \frac{\sum_j^n f(M_{\text{vir}}^j) P(\mathbf{d} | \mathbf{x}_j)}{\sum_j^n P(\mathbf{d} | \mathbf{x}_j)} \\ &= \sum_j^n f(M_{\text{vir}}^j) w_j, \end{aligned}$$

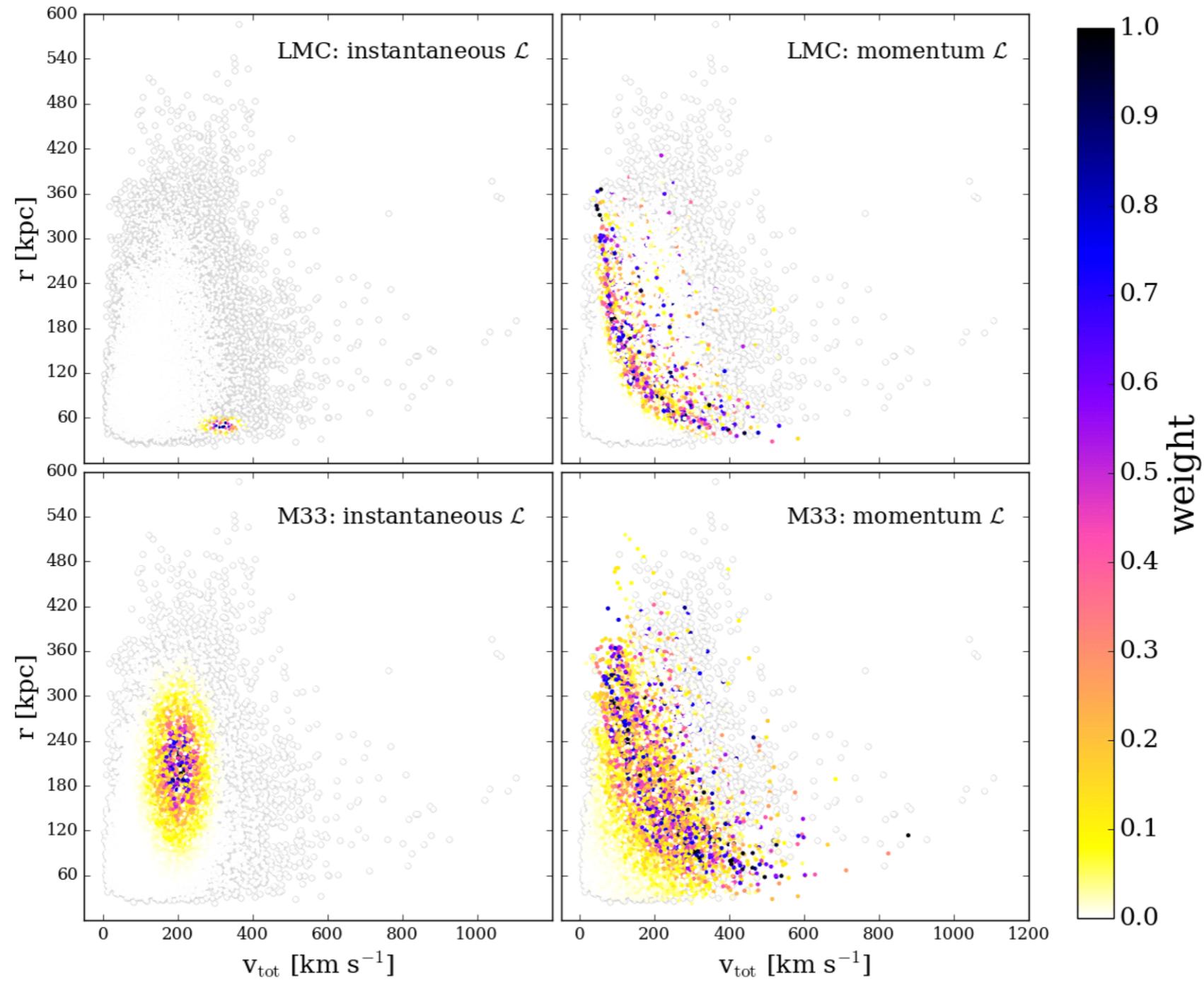
where $w_i = P(\mathbf{d} | \mathbf{x}_i) / \sum_j^n P(\mathbf{d} | \mathbf{x}_j)$ are importance weights.

