```
from __future__ import division
import random
import math
# function we are attempting to optimize (minimize)
def func1(x):
  total=0
  for i in range(len(x)):
    total+=x[i]**2
  return total
class Particle:
  def __init__(self,x0):
    self.position_i=[] # particle position
    self.velocity_i=[] # particle velocity
    self.pos_best_i=[] # best position individual
    self.err_best_i=-1 # best error individual
    self.err_i=-1 # error individual
    for i in range(0,num_dimensions):
      self.velocity_i.append(random.uniform(-1,1))
      self.position_i.append(x0[i])
  # evaluate current fitness
  def evaluate(self,costFunc):
    self.err_i=costFunc(self.position_i)
    # check to see if the current position is an individual best
    if self.err_i < self.err_best_i or self.err_best_i==-1:</pre>
      self.pos_best_i=self.position_i
      self.err_best_i=self.err_i
  # update new particle velocity
  def update_velocity(self,pos_best_g):
    w=0.5 # constant inertia weight (how much to weigh the previous velocity)
    c1=1 # cognative constant
    c2=2 # social constant
    for i in range(0,num_dimensions):
      r1=random.random()
      r2=random.random()
      vel_cognitive=c1*r1*(self.pos_best_i[i]-self.position_i[i])
      vel_social=c2*r2*(pos_best_g[i]-self.position_i[i])
      self.velocity_i[i]=w*self.velocity_i[i]+vel_cognitive+vel_social
  # update the particle position based off new velocity updates
  def update_position(self,bounds):
    for i in range(0, num dimensions):
      self.position_i[i]=self.position_i[i]+self.velocity_i[i]
      # adjust maximum position if necessary
      if self.position_i[i]>bounds[i][1]:
        self.position i[i]=bounds[i][1]
      # adjust minimum position if neseccary
      if self.position_i[i] < bounds[i][0]:</pre>
```

```
class PSO():
  def __init__(self,costFunc,x0,bounds,num_particles,maxiter):
    global num_dimensions
    num_dimensions=len(x0)
    err_best_g=-1 # best error for group
    pos_best_g=[] # best position for group
    # establish the swarm
    swarm=[]
    for i in range(0,num_particles):
      swarm.append(Particle(x0))
      # begin optimization loop
      i=0
    while i < maxiter:
      #print i,err_best_g
      # cycle through particles in swarm and evaluate fitness
      for j in range(0,num_particles):
        swarm[j].evaluate(costFunc)
      # determine if current particle is the best (globally)
        if swarm[j].err_i < err_best_g or err_best_g == -1:</pre>
          pos_best_g=list(swarm[j].position_i)
          err_best_g=float(swarm[j].err_i)
        # cycle through swarm and update velocities and position
      for j in range(0,num_particles):
        swarm[j].update_velocity(pos_best_g)
        swarm[j].update position(bounds)
      i+=1
    # print final results
    print('FINAL:')
    print(pos_best_g)
    print(err_best_g)
if __name__ == "__PSO__":
  main()
initial=[5,5] # initial starting location [x1,x2...]
bounds=[(-10,10),(-10,10)] # input bounds [(x1_min,x1_max),(x2_min,x2_max)...]
PSO(func1, initial, bounds, num particles=15, maxiter=30)
     FINAL:
     [5.5146783943078154e-05, 0.0001881527978983082]
     3.844264313622616e-08
     <__main__.PSO at 0x7fd4a0148450>
```