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```
In [1]:
        import matplotlib.pyplot as plt
        import numpy as np
        from pomegranate import State, HiddenMarkovModel, DiscreteDistribution
In [2]: model = HiddenMarkovModel(name="Climate Model")
In [3]: rainy_emissions = DiscreteDistribution({"Happy":0.9,"Sad":0.1})
        rainy_state = State(rainy_emissions,name = "rainy")
        cloudy_emissions = DiscreteDistribution({"Happy":0.6,"Sad":0.4})
        cloudy state = State(cloudy emissions, name = "cloudy")
        sunny_emissions = DiscreteDistribution({"Happy":0.2,"Sad":0.8})
        sunny_state = State(cloudy_emissions,name = "sunny")
In [4]: model.add_states(rainy_state,cloudy_state,sunny_state)
In [6]: | model.add_transition(model.start, rainy_state, 0.33)
        model.add transition(model.start, cloudy state ,0.33)
        model.add_transition(model.start, sunny_state ,0.34)
        #Adding Transitions for Rainy State
        model.add_transition(rainy_state, rainy_state, 0.5)
        model.add_transition(rainy_state, cloudy_state,0.3)
        model.add transition(rainy state, rainy state, 0.2)
        #Adding Transitions for Cloudy State
        model.add_transition(cloudy_state,rainy_state,0.4)
        model.add_transition(cloudy_state, cloudy_state, 0.2)
        model.add transition(cloudy state, sunny state, 0.4)
        #Adding Transitions for Sunny State
        model.add transition(sunny state, rainy state , 0.0)
        model.add_transition(sunny_state,cloudy_state , 0.3)
        model.add_transition(sunny_state, sunny_state , 0.7)
In [7]: model.bake()
In [8]: model.edge count()
Out[8]: 11
In [9]: model.node_count()
Out[9]: 5
```

The state transition matrix, P(Xt|Xt-1):

```
[[0. 0.33 0.33 0.34 0. ]

[0. 0.4 0.6 0. 0. ]

[0. 0.4 0.2 0.4 0. ]

[0. 0. 0.3 0.7 0. ]

[0. 0. 0. 0. 0. ]
```

The transition probability from Cloudy to Rainy is 40%

Calculate Sequence Likelihood

	cloudy	rainy	sunny	Climate Model-start	Climat	
e Model-en	d					
0%	0	% 0%	,)	100%	0%	
Happy 0%	20%	30%	20%	0%		
Sad	11%	2%	9%	0%		
0%						
Happy 0%	4%	5%	6%	0%		

The likelihood over all possible paths of this model producing the sequence ['Happy', 'Sad', 'Happy'] is 14.79%

Decoding the Most Likely Hidden State

Sequence

The most likely weather sequence to have generated these observations is ['rain y', 'cloudy', 'rainy'] at 2.57%.

Forward likelihood vs Viterbi likelihood

```
In [24]: from itertools import product
  observations = ['Happy', 'Happy', 'Sad']

p = {'Rainy' : {'Rainy': np.log(.5),'Cloudy': np.log(.3),'Sunny': np.log(.2)},'Cloudy': e = {'Rainy' : {'Sad': np.log(.9),'Happy': np.log(.1)},'Cloudy': {'Sad': np.log(.4)}
```

```
In [26]: | o = observations
             k = []
             vprob = np.exp(model.viterbi(o)[0])
             print("The likelihood of observing {} if the weather sequence is...".format(o))
             for s in product(*[['Rainy', 'Cloudy', 'Sunny']]*3):
                   k.append(np.exp(np.log(.5)+e[s[0]][o[0]] + p[s[0]][s[1]] + e[s[1]][o[1]] + p[
                   print("\t{} is {:.2f}% {}".format(s, 100 * k[-1], " <-- Viterbi path" if k[-1]</pre>
             print("\nThe total likelihood of observing {} over all possible paths is {:.2f}%'
             0.02566079999999999
             The likelihood of observing ['Happy', 'Happy', 'Sad'] if the weather sequence i
             s...
                         ('Rainy', 'Rainy', 'Rainy') is 0.11%
                         ('Rainy', 'Rainy', 'Cloudy') is 0.05% ('Rainy', 'Rainy', 'Sunny') is 0.01%
                         ('Rainy', 'Cloudy', 'Rainy') is 0.22%
                         ('Rainy', 'Cloudy', 'Cloudy') is 0.07%
                         ('Rainy', 'Cloudy', 'Sunny') is 0.05% ('Rainy', 'Sunny', 'Rainy') is 0.00% ('Rainy', 'Sunny', 'Cloudy') is 0.14%
                         ('Rainy', 'Sunny', 'Sunny') is 0.11%
                         ('Cloudy', 'Rainy', 'Rainy') is 0.36%
                         ('Cloudy', 'Rainy', 'Cloudy') is 0.14%
                         ('Cloudy', 'Rainy', 'Sunny') is 0.03%
                         ('Cloudy', 'Cloudy', 'Rainy') is 0.58%
                         ('Cloudy', 'Cloudy', 'Cloudy') is 0.19%
                         ('Cloudy', 'Cloudy', 'Sunny') is 0.13%
                        ('Cloudy', 'Sunny', 'Rainy') is 0.00%
('Cloudy', 'Sunny', 'Cloudy') is 1.15%
('Cloudy', 'Sunny', 'Sunny') is 0.90%
('Sunny', 'Rainy', 'Rainy') is 0.00%
('Sunny', 'Rainy', 'Cloudy') is 0.00%
('Sunny', 'Rainy', 'Sunny') is 0.00%
('Sunny', 'Cloudy', 'Rainy') is 1.73%
('Sunny', 'Cloudy', 'Cloudy') is 0.50%
                        ('Sunny', 'Cloudy', 'Cloudy') is 0.58% ('Sunny', 'Cloudy', 'Sunny') is 0.38% ('Sunny', 'Sunny', 'Rainy') is 0.00% ('Sunny', 'Sunny', 'Cloudy') is 4.03%
                         ('Sunny', 'Sunny', 'Sunny') is 3.14%
             The total likelihood of observing ['Happy', 'Happy', 'Sad'] over all possible p
             aths is 14.10%
```

In []: