

THE KNIGHT'S TOUR : A BACKTRACKING APPROACH

Exploring the Pathways of Chess through Algorithmic Moves

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Introduction to the Knight's Tour Problem

The Knight's Tour is a mathematical puzzle involving a knight on a chessboard.

The goal is for the knight to visit every square on the $N \times N$ chessboard exactly once without repeating any square.

It is typically posed on an $N \times N$ board (e.g., the classic 8×8 chessboard), but it can be solved on boards of any size.



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Overview of the Problem

Objective: The Knight's Tour problem requires the knight to visit every square on an $N \times N$ chessboard exactly once.

The Knight's Tour is a classic example of a pathfinding problem and can be solved using backtracking.

Backtracking is particularly useful here as it allows exploring possible paths while discarding those that lead to dead ends.



Historical Background

- **Ancient Origins**

The problem dates back to the 9th century in India and Persia, initially as a chess strategy exercise.

- **Medieval Popularity**

Spread through Asia and Europe, becoming a common intellectual puzzle among scholars and nobility.

- **Euler's Contributions (18th Century)**

Mathematician Leonhard Euler formally studied the Knight's Tour, introducing concepts of "closed tours" and laying the groundwork for graph theory.

- **Modern Significance**

Now a classic example in computer science, demonstrating backtracking, recursion, and combinatorial optimization in AI, robotics, and pathfinding.



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Defining the Knight's Tour Problem

Understanding the Knight's movement and the specific rules governing the Knight's Tour is essential for solving this intriguing chess problem.

Knight's Movement

Knight's Unique Movement:

- The knight moves in an "L" shape:
- Two squares in one direction (vertically or horizontally)
- and then one square perpendicular, or
- One square in one direction and then two squares perpendicular.

Key Characteristics

- **Jumping Ability:** Unlike other chess pieces, the knight can jump over other pieces, moving directly to its destination.
- **Eight Possible Moves:** From any position, a knight can typically make up to eight moves
- **Restricted Mobility:** The knight's movement is limited to specific squares, impacting its accessibility across the board.



Approaches:

Brute-Force Approach : Explore all possible knight moves until a valid path is found.

Backtracking Algorithm: Recursive method that explores paths and backtracks when a dead-end is reached.

Warnsdorff's Rule (Heuristic Approach): Prioritize moves to squares with fewer onward moves, improving path efficiency.

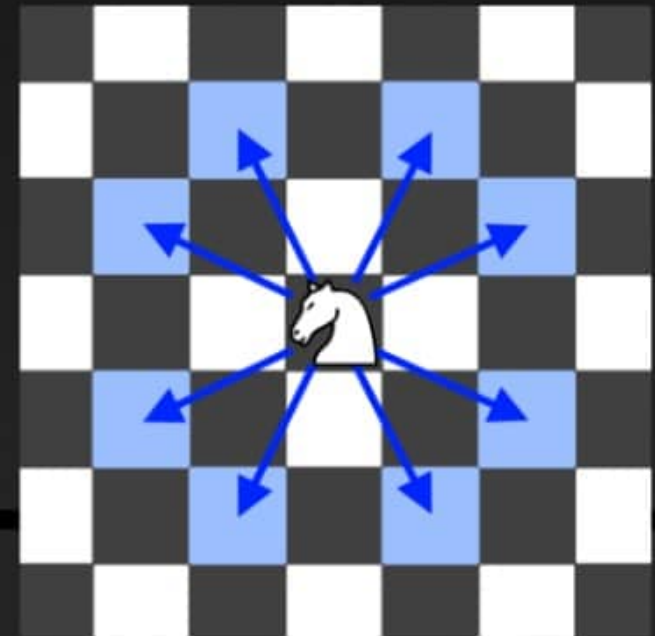
Backtracking with Warnsdorff's Rule: Combines backtracking with Warnsdorff's heuristic to optimize the solution.

