

<b>Title of the Project</b>	Parallel Computing for Autonomous Vehicle Simulation
<b>Commencement Date</b>	17-05-2012
<b>Completion Date</b>	23-07-2012
<b>Project Supervisor</b>	Prof. Ragunathan "Raj" Rajkumar
<b>Organization/Institution where the Project was accomplished</b>	Carnegie Mellon University, Pittsburgh, PA, United States of America
<p><b>Project Description</b> (You can use extra A4 sheets in case you run out of space however the extra sheets should also have the seal &amp; signature of the Project Supervisor or the relevant authority )</p> <p>The goal of the project is to making AutoSim Work on GPU (device).          AutoSim is software that simulates Autonomous car in hybrid environment i.e. real car and autonomous cars. AutoSim is been implemented in terms of models. Some models are :</p> <ol style="list-style-type: none"> <li>1. Control Model</li> <li>2. Position Model</li> <li>3. State Model</li> <li>4. Mobility Model</li> <li>5. Path Tracker</li> <li>6. Communication Model, etc.</li> </ol> <p>Each model is actually a class and inheritable. So each car call these models to change its position, state, speed, direction, avoiding collision with other cars or road and many more things. AutoSim was coded in C++. Due to sequential execution of AutoSim it could only be used for simulating smaller number of cars and hence was not useful for inheriting real world map of cities in AutoSim and run it for few thousand cars.</p> <p>We tried to implement models on GPU and use parallelism of GPU while calling same models for different cars. We implemented four models on GPU :</p> <ol style="list-style-type: none"> <li>1. Position Model</li> <li>2. Control Model</li> <li>3. State Model</li> <li>4. Path Tracker</li> </ol> <p>As all models are not yet implemented on GPU we had to copy data from host (CPU) to device and again back to host after model is updated on GPU. This memory copy is bottle neck in execution. So for less number of cars we got poorer performance for GPU. But for larger number of car GPU was way better. We also made path tracker more efficient. Initially each car stored its path separately. But we have few static paths only. So instead of copying data for each car, we can just pass Path ID to car for accessing the path.</p> <p>The future scope is to implement AutoSim completely on GPU and to add some other feature like dynamically generating path and including world model so that AutoSim can be used to generate real world simulation.</p> <p>We collected data about time of execution for various models that were running on CPU and now are implemented on GPU for different number of cars and plotted them. Using GPU would be very useful not only for AutoSim but also for Autonomous Vehicles.</p> <p>We used Qt Creator to build project. We coded in CUDA and C++.</p>	

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