Sorting



Amiya Ranjan Panda

The Sorting Problem

- <u>Input</u>:
 - A sequence of n numbers $\langle a_1, a_2, \ldots, a_n \rangle$
- Output:
 - A reordering $< a_1', a_2', \ldots, a_n' >$ of the input sequence such that $a_1' \le a_2' \le \cdots \le a_n'$

Why Study Sorting Algorithms?

- There are a <u>variety of situations</u> that are encountered:
 - Do the keys randomly ordered?
 - Are all keys distinct?
 - How large is the set of keys to be ordered?
 - Need guaranteed performance?
- Various algorithms are better suited to some of these situations

Some Definitions

Internal Sort

 The data to be sorted is all stored in the computer's main memory.

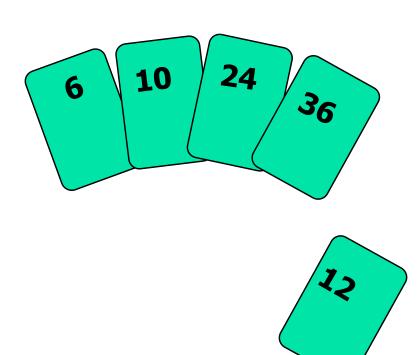
External Sort

 Some of the data to be sorted might be stored in some external, slower device.



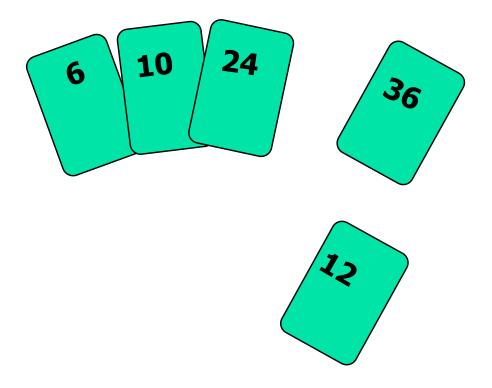
- Idea: like sorting a hand of playing cards
 - Start with an empty left hand and the cards facing down on the table.
 - Remove one card at a time from the table, and insert it into the correct position in the left hand
 - compare it with each of the cards already in the hand, from right to left
 - The cards held in the left hand are sorted
 - these cards were originally the <u>top cards of the pile</u> on the table



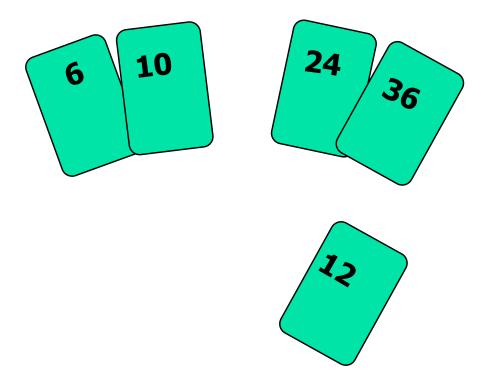


To insert 12, make a room for it by moving first 36 and then 24.





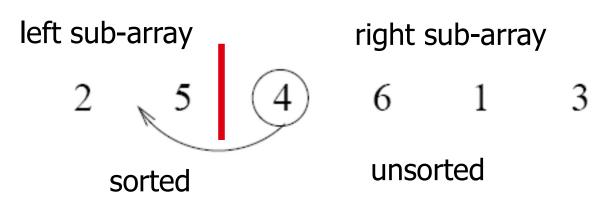


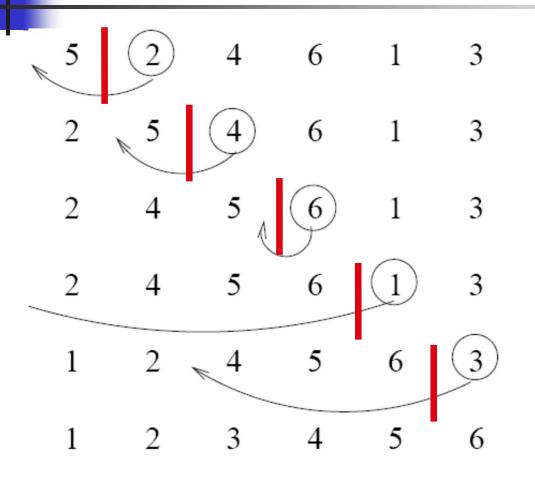


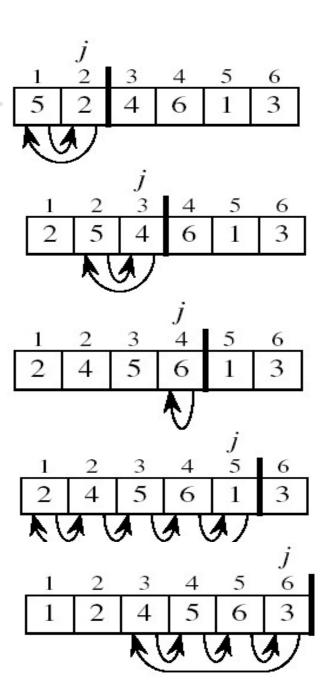
input array

5 2 4 6 1

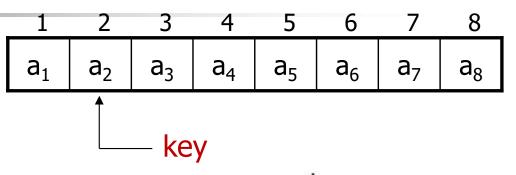
at each iteration, the array is divided in two sub-arrays:







Alg.: Insertion-Sort(A)



Insert A[j] into the sorted sequence A[

$$i = j - 1$$

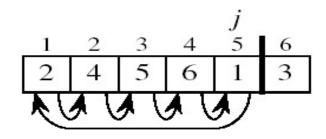
while i > 0 and A[i] > key

do
$$A[i + 1] = A[i]$$

 $i = i - 1$

$$A[i + 1] = key$$

Insertion sort – sorts the elements in place



```
Alg.: Insertion-Sort(A)
   for j = 2 to n
        do key = A[ j ]
            Insert A[j] into the sorted sequence A[1..j-1]
           i = j - 1
           while i > 0 and A[i] > key
                do A[i + 1] = A[i]
                    i = i - 1
           A[i + 1] = key
```

<u>Invariant</u>: at the start of the **for** loop the elements in A[1 . . j-1] are in sorted order



Proving loop invariants works like induction

Initialization (base case):

It is true prior to the first iteration of the loop

Maintenance (inductive step):

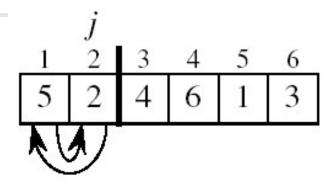
 If it is true before an iteration of the loop, it remains true before the next iteration

Termination:

- When the loop terminates, the invariant gives a useful property that helps show that the algorithm is correct
- Stop the induction when the loop terminates

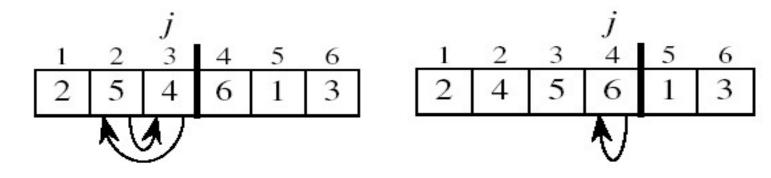
Initialization:

Just before the first iteration, j = 2:
 the subarray A[1..j-1] = A[1], (the element originally in A[1]) – is sorted



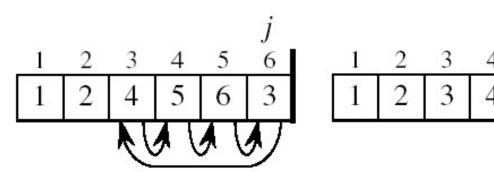
Maintenance:

- the while inner loop moves A[j -1], A[j -2], A[j -3], and so on, by one position to the right until the proper position for key (which has the value that started out in A[j]) is found
- At that point, the value of key is placed into this position.



Termination:

- The outer **for** loop ends when $j = n + 1 \Rightarrow j-1 = n$
- Replace n with j-1 in the loop invariant:
 - the subarray A[1..n] consists of the elements originally in A[1..n], but in sorted order



j - 1 j

The entire array is sorted!

Invariant: at the start of the **for** loop the elements in A[1 . . j-1] are in sorted order



Time complexity of Insertion Sort

- The worst case time complexity of Insertion sort is O(n²)
 - when the elements are in reverse sorted order
- The average case time complexity of Insertion sort is O(n²)
- The time complexity of the best case is O(n).
 - when the elements are in <u>sorted order</u>
- The space complexity is O(1)



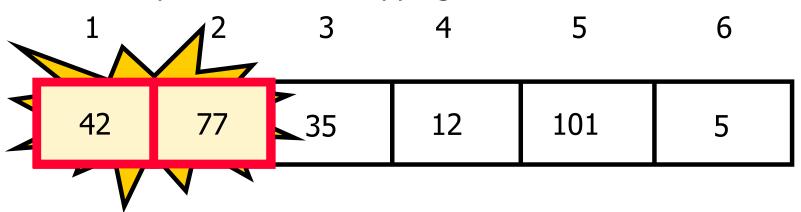
Bubble sort

- Compare each element (except the last one) with its neighbor to the right
 - If they are out of order, swap them
- This puts the largest element at the very end
- The last element is now in the correct and final place
- Compare each element (except the last two) with its neighbor to the right
 - If they are out of order, swap them
 - This puts the second largest element next to last
 - The last two elements are now in their correct and final places
- Compare each element (except the last three) with its neighbor to the right
 - Continue as above until no unsorted elements on the left

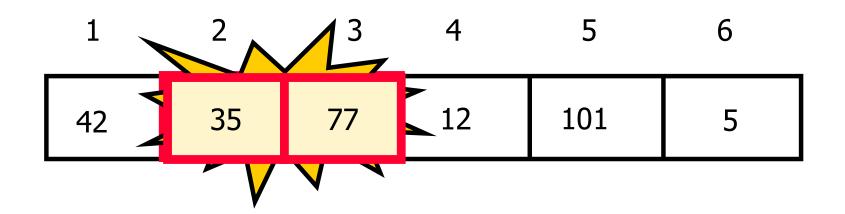
- Traverse a collection of elements
- Move from the front to the end
- "Bubble" the largest value to the end using pair-wise comparisons and swapping

1	2	3	4	5	6
77	42	35	12	101	5

- Traverse a collection of elements
 - Move from the front to the end
 - "Bubble" the largest value to the end using pair-wise comparisons and swapping

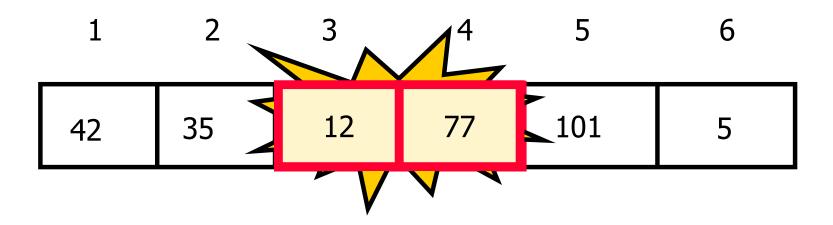


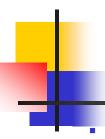
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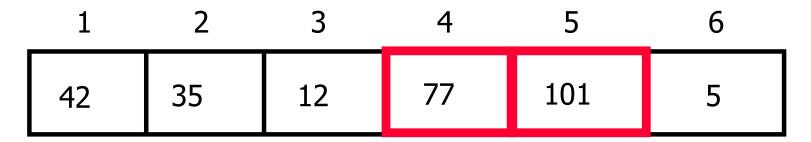
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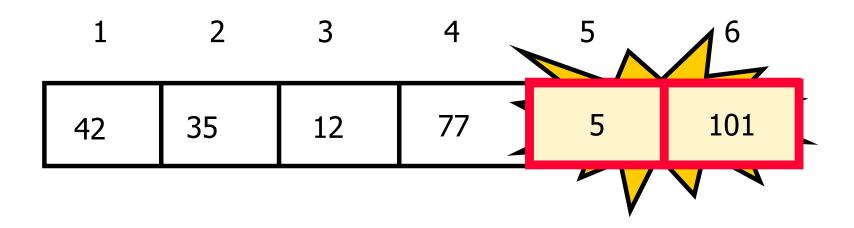


- Traverse a collection of elements
 - Move from the front to the end
 - "Bubble" the largest value to the end using pair-wise comparisons and swapping



No need to swap

- Traverse a collection of elements
 - Move from the front to the end
 - "Bubble" the largest value to the end using pair-wise comparisons and swapping

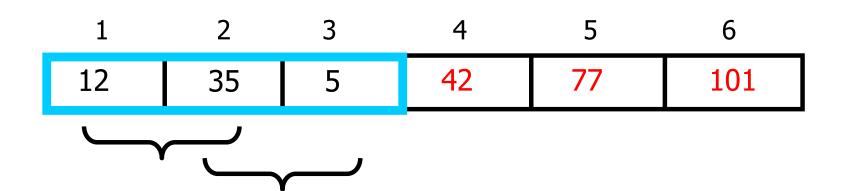


Reducing the Number of Comparisons

1	2	3	4	5	6
77	42	35	12	101	5
1	2	3	4	5	6
42	35	12	77	5	101
1	2	3	4	5	6
35	12	42	5	77	101
1	2	3	4	5	6
12	35	5	42	77	101
1	2	3	4	5	6
12	5	35	42	77	101

Reducing the Number of Comparisons

- On the nth "bubble up", we only need to do <u>MAX-n</u> comparisons.
- For example:
 - This is the 4th "bubble up"
 - MAX is 6
 - Thus we have 2 comparisons to do



Algorithm

```
BubbleSort(A: Arr_Type)
iterations, index: integer
iterations = n - 1
```

```
loop
  exitif(iterations = 0)
   index = 1
   loop
    exitif(index > iterations)
                                                            Inner loop
    if(A[index] > A[index + 1]) then
        swap(A[index], A[index + 1])
    endif
    index = index + 1
   endloop
   iterations = iterations - 1
 endloop
endprocedure
```

Outer loop

Already Sorted Collections?

- What if the collection was already sorted?
- What if only a few elements were out of place and after a couple of "<u>bubble ups</u>," the collection was sorted?
- We want to be able to <u>detect this and "stop early"!</u>

1	2	3	4	5	6
5	12	35	42	77	101

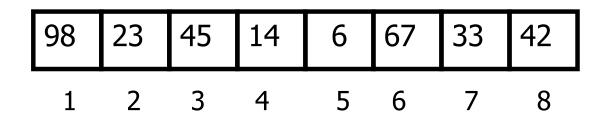
Using a Boolean "Flag"

- Use a boolean variable to determine if any swapping occurred during the "bubble up."
- If no swapping occurred, then the collection is already sorted!
- This boolean "flag" needs to be reset after each "bubble up"

Revised Algorithm

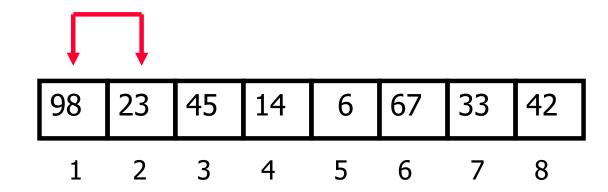
```
flag: Boolean
flag = true
  iterations = n - 1
  loop
      exitif ((iterations = 0) OR NOT(flag))
      index = 1
      flag = false
      loop
        exitif(index > iterations)
        if(A[index] > A[index + 1]) then
           swap(A[index], A[index + 1])
           flag = true
        endif
        index = index + 1
      endloop
      iterations = iterations - 1
  endloop
```

