1 Environment Dynamics

The stochastic maze environment is shown in the figure. There are a total of 12 states in the environment represented by the indices $\{0,1,...,11\}$. The agent starts in the initial state 0. Four actions are possible in each state: left, right, up, and down. The environment is stochastic and we take the intended action only with a probability p=0.8. We take an orthogonal action with a probability p=0.2. If we collide with the edge of the environment or the wall present in state 5, the agent comes back to the initial state. The transition into the goal state 3 has a +1 reward and transition into the hole state 7 has a -1 reward. All other transitions have a -0.01 reward associated with them.

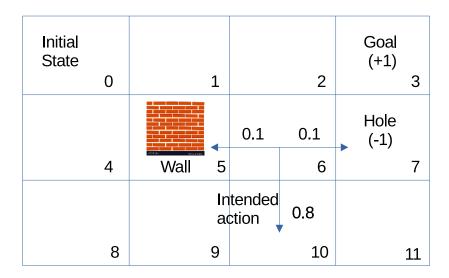


Figure 1: Stochastic Maze Environment

2 Problems

- 1. Implement the environment and check the implementation with some test cases.
- 2. Implements Policy Iteration (PI) and Value Iteration (VI).
- 3. Compare PI and VI in terms of convergence. Is the policy obtained by both same?