

PROBABILITY

RANDOM EXPERIMENT:

- An experiment that can be repeated as many times as wished under identical conditions
- For each trial the outcome of the experiment is not known in advance
- But for each trial, the set of all possible outcomes are known.

Eg: E_1 - Toss a die and observe the number that shows on the top

E_2 - Toss a coin three times and observe the total number of heads obtained.

SAMPLE SPACE:

The set of all possible outcomes of a random experiment. Usually denoted by ' S ' or Ω . Observe that an outcome of an experiment need not be a number also that number of outcomes can be finite, countably infinite or uncountably infinite.

Eg: E_1 - $\{1,2,3,4,5,6\}$

E_2 - $\{1,2,3\}$

EVENT:

An event is simply a set of possible outcomes. In general, it is a subset of the sample space.

Eg: Events that are associated with experiment E_1

A_1 : An even number occurs; that is, $A_1 = \{2,4,6\}$

A_2 : A prime number occurs; that is, $A_2 = \{2,3,5\}$

MUTUALLY EXCLUSIVE EVENTS:

Two events A and B are said to be mutually exclusive if they cannot occur together. This will be expressed as $A \cap B = \emptyset$, that is intersection of A and B is an empty set.

PROBABILITY FUNCTION:

Let ϵ be an experiment. Let S be a sample space associated with ϵ . With each event A we associate a real number, designated by $P(A)$ and called the *probability of A* satisfying the following properties.

- (1) $0 \leq P(A) \leq 1$
- (2) $P(S) = 1$
- (3) If A and B are mutually exclusive events, $P(A \cup B) = P(A) + P(B)$
- (4) If $A_1, A_2, \dots, A_n, \dots$ are pairwise mutually exclusive events, then
$$P(\cup_{i=1}^{\infty} A_i) = P(A_1) + P(A_2) + \dots + P(A_n) + \dots$$

Note:

- If Φ is the empty set, then $P(\Phi) = 0$.
- If \bar{A} is the complementary event of A, then
$$P(\bar{A}) = 1 - P(A).$$
- If A and B are any two events, then
$$P(A \cup B) = P(A) + P(B) - P(A \cap B).$$
- If A, B and C are any three events, then
$$P(A \cup B \cup C) = P(A) + P(B) + P(C) - P(A \cap B) - P(B \cap C) - P(C \cap A) + P(A \cap B \cap C).$$

FINITE SAMPLE SPACE:

A sample space S with finite number of elements i.e., S can be written as $S = \{a_1, a_2, \dots, a_k\}$. To each elementary event $\{a_i\}$, we assign a number p_i , called the probability of $\{a_i\}$, satisfying the following conditions:

- (a) $p_i \geq 0, \quad i = 1, 2, \dots, k.$
- (b) $p_1 + p_2 + \dots + p_k = 1.$

EQUALLY LIKELY OUTCOMES:

If S is a finite sample space, and if all its k outcomes are equally likely, it follows that each $p_i = 1/k$. For the condition $p_1 + p_2 + \cdots + p_k = 1$ becomes $kp_i = 1$ for all i . This follows that for any event A consisting of r outcomes, we have

$$P(A) = r/k.$$

$$P(A) = \frac{\text{number of ways in which } \varepsilon \text{ can occur favorable to } A}{\text{total number of ways in which } \varepsilon \text{ can occur}}$$

CONDITIONAL PROBABILITY:

$P(A/B)$ denotes the probability of occurrence of event A , given that event B occurs. It can be determined that

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

Also observe that the function $P(A/B)$ satisfies all the conditions of a probability function for $P(B) \geq 0$.

BAYES' THEOREM:

Let S be the sample space of a random experiment. Let B_1, B_2, \cdots, B_k be a partition of S by events i.e., they are mutually exclusive to each other. Let A be any event. Then

$$P\left(\frac{B_i}{A}\right) = \frac{P\left(\frac{A}{B_i}\right) P(B_i)}{\sum_{j=1}^k P\left(\frac{A}{B_j}\right) P(B_j)}$$

for all $i = 1, 2, \dots, k$.