Dynamic Programming (Alternative Method): Used in variations where overlapping subproblems can be stored and reused.

Graph Theory Approach: Framed as a Hamiltonian path problem where each square is a node, and a move is an edge.



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Backtracking

an algorithmic technique for solving problems by incrementally building solutions and abandoning partial solutions when they are found to be invalid.

Backtracking

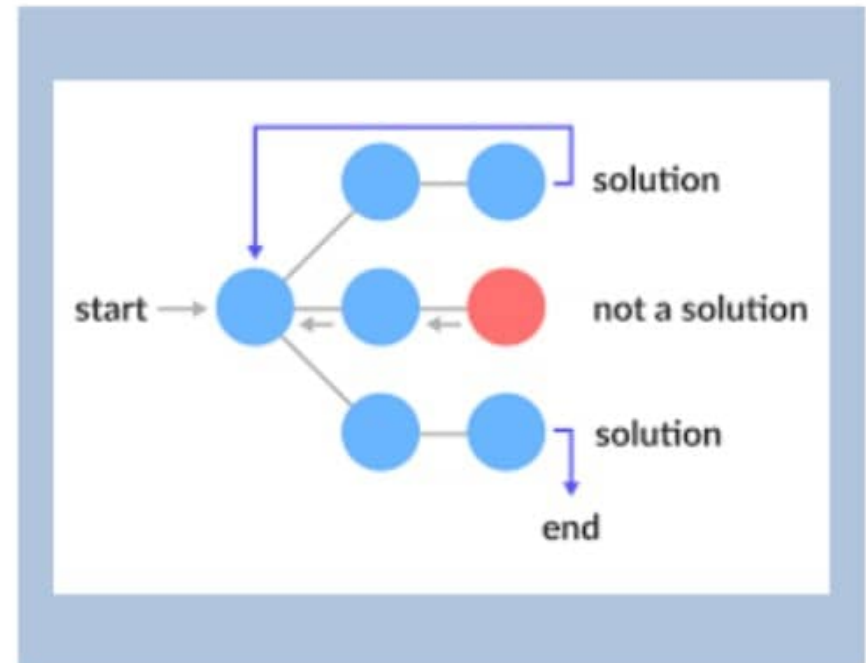
- Backtracking is a problem-solving algorithmic technique used to find solutions to problems by exploring all possible options and undoing choices when they lead to dead ends.
- It is a refinement of brute-force search that involves building solutions step by step and backtracking when a solution path is found to be invalid.

How Backtracking Works :

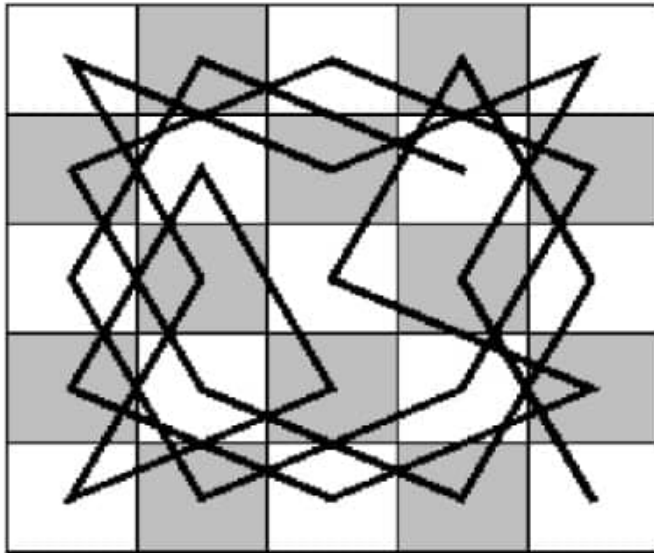
- Recursive Nature: Backtracking typically involves a recursive approach where each step tries to build upon the previous step. If the current path does not lead to a solution, the algorithm backtracks to the previous state and tries another path.
- Pruning Invalid Paths: The main idea is to stop pursuing certain branches of a decision tree when they are found to be unpromising or invalid, thereby saving computational time.

