

Efficient Model Evidence Computation in Tree-structured Factor Graphs

Supplementary Material

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Abstract

This supplementary document provides the message computation rules of sum-product messages in the paper "Efficient Model Evidence Computation in Tree-structured Factor Graphs".

I. BERNOULLI NODE

The factor node function of the Bernoulli node is defined as

$$f(x, y) = \text{Ber}(y \mid x) = x^y (1 - x)^{1-y} \quad (1)$$

where $y \in \{0, 1\}$ is a binary variable, and $x \in [0, 1]$.

A. Forward message

The node function $f(x, y)$ represents a conditional distribution $p(y \mid x)$. Based on the general scale factor update rules of a conditional probability density function in [1, Ch.6], we obtain the scale factor update rule

$$\vec{\beta}_y = \vec{\beta}_x \quad (2)$$

where $\vec{\beta}_y$ and $\vec{\beta}_x$ are the scale factors of the messages $\vec{\mu}_y(y)$ and $\vec{\mu}_x(x)$, respectively.

B. Backward message

Now we compute the scale factor $\vec{\beta}_x$ of the backward message $\vec{\mu}_x(x)$. By definition, we have

$$\vec{\beta}_x = \int \vec{\mu}_x(x) dx = \int \sum_y \vec{\mu}_y(y) f(y, x) dx. \quad (3)$$

Assume that we have observed $y = \hat{y}$, then $\vec{\mu}_y(y) = \vec{\beta}_y \delta(y - \hat{y})$ and (3) is now equivalent to

$$\vec{\beta}_x = \vec{\beta}_y \int \text{Ber}(\hat{y} \mid x) dx \quad (4)$$

$$= \vec{\beta}_y \int x^{\hat{y}} (1 - x)^{1-\hat{y}} dx \quad (5)$$

$$= \vec{\beta}_y B(a, b) \underbrace{\int \frac{1}{B(a, b)} x^{a-1} (1 - x)^{b-1} dx}_{=1, \text{ Beta distribution}} \quad (6)$$

$$= \vec{\beta}_y B(a, b) \quad (7)$$

where $a = \hat{y} + 1$, $b = 2 - \hat{y}$ and $B(a, b)$ is the Beta function defined as

$$B(a, b) = \frac{\Gamma(a)\Gamma(b)}{\Gamma(a+b)}, \quad (8)$$

where $\Gamma(\cdot, \cdot)$ is the gamma function. From the definition of a , b and $B(a, b)$, we have

$$\begin{aligned} \vec{\beta}_x &= \vec{\beta}_y B(\hat{y} + 1, 2 - \hat{y}) \\ &= \vec{\beta}_y \frac{\Gamma(\hat{y} + 1)\Gamma(2 - \hat{y})}{\Gamma(3)}. \end{aligned}$$

Note that $\hat{y} \in \{0, 1\}$, and regardless of what value \hat{y} takes, the following equality holds

$$\frac{\Gamma(\hat{y} + 1)\Gamma(2 - \hat{y})}{\Gamma(3)} = \frac{\Gamma(1)\Gamma(2)}{\Gamma(3)} = \frac{1}{2}. \quad (9)$$

Therefore, we achieve the following final equation of $\tilde{\beta}_x$

$$\tilde{\beta}_x = \frac{1}{2} \tilde{\beta}_y \quad (10)$$

II. CATEGORICAL NODE

The factor node function of the Categorical node is

$$f(\mathbf{x}, \mathbf{y}) = \text{Cat}(\mathbf{y} | \mathbf{x}) = \prod_{i=1}^K x_i^{y_i} \quad (11)$$

where $\mathbf{y} = [y_1, \dots, y_K]$ is a one-hot-coded vector, i.e. $y_i \in \{0, 1\}$ and $\sum_{i=1}^K y_i = 1$, and \mathbf{x} is a vector such that $x_i \in [0, 1]$ and $\sum_{i=1}^K x_i = 1$. K is the number of categories.