INDEPENDENT EVENTS:

Two events A, B are said to be independent if 'the occurrence of one event does not depend on the occurrence of the other'.

So, A and B are independent $\Leftrightarrow P(A/B) = P(A)$ & $P(B/A) = P(B)$.

From above relations it implies that, A and B are *independent* if and only if

$$P(A \cap B) = P(A).P(B)$$

NOTE:

- Three events A, B, C are *independent* if and only if

$$P(A \cap B) = P(A).P(B)$$

$$P(B \cap C) = P(B).P(C)$$

$$P(C \cap A) = P(C).P(A)$$

$$P(A \cap B \cap C) = P(A).P(B).P(C)$$

- If A and B are *independent*, then A, B, A^c, B^c are also independent with respect to each other.

RANDOM VARIABLE:

Let ϵ be an experiment and S be a sample space associated with the experiment. A function X assigning to every element $s \in S$, a real number $X(s)$, is called a *random variable*.

The space R_x , the set of all possible values of X , is called the *range space*.

NOTE:

- If R_x is finite or countably infinite, then X is called *Discrete Random Variable*, otherwise it is called *Continuous Random Variable*.

PROBABILITY DENSITY FUNCTION:

X is said to be a *Continuous Random Variable* if there exists a function f , called the *probability density function (pdf)* of X , satisfying the following conditions:

(a) $f(x) \geq 0$

(b) $\int_{-\infty}^{+\infty} f(x)dx = 1.$

(c) For any a, b , with $-\infty < a < b < +\infty$, we have

$$P(a \leq X \leq b) = \int_a^b f(x)dx$$

CUMULATIVE DISTRIBUTION FUNCTION:

Let X be a random variable, discrete or continuous. The cumulative distribution function $[F(x)]$ is defined as:

$$F(x) = P(X \leq x)$$

NOTE:

- If X is a discrete random variable,

$$F(x) = \sum_j p(x_j),$$

where the sum is taken over all indices j satisfying $x_j \leq x$.

- If X is a continuous random variable with pdf f ,

$$F(x) = \int_{-\infty}^x f(s)ds$$

THEOREM:

- (a) Let F be the cdf of a continuous random variable with pdf f . Then

$$f(x) = \frac{d}{dx} F(x),$$

for all x at which F is differentiable.

- (b) Let X be a discrete random variable with possible values x_1, x_2, \dots , and suppose that it is possible to label these values so that $x_1 < x_2 < \dots$

Let F be the cdf of X . Then

$$p(x_j) = P(X = x_j) = F(x_j) - F(x_{j-1})$$

THEOREM:

Let X be a continuous random variable with pdf ' f ' and cdf ' F '. Let Φ be a map from ' R ' onto $[a, b]$.

Let $Y = \Phi(X)$. Assume that Φ is strictly monotone and differentiable on $[a, b]$. Then the pdf of Y ,

$$g(y) = f(x) \left| \frac{dx}{dy} \right|$$

where $x = \Phi^{-1}(y)$ [or $y = \Phi(x)$].

EXPECTED (MEAN) VALUE and VARIANCE:

- Let X be a discrete random variable with $R_x = \{x_1, x_2, \dots\}$ and probability mass function $p(x_i) = P(X = x_i)$.

Then the *expected value* of X is given by

$$E(X) = \sum_i x_i \cdot p(x_i)$$

And the *variance* of X is given by

$$V(X) = E(X - E(X))^2 = \sum_i (x_i - E(X))^2 p(x_i)$$

- Let X be a continuous random variable with pdf ' f '.