n 8 flag iterations 7 index

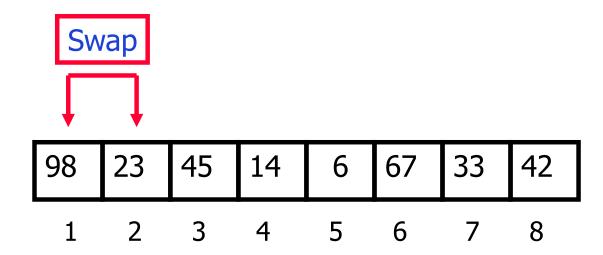


true

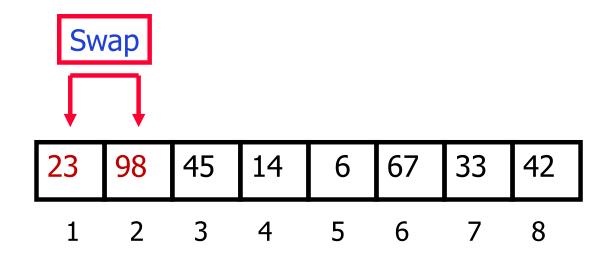




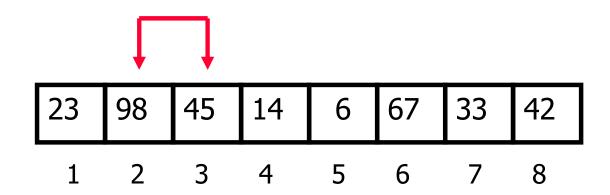


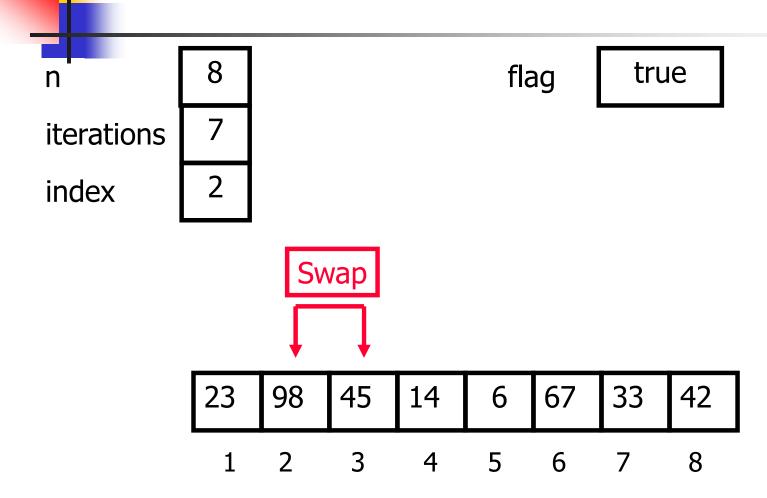


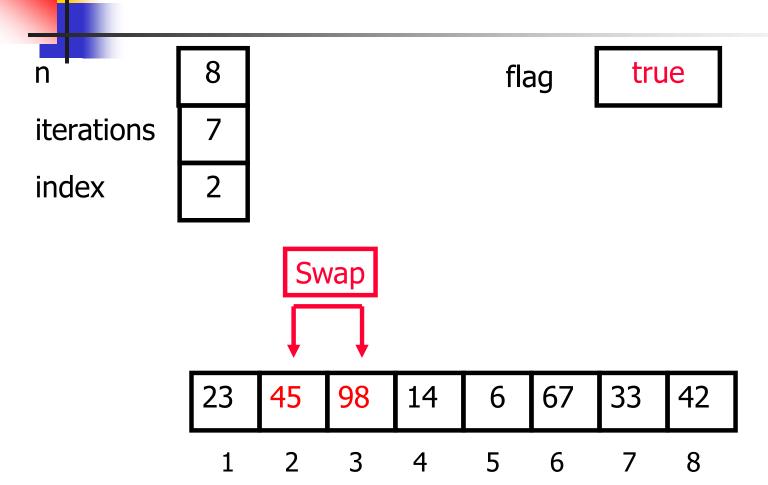












n

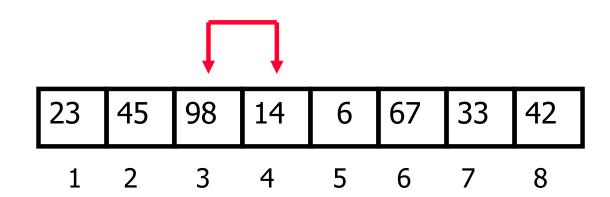
iterations

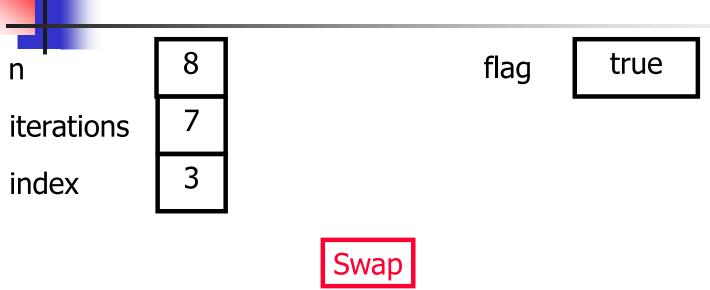
index

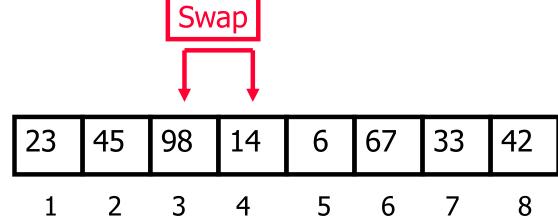
8

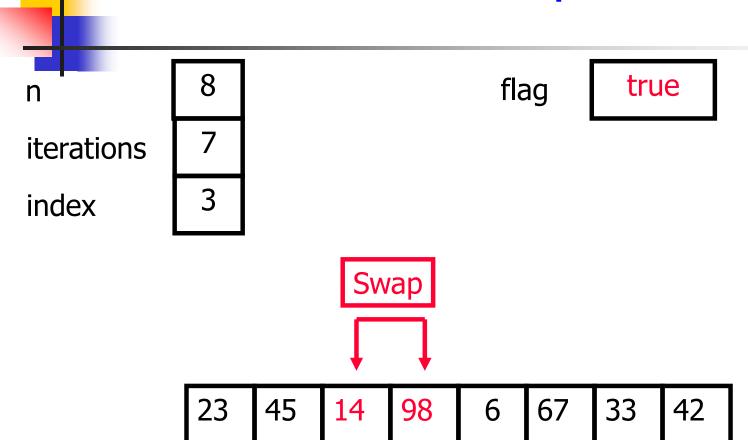
flag

true









4

An Animated Example

n iterations

index

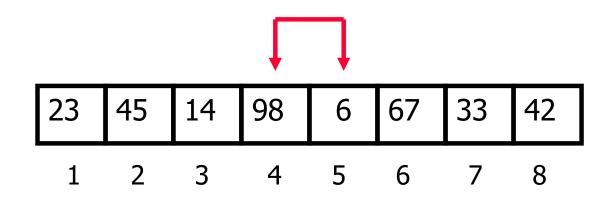
8

7

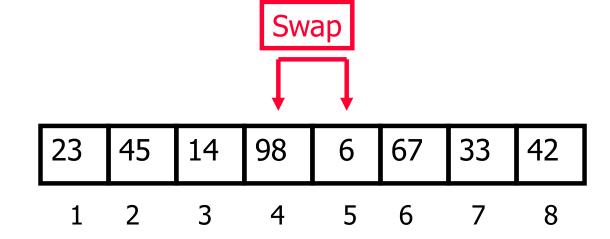
4

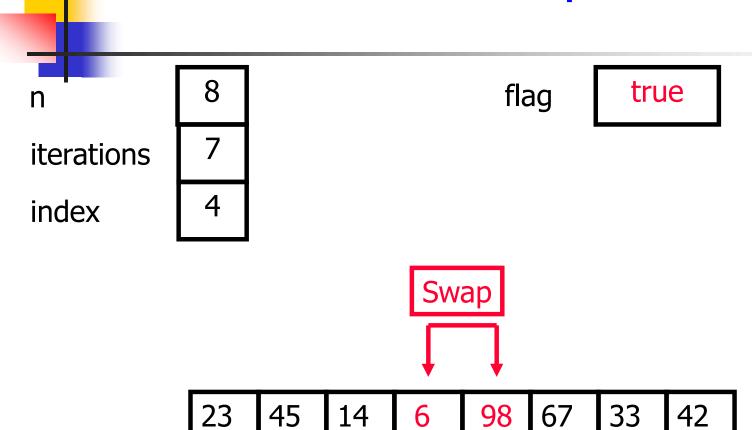
flag

true

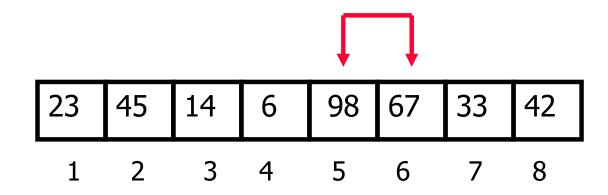


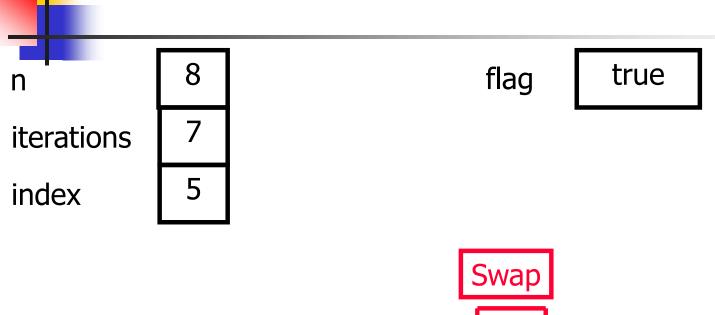


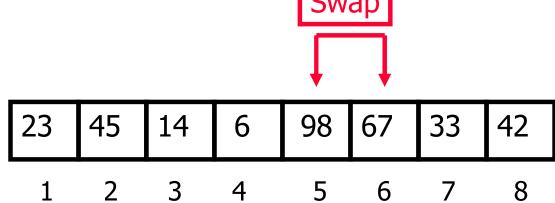


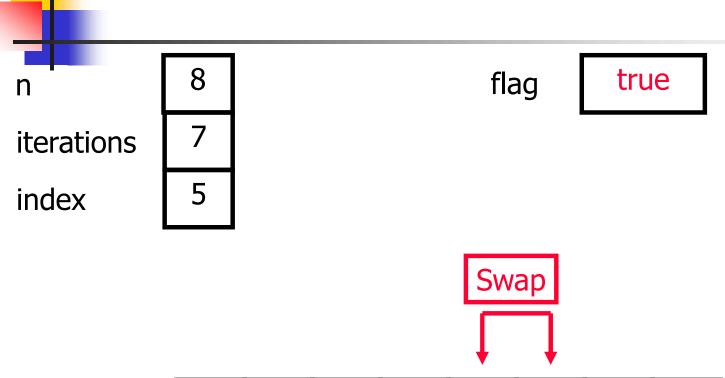




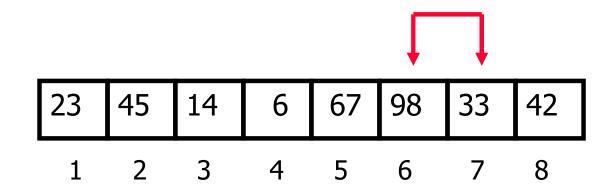




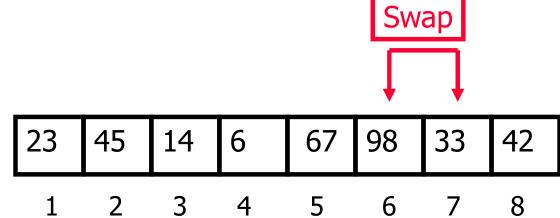


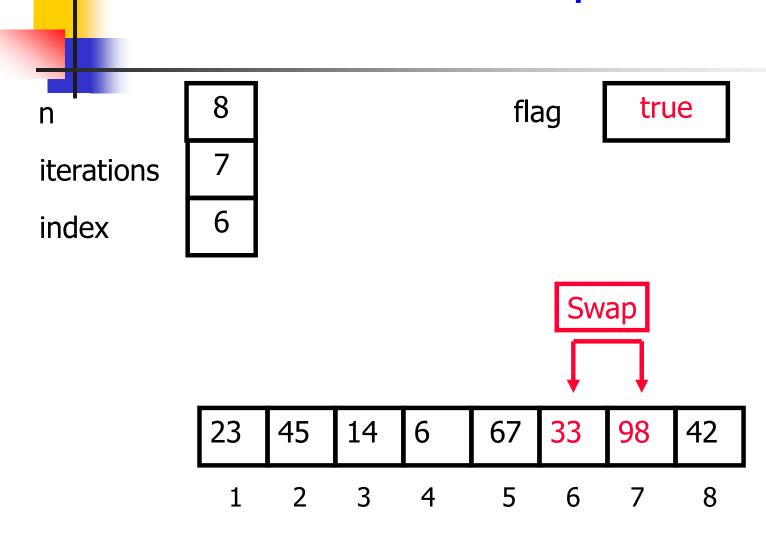




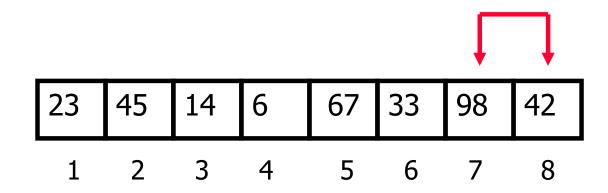


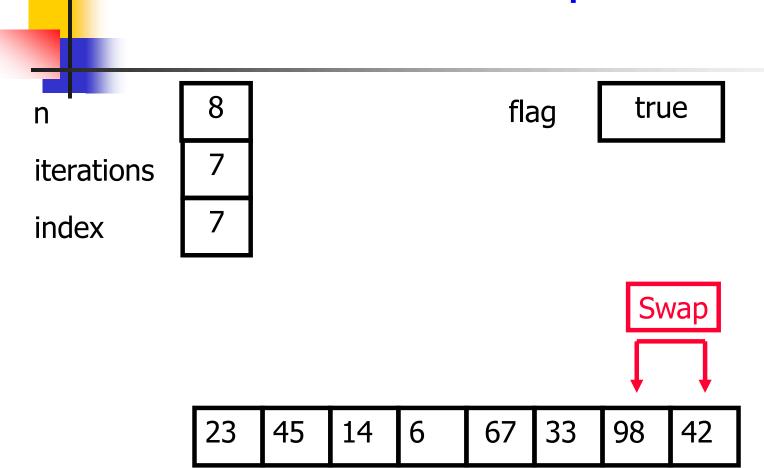


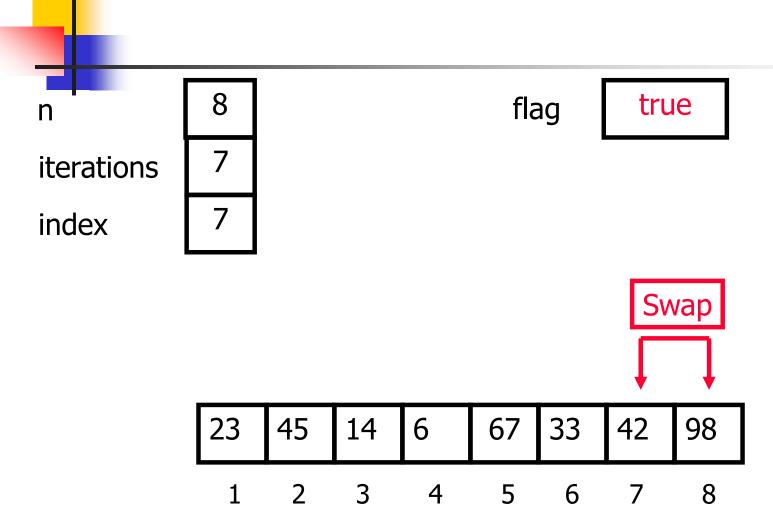






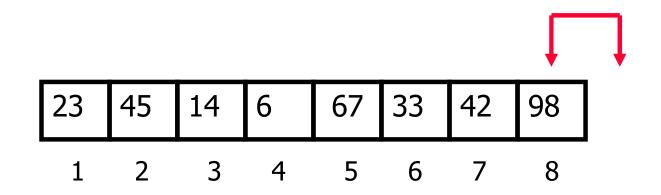




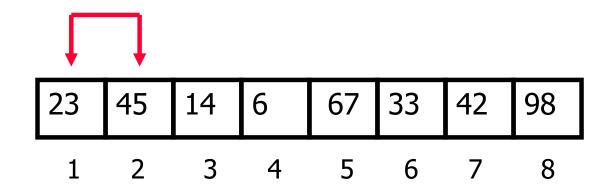


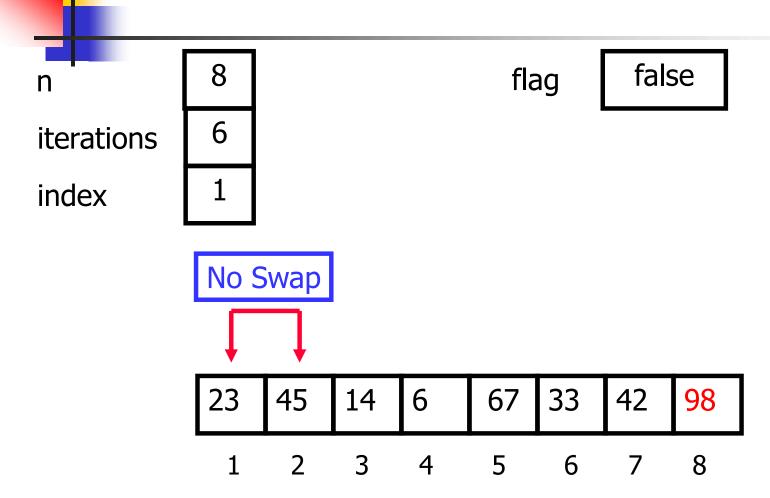
After First Pass of Outer Loop