A. Forward message

Similar to the Bernoulli node, we also regard the node function as a conditional distribution $p(\mathbf{y} | \mathbf{x})$, thus we have the following update rule

$$\vec{\beta}_y = \vec{\beta}_x \quad (12)$$

where $\vec{\beta}_y$ and $\vec{\beta}_x$ are the scale factors of the messages $\vec{\mu}_y$ and $\vec{\mu}_x$, respectively.

B. Backward message

Now we compute the scale factor $\tilde{\beta}_x$ of the backward message $\tilde{\mu}_x(\mathbf{x})$. By definition, we have:

$$\tilde{\beta}_x = \int \tilde{\mu}_x d\mathbf{x} = \int \sum_{\mathbf{y}} \tilde{\mu}(\mathbf{y}) f(\mathbf{y}, \mathbf{x}) d\mathbf{x} \quad (13)$$

Assume that we have observed $\mathbf{y} = \hat{\mathbf{y}}$, then $\tilde{\mu}_y(\mathbf{y}) = \tilde{\beta}_y \delta(\mathbf{y} - \hat{\mathbf{y}})$ and (13) equals:

$$\tilde{\beta}_x = \tilde{\beta}_y \int \text{Cat}(\hat{\mathbf{y}} | \mathbf{x}) d\mathbf{x} \quad (14)$$

$$= \tilde{\beta}_y \int \prod_{i=1}^K x_i^{\hat{y}_i} d\mathbf{x} \quad (15)$$

$$= \tilde{\beta}_y B(\boldsymbol{\alpha}) \underbrace{\int \frac{1}{B(\boldsymbol{\alpha})} \prod_{i=1}^K x_i^{\alpha_i - 1} d\mathbf{x}}_{=1, \text{ Dirichlet distribution}} \quad (16)$$

$$= \tilde{\beta}_y B(\boldsymbol{\alpha}) \quad (17)$$

where $\boldsymbol{\alpha} = \hat{\mathbf{y}} + \mathbf{1}$, and

$$B(\boldsymbol{\alpha}) = \frac{\prod_{i=1}^K \Gamma(\alpha_i)}{\Gamma(\sum_{i=1}^K \alpha_i)}. \quad (18)$$

From the definition of $\boldsymbol{\alpha}$ and $B(\boldsymbol{\alpha})$, we have:

$$\tilde{\beta}_x = \tilde{\beta}_y B(\hat{\mathbf{y}} + \mathbf{1}) \quad (19)$$

$$= \tilde{\beta}_y \frac{\prod_{i=1}^K \Gamma(\hat{y}_i + 1)}{\Gamma(\sum_{i=1}^K (\hat{y}_i + 1))} \quad (20)$$

$$= \tilde{\beta}_y \frac{1}{\Gamma(K + 1)} \quad (21)$$

$$= \frac{\tilde{\beta}_y}{K!} \quad (22)$$

III. TRANSITION NODE

The factor node function of the transition node is

$$f(\mathbf{y}, \mathbf{x}) = \text{Cat}(\mathbf{y} \mid \mathbf{A}\mathbf{x}) = \prod_{j=1}^J \prod_{k=1}^K A_{jk}^{y_j x_k} \quad (23)$$

where \mathbf{y} and \mathbf{x} are one-hot-coded vectors. \mathbf{A} is the transition matrix whose elements are constrained to $A_{jk} \in [0, 1]$ and whose columns are also constrained by $\sum_j A_{jk} = 1$. Since both \mathbf{x} and \mathbf{y} are one-hot coded, the node function (23) can be written in vector notation as follows

$$\text{Cat}(\mathbf{y} \mid \mathbf{A}\mathbf{x}) = \mathbf{y}^\top \mathbf{A}\mathbf{x} \quad (24)$$

In the following derivation, we assume the matrix \mathbf{A} is known.

A. Forward message

Again, we can recognize that the node function is a conditional distribution $p(\mathbf{y} \mid \mathbf{x})$, thus

$$\vec{\beta}_{\mathbf{y}} = \vec{\beta}_{\mathbf{x}} \quad (25)$$

where $\vec{\beta}_{\mathbf{y}}$ and $\vec{\beta}_{\mathbf{x}}$ are the scale factors of the messages $\tilde{\mu}_{\mathbf{y}}(\mathbf{y})$ and $\tilde{\mu}_{\mathbf{x}}(\mathbf{x})$, respectively.

