

Practical Machine Learning Project

Babangida Babura

Background

Using devices such as Jawbone Up, Nike FuelBand, and Fitbit it is now possible to collect a large amount of data about personal activity relatively inexpensively. These type of devices are part of the quantified self movement – a group of enthusiasts who take measurements about themselves regularly to improve their health, to find patterns in their behavior, or because they are tech geeks. One thing that people regularly do is quantify how much of a particular activity they do, but they rarely quantify how well they do it. In this project, your goal will be to use data from accelerometers on the belt, forearm, arm, and dumbbell of 6 participants. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways. More information is available from the website here: <http://groupware.les.inf.puc-rio.br/har> (see the section on the Weight Lifting Exercise Dataset).

Data

The training data for this project are available here: <https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv> The test data are available here: <https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv>

The data for this project come from this source: <http://groupware.les.inf.puc-rio.br/har>. If you use the document you create for this class for any purpose please cite them as they have been very generous in allowing their data to be used for this kind of assignment.

Purpose of the Project

The goal of your project is to predict the manner in which they did the exercise. This is the “classe” variable in the training set. You may use any of the other variables to predict with. You should create a report describing how you built your model, how you used cross validation, what you think the expected out of sample error is, and why you made the choices you did. You will also use your prediction model to predict 20 different test cases.

Peer Review Portion

Your submission for the Peer Review portion should consist of a link to a Github repo with your R markdown and compiled HTML file describing your analysis. Please constrain the text of the writeup to < 2000 words and the number of figures to be less than 5. It will make it easier for the graders if you submit a repo with a gh-pages branch so the HTML page can be viewed online (and you always want to make it easy on graders :-).

Course Project Prediction Quiz Portion

Apply your machine learning algorithm to the 20 test cases available in the test data above and submit your predictions in appropriate format to the Course Project Prediction Quiz for automated grading.

Reproducibility

Due to security concerns with the exchange of R code, your code will not be run during the evaluation by your classmates. Please be sure that if they download the repo, they will be able to view the compiled HTML version of your analysis.

Loading Packages

```
library(lattice)
library(ggplot2)
library(caret)
library(randomForest)
```

```
## randomForest 4.6-14

## Type rfNews() to see new features/changes/bug fixes.

##
## Attaching package: 'randomForest'

## The following object is masked from 'package:ggplot2':
##
##     margin

library(rpart)
library(rpart.plot)
```

Data Cleaning and Preparation

```
set.seed(717)
trainurl = "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv"
testurl = "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv"
#download.file(trainurl, "pml-training.csv")
#download.file(testurl, "pml-testing.csv")
training <- read.csv("pml-training.csv", na.strings=c("NA","#DIV/0!", ""))
testing <- read.csv("pml-testing.csv", na.strings=c("NA","#DIV/0!", ""))
#Look for variables that could use to predict classe
#update datasets to exclude those variables with NA values
training <- training[,colSums(is.na(training)) == 0]
testing <- testing[,colSums(is.na(testing)) == 0]
#remove irrelevant variables to the prediction
newtraining <- training[, -c(1:7)]
newtesting <- testing[, -c(1:7)]
#For cross validation purpose, the training data will be split into training training and training test
cv <- createDataPartition(y=newtraining$classe, p=0.75, list=FALSE)
training_train <- newtraining[cv, ]
training_test <- newtraining[-cv, ]
summary(newtraining)
```

