```
import pandas as pd
import numpy as np
import pickle
```

```
from google.colab import files
uploaded = files.upload()
```

Choose Files No file chosen Upload widget is only available when the cell has been executed in the current browser session. Please rerun this cell to enable.
Saving train_final.csv to train_final.csv

```
df_train=pd.read_csv('train_final.csv',index_col=False)
labels=df_train[['784']]
```

```
df_train.drop(df_train.columns[[784]],axis=1,inplace=True)
df_train.head()
```

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	1
0	255	255	255	255	255	255	255	255	255	255	255	255	255	255	255	255	25
1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	205	255	25
2	255	255	255	0	0	0	0	0	0	0	0	0	0	0	0	0	
3	255	255	255	255	255	255	255	255	255	255	255	255	255	255	255	255	25
4	255	23	0	0	0	0	0	0	0	0	0	0	0	0	0	0	

5 rows × 784 columns

```
np.random.seed(1212)
import keras
from keras.models import Model
from keras.layers import *
from keras import optimizers
from keras.layers import Input, Dense
from keras.models import Sequential
from keras.layers import Dense
from keras.layers import Dropout
from keras.layers import Flatten
from keras.layers.convolutional import Conv2D
from keras.layers.convolutional import MaxPooling2D
from keras.utils import np_utils
from keras import backend as K
K.image_data_format()
```

```
'channels_last'
```

```
labels=np.array(labels)
```

```
from keras.utils.np_utils import to_categorical
cat=to_categorical(labels,num_classes=13)
```

```
print(cat[0])
```

```
[0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 1. 0. 0.]
```

```
df_train.head()
```

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	1
0	255	255	255	255	255	255	255	255	255	255	255	255	255	255	255	255	25
1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	205	255	25
2	255	255	255	0	0	0	0	0	0	0	0	0	0	0	0	0	
3	255	255	255	255	255	255	255	255	255	255	255	255	255	255	255	255	25
4	255	23	0	0	0	0	0	0	0	0	0	0	0	0	0	0	