Run code demonstration

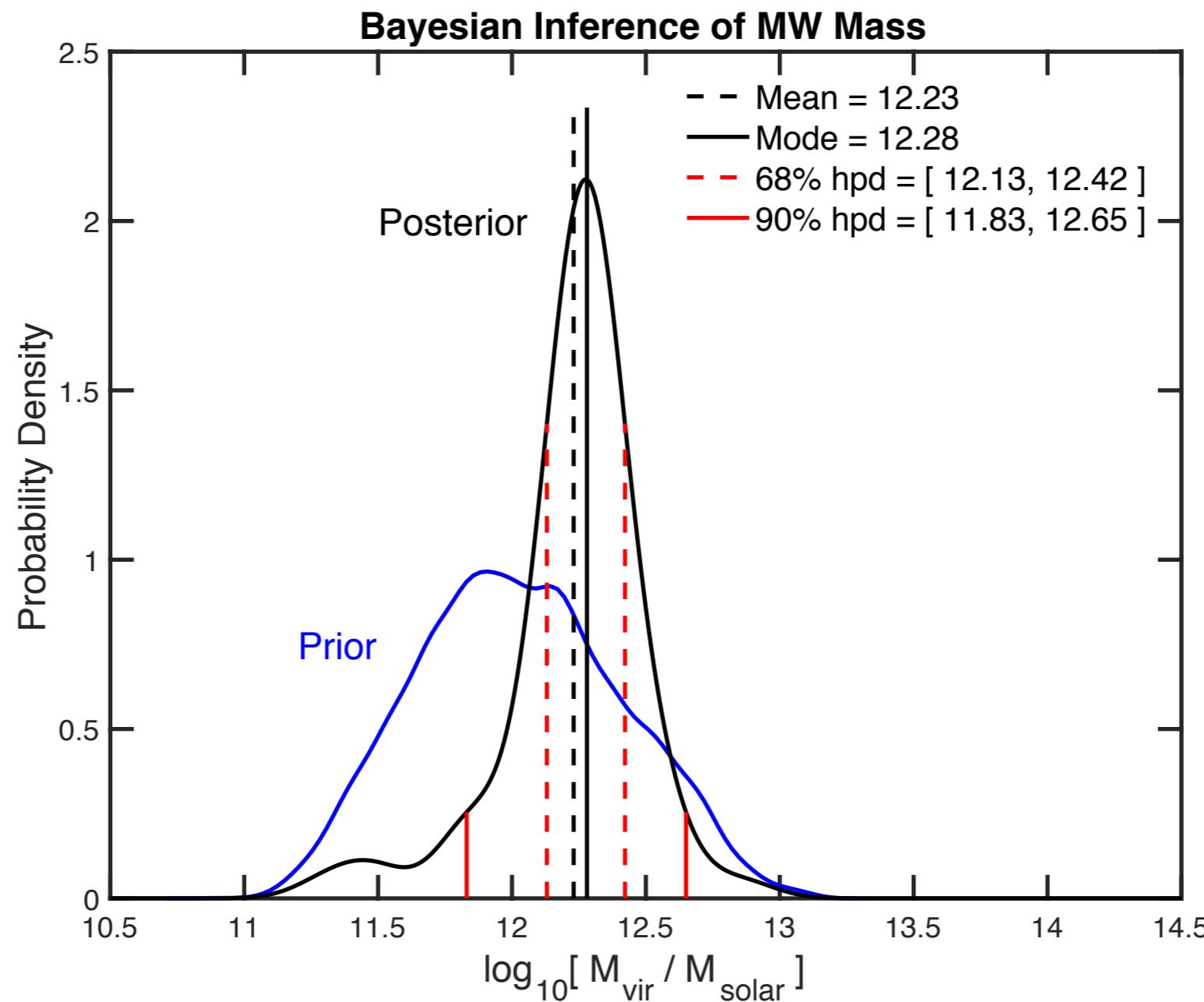


Distribution of Importance Weights

Distribution of Importance Weights



Code Demo: Posterior using weighted KDE



$x\%$ HPD = Highest Posterior Density $x\%$ credible region
= interval(s) with highest density containing $x\%$ of posterior

Bayesian estimates of the Milky Way and Andromeda masses using high-precision astrometry and cosmological simulations

Posterior Density of Milky Way Galaxy Mass with KDE