Backtracking in the Knight's Tour

- In the Knight's Tour problem, backtracking allows us to explore potential moves for the knight and abandon paths that do not lead to a solution (i.e., paths where the knight cannot visit all squares).



Algorithm



Check if All Squares are Visited:

- If yes, print the solution.

Recursive Exploration:

- If not all squares are visited:
 - Try Next Move:
 - Add one of the next possible moves to the solution vector.
 - Recursively check if this move leads to a solution (choose one of the 8 possible knight moves).
 - Backtrack if Invalid:
 - If the current move doesn't lead to a solution, remove it from the solution vector and try another move.
 - Return False if No Move Works:
 - If no alternative moves are valid, return false (indicating no solution from the current path).

Base Case:

- If recursion returns false, backtrack and explore previous moves. If no solution exists, display "No solution exists".



The background image shows a blurred view of a code editor. On the left, a file explorer sidebar is visible with folders like 'lib' and 'spec'. The main editor area displays Ruby code with syntax highlighting. Line numbers 7 through 21 are visible on the left margin. The code includes 'require' statements for 'copybara/rspec' and 'copybara/rella', followed by configuration for 'Copybara.javascript_driver', 'Category.delete_all', 'Shoulda: Matchers.configure', 'config.integrate', 'with.test_framework', and 'with.library :rella'.

CODE SNIPPETS

Key code snippets demonstrating the core components of the backtracking algorithm for problem-solving.

Code:

Checking Valid Moves:

```
def isValid(x, y, board):  
    return 0 <= x < N and 0 <= y < N  
    and board[x][y] == -1
```

Initialization and Starting the Knight's Tour:

```
def solveKT():  
    board = [[-1 for _ in range(N)] for _ in range(N)]  
    xMove = [2, 1, -1, -2, -2, -1, 1, 2]  
    yMove = [1, 2, 2, 1, -1, -2, -2, -1]  
    board[0][0] = 0  
  
    if not solveKTUtil(0, 0, 1, board, xMove, yMove):  
        print("Solution does not exist")  
    else:  
        printSolution(board)
```

Recursive Backtracking Function:

```
def solveKTUtil(x, y, movei, board, xMove, yMove):  
    if movei == N * N:  
        return True  
    for i in range(8):  
        next_x = x + xMove[i]  
        next_y = y + yMove[i]  
        if isValid(next_x, next_y, board):  
            board[next_x][next_y] = movei  
            if solveKTUtil(next_x, next_y, movei + 1, board,  
xMove, yMove):  
                return True  
            board[next_x][next_y] = -1 # Backtracking  
    return False
```



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0	59	38	33	30	17	8	63
37	34	31	60	9	62	29	16
58	1	36	39	32	27	18	7
35	48	41	26	61	10	15	28
42	57	2	49	40	23	6	19
47	50	45	54	25	20	11	14
56	43	52	3	22	13	24	5
51	46	55	44	53	4	21	12

The path followed by Knight to cover all the cells



Performance and Limitations



Time Complexity :

There are N^2 Cells and for each, we have a maximum of 8 possible moves to choose from, so the worst running time is $O(8N^2)$.

Auxiliary Space: $O(N^2)$

Efficiency: Works well for smaller problem sizes or problems with many constraints that help prune invalid paths early.