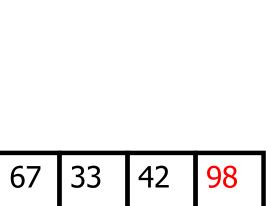




n

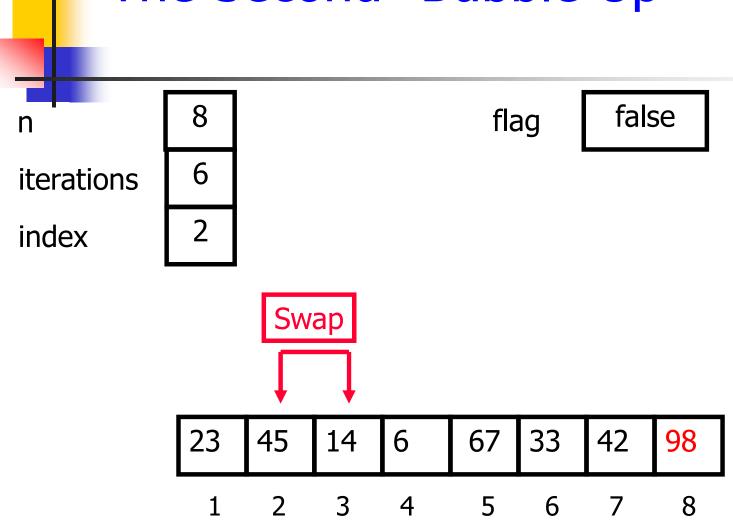
iterations

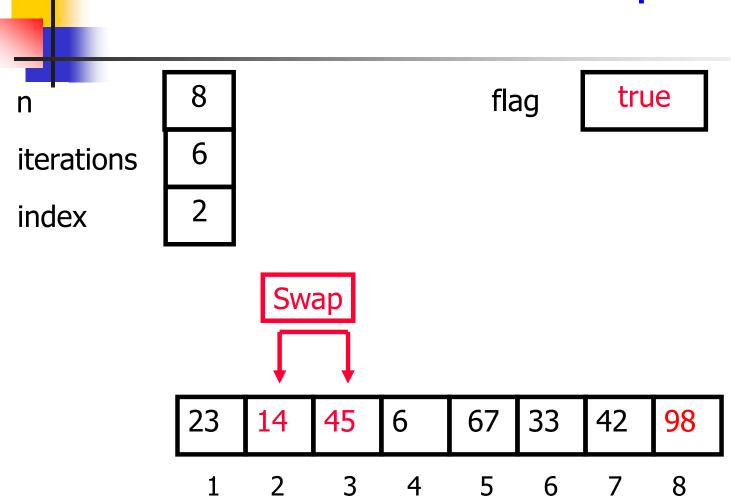
index



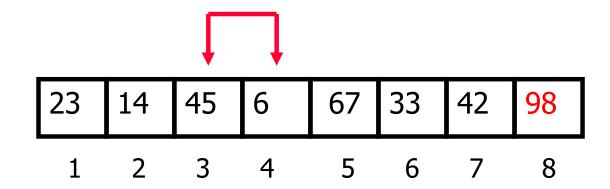
flag

false

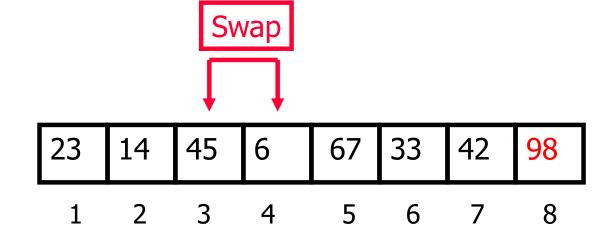


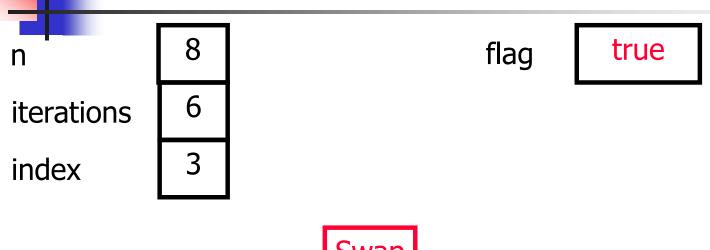


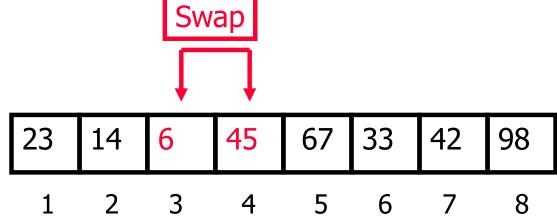


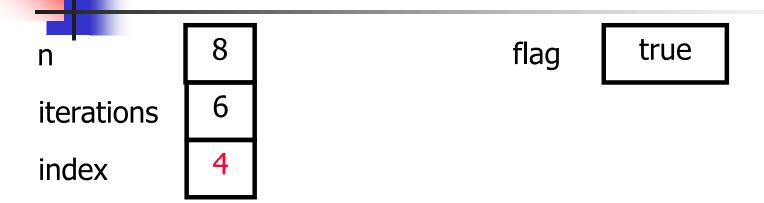


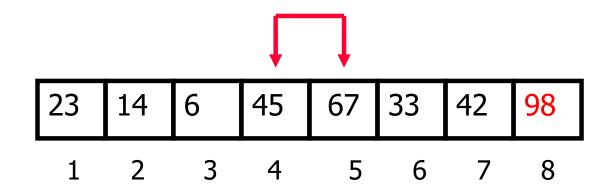




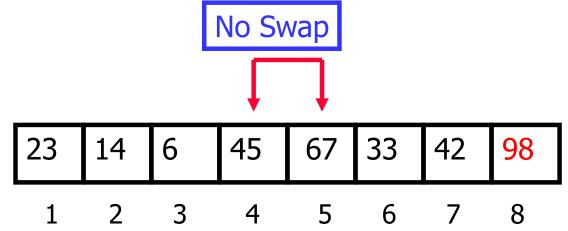




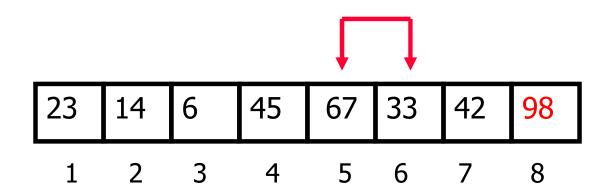


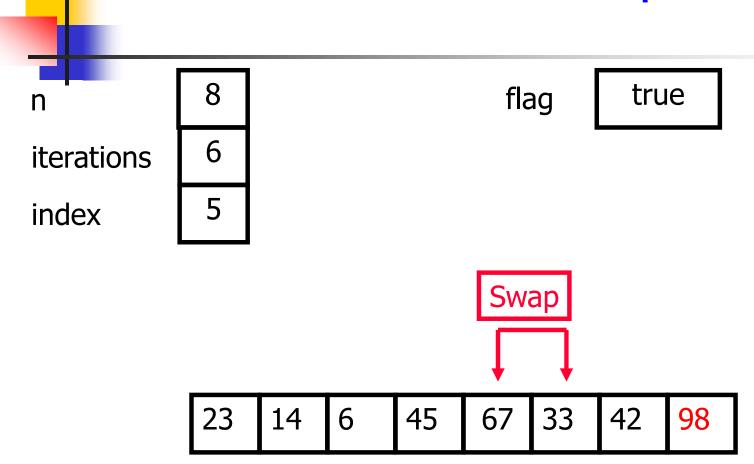


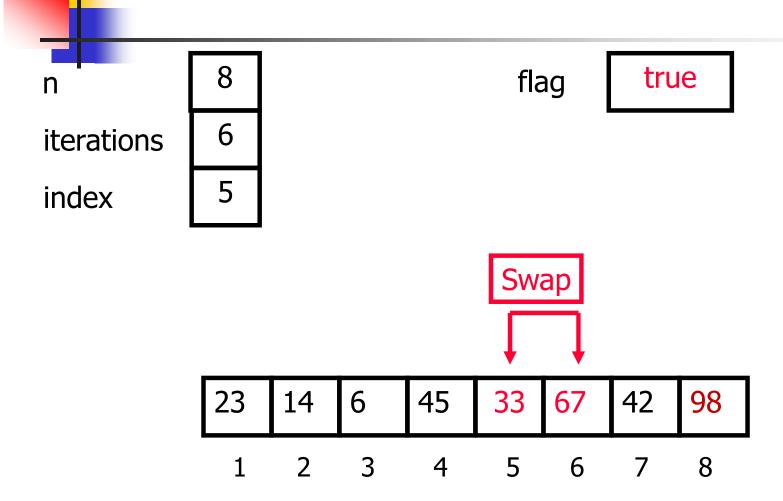




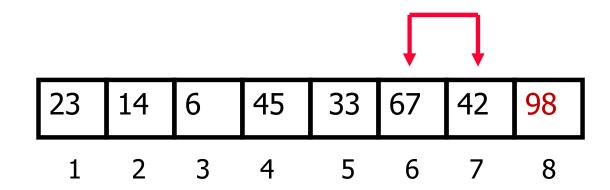
n 8 flag true iterations 6 index 5

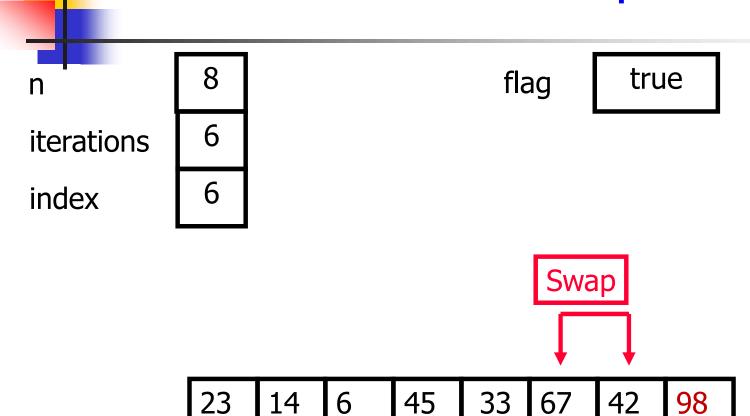


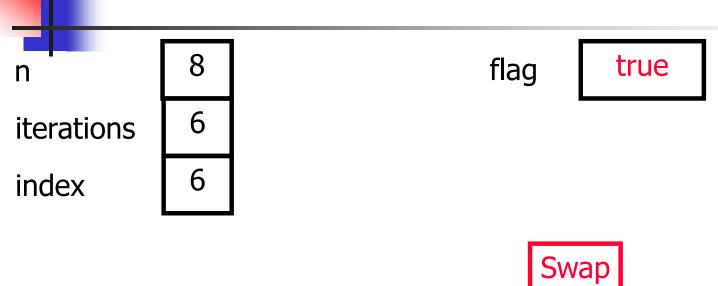


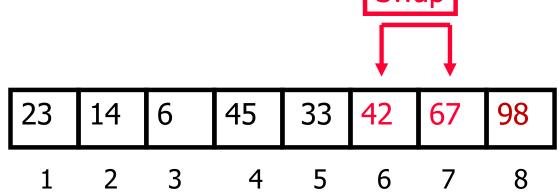






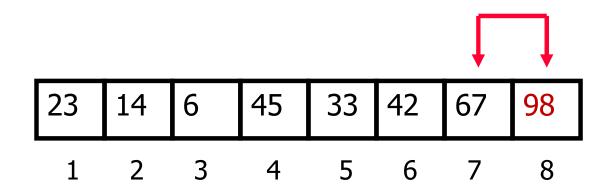




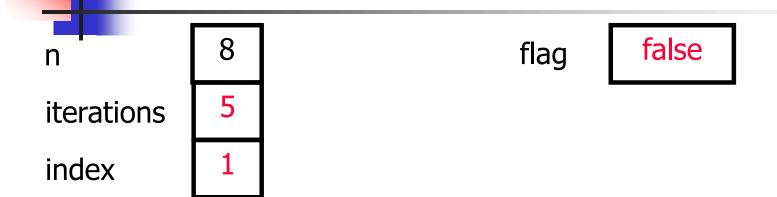


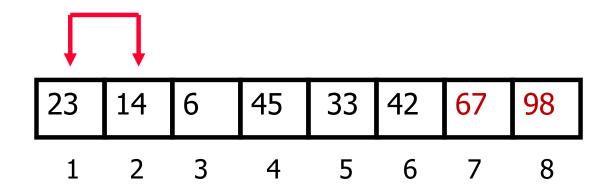
After Second Pass of Outer Loop



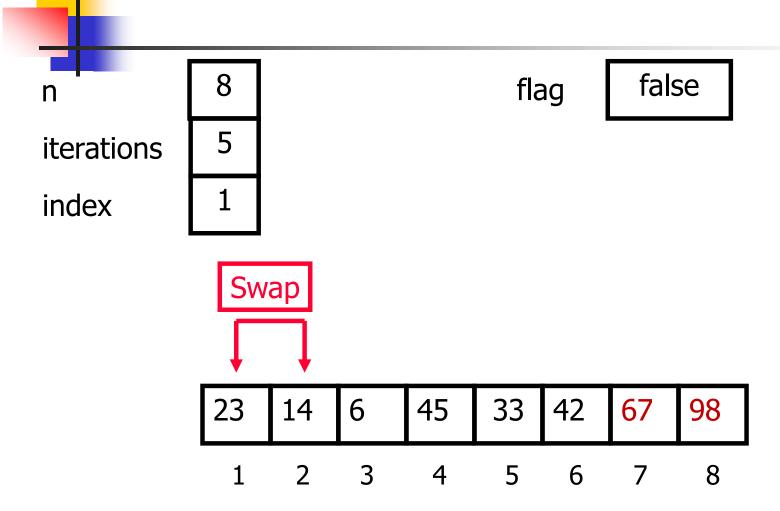


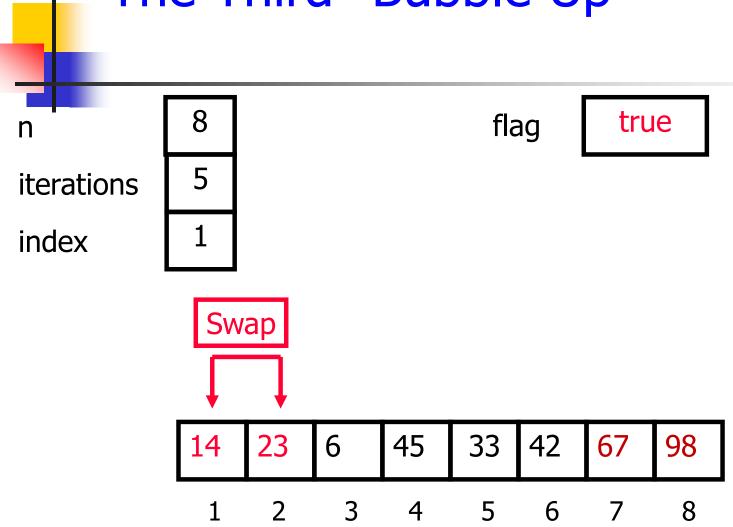
The Third "Bubble Up"

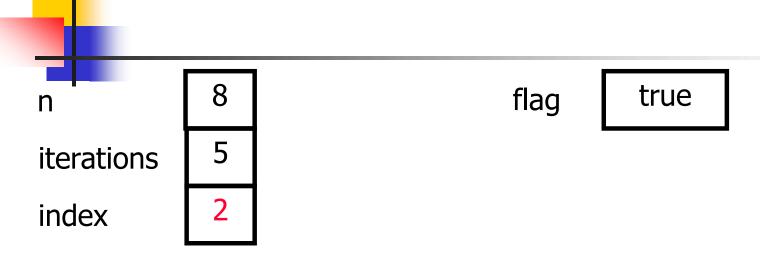


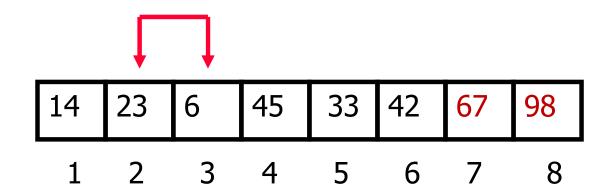


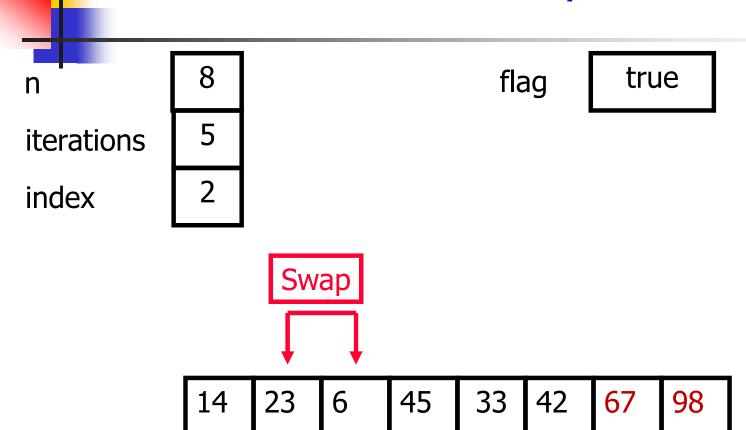
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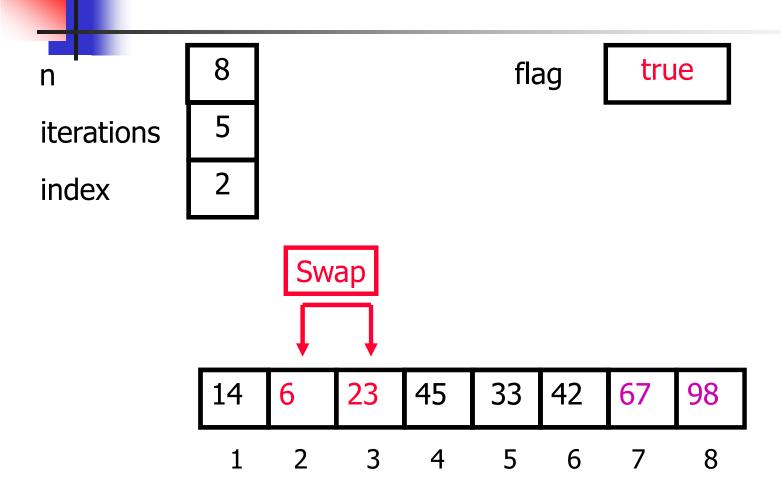