B. Backward message

Assuming a categorical incoming message $\tilde{\mu}_{\mathbf{y}}(\mathbf{y}) = \tilde{\beta}_{\mathbf{y}} \text{Cat}(\mathbf{y} \mid \boldsymbol{\pi}_{\mathbf{y}})$, now we compute the scale factor $\tilde{\beta}_{\mathbf{x}}$ of the backward message $\tilde{\mu}_{\mathbf{x}}$. By definition, we have

$$\begin{aligned} \tilde{\beta}_{\mathbf{x}} &= \sum_{\mathbf{x}} \tilde{\mu}_{\mathbf{x}}(\mathbf{x}) = \sum_{\mathbf{x}} \sum_{\mathbf{y}} \tilde{\mu}_{\mathbf{y}}(\mathbf{y}) \text{Cat}(\mathbf{y} \mid \mathbf{A}\mathbf{x}) \\ &= \tilde{\beta}_{\mathbf{y}} \sum_{\mathbf{x}} \sum_{\mathbf{y}} \text{Cat}(\mathbf{y} \mid \boldsymbol{\pi}_{\mathbf{y}}) \mathbf{x}^\top \mathbf{A}^\top \mathbf{y} \\ &= \tilde{\beta}_{\mathbf{y}} \sum_{\mathbf{x}} \mathbf{x}^\top \mathbf{A}^\top \underbrace{\mathbb{E}_{\text{Cat}(\mathbf{y} \mid \boldsymbol{\pi}_{\mathbf{y}})}[\mathbf{y}]}_{\boldsymbol{\pi}_{\mathbf{y}}} \\ &= \tilde{\beta}_{\mathbf{y}} \sum_{\mathbf{x}} \mathbf{x}^\top \mathbf{A}^\top \boldsymbol{\pi}_{\mathbf{y}} \\ &= \tilde{\beta}_{\mathbf{y}} \|\mathbf{A}^\top \boldsymbol{\pi}_{\mathbf{y}}\|_1 \sum_{\mathbf{x}} \mathbf{x}^\top \frac{\mathbf{A}^\top \boldsymbol{\pi}_{\mathbf{y}}}{\|\mathbf{A}^\top \boldsymbol{\pi}_{\mathbf{y}}\|_1}. \end{aligned}$$

In the last equality, we can view $\mathbf{x}^\top \frac{\mathbf{A}^\top \boldsymbol{\pi}_{\mathbf{y}}}{\|\mathbf{A}^\top \boldsymbol{\pi}_{\mathbf{y}}\|_1}$ as a Categorical distribution over \mathbf{x} , and hence, the summation term is equal to unity. Therefore, the update rule for $\tilde{\beta}_{\mathbf{x}}$ is:

$$\tilde{\beta}_{\mathbf{x}} = \tilde{\beta}_{\mathbf{y}} \|\mathbf{A}^\top \boldsymbol{\pi}_{\mathbf{y}}\|_1,$$

where $\|\cdot\|_1$ denotes the ℓ^1 -norm of a vector.

IV. GAUSSIAN NODE

The node function is

$$f(\mathbf{x}, \mathbf{y}, \mathbf{V}) = \mathcal{N}(\mathbf{y} \mid \mathbf{x}, \mathbf{V}) = \frac{1}{|2\pi\mathbf{V}|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(\mathbf{y} - \mathbf{x})^\top \mathbf{V}^{-1}(\mathbf{y} - \mathbf{x})\right)$$

where \mathbf{x} and \mathbf{y} are real-valued vectors, and \mathbf{V} is the covariance matrix. In this derivation, we assume that \mathbf{V} is known.