5 rows × 784 columns

```
df_train.shape
```

```
(47504, 784)
```

```
temp=df_train.to_numpy()
```

```
X_train = temp.reshape(temp.shape[0], 28, 28, 1)
```

```
temp.shape[0]
```

```
47504
```

```
X_train.shape
```

```
(47504, 28, 28, 1)
```

```
l=[]
for i in range(47504):
    l.append(np.array(df_train[i:i+1]).reshape(1,28,28))
```

```
np.random.seed(7)
```

```
len(l[0])
```

```
1
```

```
X_train.shape
```

```
(47504, 28, 28, 1)
```

```
model = Sequential()
model.add(Conv2D(32, (3,3), input_shape=(28, 28,1), activation='relu',padding='same'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Conv2D(15, (3, 3), activation='relu'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Dropout(0.2))
model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dense(50, activation='relu'))
model.add(Dense(13, activation='softmax'))
# Compile model
model.compile(loss='categorical_crossentropy', optimizer='adam', metrics=['accuracy'])
```

```
from keras.models import model_from_json
```

```
model.fit(X_train, cat, epochs=10, batch_size=200,shuffle=True,verbose=1)
```

```
Epoch 1/10
238/238 [==============================] - 31s 125ms/step - loss: 1.1159 - accuracy:
Epoch 2/10
238/238 [==============================] - 30s 126ms/step - loss: 0.2149 - accuracy:
Epoch 3/10
238/238 [==============================] - 30s 126ms/step - loss: 0.1241 - accuracy:
Epoch 4/10
238/238 [==============================] - 30s 126ms/step - loss: 0.0903 - accuracy:
Epoch 5/10
238/238 [==============================] - 30s 127ms/step - loss: 0.0705 - accuracy:
Epoch 6/10
238/238 [==============================] - 30s 127ms/step - loss: 0.0578 - accuracy:
Epoch 7/10
238/238 [==============================] - 30s 127ms/step - loss: 0.0470 - accuracy:
Epoch 8/10
238/238 [==============================] - 30s 127ms/step - loss: 0.0405 - accuracy:
Epoch 9/10
238/238 [==============================] - 30s 128ms/step - loss: 0.0371 - accuracy:
Epoch 10/10
238/238 [==============================] - 30s 127ms/step - loss: 0.0321 - accuracy:
<keras.callbacks.History at 0x7f08ae56c190>
```

```
model_json = model.to_json()
with open("model_final.json", "w") as json_file:
    json_file.write(model_json)
# serialize weights to HDF5
model.save_weights("model_final.h5")
```

```
import cv2
```

```
import numpy
from keras.datasets import mnist
from keras.models import Sequential
from keras.layers import Dense
from keras.layers import Dropout
from keras.layers import Flatten
from keras.layers.convolutional import Conv2D
from keras.layers.convolutional import MaxPooling2D
from keras.utils import np_utils
from keras import backend as K
# K.set_image_dim_ordering('th')
from keras.models import model_from_json

json_file = open('model_final.json', 'r')
loaded_model_json = json_file.read()
json_file.close()
loaded_model = model_from_json(loaded_model_json)
# load weights into new model
loaded_model.load_weights("model_final.h5")


print(5)
```

```
5
```

```
import cv2
import numpy as np
img = cv2.imread('test.jpg',cv2.IMREAD_GRAYSCALE)


img
```

```
if img is not None:
    #images.append(img)
    img=~img
    ret,thresh=cv2.threshold(img,127,255,cv2.THRESH_BINARY)
    ctrs,ret=cv2.findContours(thresh,cv2.RETR_TREE,cv2.CHAIN_APPROX_SIMPLE)
    cnt=sorted(ctrs, key=lambda ctr: cv2.boundingRect(ctr)[0])
    w=int(28)
    h=int(28)
    train_data=[]
    print(len(cnt))
    rects=[]
    for c in cnt :
        x,y,w,h= cv2.boundingRect(c)
        rect=[x,y,w,h]
        rects.append(rect)
    print(rects)
    bool_rect=[]
    for r in rects:
        l=[]
        for rec in rects:
            flag=0
            if rec!=r:
```

```
                if r[0]<(rec[0]+rec[2]+10) and rec[0]<(r[0]+r[2]+10) and r[1]<(rec[1]+rec[
                    flag=1
                l.append(flag)
            if rec==r:
                l.append(0)
        bool_rect.append(l)
    print(bool_rect)
    dump_rect=[]
    for i in range(0,len(cnt)):
        for j in range(0,len(cnt)):
            if bool_rect[i][j]==1:
                area1=rects[i][2]*rects[i][3]
                area2=rects[j][2]*rects[j][3]
                if(area1==min(area1,area2)):
                    dump_rect.append(rects[i])
    print(len(dump_rect))
    final_rect=[i for i in rects if i not in dump_rect]
    print(final_rect)
    for r in final_rect:
        x=r[0]
        y=r[1]
        w=r[2]
        h=r[3]
        im_crop =thresh[y:y+h+10,x:x+w+10]


        im_resize = cv2.resize(im_crop,(28,28))


        im_resize=np.reshape(im_resize,(28,28,1))
        train_data.append(im_resize)


s=''
for i in range(len(train_data)):
    train_data[i]=np.array(train_data[i])
    train_data[i]=train_data[i].reshape(1,28,28,1)
    #result=loaded_model.predict_classes(train_data[i])
    result=np.argmax(loaded_model.predict(train_data[i]), axis=-1)
    if(result[0]==10):
        s=s+'-'
    if(result[0]==11):
        s=s+'+'
    if(result[0]==12):
        s=s+'*'
    if(result[0]==0):
        s=s+'0'
    if(result[0]==1):
        s=s+'1'
    if(result[0]==2):
        s=s+'2'
    if(result[0]==3):
        s=s+'3'
    if(result[0]==4):
```

```
            s=s+'4'
        if(result[0]==5):
            s=s+'5'
        if(result[0]==6):
            s=s+'6'
        if(result[0]==7):
            s=s+'7'
        if(result[0]==8):
            s=s+'8'
        if(result[0]==9):
            s=s+'9'

print(s)
```

```
 7+3
```

```
eval(s)
```

```
 10
```