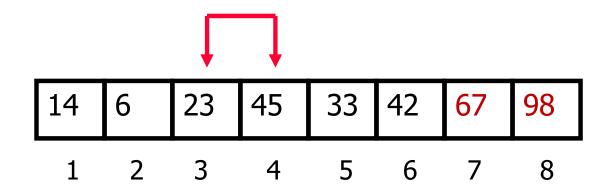




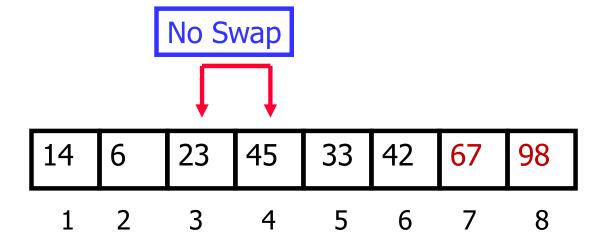


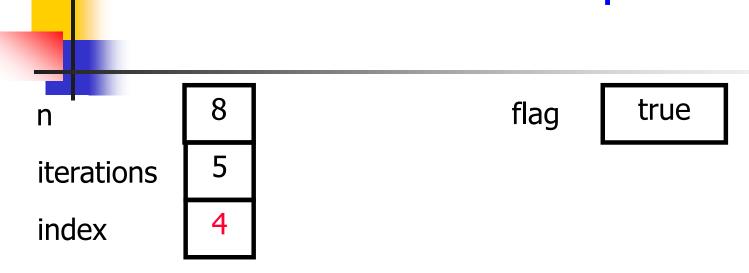


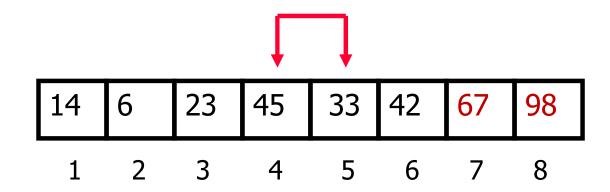




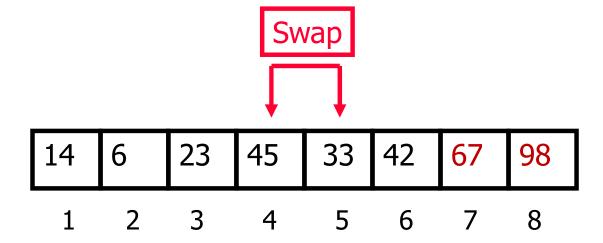


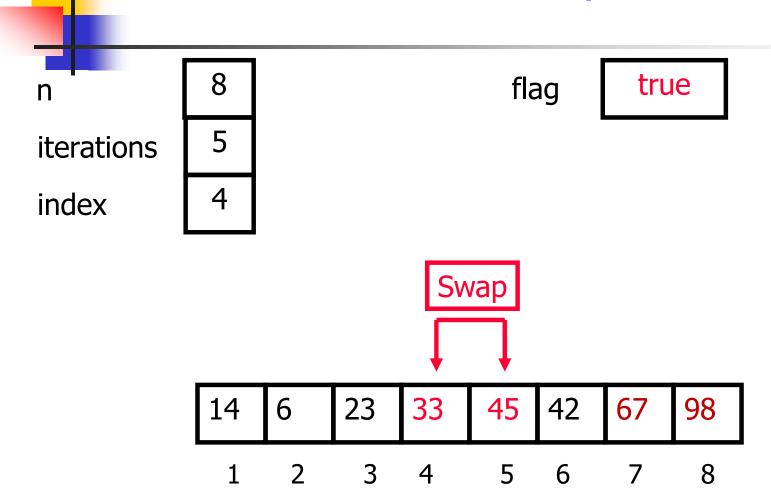




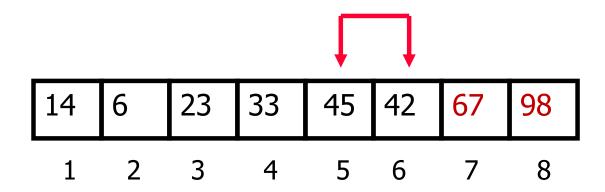


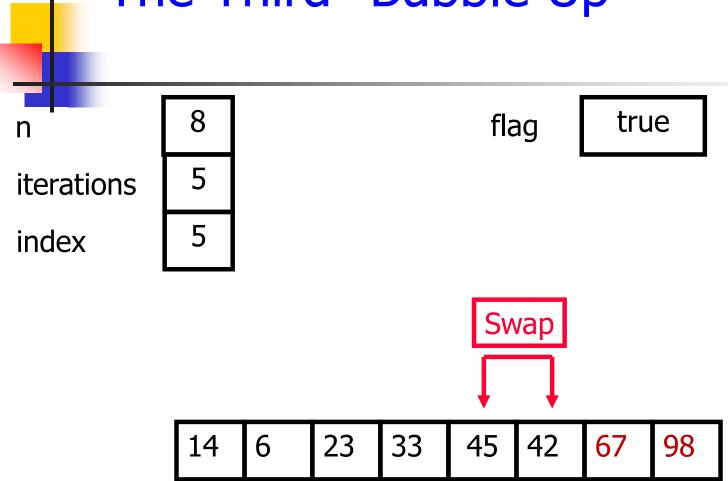


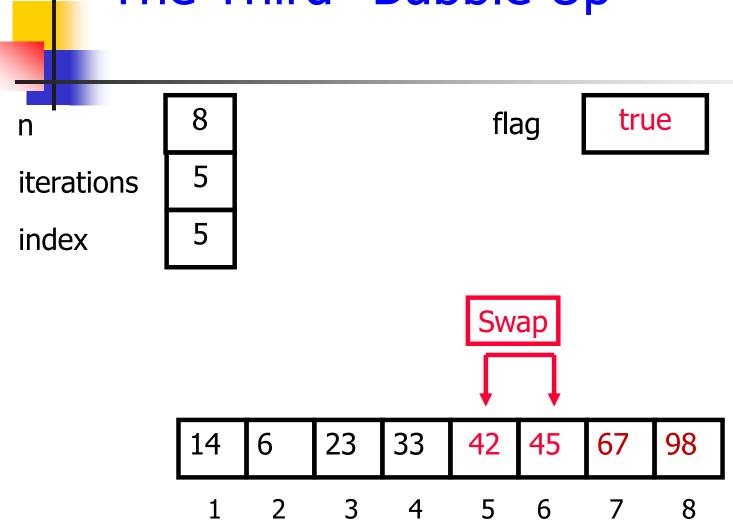






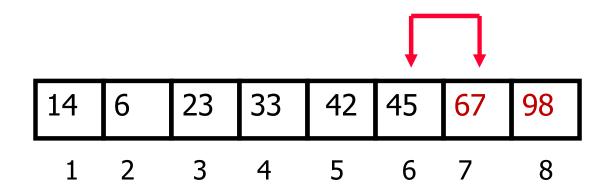


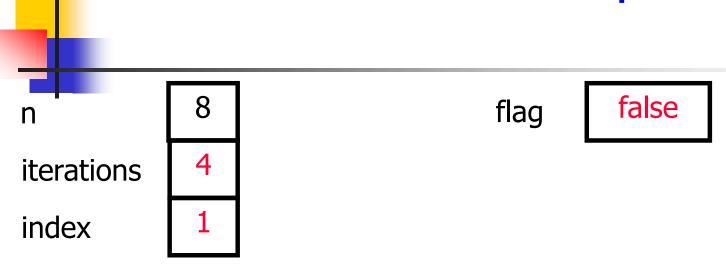


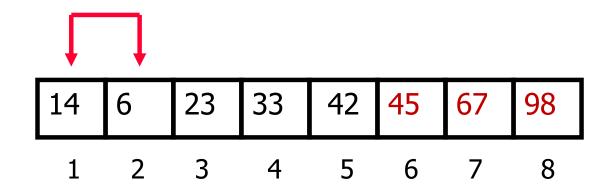


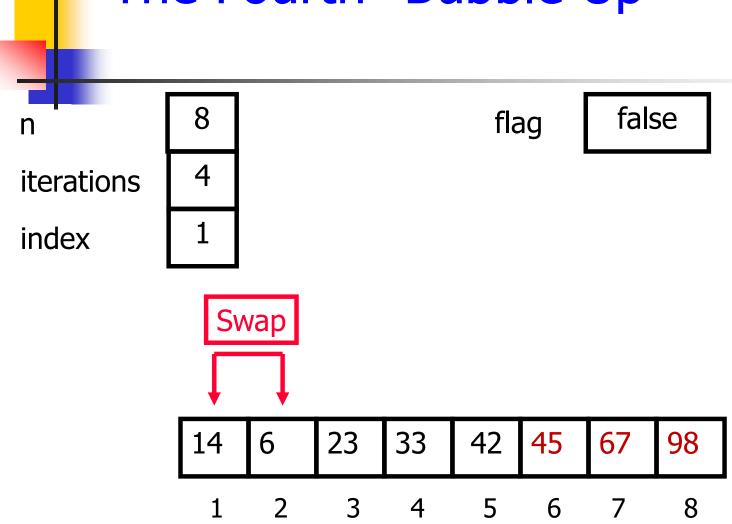
After Third Pass of Outer Loop

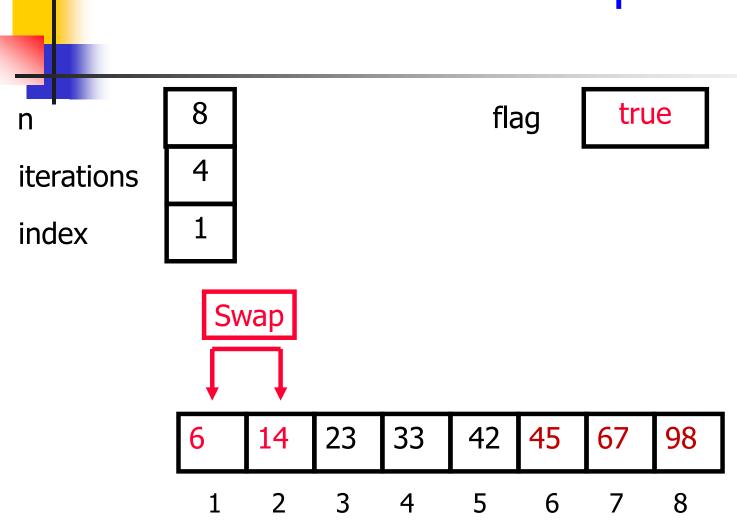


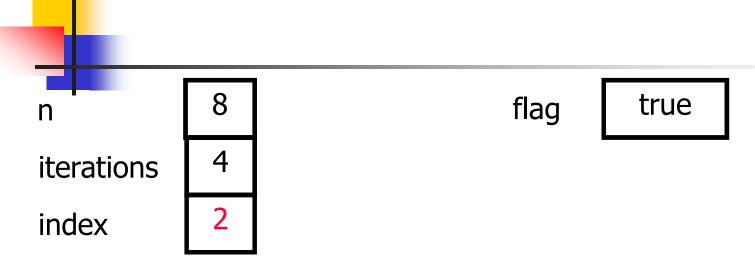


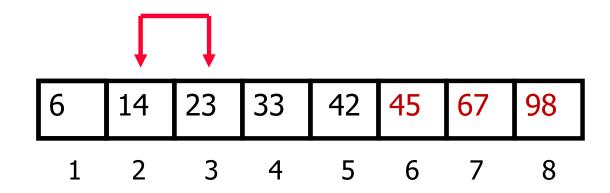


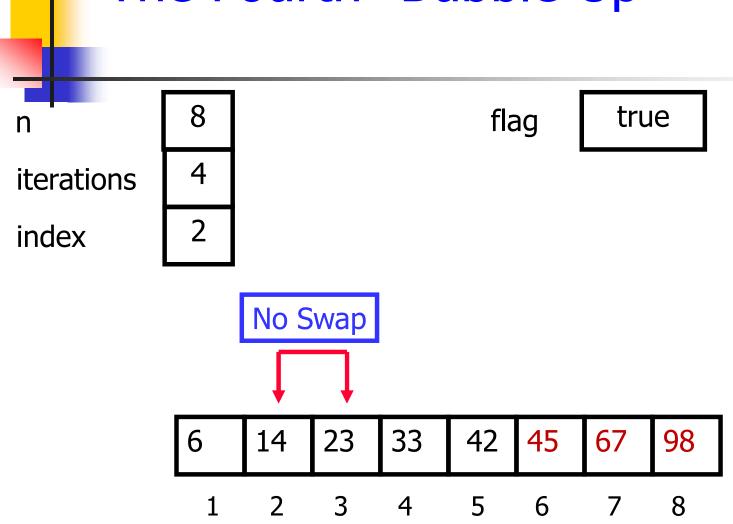


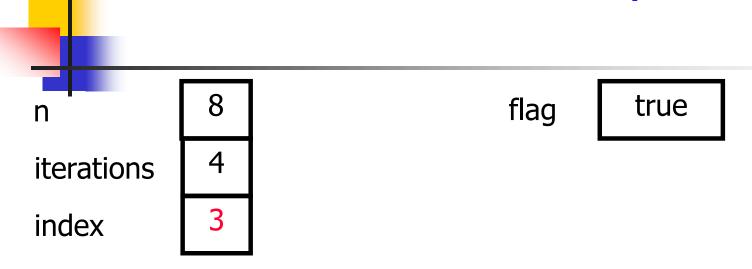


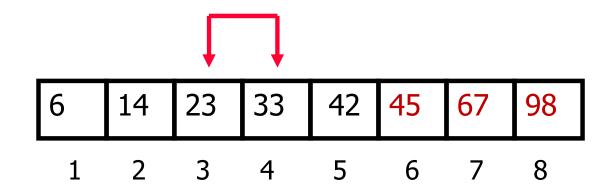


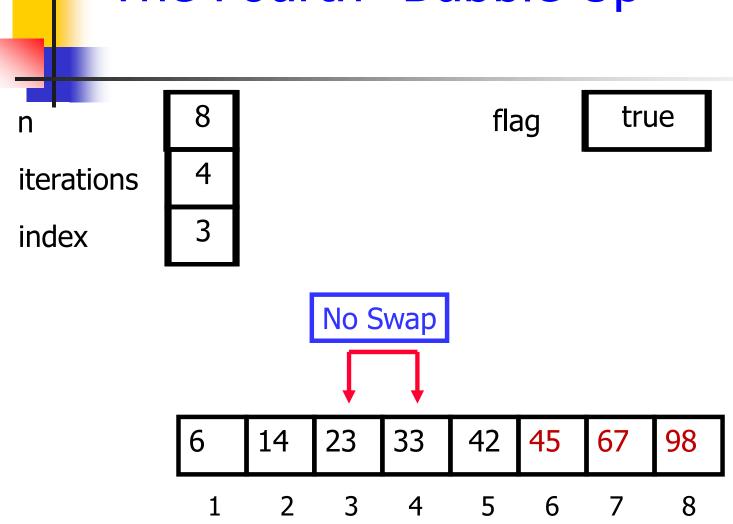


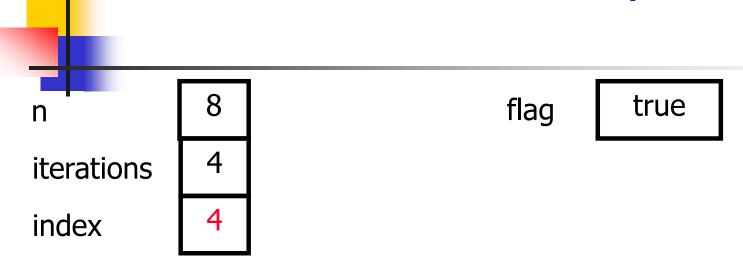


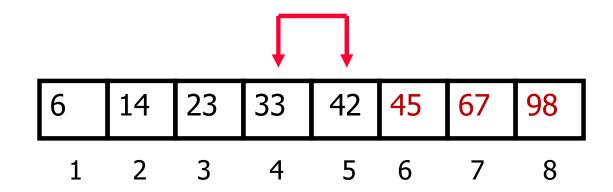


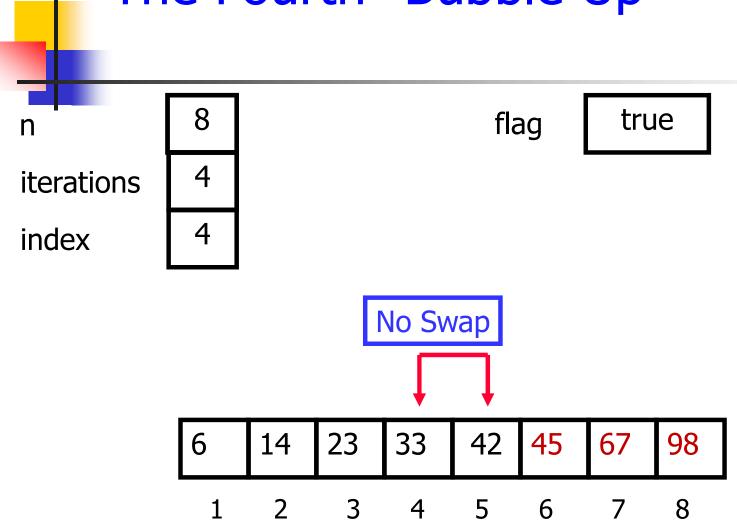






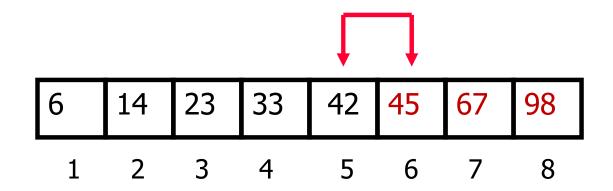


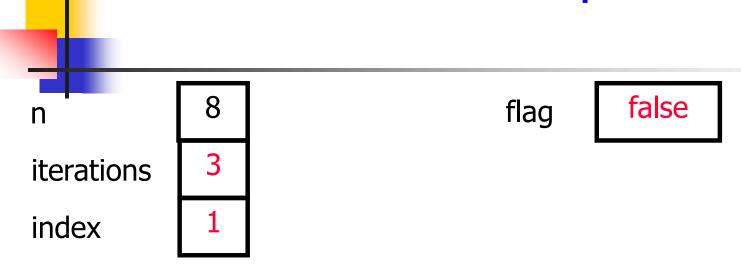


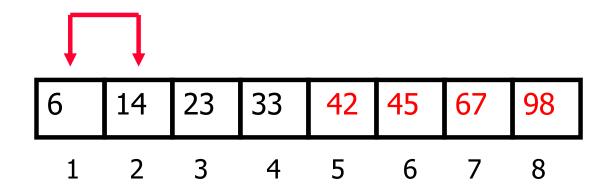


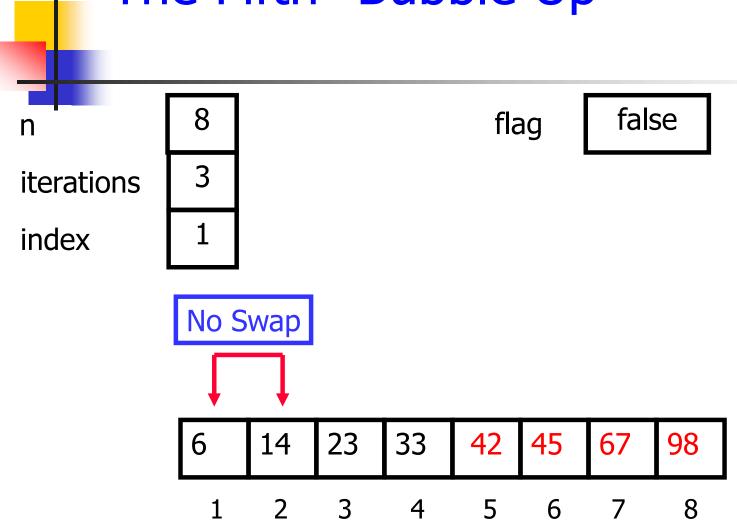
After Fourth Pass of Outer Loop

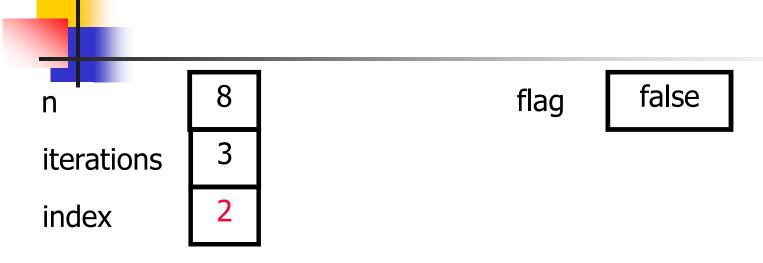


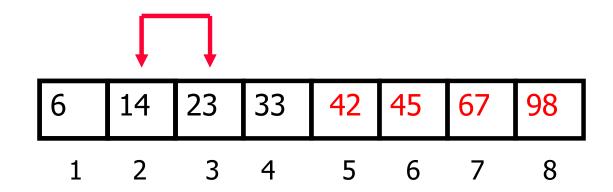


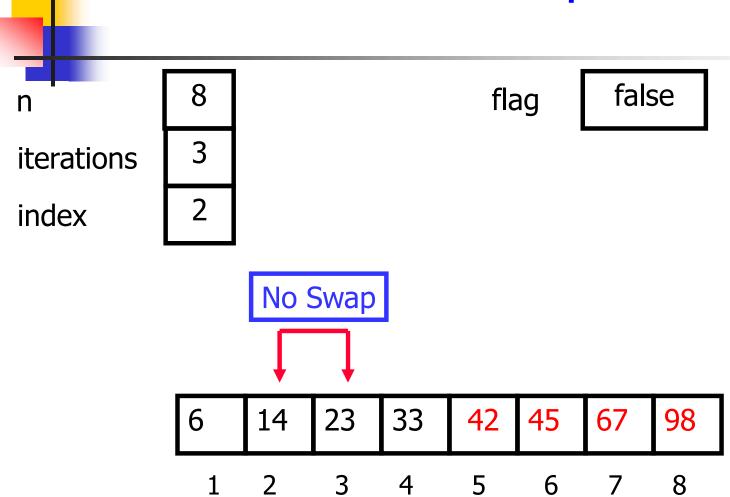


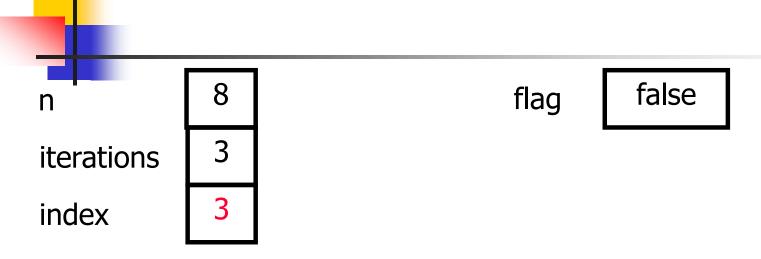


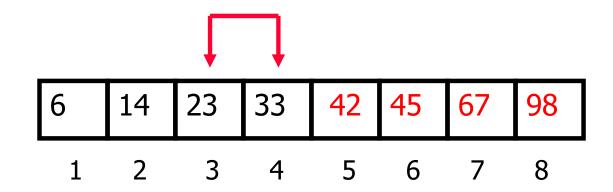


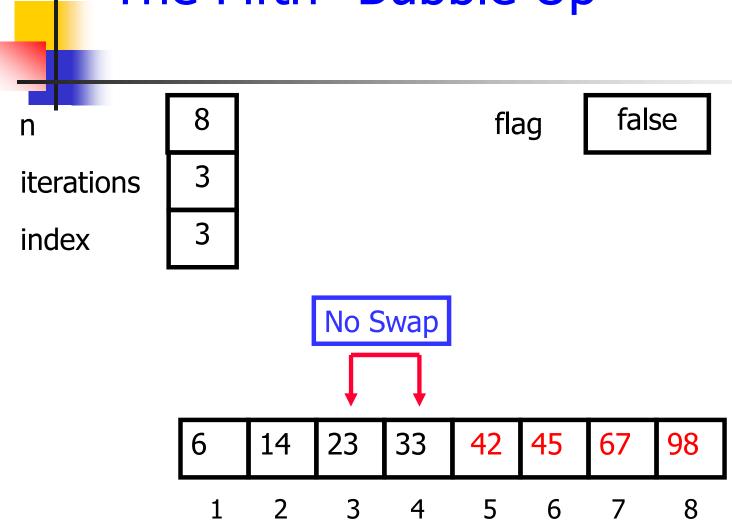






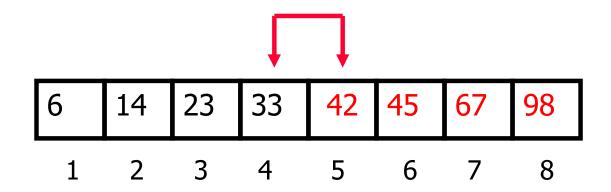




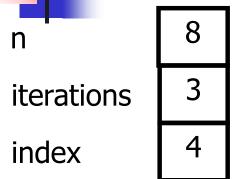


After Fifth Pass of Outer Loop





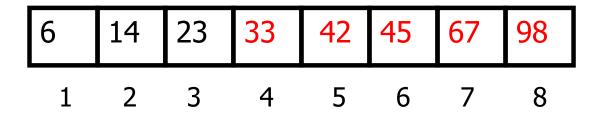
Finished "Early"



flag false
do any swapping.

We didn't do any swapping, so all of the other elements must be correctly placed.

We can "skip" the last two passes of the outer loop.



Bubble Sort

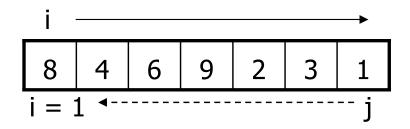
```
Alg.: Bubble-Sort(A)

for i \leftarrow 1 to length[A]

do for j \leftarrow length[A] downto i + 1

do if A[j] < A[j -1]

then exchange A[j] \leftrightarrow A[j-1]
```



Bubble Sort: Analysis

- The biggest items "bubble up" to the end of the array, as the algorithm progresses.
- Efficiency:
 - if n is number of items,
 - n-1 comparisons in first pass, n-2 in second pass, so on and so forth.
 - The formula is : $(n-1) + (n-2) + ... + 1 = n \times (n-1)/2$.
 - hence runs in $O(n^2)$ time.



Time complexity of Bubble Sort

- The worst case time complexity of Bubble sort is O(n²)
 - when the elements are in reverse sorted order
- The average case time complexity of Bubble sort is O(n²)
- The time complexity of the best case is O(n).
 - when thr elements are in <u>sorted order</u>
- The space complexity is O(1)



Selection Sort

Idea:

- Find the smallest/ largest element in the array
- Exchange it with the element in the first/ last position
- Find the <u>second</u> <u>smallest</u>/ <u>largest</u> element and exchange it with the element in the second position
- Continue until the array is sorted

Selection Sort

5 1 3 4 6 2

Comparison

Data Movement

Sorted



5 1 3 4 6 2

- Comparison
- Data Movement
- Sorted



5 1 3 4 6 2

Comparison

Data Movement

Sorted



5 1 3 4 6 2

Comparison

Data Movement

Sorted



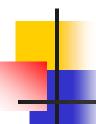
5	1	3	4	6	2

- Comparison
- Data Movement
- Sorted



5	1	3	4	6	2

- Comparison
- Data Movement
- Sorted



5	1	3	4	6	2

- Comparison
- Data Movement
- Sorted



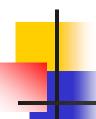
5	1	3	4	6	2

† Largest

- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



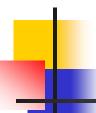
- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted





† Largest

- Comparison
- Data Movement
- Sorted



 2
 1
 3
 4
 5
 6

- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



Comparison

Data Movement

Sorted



- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted





† Largest

- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted





T **Largest**

- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted



Comparison

Data Movement

Sorted

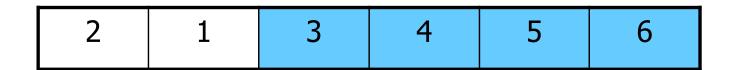


- Comparison
- Data Movement
- Sorted



- Comparison
- Data Movement
- Sorted





† Largest

- Comparison
- Data Movement
- Sorted



 1
 2
 3
 4
 5
 6

Comparison

Data Movement

Sorted



1	2	3	4	5	6

DONE!

- Comparison
- Data Movement
- Sorted

4

```
Alg.: Selection-Sort(A)
  n ← length[A]
  for j ← 1 to n-1
    do smallest ← j
    for i ← j + 1 to n
    do if A[i] < A[smallest]
        then smallest ← i
    exchange A[j] ↔ A[smallest]</pre>
```

```
Alg.: Selection-Sort(A)
  n ← length[A]
  for j ← n downto 2
    do largest ← 1
    for i ← 2 to j
    do if A[i] > A[largest]
        then largest ← i
    exchange A[j] ↔ A[largest]
```

Time complexity of Selection Sort

- The worst case time complexity of Bubble sort is O(n²)
 - when the elements are in reverse sorted order
- The average case time complexity of Bubble sort is O(n²)
- The time complexity of the best case is O(n²).
 - when thr elements are in <u>sorted order</u>
- The space complexity is O(1)

The <u>number of swaps</u> in Selection Sort are as follows:

Worst case: O(n)

Average Case: O(n)

Best Case: O(1)

Divide and Conquer

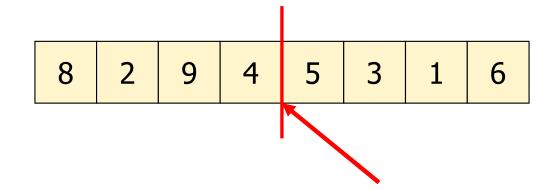
- Recursive in structure
 - <u>Divide</u> the problem into sub-problems that are similar to the original but smaller in size
 - <u>Conquer</u> the sub-problems by solving them <u>recursively</u>. If they are small enough, just solve them in a straightforward manner.
 - <u>Combine</u> the solutions to create a solution to the original problem

An Example: Merge Sort

<u>Sorting Problem:</u> Sort a sequence of n elements into non-decreasing order.

- Divide: Divide the n-element sequence to be sorted into two subsequences of n/2 elements each
- Conquer: Sort the two subsequences recursively using merge sort.
- Combine: Merge the two sorted subsequences to produce the sorted answer.