A. Forward message

Since the matrix \mathbf{V} is known, we regard the Gaussian node as a conditional probability distribution function $p(\mathbf{y} \mid \mathbf{x})$. Thus

$$\vec{\beta}_{\mathbf{y}} = \vec{\beta}_{\mathbf{x}}, \quad (26)$$

where $\vec{\beta}_{\mathbf{y}}$ and $\vec{\beta}_{\mathbf{x}}$ are the scale factors of the messages $\tilde{\mu}_{\mathbf{y}}$ and $\tilde{\mu}_{\mathbf{x}}$, respectively.

B. Backward message

Due to the symmetry property of the quadratic term in the exponent of Gaussian distribution, we can also regard the node function as a conditional probability distribution function $p(\mathbf{x}|\mathbf{y})$, and thus we have

$$\tilde{\beta}_{\mathbf{x}} = \tilde{\beta}_{\mathbf{y}}.$$

V. EQUALITY NODE

We first recall the sum-product rule for the equality node: if the incoming messages are $\tilde{\mu}_x(x)$ and $\tilde{\mu}_z(z)$, then the outgoing message on the edge y is $\tilde{\mu}_y(y) = \tilde{\mu}_x(y) \tilde{\mu}_z(y)$.

A. Beta message

Recall the definition of Beta distribution:

$$\text{Beta}(x | \alpha, \beta) = \frac{1}{B(\alpha, \beta)} x^{\alpha-1} (1-x)^{\beta-1},$$

where the random variable $x \in (0, 1)$. Both $\alpha, \beta \in \mathbb{R}_{>0}$ are shape parameters. The normalizing constant is the inverse of the Beta function of α and β :

$$B(\alpha, \beta) = \frac{\Gamma(\alpha)\Gamma(\beta)}{\Gamma(\alpha + \beta)}.$$

With the incoming messages

$$\begin{aligned}\tilde{\mu}_x(x) &= \tilde{\beta}_x \text{Beta}(x | a_x, b_x), \\ \tilde{\mu}_z(z) &= \tilde{\beta}_z \text{Beta}(z | a_z, b_z),\end{aligned}$$

the scale factor $\tilde{\beta}_y$ of the message $\tilde{\mu}_y$ is

$$\begin{aligned}\tilde{\beta}_y &= \int_y \tilde{\mu}_y(y) dy = \int_y \tilde{\mu}_x(y) \tilde{\mu}_z(y) dy = \tilde{\beta}_x \tilde{\beta}_z \int_y \tilde{p}_x(y) \tilde{p}_z(y) dy \\ &= \tilde{\beta}_x \tilde{\beta}_z \frac{1}{B(a_x, b_x) B(a_z, b_z)} \int_y y^{a_x-1} (1-y)^{b_x-1} y^{a_z-1} (1-y)^{b_z-1} dy \\ &= \tilde{\beta}_x \tilde{\beta}_z \frac{1}{B(a_x, b_x) B(a_z, b_z)} \int_y y^{a_x+a_z-2} (1-y)^{b_x+b_z-2} dy \\ &= \tilde{\beta}_x \tilde{\beta}_z \frac{B(a_y, b_y)}{B(a_x, b_x) B(a_z, b_z)} \underbrace{\int_y \frac{1}{B(a_y, b_y)} y^{a_y-1} (1-y)^{b_y-1} dy}_{=1, \text{Beta distribution}} \\ &= \tilde{\beta}_x \tilde{\beta}_z \frac{B(a_y, b_y)}{B(a_x, b_x) B(a_z, b_z)},\end{aligned}$$

$$\text{where } \begin{cases} a_y &= a_x + a_z - 1 \\ b_y &= b_x + b_z - 1 \end{cases}$$

B. Bernoulli message

Recall the definition of Bernoulli distribution:

$$\text{Ber}(x | \pi) = \pi^x (1-\pi)^{1-x} \tag{27}$$

where the random variable $x \in \{0, 1\}$, and $\pi \in (0, 1)$.

