

Robotics Competition

2019-20

If you're reading this, you'll find a "sr_task_0" folder along with this file. Inside that folder, you'll find another folder called as "model". This model folder contains "whycon_marker" folder.

Now follow the step as mentioned below:

Method I:

- 1. Copy that file inside your system's model directory, to do so, follow the steps...
 - a. Copy the "whycon marker "folder(select the folder and press CTRL+C)
 - b.Now, go to your home directory/folder
 - c. Find ".gazebo" folder there. if you're unable to locate it, simply press CTRL+H button from your keyboard. All the hidden folder will now be visible.
 - d.Inside this folder go to "models" folder and paste it (CTRL+V)
 OR

Method II:

- 1. Inside this the problem statement folder itself, Open your terminal by pressing CTRL+ALT+T
- 2. After terminal window appears, we need to go where our whycon_marker folder is, for that, type the following line in terminal to go inside your models folder:

3. Now to copy paste your whycon marker folder to desired location type:

That's it, Done!

Note: to better understand this command:

- the "cp" call for copy instruction
- next "-a" is an improved recursive option, that preserve all file attributes, and also preserve symlinks
- "whycon_marker/." is the source or the folder which is intended to be copied, Notice, the "." at the end; that's mean the entire internal content
- Lastly the destination, "~/.gazebo/models/", over here the "~/" mean your home location. And ".gazebo/models/" is your destination.