##	roll_belt	pitch_belt	yaw_belt	total_accel_belt
##	Min. :-28.90	Min. :-55.8000	Min. :-180.00	Min. : 0.00
##	1st Qu.: 1.10	1st Qu.: 1.7600	1st Qu.: -88.30	1st Qu.: 3.00
##	Median :113.00	Median : 5.2800	Median : -13.00	Median :17.00
##	Mean : 64.41	Mean : 0.3053	Mean : -11.21	Mean :11.31
##	3rd Qu.:123.00	3rd Qu.: 14.9000	3rd Qu.: 12.90	3rd Qu.:18.00
##	Max. :162.00	Max. : 60.3000	Max. : 179.00	Max. :29.00

```

## gyros_belt_x      gyros_belt_y      gyros_belt_z      accel_belt_x
## Min.      :-1.040000    Min.      :-0.64000    Min.      :-1.4600    Min.      :-120.000
## 1st Qu.: -0.030000    1st Qu.: 0.00000    1st Qu.: -0.2000    1st Qu.: -21.000
## Median : 0.030000    Median : 0.02000    Median : -0.1000    Median : -15.000
## Mean      :-0.005592    Mean      : 0.03959    Mean      :-0.1305    Mean      : -5.595
## 3rd Qu.: 0.110000    3rd Qu.: 0.11000    3rd Qu.: -0.0200    3rd Qu.: -5.000
## Max.      : 2.220000    Max.      : 0.64000    Max.      : 1.6200    Max.      : 85.000
## accel_belt_y      accel_belt_z      magnet_belt_x      magnet_belt_y
## Min.      :-69.00    Min.      :-275.00    Min.      :-52.0    Min.      :354.0
## 1st Qu.: 3.00    1st Qu.: -162.00    1st Qu.: 9.0    1st Qu.:581.0
## Median : 35.00    Median : -152.00    Median : 35.0    Median :601.0
## Mean      : 30.15    Mean      : -72.59    Mean      : 55.6    Mean      :593.7
## 3rd Qu.: 61.00    3rd Qu.: 27.00    3rd Qu.: 59.0    3rd Qu.:610.0
## Max.      :164.00    Max.      : 105.00    Max.      :485.0    Max.      :673.0
## magnet_belt_z      roll_arm      pitch_arm      yaw_arm
## Min.      :-623.0    Min.      :-180.00    Min.      :-88.800    Min.      :-180.0000
## 1st Qu.: -375.0    1st Qu.: -31.77    1st Qu.: -25.900    1st Qu.: -43.1000
## Median : -320.0    Median : 0.00    Median : 0.000    Median : 0.0000
## Mean      : -345.5    Mean      : 17.83    Mean      : -4.612    Mean      : -0.6188
## 3rd Qu.: -306.0    3rd Qu.: 77.30    3rd Qu.: 11.200    3rd Qu.: 45.8750
## Max.      : 293.0    Max.      : 180.00    Max.      : 88.500    Max.      : 180.0000
## total_accel_arm      gyros_arm_x      gyros_arm_y      gyros_arm_z
## Min.      : 1.00    Min.      :-6.37000    Min.      :-3.4400    Min.      :-2.3300
## 1st Qu.:17.00    1st Qu.: -1.33000    1st Qu.: -0.8000    1st Qu.: -0.0700
## Median :27.00    Median : 0.08000    Median : -0.2400    Median : 0.2300
## Mean      :25.51    Mean      : 0.04277    Mean      : -0.2571    Mean      : 0.2695
## 3rd Qu.:33.00    3rd Qu.: 1.57000    3rd Qu.: 0.1400    3rd Qu.: 0.7200
## Max.      :66.00    Max.      : 4.87000    Max.      : 2.8400    Max.      : 3.0200
## accel_arm_x      accel_arm_y      accel_arm_z      magnet_arm_x
## Min.      :-404.00    Min.      :-318.0    Min.      :-636.00    Min.      :-584.0
## 1st Qu.: -242.00    1st Qu.: -54.0    1st Qu.: -143.00    1st Qu.: -300.0
## Median : -44.00    Median : 14.0    Median : -47.00    Median : 289.0
## Mean      : -60.24    Mean      : 32.6    Mean      : -71.25    Mean      : 191.7
## 3rd Qu.: 84.00    3rd Qu.: 139.0    3rd Qu.: 23.00    3rd Qu.: 637.0
## Max.      : 437.00    Max.      : 308.0    Max.      : 292.00    Max.      : 782.0
## magnet_arm_y      magnet_arm_z      roll_dumbbell      pitch_dumbbell
## Min.      :-392.0    Min.      :-597.0    Min.      :-153.71    Min.      :-149.59
## 1st Qu.: -9.0    1st Qu.: 131.2    1st Qu.: -18.49    1st Qu.: -40.89
## Median : 202.0    Median : 444.0    Median : 48.17    Median : -20.96
## Mean      : 156.6    Mean      : 306.5    Mean      : 23.84    Mean      : -10.78
## 3rd Qu.: 323.0    3rd Qu.: 545.0    3rd Qu.: 67.61    3rd Qu.: 17.50
## Max.      : 583.0    Max.      : 694.0    Max.      : 153.55    Max.      : 149.40
## yaw_dumbbell      total_accel_dumbbell      gyros_dumbbell_x      gyros_dumbbell_y
## Min.      :-150.871    Min.      : 0.00    Min.      :-204.0000    Min.      :-2.10000
## 1st Qu.: -77.644    1st Qu.: 4.00    1st Qu.: -0.0300    1st Qu.: -0.14000
## Median : -3.324    Median :10.00    Median : 0.1300    Median : 0.03000
## Mean      : 1.674    Mean      :13.72    Mean      : 0.1611    Mean      : 0.04606
## 3rd Qu.: 79.643    3rd Qu.:19.00    3rd Qu.: 0.3500    3rd Qu.: 0.21000
## Max.      : 154.952    Max.      :58.00    Max.      : 2.2200    Max.      :52.00000
## gyros_dumbbell_z      accel_dumbbell_x      accel_dumbbell_y      accel_dumbbell_z
## Min.      : -2.380    Min.      :-419.00    Min.      :-189.00    Min.      :-334.00
## 1st Qu.: -0.310    1st Qu.: -50.00    1st Qu.: -8.00    1st Qu.: -142.00
## Median : -0.130    Median : -8.00    Median : 41.50    Median : -1.00
## Mean      : -0.129    Mean      : -28.62    Mean      : 52.63    Mean      : -38.32