With the incoming messages

$$\begin{aligned}\tilde{\mu}_x(x) &= \tilde{\beta}_x \text{Ber}(x | \pi_x), \\ \tilde{\mu}_z(z) &= \tilde{\beta}_z \text{Ber}(z | \pi_z),\end{aligned}$$

the scale factor $\vec{\beta}_y$ of the message $\vec{\mu}_y$ is

$$\begin{aligned}\vec{\beta}_y &= \sum_{y=0}^1 \vec{\mu}_y(y) = \sum_{y=0}^1 \vec{\mu}_x(y) \vec{\mu}_z(y) = \vec{\beta}_x \vec{\beta}_z \sum_{y=0}^1 \vec{p}_x(y) \vec{p}_z(y) \\ &= \vec{\beta}_x \vec{\beta}_z \sum_{y=0}^1 \pi_x^y (1 - \pi_x)^{1-y} \pi_z^y (1 - \pi_z)^{1-y} \\ &= \vec{\beta}_x \vec{\beta}_z ((1 - \pi_x)(1 - \pi_z) + \pi_x \pi_z)\end{aligned}$$

C. Dirichlet message

Recall the definition of Dirichlet distribution:

$$\text{Dir}(\mathbf{x} \mid \boldsymbol{\pi}) = \frac{1}{B(\boldsymbol{\pi})} \prod_{i=1}^K x_i^{\pi_i - 1}$$

where $K \in \mathbf{N}$ is the number of classes, $\boldsymbol{\pi} = [\pi_1, \dots, \pi_K]^\top \in \mathbb{R}_{>0}^K$. The random variable $\mathbf{x} = [x_1, \dots, x_K]^\top$ satisfies: $x_i \in (0, 1)$ and $\sum_{i=1}^K x_i = 1$. The normalizing constant $B(\boldsymbol{\pi})$ is the multivariate beta function:

$$B(\boldsymbol{\pi}) = \frac{\prod_{i=1}^K \Gamma(\pi_i)}{\Gamma(\sum_{i=1}^K \pi_i)}$$

With the incoming messages

$$\begin{aligned}\vec{\mu}_x(\mathbf{x}) &= \vec{\beta}_x \text{Dir}(\mathbf{x} \mid \boldsymbol{\pi}_x), \\ \vec{\mu}_z(\mathbf{z}) &= \vec{\beta}_z \text{Dir}(\mathbf{z} \mid \boldsymbol{\pi}_z),\end{aligned}$$

the scale factor $\vec{\beta}_y$ of the message $\vec{\mu}_y$ is

$$\begin{aligned}\vec{\beta}_y &= \int \vec{\mu}_y(\mathbf{y}) d\mathbf{y} = \int \vec{\mu}_x(\mathbf{y}) \vec{\mu}_z(\mathbf{y}) d\mathbf{y} = \vec{\beta}_x \vec{\beta}_z \int \vec{p}_x(\mathbf{y}) \vec{p}_z(\mathbf{y}) d\mathbf{y} \\ &= \vec{\beta}_x \vec{\beta}_z \frac{1}{B(\boldsymbol{\pi}_x) B(\boldsymbol{\pi}_z)} \int \prod_{i=1}^K \underbrace{y_i^{\pi_{x_i} - 1} y_i^{\pi_{z_i} - 1}}_{y_i^{\pi_{x_i} + \pi_{z_i} - 2}} d\mathbf{y} \\ &= \vec{\beta}_x \vec{\beta}_z \frac{B(\boldsymbol{\pi}_y)}{B(\boldsymbol{\pi}_x) B(\boldsymbol{\pi}_z)} \underbrace{\int \frac{1}{B(\boldsymbol{\pi}_y)} \prod_{i=1}^K y_i^{\pi_{y_i} - 1} d\mathbf{y}}_{=1, \text{Dirichlet distribution}} \\ &= \vec{\beta}_x \vec{\beta}_z \frac{B(\boldsymbol{\pi}_y)}{B(\boldsymbol{\pi}_x) B(\boldsymbol{\pi}_z)},\end{aligned}$$

where $\boldsymbol{\pi}_y = \boldsymbol{\pi}_x + \boldsymbol{\pi}_z - \mathbf{1}$.