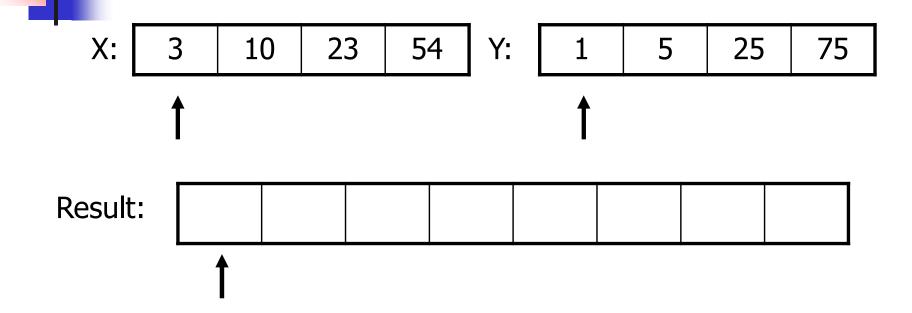
- Divide it in two at the midpoint
- Conquer each side in turn (by recursively sorting)
- Merge two halves together

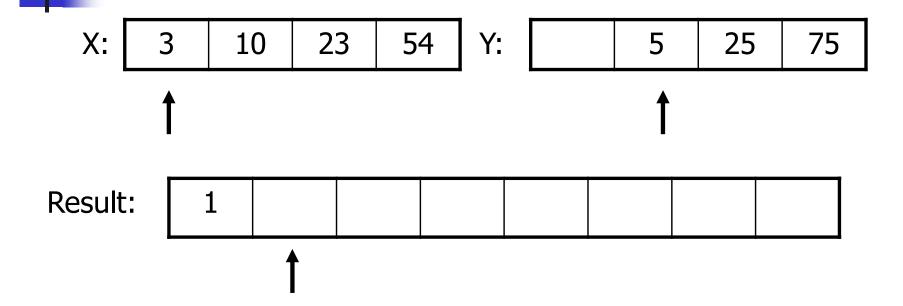
Merging

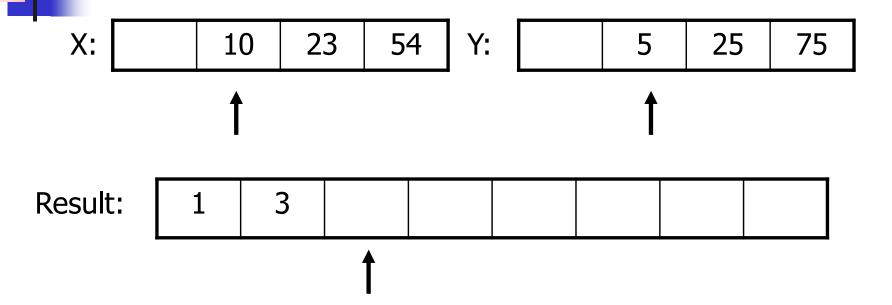
- The <u>key point</u> to Merge Sort is <u>merging</u> two sorted lists into one.
- Suppose, there are two lists X $(x_1 \le x_2 \le \dots \le x_m)$ and Y $(y_1 \le y_2 \le \dots \le y_n)$ the resulting list is $Z(z_1 \le z_2 \le \dots \le z_{m+n})$

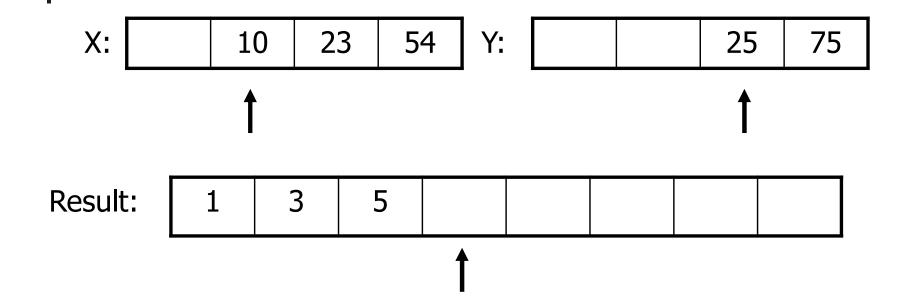
Example:

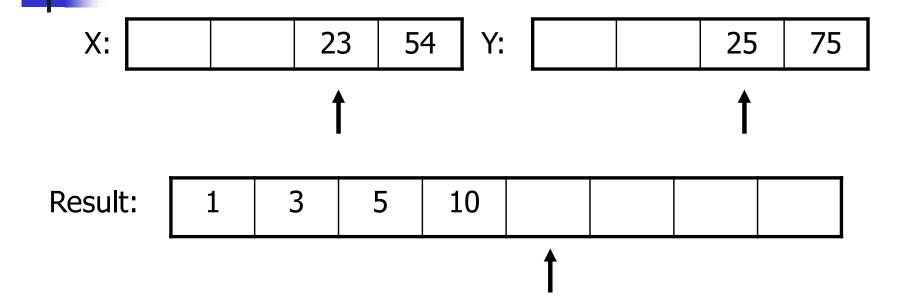
$$L_1 = \{3, 8, 9\}$$
 $L_2 = \{1, 5, 7\}$
merge(L_1 , L_2) = $\{1, 3, 5, 7, 8, 9\}$

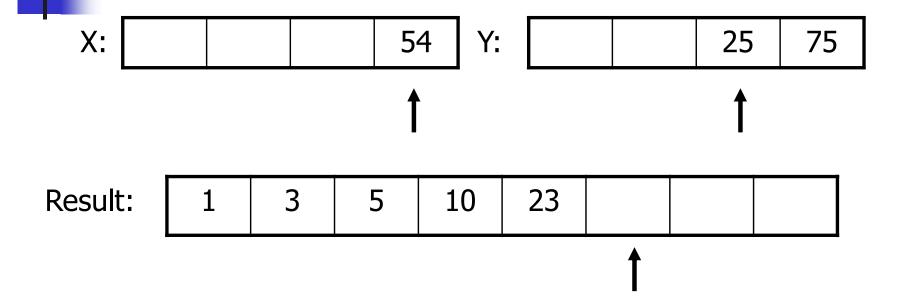


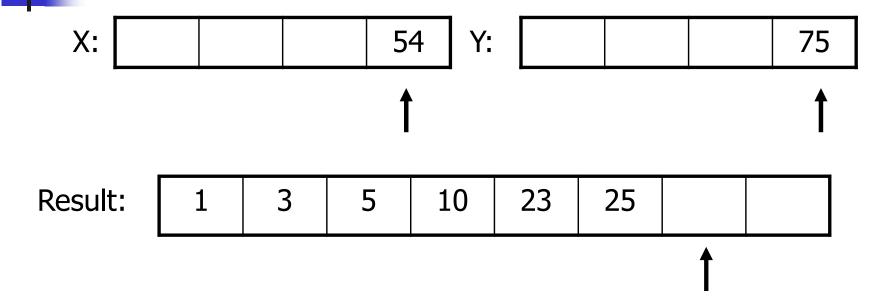


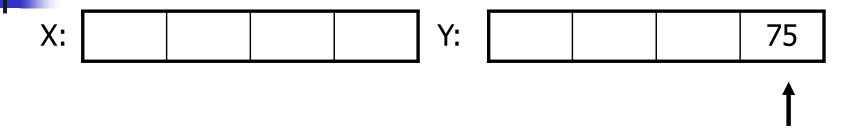












Result: 1 3 5 10 23 25 54

X: Y:

Result: 1 3 5 10 23 25 54 75

Merge-Sort (A, p, r)

Input: a sequence of *n* numbers stored in array A

Output: an ordered sequence of *n* numbers

```
MergeSort (A, p, r) // sort A[p...r] by divide & conquer 1 if p < r 2 then q \leftarrow \lfloor (p+r)/2 \rfloor 3 MergeSort (A, p, q) 4 MergeSort (A, q+1, r) 5 Merge (A, p, q, r) // merges A[p..q] with A[q+1..r]
```

Initial Call: MergeSort(A, 1, n)

99	6	86	15	58	35	86	4	0
----	---	----	----	----	----	----	---	---



99 6 86 15 58 35 86 4 0

99 6 86 15

58	35	86	4	0



99 6 86 15 58 35 86 4 0

99 6 86 15

58 35 86 4 0

99 6

86 | 15

58 35

86 4 0



99 6 86 15 58 35 86 4 0

99 6 86 15

58 35 86 4 0

99 6

86 | 15

58 35

86 4 0

99

6

86

15

58

35

86

4 0



99 6 86 15 58 35 86 4 0

99 6 86 15 58 35 86 4 0

99 | 6 | 86 | 15

58 | 35 | 86 | 4

99 6 86 15 58 35 86 4 0

ļ ||

0

0

4

Merge Sort Example



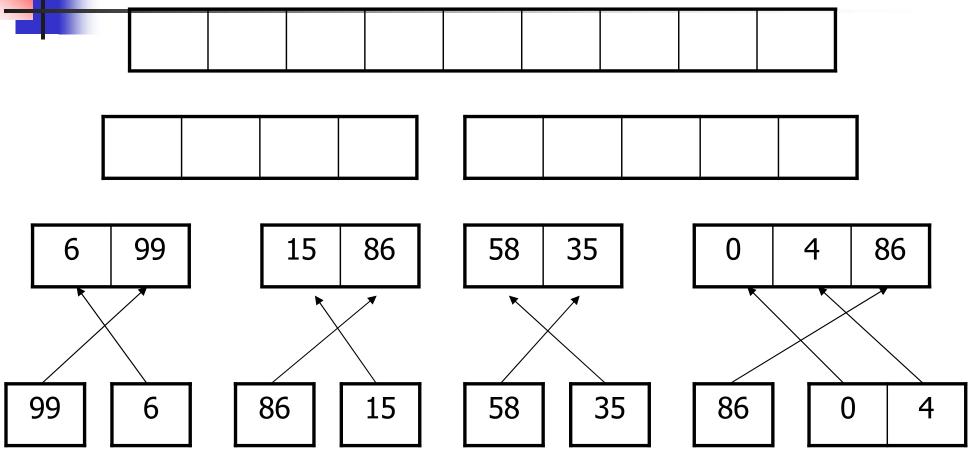




99 6 86 15 58 35 86 0 4

Merge 4

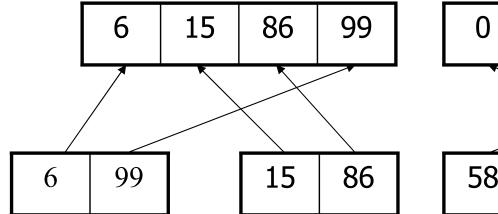


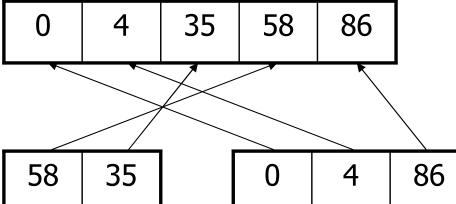


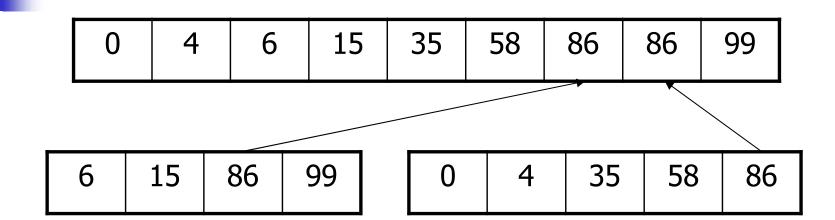
Merge











0	4	6	15	35	58	86	86	99
---	---	---	----	----	----	----	----	----

Merge Algorithm

```
void merge(int *arr, int beg, int mid, int end) {
          int temp[end - beg + 1];
           int i = beg, j = mid+1, k = 1;
          while(i \leq mid && j \leq end) {
                     if(arr[i] <= arr[j]) {</pre>
                                temp[k] = arr[i];
                                k += 1; i += 1;
                     }
                     else {
                                temp[k] = arr[j];
                                k += 1; j += 1;
           }
          // add elements left in the first interval
          while(i <= mid) {</pre>
                     temp[k] = arr[i];
                     k += 1; i += 1;
```

```
// add elements left in the second interval
          while(j \le end) {
                    temp[k] = arr[j];
                    k += 1; i += 1;
          }
          // copy temp to original interval
          for(i = beg; i \le end; i++)
                     arr[i] = temp[i - beg];
```

Implementing Merge Sort

Basic way to implement merge sort:

- Merging is done with a temporary array of the same size as the input array
 - Pro: Faster
 - Con: The memory requirement is doubled.

Merge Sort Analysis

The Double Memory Merge Sort runs O(n log n) for all cases, because of its Divide and Conquer approach.

$$T(n) = 2T(n/2) + n = O(n log n)$$

QuickSort

- The quick sort uses divide and conquer to gain the same advantages as the merge sort, while not using additional storage.
- As a trade-off, it is possible that the list <u>may not</u> be divided in half.
- When this happens, it has been seen that <u>performance is</u> diminished.



Quick Sort

- Fastest known sorting algorithm in practice
- Average case: O(n log n)
- Worst case: $O(n^2)$
 - But the worst case can be made <u>exponentially unlikely</u>.
- Another <u>divide-and-conquer recursive algorithm</u>, like merge sort.



- A quick sort first selects a value, which is called the <u>pivot value</u>.
- Although there are many different ways to choose the pivot value, it is simply used the <u>first/last item</u> in the list
- The role of the pivot value is to assist with splitting the list.
- The actual position where the pivot value belongs in the final sorted list, commonly called the split point, will be used to divide the list for subsequent calls to the quick sort.



Quick Sort: Main Idea

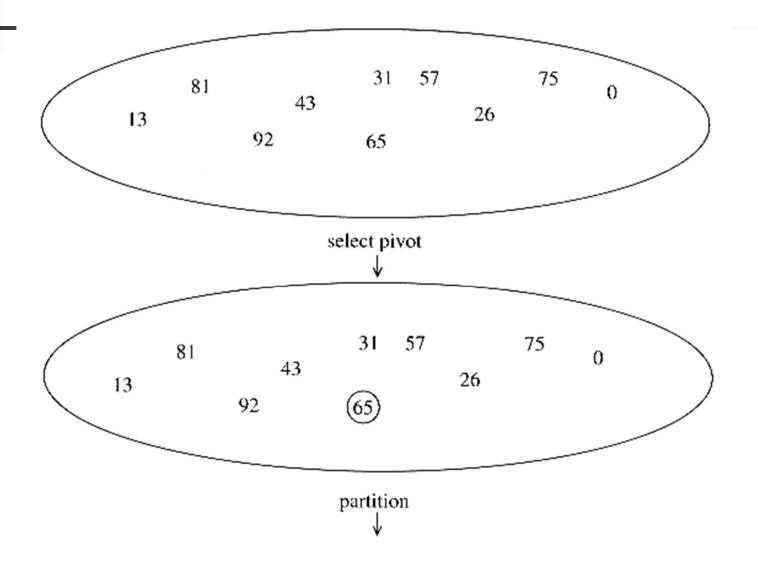
- 1. If the number of elements in S is 0 or 1, then return (<u>base case</u>).
- 2. Pick any element v in S (called the <u>pivot</u>).
- 3. Partition the elements in S except v into two disjoint groups:

1.
$$S_1 = \{x \in S - \{v\} \mid x \le v\}$$

2.
$$S_2 = \{x \in S - \{v\} \mid x \ge v\}$$

4. Return $\{QuickSort(S_1) + v + QuickSort(S_2)\}$

Quick Sort: Example



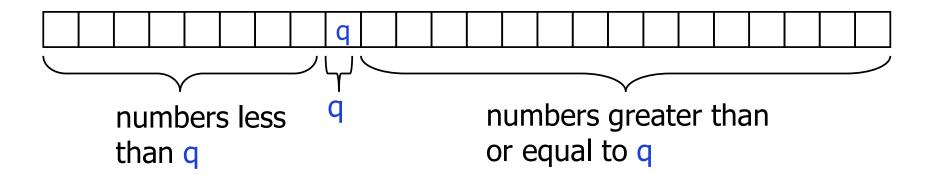
QuickSort

<u>Divide-and-Conquer</u>:

- Divide: partition A[p..r] into two subarrays A[p..q-1] and A[q+1..r] such that each element of A[p..q-1] is ≤ A[q], and each element of A[q+1..r] is ≥ A[q].
 - Compute q as part of this partitioning.
- Conquer: sort the subarrays A[p..q-1] and A[q+1..r] by recursive calls to Quicksort.
- Combine: the partitioning and recursive sorting leave us with a sorted A[p..r]

Partitioning (Quicksort)

- A key step in the Quicksort algorithm is partitioning the array
 - choose some (any) number q in the array to use as a pivot
 - partition the array into three parts:



QuickSort

The Pseudo-Code

```
QUICKSORT(A, p, r) PARTITION(A, p, r)

1 if p < r

2 q = PARTITION(A, p, r)

3 QUICKSORT(A, p, q - 1)

4 QUICKSORT(A, q + 1, r)

1 x = A[r]

2 i = p - 1

3 for j = p to r - 1

4 if A[j] \le x

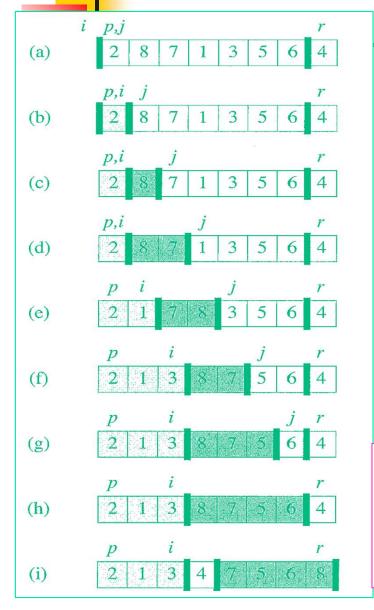
5 i = i + 1

6 exchange A[i] with A[j]

7 exchange A[i + 1] with A[r]

8 return i + 1
```

QuickSort



```
PARTITION(A, p, r)

1  x = A[r]

2  i = p - 1

3  for j = p to r - 1

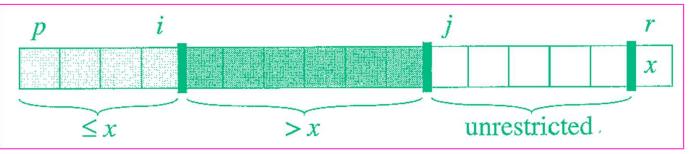
4   if A[j] \le x

5   i = i + 1

6   exchange A[i] with A[j]

7  exchange A[i + 1] with A[r]

8  return i + 1
```



Partitioning

- Choose an array value (say, the first/ last) to use as the pivot
- Starting from the left end, find the first element that is greater than or equal to the pivot
- Searching backward from the right end, find the first element that is less than the pivot
- Interchange (swap) these two elements
- Repeat, searching from where <u>we left off, until done</u>

Another way: Partition method

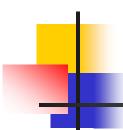
```
int partition(int a[], int left, int right) {
   int p = a[left], l = left + 1, r = right;
   int temp;
   while (l < r) {
      while (I < right \&\& a[I] < p) I++;
      while (r > left && a[r] >= p) r--;
      if (1 < r) {
          temp = a[I];
         a[l] = a[r];
         a[r] = temp;
   a[left] = a[r];
   a[r] = p;
   return r;
```

left moves to the right until value that should be to right of pivot...

right moves to the left until value that should be to left of pivot...

Quicksort method

```
void quicksort(int a[], int left, int right) {
   if (left < right) {
      int p = partition(a, left, right);
      quicksort(a, left, p - 1);
      quicksort(a, p + 1, right);
   }
}</pre>
```



0	1	2	3	4	5
6	5	9	12	3	4



partition(a, 0, 5)

0	1	2	3	4	5
6	5	9	12	3	4



partition(a, 0, 5)

pivot=?

 0
 1
 2
 3
 4
 5

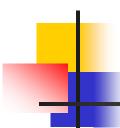
 6
 5
 9
 12
 3
 4

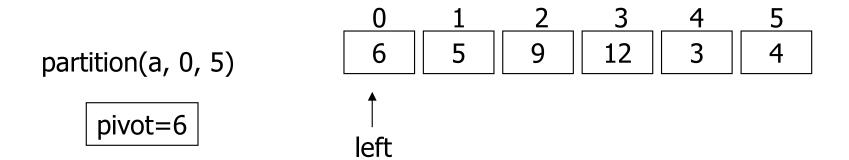


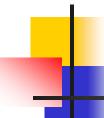
partition(a, 0, 5)

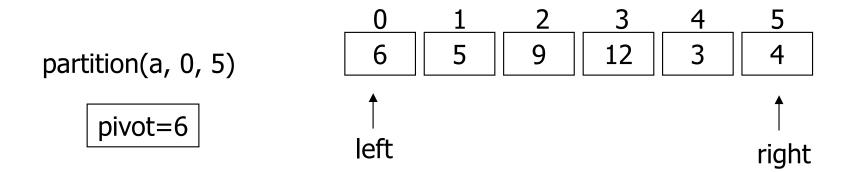
pivot=6

0	1	2	3	4	5
6	5	9	12	3	4

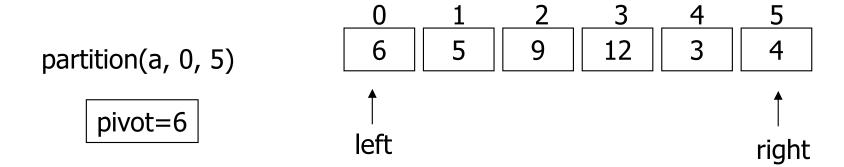






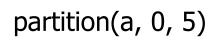


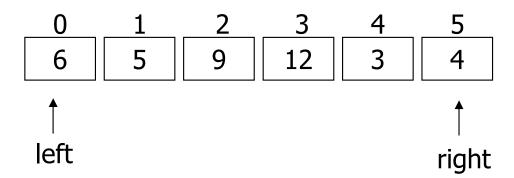




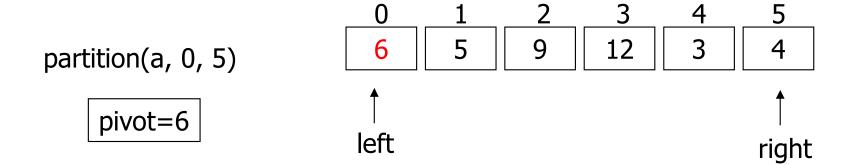
right moves to the left until value that should be to left of pivot...