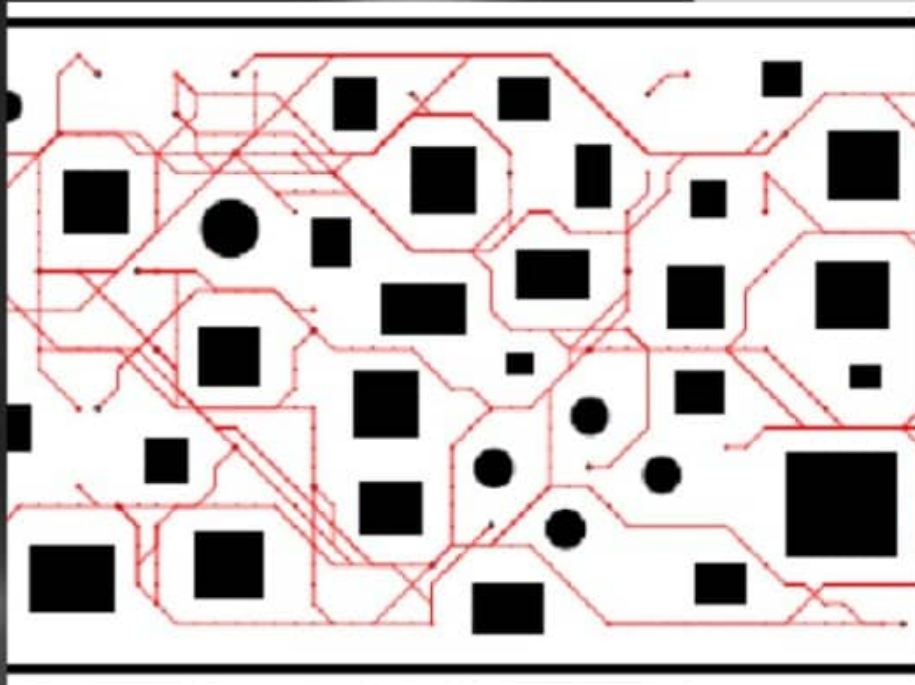
High Computational Cost: The exponential time complexity makes backtracking impractical for large chessboards, leading to long processing times.

Inefficiency in Larger Searches: With no inherent optimization, backtracking explores many dead-end paths, resulting in redundant calculations.

Memory Usage: Recursive calls in backtracking can lead to high memory consumption, especially for larger values of N



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Applications

- Testing and Benchmarking Algorithms
- AI and Game Development
- Robotic Path Planning
- Network Traversal and Graph Theory
- Computer Graphics and Image Processing
- Puzzle and Maze Design

Challenges of the Knight's Tour on Larger Chess Boards

Exponential Growth:

As the size of the chessboard increases (e.g., 16x16, 32x32), the number of possible paths grows exponentially. For an $N \times N$ board, there can be up to $O(8^N)$ possible moves, making exhaustive search highly impractical.

Backtracking Limitations:

- **Computational Time:** The backtracking approach involves exploring all possible moves, which is manageable for smaller boards but becomes excessively time-consuming on larger boards due to the sheer number of recursive calls.
- **Memory Usage:** Recursive backtracking on larger boards consumes a significant amount of memory. Each call adds to the call stack, which can lead to stack overflow on very large boards.

Increased Dead-Ends:

Path Complexity: As board size grows, the knight is more likely to encounter paths that do not cover all squares, leading to increased dead-ends and repeated backtracking. This creates inefficient paths and longer search times.



Alternative Solutions:

Heuristics: Techniques like Warnsdorff's Rule can prioritize moves, reducing unnecessary backtracking.

Heuristic Search Algorithms: Algorithms such as genetic algorithms or simulated annealing can offer faster, though not guaranteed, solutions for larger boards.

Approximation Methods: For very large boards, approximate solutions may be more feasible than exhaustive backtracking, especially when perfect coverage isn't essential.



Conclusion

- The Knight's Tour problem using backtracking showcases an elegant but computationally expensive solution for small to moderate-sized boards (up to 8×8).
- While backtracking explores all possible moves, its exponential time complexity makes it impractical for larger boards.
- Optimizations like Warnsdorff's Rule can improve efficiency, but for very large boards, alternative methods such as heuristic algorithms may be required.
- Despite these challenges, the Knight's Tour remains a valuable problem in AI, robotics, and optimization, highlighting the importance of backtracking and the need for optimization in real-world applications.



THANK YOU