Then the *expected value* of X is given by

$$E(X) = \int_{-\infty}^{+\infty} x f(x) dx$$

And the *variance* of X is given by

$$V(X) = E(X - E(X))^2 = \int_{-\infty}^{+\infty} (x - E(x))^2 f(x) dx$$

NOTE:

- Variance can also be found by using the relation

$$V(X) = E(X^2) - E(X)^2$$

- The *standard deviation* of X is defined as the positive square root of the Variance i.e.,

$$\sigma_x = \sqrt{V(X)}.$$

CHEBYSHEV'S INEQUALITY:

Let X be a random variable and let ' c ' be any constant. Then, for any $\varepsilon > 0$,

$$P(|x - c| \geq \varepsilon) \leq \frac{E[(x - c)^2]}{\varepsilon^2}$$

NOTE:

In the above theorem let $c = \mu = E(X)$, $\sigma^2 = V(X)$ and $\varepsilon = k\sigma$, then

$$P(|X - \mu| \geq k\sigma) \leq 1/k^2$$

MOMENTS AND MOMENT GENERATING FUNCTION:

- The k^{th} moment of a random variable X is : $\mu_k = E(X^k)$
- The Moment Generating Function of a random variable X is

$$M(t) = E(e^{tX})$$

NOTES:

$$M(t) = E\left(1 + tX + \frac{t^2 X^2}{2!} + \cdots + \frac{t^k X^k}{k!} + \cdots\right)$$

$$\Rightarrow M(t) = 1 + tE(X) + \frac{t^2 E(X^2)}{2!} + \cdots + \frac{t^k E(X^k)}{k!} + \cdots$$

Observe that $\frac{d^k M(t)}{dt^k} \Big|_{t=0} = E(X^k) = \mu_k$

TWO-DIMENSIONAL VECTOR:

A pair (X, Y) of random variables is called a Two-dimensional random variable/ vector.

NOTE:

- If the range of (X, Y) is finite and countable, it is called Discrete random variable.
- (X, Y) is called Continuous random variable if there exists a two-dimensional pdf $f=f(x, y)$ such that

$$p(a < X < b, c < Y < d) = \int_{x=a}^b \int_{y=c}^d f(x, y) dx dy$$

Whenever $b > a$ and $d > c$

CUMULATIVE DISTRIBUTION FUNCTION:

If (X, Y) is a two-dimensional random variable, the *joint cdf* of X and Y is:

$$F_{x,y}(x, y) = p(X \leq x, Y \leq y)$$

- Continuous random variable:

$$F_{x,y}(x, y) = \int_{u=-\infty}^x \int_{v=-\infty}^y f(u, v) du dv$$

NOTE:

1) Continuous random variable:

- Marginal pdf of x : $f_X(x) = \int_{-\infty}^{\infty} f(x, y) dy$

- Marginal pdf of x: $f_Y(y) = \int_{-\infty}^{\infty} f(x, y) dx$

2) Discrete random variable:

- Marginal pmf of x: $p_X(x_i) = \sum_j P_{X,Y}(x_i, y_j)$
- Marginal pmf of y: $p_Y(y) = \sum_i P_{X,Y}(x_i, y_j)$

CO-VARIANCE:

The co-variance of the random variable (X,Y) is given by:

$$\begin{aligned} cov(X, Y) &= E[(X - E(X))(Y - E(Y))] \\ &= E(X, Y) - E(X)E(Y) \end{aligned}$$

CAUCHY-SCHWARTZ INEQUALITY:

Continuous case: $|\int \psi \Phi| \leq (\int |\psi|^2)^{1/2} (\int |\Phi|^2)^{1/2}$

Discrete case: $|\sum_{k=1}^n a_k b_k| \leq (\sum_{k=1}^n |a_k|^2)^{1/2} (\sum_{k=1}^n |b_k|^2)^{1/2}$

CO-RELATION COEFFICIENT:

The co-relation coefficient of X and Y is:

$$\rho = \frac{cov(X, Y)}{[var(X)]^{1/2} [var(Y)]^{1/2}}$$

Note: Observe that $|\rho| \leq 1$

CONDITIONAL PROBABILITY:

The conditional pmf of X given Y=y_j is:

$$P_X(x_i | y_j) = P(X=x_i | Y=y_j) = \frac{P(X=x_i, Y=y_j)}{P(Y=y_j)}$$

The conditional pdf of X given Y=y is:

$$f_X(x|y) = \frac{f_{X,Y}(x, y)}{f_Y(y)}$$

Some Standard Distributions

Distribution	PDF	μ	Var
Binomial Distribution	${}^n_k C p^k (1-p)^{n-k}$	np	$np(1-p)$
Poisson Distribution	$\frac{\lambda^x e^{-\lambda}}{x!}$	λ	λ
Gamma Distribution	$\frac{1}{\beta^\alpha \Gamma(\alpha)} x^{\alpha-1} e^{-x/\beta}; \text{ for } x>0$ $0; \text{ otherwise}$	$\alpha\beta$	$\alpha\beta^2$
Exponential Distribution	$\lambda e^{-\lambda x}; \quad x > 0$ $0; \text{ otherwise}$	$1/\lambda$	$1/\lambda^2$
Normal Distribution	$\frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}(\frac{x-\mu}{\sigma})^2}; \quad -\infty < x < +\infty$	μ	σ^2

STATISTICS:

SAMPLE DATA:

Given n-data: $x_1 \leq x_2 \leq \dots \leq x_n$

- Sample Mean, $\bar{x} = \frac{\sum_{i=1}^n x_i}{n}$
- Sample Variance, $s^2 = \frac{\sum_{i=1}^n (x_i - \bar{x})^2}{n-1}$
- Standard Deviation, $\sigma = \sqrt{s^2}$

RANDOM SAMPLE (from infinite population):

A set of observations x_1, x_2, \dots, x_n constitute a random sample of size 'n', from a population $f(x)$ if

- (1) Each x_i has distribution $f(x)$
- (2) x_1, x_2, \dots, x_n are independent random variables

Theorem:

Let x_1, x_2, \dots, x_n be independent random variables then,

$$\text{var}(x_1 + x_2 + \dots + x_n) = \text{var}(x_1) + \text{var}(x_2) + \dots + \text{var}(x_n)$$

LAW OF LARGE NUMBERS:

Let x_1, x_2, \dots, x_n be a random sample. If ' μ ' is the population mean, then

- (1) $\bar{x} \rightarrow \mu$ as $n \rightarrow \infty$
- (2) $P(|\bar{x} - \mu| > \epsilon) \rightarrow 0$ as $n \rightarrow \infty, \forall \epsilon > 0$

CENTRAL LIMIT THEOREM:

Random sample x_1, x_2, \dots, x_n (for each 'n') and \bar{x} is the sample mean

$$[\mu_{\bar{x}} = \mu; \sigma_{\bar{x}}^2 = \frac{\sigma^2}{n}] \quad z_n = \frac{\bar{x} - \mu}{(\frac{\sigma}{\sqrt{n}})} \quad [z_n \text{ has mean '0' and variance '1'}]$$

Then, $z_n \rightarrow z \sim N(0,1)$ {i.e., convergence in distribution}

STOCHASTIC PROCESS:

A Stochastic process $\{X(t); t \in T\}$ is a collection of random variables

MARKOV CHAIN:

A stochastic process $\{x_n; n=0,1,2,\dots\}$ with state space $(Z, N \text{ or } N \cup \{0\})$ is called a Markov Chain if,

$$P(X_{n+1} = j \mid x_n = i, x_{n-1} = i_{n-1}, \dots, x_0 = i_0) = P(x_{n+1} = j \mid x_n = i)$$

Note:

A Markov chain $\{x_n; n=0,1,2,\dots\}$ is called *time homogenous* if

$P(x_{n+1} = j \mid x_n = i)$ is independent of n , for each $i, j \in S$