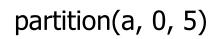


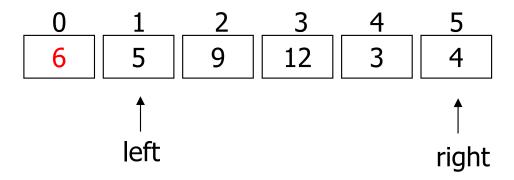




left moves to the right until value that should be to right of pivot...



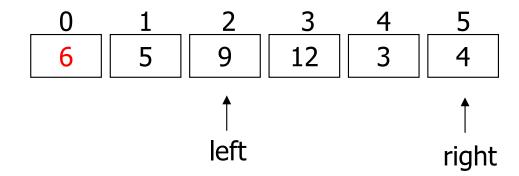




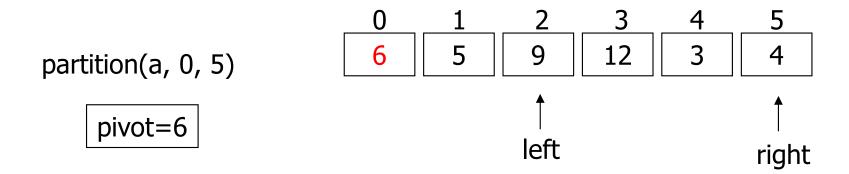


partition(a, 0, 5)

pivot=6

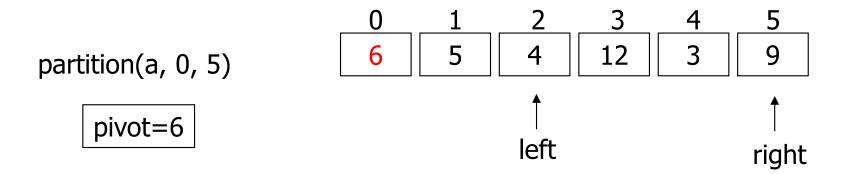






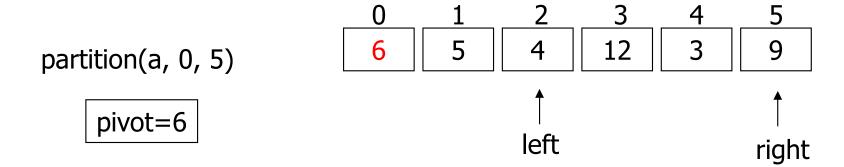
swap arr[left] and arr[right]





repeat right/left scan UNTIL left & right cross





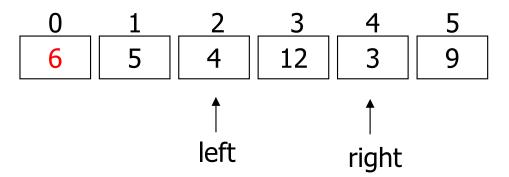
right moves to the left until value that should be to left of pivot...



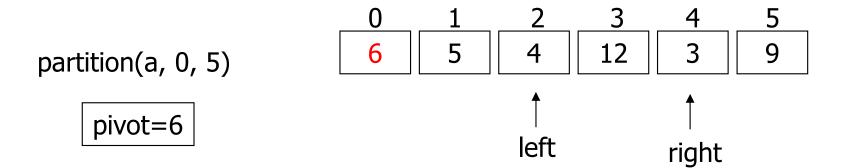
quickSort(arr,0,5)

partition(arr,0,5)

pivot=6





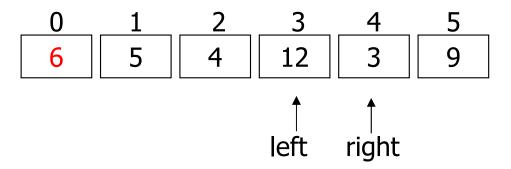


left moves to the right until value that should be to right of pivot...

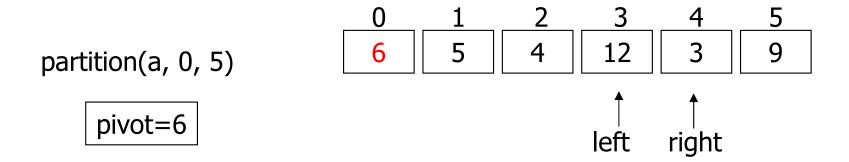


partition(a, 0, 5)

pivot=6

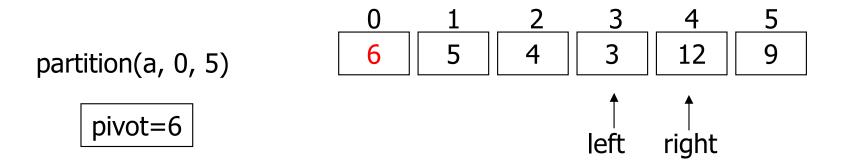






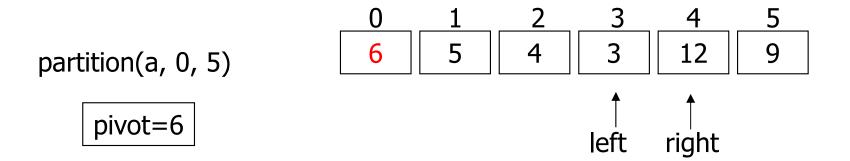
swap arr[left] and arr[right]



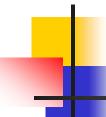


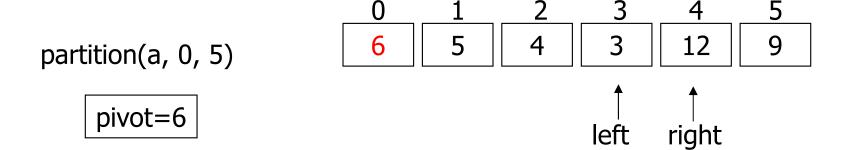
swap arr[left] and arr[right]





repeat right/left scan UNTIL left & right cross



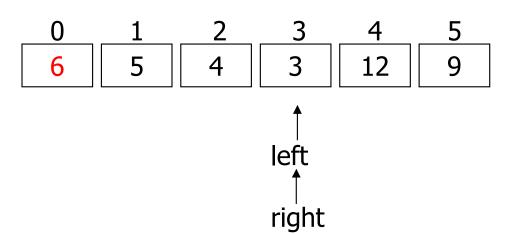


right moves to the left until value that should be to left of pivot...

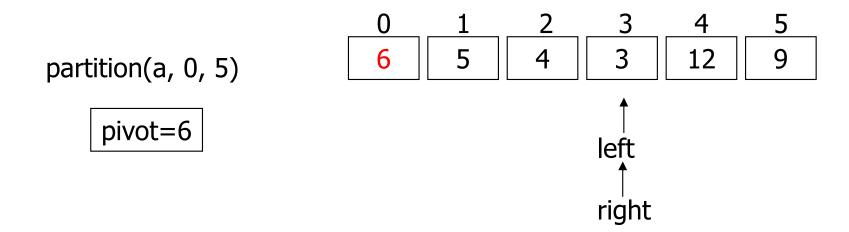


partition(a, 0, 5)

pivot=6







right & left CROSS!!!



partition(a, 0, 5)

6

5

4

5

pivot=6

pivot=6

right & left CROSS!!!

1 - Swap pivot and arr[right]

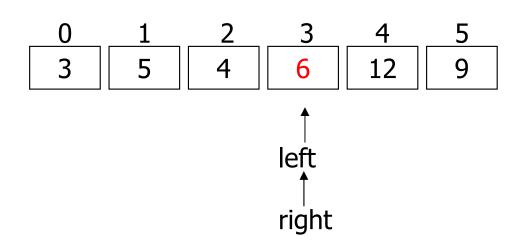


right & left CROSS!!!
1 - Swap pivot and arr[right]



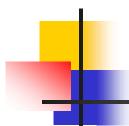
partition(a, 0, 5)

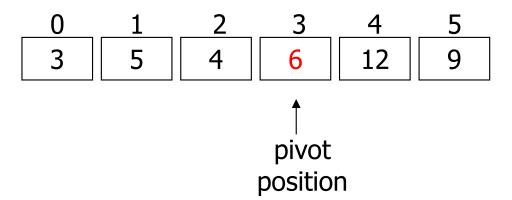
pivot=6



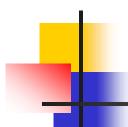
right & left CROSS!!!

- 1 Swap pivot and arr[right]
- 2 Return new location of pivot to caller





Recursive calls to quickSort() using partitioned array...





6



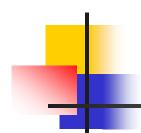
quickSort(a, 0, 2)

5

	3	

4	5	
12	9	

quickSort(a, 4, 5)

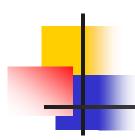


quickSort(a, 0, 2) partition(a, 0, 2)

 $\begin{array}{c|ccccc}
0 & 1 & 2 \\
\hline
3 & 5 & 4 \\
\end{array}$

<u>3</u> 6 4 5 12 9

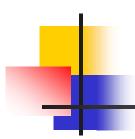
quickSort(a, 4, 5)



quickSort(a, 0, 2) partition(a, 0, 2)

0	1	2
3	5	4

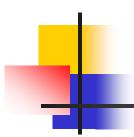
quickSort(a, 4, 5)



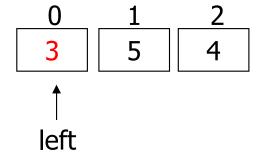
quickSort(a, 0, 2) partition(a, 0, 2)

<u>3</u> 6 4 5 12 9

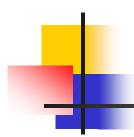
quickSort(a, 4, 5)



quickSort(a, 0, 2) partition(a, 0, 2)

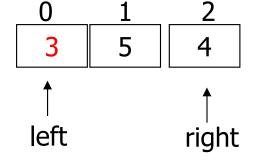


quickSort(a, 4, 5)



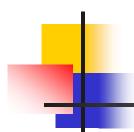


quickSort(a, 0, 2) partition(a, 0, 2)



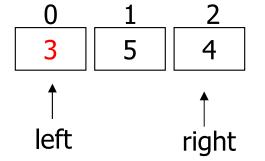
quickSort(a, 4, 5)

Partition Initialization...

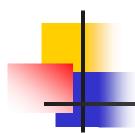




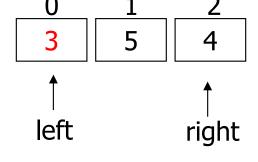




right moves to the left until value that should be to left of pivot...



quickSort(a, 0, 2) partition(a, 0, 2)



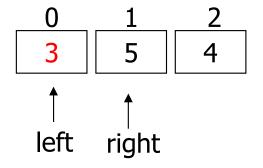
3	
6	

4	5
12	9

quickSort(a, 4, 5)



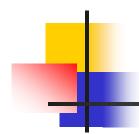
quickSort(a, 0, 2) partition(a, 0, 2)



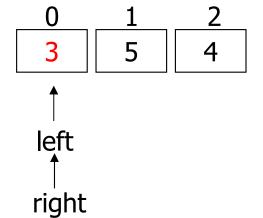
3	
6	

4	5
12	9

quickSort(a, 4, 5)



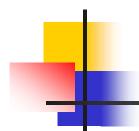
quickSort(a, 0, 2) partition(a, 0, 2)



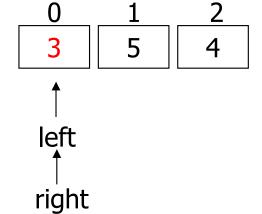
3	
6	

4	5
12	9

quickSort(a, 4, 5)



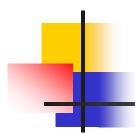
quickSort(a, 0, 2) partition(a, 0, 2)



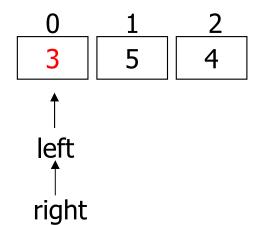
3	
6	

quickSort(a, 4, 5)

right & left CROSS!!!



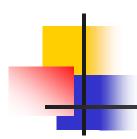
quickSort(a, 0, 2) partition(a, 0, 2)



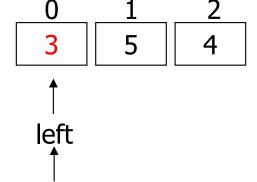
3 6 4 5 12 9

quickSort(a, 4, 5)

right & left CROSS!!!
1 - Swap pivot and arr[right]



quickSort(a, 0, 2) partition(a, 0, 2)



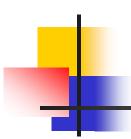
right

<u>3</u> 6 4 5 12 9

quickSort(a, 4, 5)

right & left CROSS!!!

- 1 Swap pivot and arr[right]
- 2 Return new location of pivot to caller



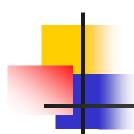
quickSort(a, 0, 2)

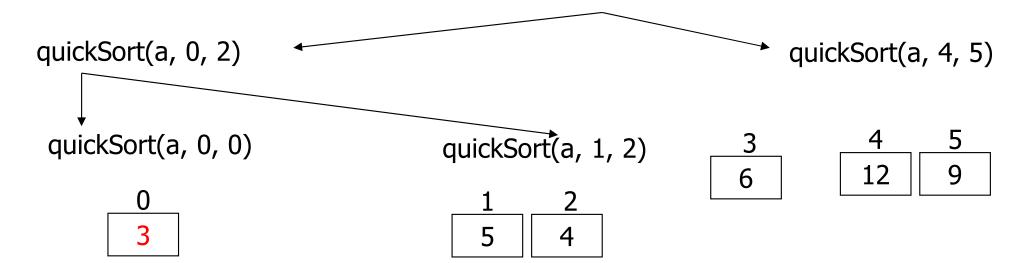
3

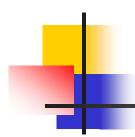
4 5 12 9

quickSort(a, 4, 5)

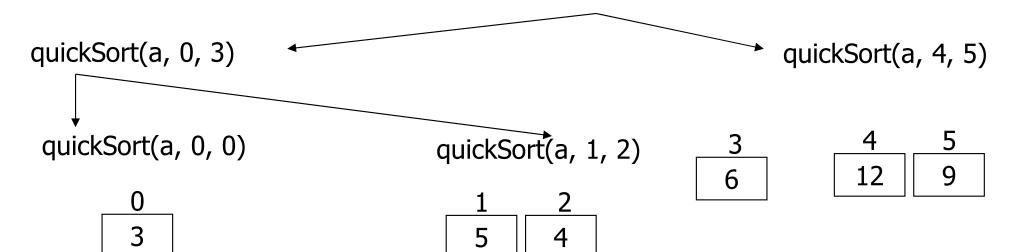
Recursive calls to quickSort() using partitioned array...



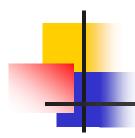


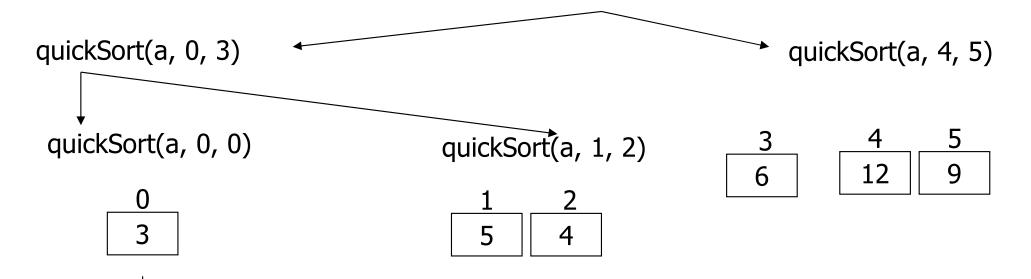




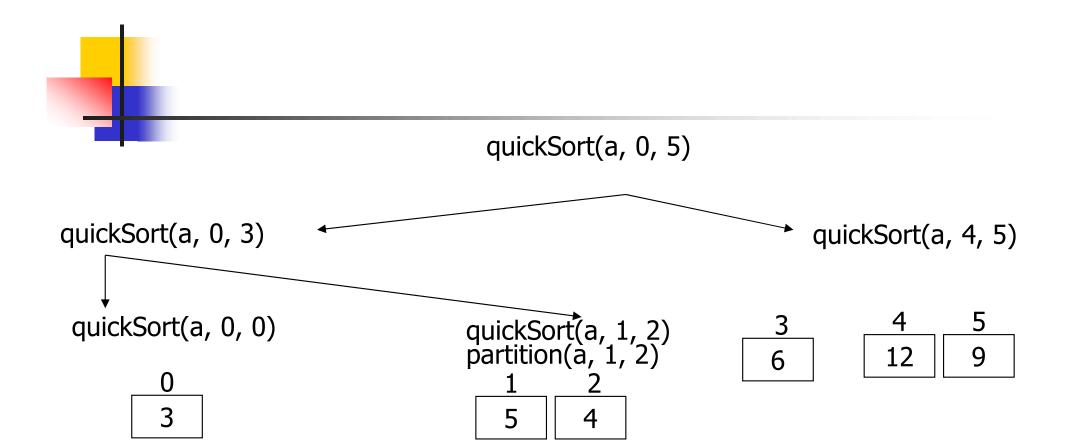


Base case triggered... halting recursion.

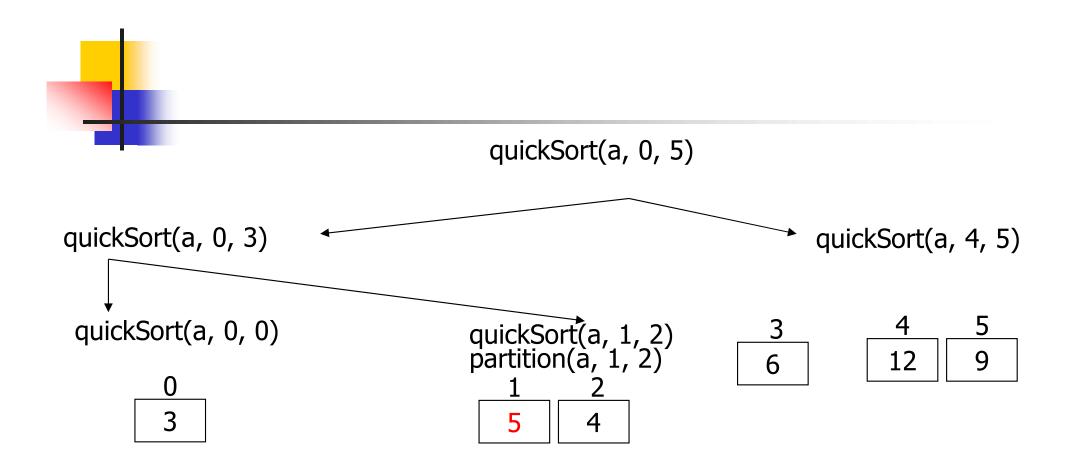




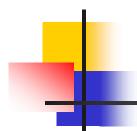
Base Case: Return



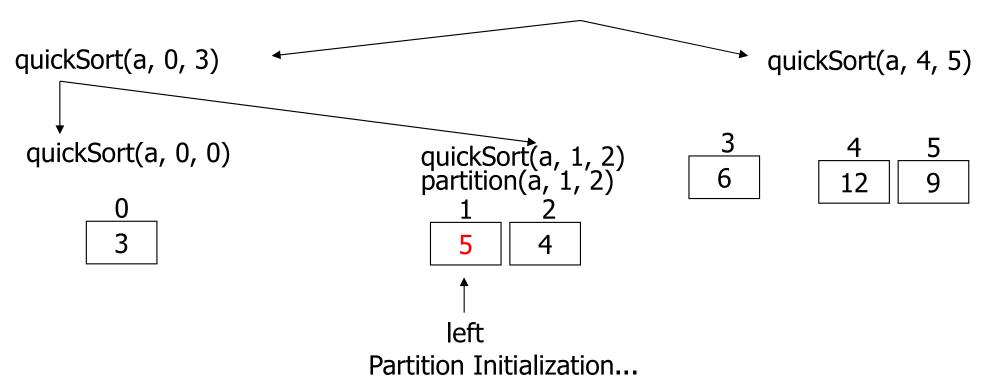
Partition Initialization...

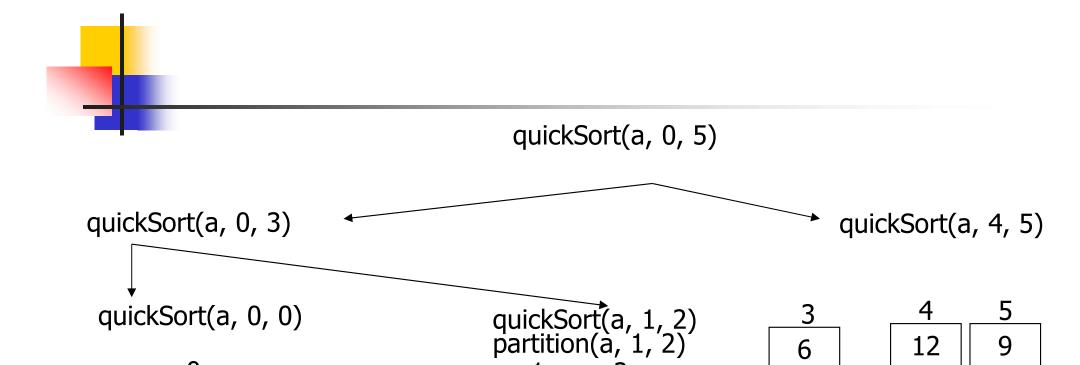


Partition Initialization...