```

```

## 3rd Qu.: 0.030 3rd Qu.: 11.00 3rd Qu.: 111.00 3rd Qu.: 38.00
## Max. :317.000 Max. : 235.00 Max. : 315.00 Max. : 318.00
## magnet_dumbbell_x magnet_dumbbell_y magnet_dumbbell_z roll_forearm
## Min. : -643.0 Min. : -3600 Min. : -262.00 Min. : -180.0000
## 1st Qu.: -535.0 1st Qu.: 231 1st Qu.: -45.00 1st Qu.: -0.7375
## Median : -479.0 Median : 311 Median : 13.00 Median : 21.7000
## Mean : -328.5 Mean : 221 Mean : 46.05 Mean : 33.8265
## 3rd Qu.: -304.0 3rd Qu.: 390 3rd Qu.: 95.00 3rd Qu.: 140.0000
## Max. : 592.0 Max. : 633 Max. : 452.00 Max. : 180.0000
## pitch_forearm yaw_forearm total_accel_forearm gyros_forearm_x
## Min. : -72.50 Min. : -180.00 Min. : 0.00 Min. : -22.000
## 1st Qu.: 0.00 1st Qu.: -68.60 1st Qu.: 29.00 1st Qu.: -0.220
## Median : 9.24 Median : 0.00 Median : 36.00 Median : 0.050
## Mean : 10.71 Mean : 19.21 Mean : 34.72 Mean : 0.158
## 3rd Qu.: 28.40 3rd Qu.: 110.00 3rd Qu.: 41.00 3rd Qu.: 0.560
## Max. : 89.80 Max. : 180.00 Max. : 108.00 Max. : 3.970
## gyros_forearm_y gyros_forearm_z accel_forearm_x accel_forearm_y
## Min. : -7.02000 Min. : -8.0900 Min. : -498.00 Min. : -632.0
## 1st Qu.: -1.46000 1st Qu.: -0.1800 1st Qu.: -178.00 1st Qu.: 57.0
## Median : 0.03000 Median : 0.0800 Median : -57.00 Median : 201.0
## Mean : 0.07517 Mean : 0.1512 Mean : -61.65 Mean : 163.7
## 3rd Qu.: 1.62000 3rd Qu.: 0.4900 3rd Qu.: 76.00 3rd Qu.: 312.0
## Max. : 311.00000 Max. : 231.0000 Max. : 477.00 Max. : 923.0
## accel_forearm_z magnet_forearm_x magnet_forearm_y magnet_forearm_z
## Min. : -446.00 Min. : -1280.0 Min. : -896.0 Min. : -973.0
## 1st Qu.: -182.00 1st Qu.: -616.0 1st Qu.: 2.0 1st Qu.: 191.0
## Median : -39.00 Median : -378.0 Median : 591.0 Median : 511.0
## Mean : -55.29 Mean : -312.6 Mean : 380.1 Mean : 393.6
## 3rd Qu.: 26.00 3rd Qu.: -73.0 3rd Qu.: 737.0 3rd Qu.: 653.0
## Max. : 291.00 Max. : 672.0 Max. : 1480.0 Max. : 1090.0
## classe
## Length:19622
## Class :character
## Mode :character
##
##
##

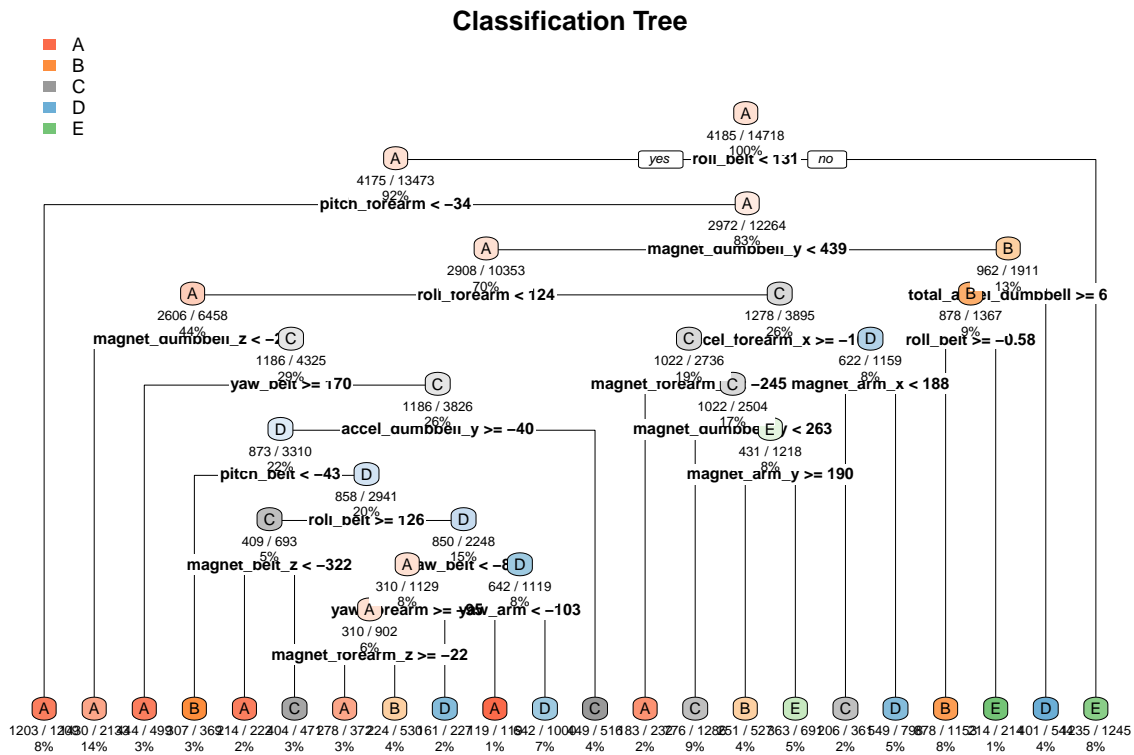
```

Decision Tree

```

tree_mod <- rpart(classe ~ ., data=training_train, method="class")
tree_pred <- predict(tree_mod, training_test, type = "class")
rpart.plot(tree_mod, main = "Classification Tree", extra=102, under=TRUE, faclen = 0, cex = .5)

```



```
#confusionMatrix(tree_pred, training_test$classe)$overall[1]
```

Random Forest

```
#rf_mod <- randomForest(classe ~. , data = training_train, method = "class")
#rf_pred <- predict(rf_mod, training_test, type = "class")
#confusionMatrix(rf_pred, training_test$classe)
```

Looking at the results, clearly, the random forest model provides a more accurate prediction of classe with 0.9955 compare to decision tree's 0.7488. The expected out-of-sample error is estimated at 0.005.