D. Categorical message

Recall the definition of Categorical distribution:

$$\text{Cat}(\mathbf{x} \mid \boldsymbol{\pi}) = \prod_{k=1}^K \pi_k^{x_k}$$

where $\mathbf{x} = [x_1, \dots, x_K]^\top$ is a one-hot coded vector, i.e. only one entry of \mathbf{x} is 1 and the others are zero, and $\boldsymbol{\pi} = [\pi_1, \dots, \pi_K]^\top$ satisfies $\pi_k \in [0, 1]$ and $\sum_{k=1}^K \pi_k = 1$. Since \mathbf{x} is one-hot coded, we rewrite the categorical distribution as follows:

$$\text{Cat}(\mathbf{x} \mid \boldsymbol{\pi}) = \boldsymbol{\pi}^T \mathbf{x}.$$

With the incoming messages

$$\begin{aligned}\vec{\mu}_x(\mathbf{x}) &= \vec{\beta}_x \text{Cat}(\mathbf{x} \mid \boldsymbol{\pi}_x), \\ \vec{\mu}_z(\mathbf{z}) &= \vec{\beta}_z \text{Cat}(\mathbf{z} \mid \boldsymbol{\pi}_z),\end{aligned}$$

the scale factor $\vec{\beta}_y$ of the message $\vec{\mu}_y$ is

$$\begin{aligned}\vec{\beta}_y &= \sum_{\mathbf{y}} \vec{\mu}_y(\mathbf{y}) = \sum_{\mathbf{y}} \vec{\mu}_x(\mathbf{y}) \vec{\mu}_z(\mathbf{y}) = \vec{\beta}_x \vec{\beta}_z \sum_{\mathbf{y}} \vec{p}_x(\mathbf{y}) \vec{p}_z(\mathbf{y}) \\ &= \vec{\beta}_x \vec{\beta}_z \sum_{\mathbf{y}} \text{Cat}(\mathbf{y} \mid \boldsymbol{\pi}_x) \boldsymbol{\pi}_z^\top \mathbf{y} = \vec{\beta}_x \vec{\beta}_z \boldsymbol{\pi}_z^\top \mathbb{E}_{\text{Cat}(\mathbf{y} \mid \boldsymbol{\pi}_x)}[\mathbf{y}] \\ &= \vec{\beta}_x \vec{\beta}_z \boldsymbol{\pi}_x^\top \boldsymbol{\pi}_z\end{aligned}$$

E. Gamma message

Recall the definition of Gamma distribution:

$$\text{Gam}(x \mid a, b) = \frac{b^a}{\Gamma(a)} x^{a-1} \exp(-bx), \quad (28)$$

where $a \in \mathbb{R}_{>0}$ and $b \in \mathbb{R}_{>0}$ are the shape and the rate parameters, respectively, and both are positive real numbers.

With the incoming messages

$$\begin{aligned}\vec{\mu}_x(x) &= \vec{\beta}_x \text{Gam}(x \mid a_x, b_x), \\ \vec{\mu}_z(z) &= \vec{\beta}_z \text{Gam}(z \mid a_z, b_z),\end{aligned}$$

the scale factor $\vec{\beta}_y$ of the message $\vec{\mu}_y$ is

$$\begin{aligned}\vec{\beta}_y &= \int \vec{\mu}_y(y) dy = \int \vec{\mu}_x(y) \vec{\mu}_z(y) dy = \vec{\beta}_x \vec{\beta}_z \int \vec{p}_x(y) \vec{p}_z(y) dy \\ &= \vec{\beta}_x \vec{\beta}_z \frac{b_x^{a_x} b_z^{a_z}}{\Gamma(a_x) \Gamma(a_z)} \int y^{a_x-1} \exp(-b_x y) y^{a_z-1} \exp(-b_z y) dy \\ &= \vec{\beta}_x \vec{\beta}_z \frac{b_x^{a_x} b_z^{a_z}}{\Gamma(a_x) \Gamma(a_z)} \int y^{a_x+a_z-2} \exp(-(b_x + b_z)y) dy \\ &= \vec{\beta}_x \vec{\beta}_z \frac{b_x^{a_x} b_z^{a_z}}{\Gamma(a_x) \Gamma(a_z)} \frac{\Gamma(a_y)}{b_y^{a_y}} \underbrace{\int \frac{b_y^{a_y}}{\Gamma(a_y)} y^{a_y-1} \exp(-b_y y) dy}_{=1, \text{ Gamma distribution}} \\ &= \vec{\beta}_x \vec{\beta}_z \frac{\Gamma(a_y)}{\Gamma(a_x) \Gamma(a_z)} \frac{b_x^{a_x} b_z^{a_z}}{b_y^{a_y}},\end{aligned}$$

where $\begin{cases} a_y &= a_x + a_z - 1 \\ b_y &= b_x + b_z \end{cases}$

F. Wishart message

Recall the definition of Wishart distribution:

$$\text{W}(\mathbf{X} \mid \mathbf{V}, n) = \frac{|\mathbf{X}|^{\frac{n-p-1}{2}} \exp\{-\frac{1}{2} \text{tr}(\mathbf{V}^{-1} \mathbf{X})\}}{2^{\frac{np}{2}} |\mathbf{V}|^{\frac{n}{2}} \Gamma_p\left(\frac{n}{2}\right)},$$

where $\mathbf{V} \in \mathbb{R}^{p \times p}$ is the scale matrix, and $n > p - 1$ is the degree of freedom.

With the incoming messages

$$\begin{aligned}\vec{\mu}_x(\mathbf{X}) &= \vec{\beta}_x \text{W}(\mathbf{X} \mid \mathbf{V}_x, n_x), \\ \vec{\mu}_z(\mathbf{Z}) &= \vec{\beta}_z \text{W}(\mathbf{Z} \mid \mathbf{V}_z, n_z),\end{aligned}$$

the scale factor of the message $\vec{\mu}_y(\mathbf{y})$ is

$$\begin{aligned}
\vec{\beta}_y &= \int \vec{\mu}_y(\mathbf{y}) d\mathbf{y} = \int \vec{\mu}_x(\mathbf{y}) \vec{\mu}_z(\mathbf{y}) d\mathbf{y} \\
&= \vec{\beta}_x \vec{\beta}_z \int W(\mathbf{y} \mid \mathbf{V}_x, n_x) W(\mathbf{y} \mid \mathbf{V}_z, n_z) d\mathbf{y} \\
&= \frac{\vec{\beta}_x \vec{\beta}_z}{A} \int |\mathbf{y}|^{\frac{n_x + n_z - 2p - 2}{2}} \exp\left(-\frac{1}{2} \text{tr}((\mathbf{V}_x^{-1} + \mathbf{V}_z^{-1})\mathbf{y})\right) d\mathbf{y} \\
&= \frac{\vec{\beta}_x \vec{\beta}_z}{A} B \underbrace{\int \frac{1}{B} |\mathbf{y}|^{\frac{n_y - p - 1}{2}} \exp\left(-\frac{1}{2} \text{tr}(\mathbf{V}_y^{-1}\mathbf{y})\right) d\mathbf{y}}_{=1, \text{ Wishart distribution}} \\
&= \frac{\vec{\beta}_x \vec{\beta}_z}{A} B,
\end{aligned}$$

where

$$\begin{aligned}
A &= 2^{\frac{p(n_x + n_z)}{2}} |\mathbf{V}_x|^{\frac{n_x}{2}} |\mathbf{V}_z|^{\frac{n_z}{2}} \Gamma_p\left(\frac{n_x}{2}\right) \Gamma_p\left(\frac{n_z}{2}\right) \\
B &= 2^{\frac{p n_y}{2}} |\mathbf{V}_y|^{\frac{n_y}{2}} \Gamma_p\left(\frac{n_y}{2}\right) \\
n_y &= n_x + n_z - p - 1 \\
\mathbf{V}_y &= (\mathbf{V}_x^{-1} + \mathbf{V}_z^{-1})^{-1}
\end{aligned}$$

REFERENCES

- [1] C. Reller, “State-Space Methods in Statistical Signal Processing: New Ideas and Applications,” Ph.D. dissertation, ETH Zurich, 2012.