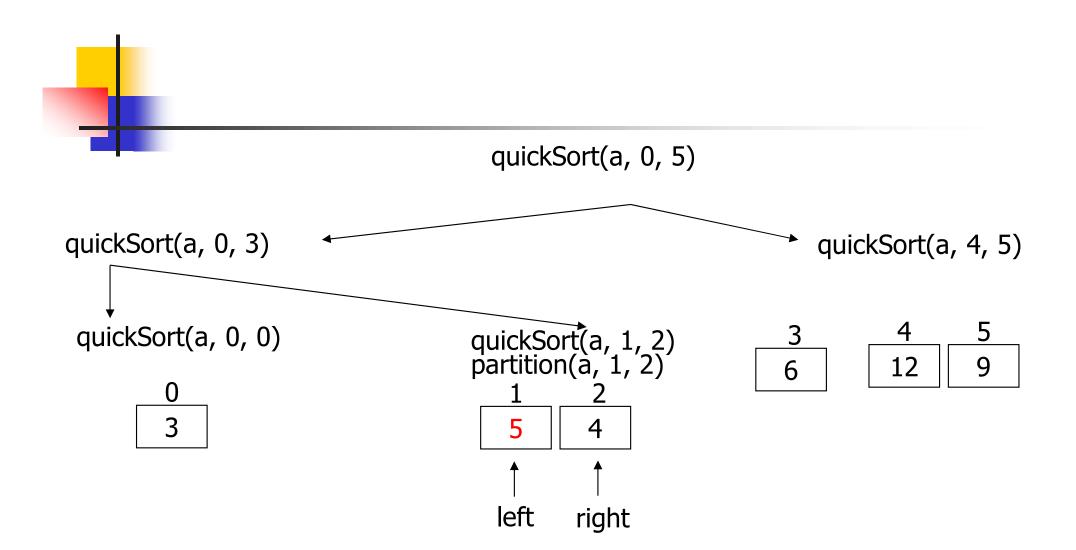




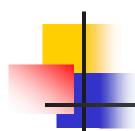
left

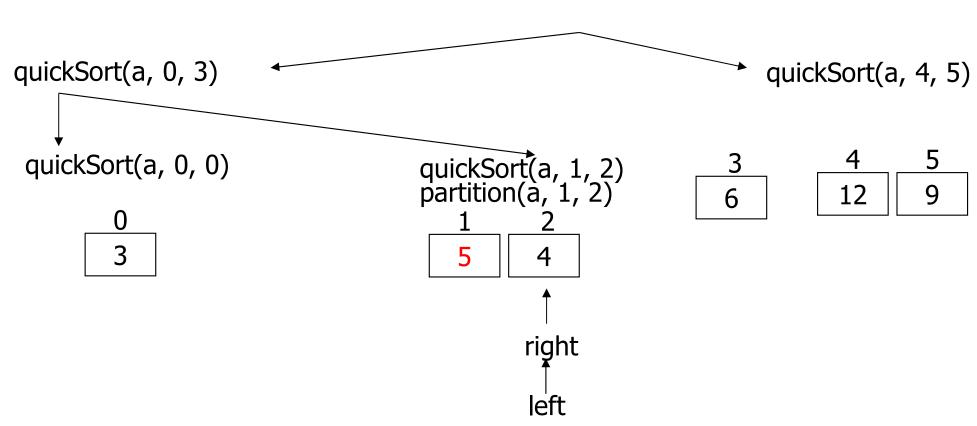
right moves to the left until value that should be to left of pivot...

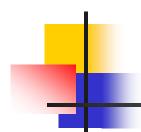
right

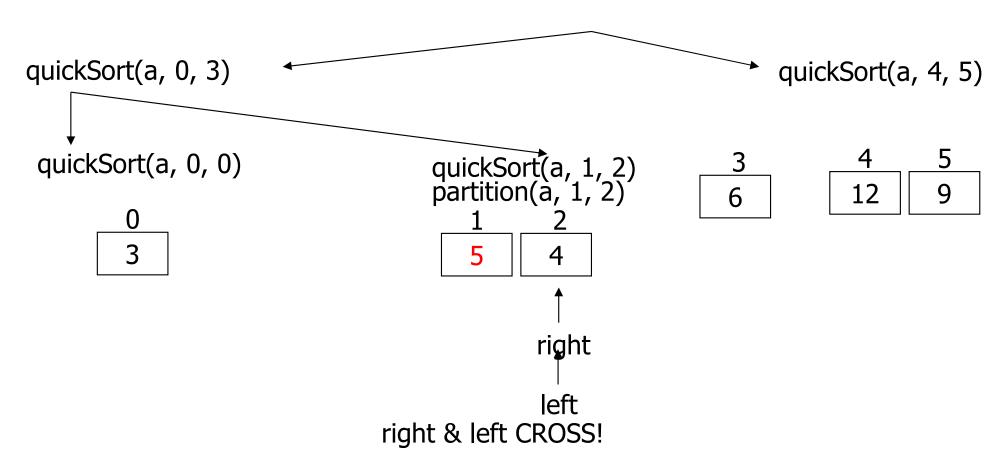


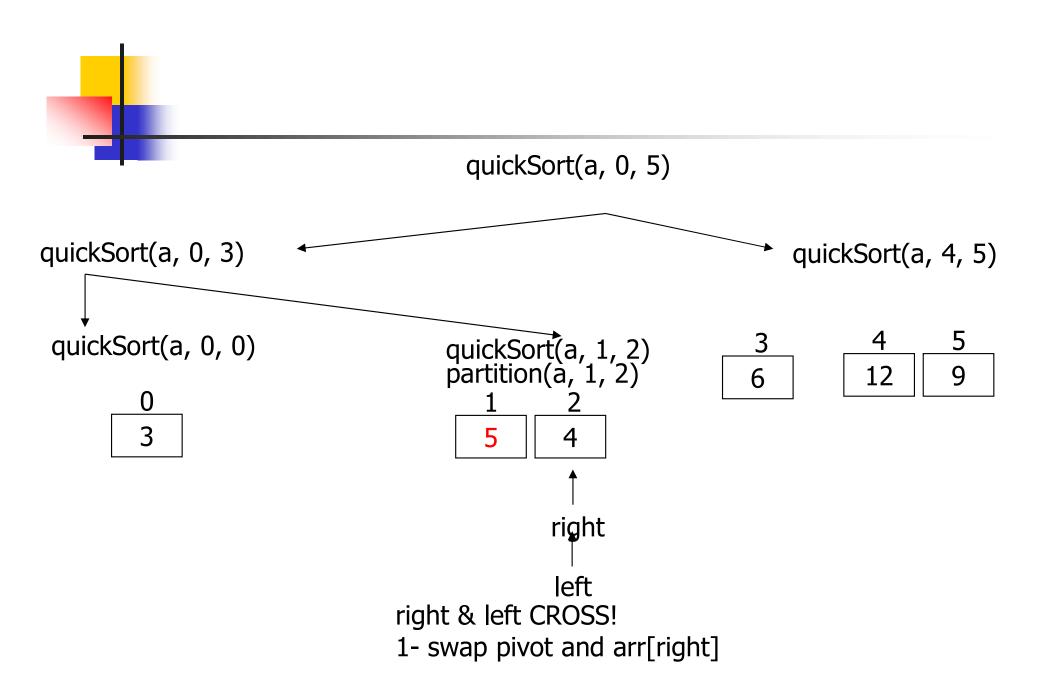
left moves to the right until value that should be to right of pivot...

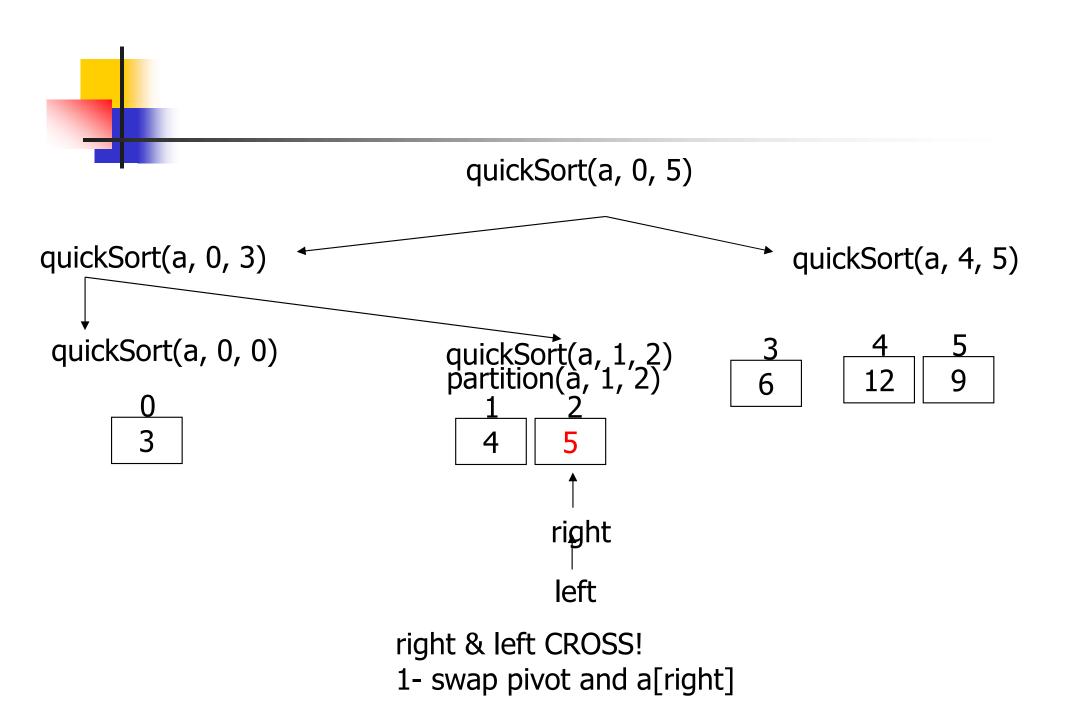


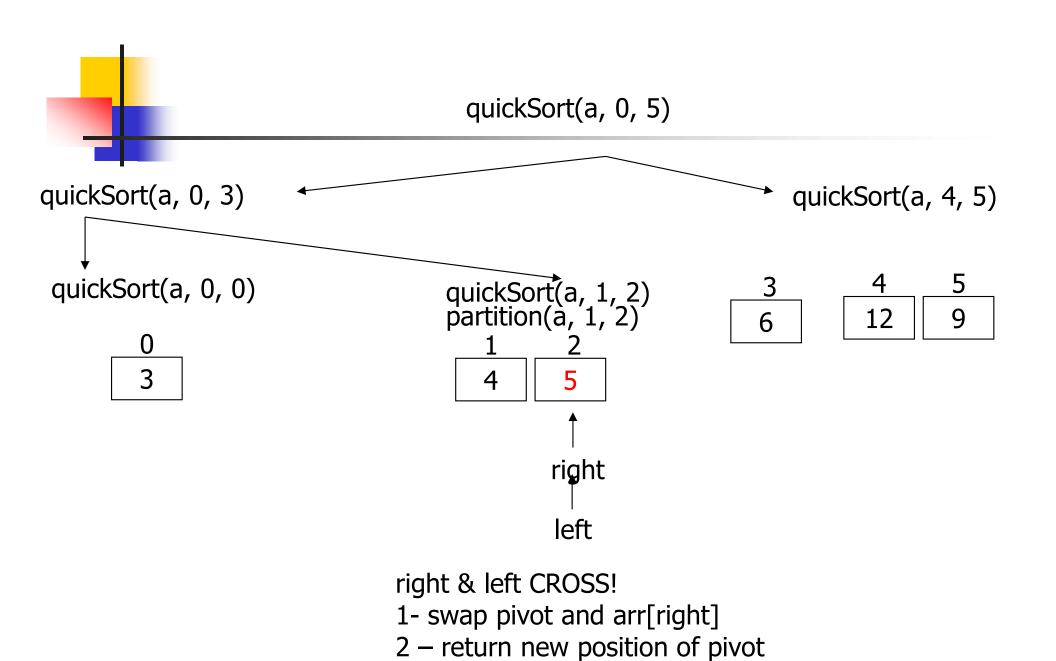




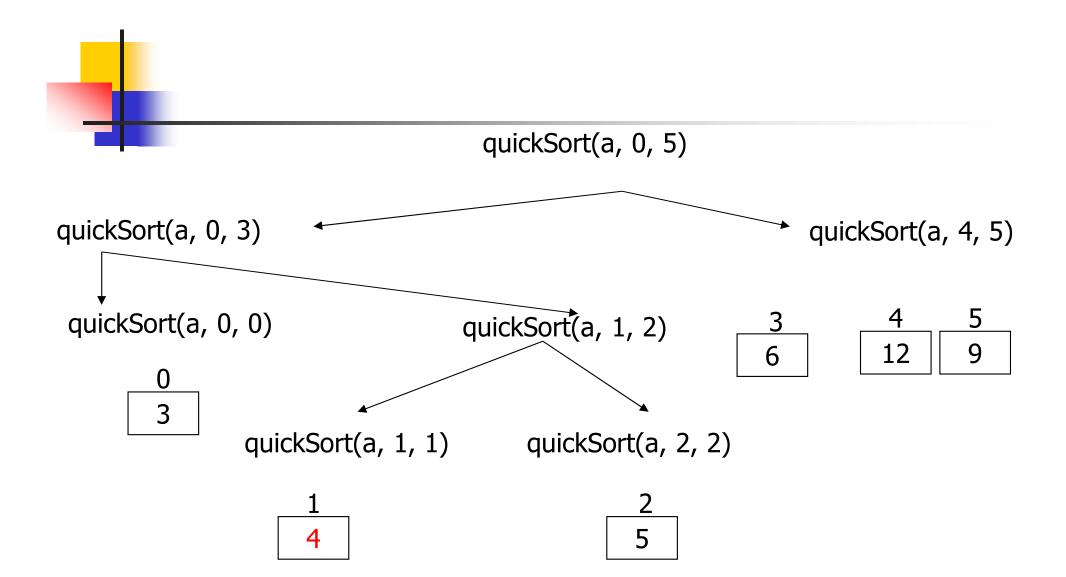


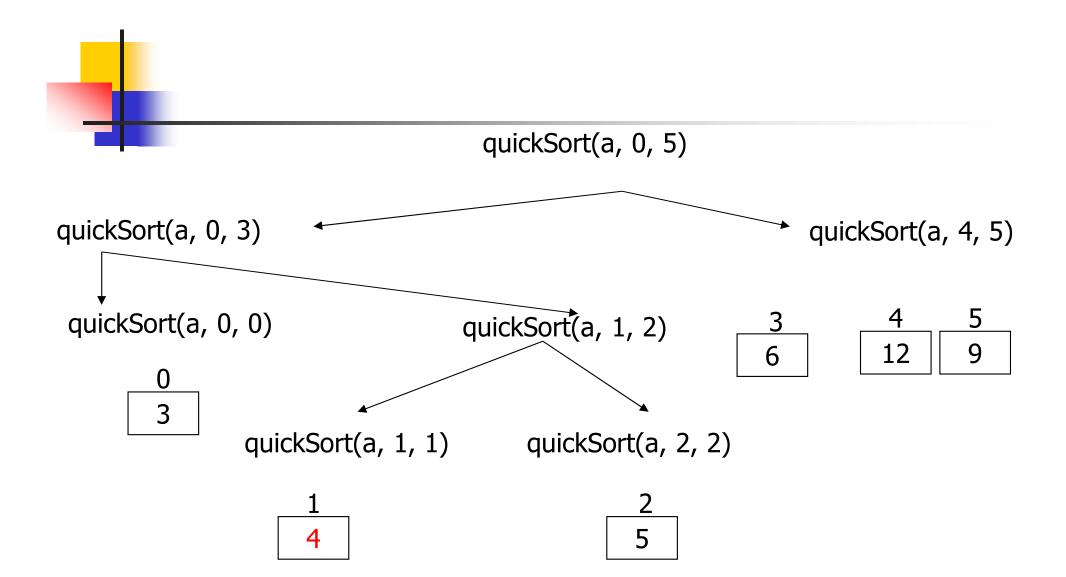


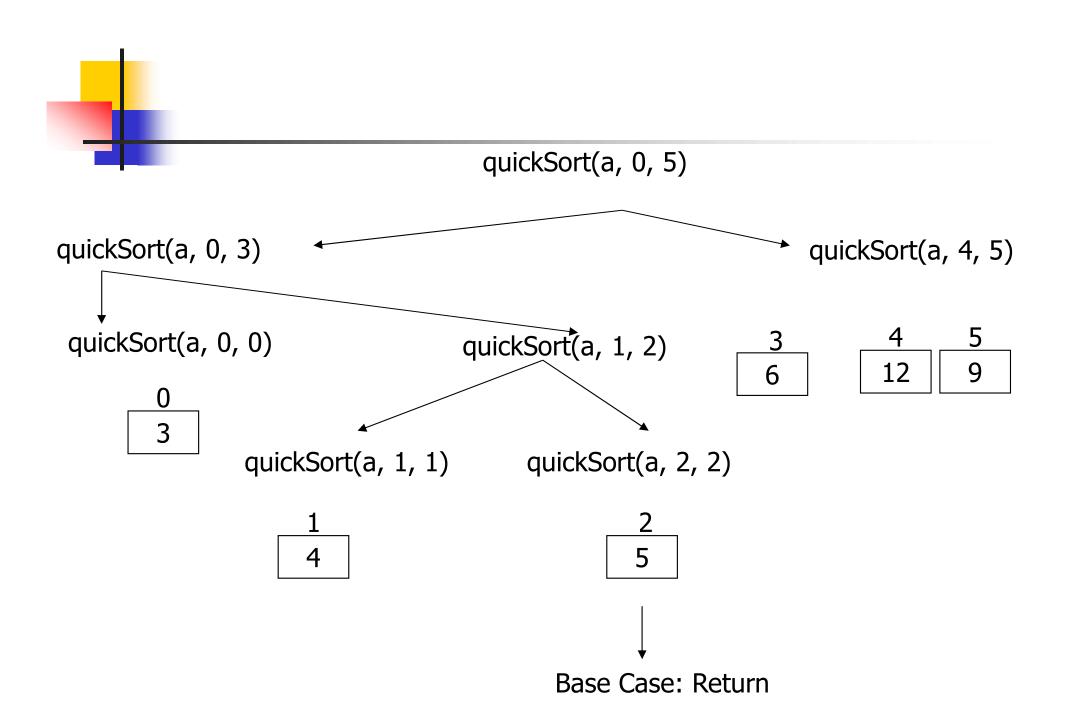


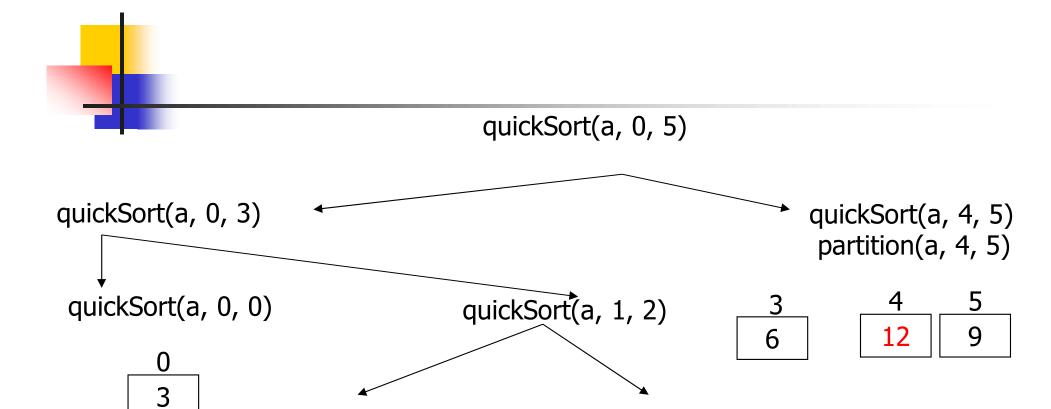


return 2







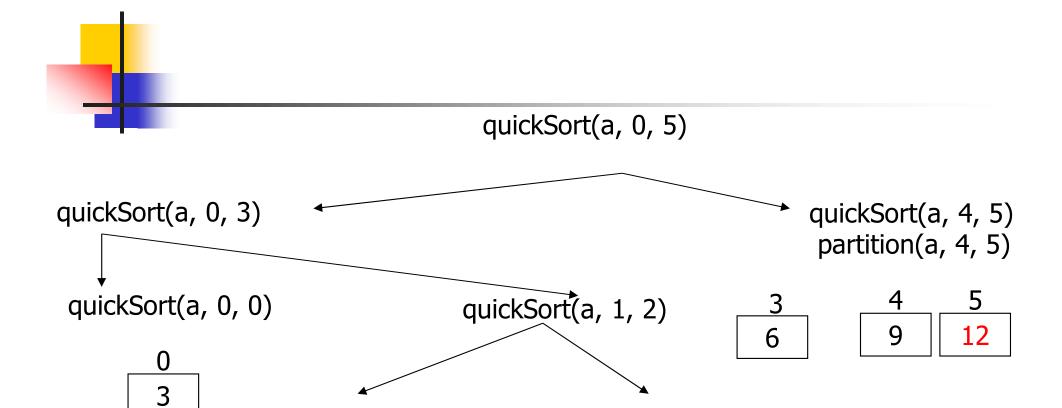


1 4

quickSort(a, 1, 1)

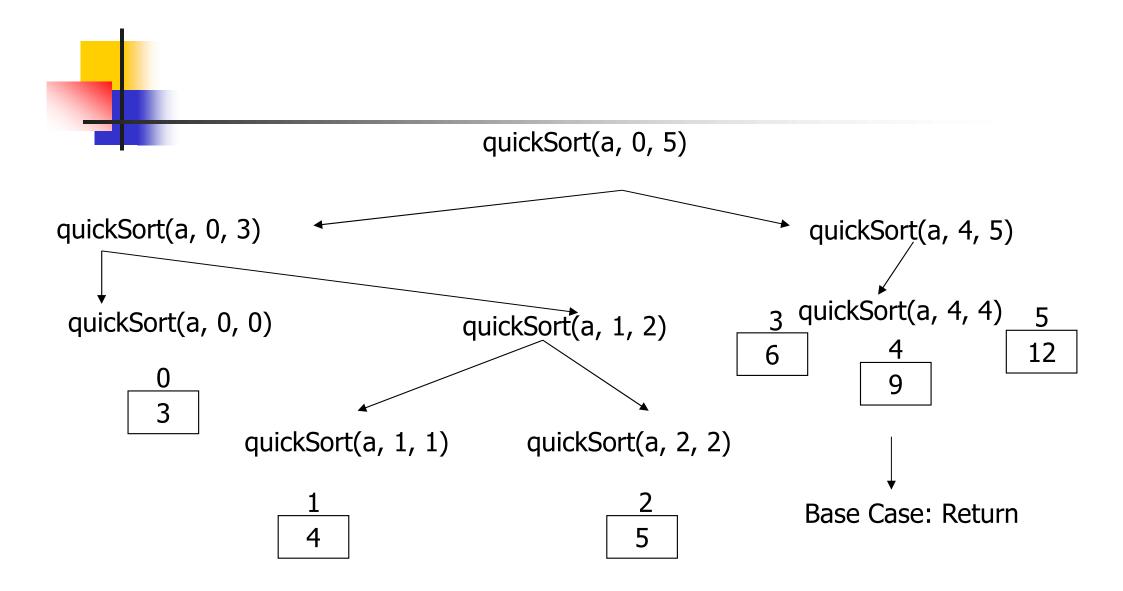
5

quickSort(a, 2, 2)



quickSort(a, 2, 2)

quickSort(a, 1, 1)





Example for Quick Sort

R0	R 1	R2	R3	R4	R.5	R6	R7	R8	R9	left	right
{ 26	5	37	1	61	11	59	15	48	19}	0	9
11	5	19	1	15}	26	{ 59	61	48	37}	0	4
f 1	5 }	11	{ 19	15}	26	₹ 59	61	48	37	0	1
1	5	11	15	19	26	{ 59	61	48	37	3	4
1	5	11	15	19	26	₹ 48	37}	59 {	61}	6	9
1	5	11	15	19	26	37	48	59	61	6	7
1	5	11	15	19	26	37	48	59	61	9	9
1	5	11	15	19	26	37	48	59	61		

Quicksort Analysis

- Assume that keys are random, uniformly distributed.
- Best case running time: O(n log₂n)
- Worst case running time?
 - Recursion:
 - Partition splits array in two sub-arrays:
 - one sub-array of size 0
 - the other sub-array of size n-1
 - Quicksort each sub-array
 - Depth of recursion tree? O(n)
 - Number of accesses per partition? O(n)

Quicksort Analysis

- Assume that keys are random, uniformly distributed.
- Best case running time: O(n log₂n)
- Worst case running time: O(n²)!!!
- What can we do to avoid worst case?

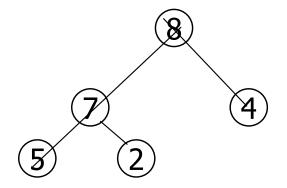
Improved Pivot Selection

Pick median value of three elements from data array: data[0], data[n/2], and data[n-1].

Use this median value as pivot.



- Def: A heap is a <u>nearly complete</u> binary tree with the following two properties:
 - Structural property: all levels are full, except possibly the last one, which is filled from left to right
 - Order (heap) property: for any node x
 Parent(x) ≥ x



Heap

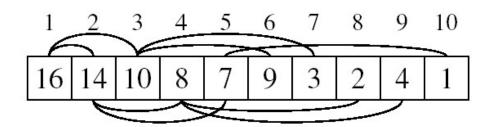
From the heap property, it follows that:

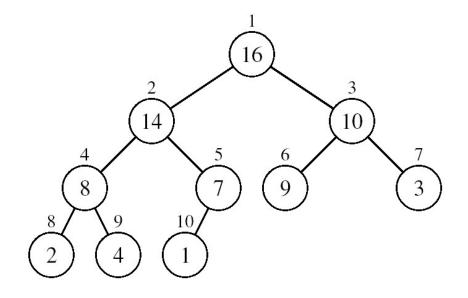
"The root is the maximum element of the heap!"

A heap is a binary tree that is filled in order

Array Representation of Heaps

- A heap can be stored as an array A.
 - Root of tree is A[1]
 - Left child of A[i] = A[2*i]
 - Right child of A[i] = A[2*i + 1]
 - Parent of A[i] = A[$\lfloor i/2 \rfloor$]
 - Heapsize[A] ≤ length[A]
- The elements in the subarray $A[(\lfloor n/2 \rfloor + 1) ... n]$ are leaves





Heap Types

- Max-heaps (largest element at root), have the max-heap property:
 - for all nodes i, excluding the root:

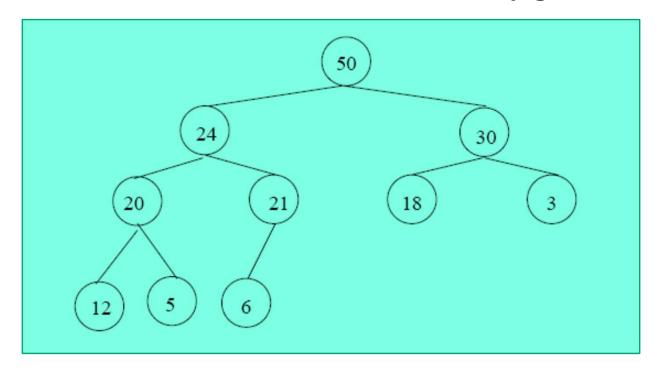
$$A[PARENT(i)] \ge A[i]$$

- Min-heaps (smallest element at root), have the min-heap property:
 - for all nodes i, excluding the root:

$$A[PARENT(i)] \le A[i]$$

Adding/Deleting Nodes

- New nodes are always inserted at the bottom level (left to right)
- Nodes are removed from the bottom level (right to left)

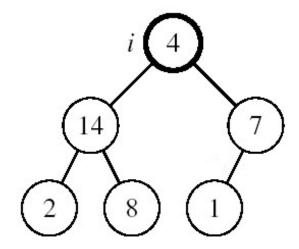


Operations on Heaps

- Maintain/Restore the max-heap property
 - Max-Heapify
- Create a max-heap from an unordered array
 - Build-Max-Heap
- Sort an array in place
 - Heapsort
- Priority queues

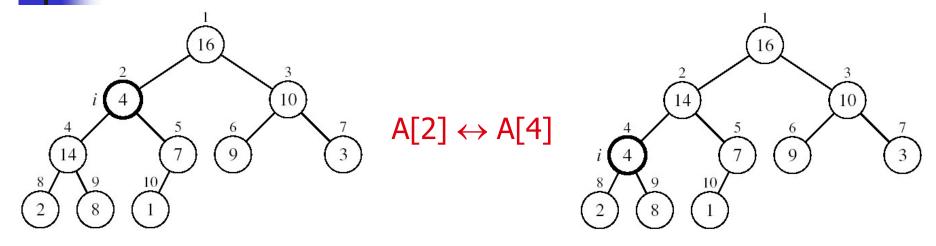
Maintaining the Heap Property

- Suppose a node is smaller than a child
 - Left and Right subtrees of i are max-heaps
- To eliminate the violation:
 - Exchange with larger child
 - Move down the tree
 - Continue until node is not smaller than children



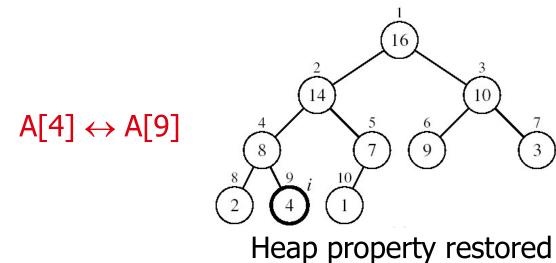
Example

Max-Heapify(A, 2, 10)



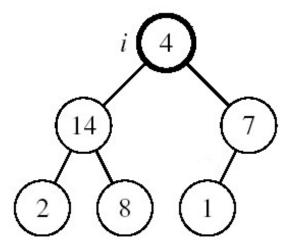
A[2] violates the heap property

A[4] violates the heap property



Maintaining the Heap Property

- Assumptions:
 - Left and Right subtrees of i are max-heaps
 - A[i] may be smaller than its children



Alg: Max-Heapify(A, i, n)

- 1. I ← left(i)
- 2. $r \leftarrow right(i)$
- 3. if $I \le n$ and A[I] > A[i]
- 4. **then** largest ←l
- 5. **else** largest ←i
- **6.** if $r \le n$ and A[r] > A[largest]
- 7. **then** largest ←r
- **8. if** largest ≠ i
- 9. **then** exchange $A[i] \leftrightarrow A[largest]$
- 10. Max-Heapify(A, largest, n)

Max-Heapify Running Time

Intuitively:

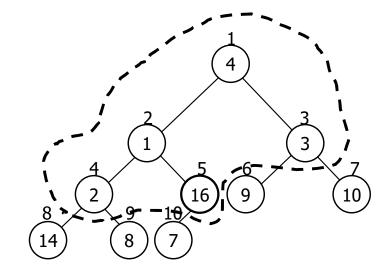
- It traces a path from the root to a leaf (longest path length: h)
- At each level, it makes exactly two comparisons.
- Total number of comparisons is 2h
- Running time is O(h) or $O(log_2 n)$
- Running time of Max-Heapify is O(log₂n)
- Can be written in terms of the height of the heap, as being O(h)
 - Since the height of the heap is \[log_2 n \]

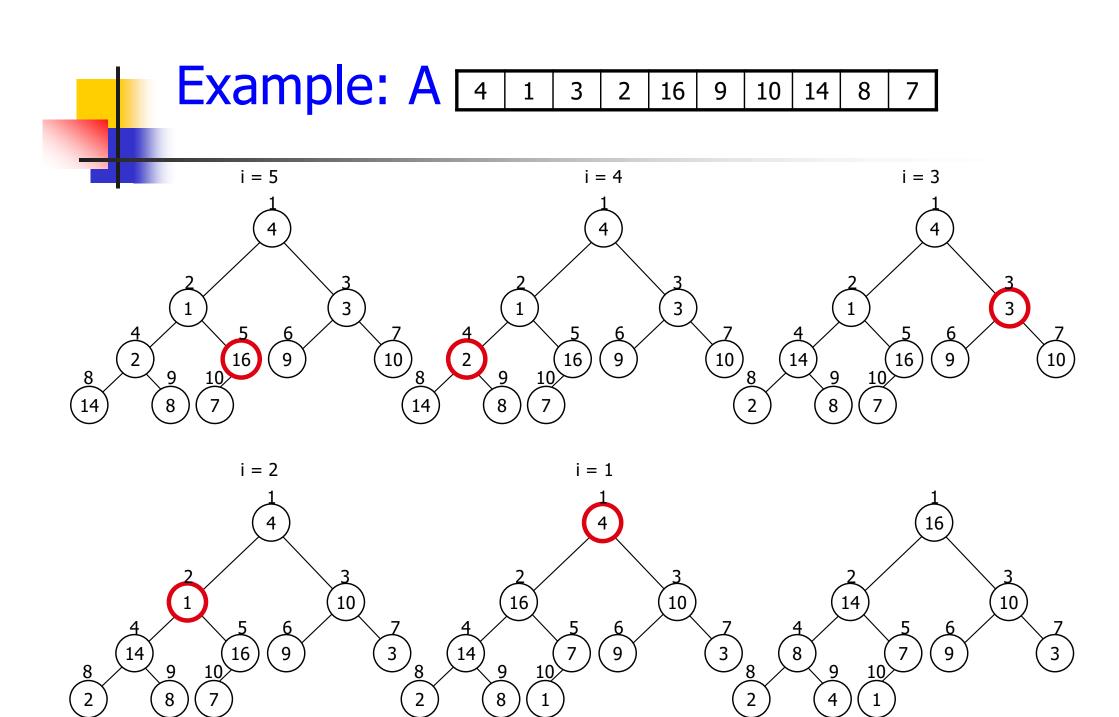
Building a Heap

- Convert an array A[1 ... n] into a max-heap (n = length[A])
- The elements in the subarray $A[(\lfloor n/2 \rfloor + 1) ... n]$ are leaves
- Apply MAX-HEAPIFY on elements between 1 and \[\ln/2 \]

Alg: Build-Max-Heap(A)

- 1. n = length[A]
- 2. **for** $i \leftarrow \lfloor n/2 \rfloor$ **downto** 1
- 3. **do** Max-Heapify(A, i, n)





Running Time of Build-Max-Heap

Alg: Build-Max-Heap(A)

```
1. n = length[A]
```

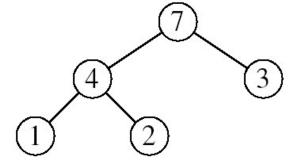
2. **for**
$$i \leftarrow \lfloor n/2 \rfloor$$
 downto 1

$$O(\log_2 n)$$
 $O(n)$

- \Rightarrow Running time: O(nlog₂n)
- This is not an asymptotically tight upper bound

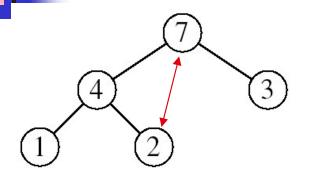
Heapsort

- Goal:
 - Sort an array using heap representations
- Idea:
 - Build a max-heap from the array
 - Swap the root (the maximum element) with the last element in the array
 - "Discard" this last node by decreasing the heap size
 - Call Max-Heapify on the new root
 - Repeat this process until only one node remains

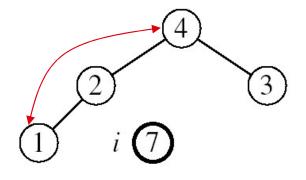


Example:

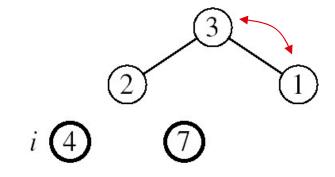
A=[7, 4, 3, 1, 2]



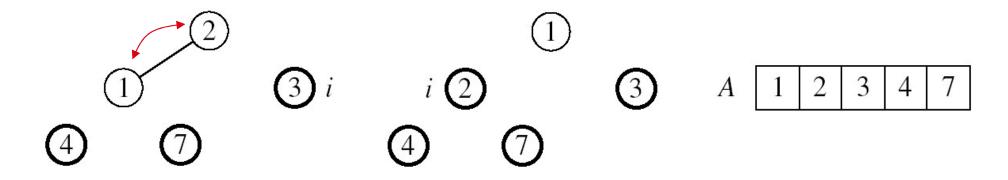
Max-Heapify(A, 1, 4)



Max-Heapify(A, 1, 3)



Max-Heapify(A, 1, 2)



Max-Heapify(A, 1, 1)

Alg: Heapsort(A)

Build-Max-Heap(A)

```
2. for i \leftarrow length[A] downto 2 O(n)
3. do exchange A[1] \leftrightarrow A[i]
4. Max-Heapify(A, 1, i - 1) O(log_2n) O(log_2n)
```

Running time: $O(nlog_2n)$ --- Can be shown to be $O(nlog_2n)$



- If integers are in a larger range then do bucket sort on each digit
- Start by sorting with the low-order digit using a <u>STABLE</u> bucket sort.
- Then, do the next-lowest, and so on

Radix Sort

- Extra information: every integer can be represented by at most k digits
 - $d_1d_2...d_k$ where d_i are digits in base r
 - d₁: most significant digit
 - d_k: least significant digit

Radix Sort

- Algorithm
 - sort by the least significant digit first (counting sort)
 - => Numbers with the same digit go to same bin
 - reorder all the numbers: the numbers in bin 0 precede the numbers in bin 1, which precede the numbers in bin 2, and so on
 - sort by the next least significant digit
 - continue this process until the numbers have been sorted on all k digits

Radix sort characteristics

- Each sorting step can be performed via bucket sort, and is thus O(N).
- If the numbers are all b bits long, then there are b sorting steps.
- Hence, radix sort is O(bN).

```
// Function to get the largest element from an array
int getMax(int arr[], int n) {
  int max = arr[0];
  for (int i = 1; i < n; i++)
    if (arr[i] > max)
      max = arr[i];
  return max;
}
```

// Counting sort
void countingSort(int arr[], int n, int place) {

```
int i;
int output[n + 1];
int count[10] = \{0\};
// Calculate count of elements
for(i=0; i<n; i++)
   count[(arr[i] / place) % 10]++;
// Calculate cummulative count
for(i=1; i<10; i++)
   count[i] += count[i-1];
// Place the elements in sorted order
for(i=n-1; i>=0; i--) {
   output[count[(arr[i] / place) % 10] - 1] = arr[i];
   count[(arr[i] / place) % 10]--;
for(i=0; i<n; i++)
   arr[i] = output[i];
```

```
// Main function to implement radix sort
void radixsort(int arr[], int n) {
  int max = getMax(arr, n); // Get maximum element
  // Apply counting sort to sort elements based on place value.
  for (int place=1; max / place > 0; place *= 10)
    countingSort(arr, n, place);
// Print an array
void printArray(int arr[], int n) {
 for (int i=0; i< n; ++i)
  printf("%d ", arr[i]);
 printf("\n");
```

```
// Code
int main() {
  int arr[] = {121, 432, 564, 23, 1, 45, 788};
  int n = sizeof(arr) / sizeof(arr[0]);
  radixsort(arr, n);
  printArray(arr, n);
}
```

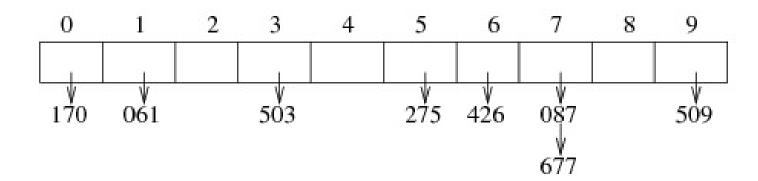
1

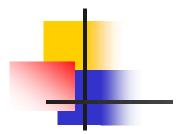
Radix Sort

Least-significant-digit-first

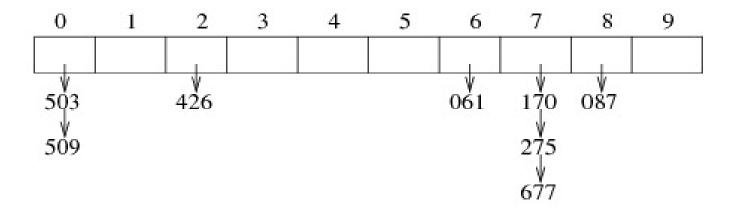
Example: 275, 087, 426, 061, 509, 170, 677, 503

1st pass

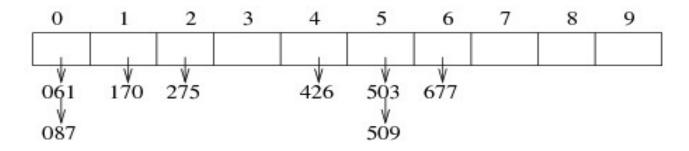




2nd pass



3rd pass



in sorted order

Radix Sort

- Increasing the base r decreases the number of passes
- Running time
 - k passes over the numbers (i.e. k counting sorts, with range being 0...r)
 - each pass takes O(n+r)
 - total: O(nk+rk)
 - r and k are constants: O(n)