



**KIIT Deemed to be University**  
**Online Mid Semester Examination(Spring Semester-2021)**

**Subject Name & Code: OS**

**Applicable to Courses:B.Tech**

**Full Marks=20**

**Time:1 Hour**

**SECTION-A(Answer All Questions. All questions carry 2 Marks)**

**Time:20 Minutes**

**(5×2=10 Marks)**

<u>Que stio n No</u>	<u>Question Type(M CQ/SAT )</u>	<u>Question</u>	<u>Answer Key(if MCQ)</u>												
<u>Q.N o:1( a)</u>	<u>MCQ</u>	Which of the following operation is performed when an interrupt occurs. (a) Interrupt is ignored (b) The change in the state of the interrupted process after processing of interrupt (c) Save the state of the interrupted process and reload the state of the new process (d) Resume the interrupted process's execution after processing of interrupt	C												
	<u>MCQ</u>	Which of the following information are saved when a context switch is occurred among the processes. (a) Translation look-aside buffer (b) Program Counter (c) General purpose registers (d) None of the above	B and C												
	<u>MCQ</u>	Which of the following below statements are correct with respect to user level and kernel level threads (a) Context switch is faster in kernel threads (b) A system call in user thread can block the entire process (c) User threads are transparent to kernel (d) All of the above	B and C												
	<u>MCQ</u>	Consider three processes P1, P2, and P3 with burst time 10, 20, and 30 units and the arrival times are 0, 2, and 6 respectively. Determine the number of context switches (without considering the context switches at start and end) are required, if OS uses SRTF scheduling algorithm. (a) 3 (b) 4 (c) 2 (d) 1	C												
<u>Q.N o:1( b)</u>	<u>MCQ</u>	Consider three processes P1, P2 and P3 along with their burst time and arrival time are specified in the below table. <table><tr><td>Processes</td><td>Burst Time (ms)</td><td>Arrival Time(ms)</td></tr><tr><td>P1</td><td>9</td><td>0</td></tr><tr><td>P2</td><td>4</td><td>1</td></tr><tr><td>P3</td><td>9</td><td>2</td></tr></table>	Processes	Burst Time (ms)	Arrival Time(ms)	P1	9	0	P2	4	1	P3	9	2	C
Processes	Burst Time (ms)	Arrival Time(ms)													
P1	9	0													
P2	4	1													
P3	9	2													

		Find the average waiting time (ms) of above three processes using preemptive shortest job first scheduling algorithm. (a) 4.33 (b) 7.33 (c) 5.0 (d) 6.33																									
	<b>MCQ</b>	Consider three processes P0, P1 and P2 along with their burst time and arrival time are specified in the below table. <table><tr><td>Processes</td><td>Burst Time (ms)</td><td>Arrival Time(ms)</td></tr><tr><td>P0</td><td>5</td><td>0</td></tr><tr><td>P1</td><td>7</td><td>1</td></tr><tr><td>P2</td><td>4</td><td>3</td></tr></table> Determine the order of completion of above three processes using Round Robin scheduling algorithm with time quantum of 2 units. (a) P0, P2, and P1 (b) P0, P1, and P2 (c) P1, P0, and P2 (d) P2, P1, and P0	Processes	Burst Time (ms)	Arrival Time(ms)	P0	5	0	P1	7	1	P2	4	3	A												
Processes	Burst Time (ms)	Arrival Time(ms)																									
P0	5	0																									
P1	7	1																									
P2	4	3																									
	<b>MCQ</b>	Consider five processes P0, P1, P2, P3 and P4 along with their burst time and arrival time are specified in the below table. <table><tr><td>Processes</td><td>Burst Time (ms)</td><td>Arrival Time(ms)</td></tr><tr><td>P0</td><td>6</td><td>0</td></tr><tr><td>P1</td><td>2</td><td>3</td></tr><tr><td>P2</td><td>4</td><td>5</td></tr><tr><td>P3</td><td>6</td><td>7</td></tr><tr><td>P4</td><td>3</td><td>10</td></tr></table> Find the average turnaround time (ms) of above five processes using shortest remaining time first scheduling algorithm. (a) 7.2 (b) 6 (c) 8.5 (d) 5.6	Processes	Burst Time (ms)	Arrival Time(ms)	P0	6	0	P1	2	3	P2	4	5	P3	6	7	P4	3	10	A						
Processes	Burst Time (ms)	Arrival Time(ms)																									
P0	6	0																									
P1	2	3																									
P2	4	5																									
P3	6	7																									
P4	3	10																									
	<b>MCQ</b>	Consider five processes P0, P1, P2, P3 and P4 along with their burst time, arrival time, priority (lower number is the higher priority) are specified in the below table. <table><tr><td>Processes</td><td>Burst Time (ms)</td><td>Arrival Time(ms)</td><td>Priority</td></tr><tr><td>P0</td><td>11</td><td>0</td><td>2</td></tr><tr><td>P1</td><td>28</td><td>5</td><td>0</td></tr><tr><td>P2</td><td>2</td><td>12</td><td>3</td></tr><tr><td>P3</td><td>10</td><td>2</td><td>1</td></tr><tr><td>P4</td><td>16</td><td>9</td><td>4</td></tr></table> Find the average waiting time (ms) of all the processes using preemptive priority scheduling algorithm. (a) 28 (b) 29 (c) 32 (d) 26	Processes	Burst Time (ms)	Arrival Time(ms)	Priority	P0	11	0	2	P1	28	5	0	P2	2	12	3	P3	10	2	1	P4	16	9	4	B
Processes	Burst Time (ms)	Arrival Time(ms)	Priority																								
P0	11	0	2																								
P1	28	5	0																								
P2	2	12	3																								
P3	10	2	1																								
P4	16	9	4																								
<b>Q.No:1(c)</b>	<b>MCQ</b>	Consider the following statements.  1-FCFS scheduling by its nature is always Non-Preemptive type. 2-A process can directly go from waiting state to Running State	C																								

	<p>3-Round Robin Scheduling is best suited for interactive Processes</p> <p>4-Middle Term Scheduler is required when there is absence of long term Scheduler or presence of Long term scheduler with minimal functionality.</p> <p>5-Switching between threads of same process is inefficient and takes more time as compared to process switching.</p> <p>6-Starvation is a problem with Fixed Priority Scheduling.</p> <p>7-SJF Scheduling results into optimal average waiting time of the processes.</p> <p>Which of the above mentioned statements are true?</p> <p>(a)1,2,3,4 &amp; 7 only (b)1,3,4,5 &amp; 6 only (c)1,3,4,6 &amp; 7 only (d)1,2,4,5 &amp; 6 only</p>	
	<p><b><u>MCQ</u></b> Consider the following statements.</p> <p>1-FCFS scheduling by its nature is always Preemptive type.</p> <p>2-A process can directly go from Running state to Ready State</p> <p>3-Multilevel feedback queue scheduling has simpler algorithm as compared to multilevel queue scheduling.</p> <p>4-Switching between threads of same process is efficient and takes less time as compared to process switching.</p> <p>5-Starvation problem can be resolved with aging priority.</p> <p>6-SJF Scheduling results into large average waiting time of the processes.</p> <p>7-In Round Robin Scheduling a process is bound to get the CPU attention after a fixed time.</p> <p>Which of the above mentioned statements are false?</p> <p>(a)1,2,4 &amp; 6 only (b)1,3 &amp; 6 only (c)2,3,6 &amp; 7 only (d)1,3, &amp; 7 only</p>	B
	<p><b><u>MCQ</u></b> Consider the following statements.</p> <p>1-A Short Term Scheduler is in charge of waiting to ready state transition of a process.</p> <p>2-A process will not suffer from starvation in Round Robin Scheduling.</p> <p>3-Switching between threads of different processes is same as process switching.</p> <p>4-A single program can give rise to several processes</p> <p>5-The response time and waiting time of the processes are same for FCFS scheduling.</p> <p>6-Dispatch latency is a part of the context switching time</p> <p>7-When processes arrive at the same time, the Preemptive and Non Preemptive version of priority scheduling will result into different waiting time of the processes.</p> <p>Which of the above mentioned statements are true?</p>	C

		(a)1,2,3,4 & 7 only (b)1,3,4,5 & 6 only (c)2,3,4,5 & 6 only (d)2,4,5,6 & 7 only															
	<b>MCQ</b>	Consider the following statements.  1-A Short Term Scheduler is in charge of waiting to ready state transition of a process. 2-SJF Scheduling results into optimal average waiting time of the processes. 3-Switching between threads of different processes is same as process switching. 4-Middle Term Scheduler is required when there is absence of long term Scheduler or presence of Long term scheduler with minimal functionality. 5-The response time and waiting time of the processes are same for FCFS scheduling. 6-Dispatch latency is a part of the context switching time 7-Process Control Block has a Pointer field to add them to the particular scheduling queue implemented as a linked list  Which of the above mentioned statements are true?  (a)2,3,4,5,6 & 7 only (b)1,3,4,5 & 6 only (c)2,3,4,5 & 6 only (d)2,4,5,6 & 7 only	A														
<b>Q.N o:1( d)</b>	<b>MCQ</b>	In a uniprocessor system, there are two concurrent processes A and B as follows: <table border="1"> <tr> <th>Process A:</th> <th>Process B:</th> </tr> <tr> <td>Begin</td> <td>Begin</td> </tr> <tr> <td>WAIT(S);</td> <td>DI; //Disable Interrupt</td> </tr> <tr> <td>Read(x);</td> <td>Read(x);</td> </tr> <tr> <td>Increase x by 1;</td> <td>Left shift x once;</td> </tr> <tr> <td>SIGNAL(S);</td> <td>EI; //Enable Interrupt</td> </tr> <tr> <td>End</td> <td>End</td> </tr> </table> ed int x =3; // x is a global variable  What would be the smallest value of x from all possible values of x after completion A and B?  (A) 4 (B) 5 (C) 6 (D) 7	Process A:	Process B:	Begin	Begin	WAIT(S);	DI; //Disable Interrupt	Read(x);	Read(x);	Increase x by 1;	Left shift x once;	SIGNAL(S);	EI; //Enable Interrupt	End	End	A
Process A:	Process B:																
Begin	Begin																
WAIT(S);	DI; //Disable Interrupt																
Read(x);	Read(x);																
Increase x by 1;	Left shift x once;																
SIGNAL(S);	EI; //Enable Interrupt																
End	End																
	<b>MCQ</b>	In a uniprocessor system, there are two concurrent processes A and B as follows:	D														

	<table><tr><td>Process A:</td><td>Process B:</td></tr><tr><td>Begin WAIT(S); Read(x); Increase x by 1; SIGNAL(S); End</td><td>Begin DI; //Disable Interrupt Read(x); Left shift x once; EI; //Enable Interrupt End</td></tr></table> <p>Semaphore S=1; unsigned int x =3; // x is a global variable</p> <p>What would be the sum of all possible values of x after completion A and B?</p> <p>(A) 21 (B) 25 (C) 15 (D) None of the above</p>	Process A:	Process B:	Begin WAIT(S); Read(x); Increase x by 1; SIGNAL(S); End	Begin DI; //Disable Interrupt Read(x); Left shift x once; EI; //Enable Interrupt End	
Process A:	Process B:					
Begin WAIT(S); Read(x); Increase x by 1; SIGNAL(S); End	Begin DI; //Disable Interrupt Read(x); Left shift x once; EI; //Enable Interrupt End					
<u>MCQ</u>	<p>In a uniprocessor system, there are two concurrent processes A and B as follows:</p> <table><tr><td>Process A:</td><td>Process B:</td></tr><tr><td>Begin WAIT(S); Read(x); Increase x by 1; SIGNAL(S); End</td><td>Begin DI; //Disable Interrupt Read(x); Left shift x once; EI; //Enable Interrupt End</td></tr></table> <p>Semaphore S=1; unsigned int x =3; // x is a global variable</p> <p>How many different possible values of x can be there after completion A and B?</p> <p>(A) 2 (B) 3 (C) 4 (D) None of the above</p>	Process A:	Process B:	Begin WAIT(S); Read(x); Increase x by 1; SIGNAL(S); End	Begin DI; //Disable Interrupt Read(x); Left shift x once; EI; //Enable Interrupt End	B
Process A:	Process B:					
Begin WAIT(S); Read(x); Increase x by 1; SIGNAL(S); End	Begin DI; //Disable Interrupt Read(x); Left shift x once; EI; //Enable Interrupt End					
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Process A:	Process B:					
Begin WAIT(S); Read(x); Decrease x by 1; SIGNAL(S); End	Begin DI; //Disable Interrupt Read(x); Left shift x once; EI; //Enable Interrupt End					

		<p>Semaphore S=1; unsigned int x =2; // x is a global variable</p> <p>What would be the smallest value of x from all possible values of x after completion A and B?</p> <p>(A) 1 (B) 2 (C) 5 (D) 3</p>	
<b>Q.N o:1( e)</b>	<b>MCQ</b>	<p>Semaphore mutex=1; Each process P<sub>i</sub>, i = 1, 2, ..., 9 is coded as follows:     P(mutex);     { Critical Section }     V(mutex);</p> <p>The code for P10 is as follows: for j = 1 to 3 do     V(mutex);     { Critical Section }     V(mutex);</p> <p>What is the largest number of processes that can be inside the critical section at any moment?</p> <p>(a) 1 (b) 3 (c) 7 (d) 10</p>	C
	<b>MCQ</b>	<p>Semaphore mutex=1; Each process P<sub>i</sub>, i = 1, 2, ..., 8 is coded as follows:     P(mutex);     { Critical Section }     V(mutex);</p> <p>The code for P9 is as follows: for j = 1 to 2 do     V(mutex);     { Critical Section }     V(mutex);</p> <p>What is the largest number of processes that can be inside the critical section at any moment?</p> <p>(a) 1 (b) 3 (c) 5 (d) 9</p>	C
	<b>MCQ</b>	<p>Semaphore mutex=1; Each process P<sub>i</sub>, i = 1, 2, ..., 9 is coded as follows:     P(mutex);     { Critical Section }     V(mutex);</p>	4

		<p>The code for P10 is as follows:</p> <pre>V(mutex); V(mutex); { Critical Section } V(mutex);</pre> <p>What is the largest number of processes that can be inside the critical section at any moment?</p> <p>(a) 1 (b) 3 (c) 5 (d) 9</p>	
	<b>MCQ</b>	<p>Semaphore mutex=1;</p> <p>Each process <math>P_i</math>, <math>i = 1, 2, \dots, 9</math> is coded as follows:</p> <pre>P(mutex); { Critical Section } V(mutex);</pre> <p>The code for P10 is as follows:</p> <pre>V(mutex); V(mutex); V(mutex); { Critical Section } P(mutex);</pre> <p>What is the largest number of processes that can be inside the critical section at any moment?</p> <p>(a) 1 (b) 3 (c) 7 (d) 10</p>	5

**SECTION-B(Answer Any One Question. Each Question carries 10 Marks)**

**Time: 30 Minutes**

**(1×10=10 Marks)**

<b><u>Que stio n No</u></b>	<b><u>Question</u></b>
<b><u>Q.No:2</u></b>	<p>The Cats and Mice Problem: <b>(10 marks)</b></p> <p>A number of cats and mice inhabit a house. Your job is to synchronize the cats and mice so that the following requirements for the common food dish are satisfied:</p> <p>If a cat is eating at the food dish, other cats can't share the food dish at the same time. But, if any mouse is eating at the food dish, other mice can share the food dish. If any cat see the mice/mouse with the food dish, then the cat</p>

must eat the mice/mouse. No mouse should ever get eaten.

Answer the following for the above "The Cats and Mice Problem"

- List all of the synchronization primitives and shared variables that you have used to synchronize the cats and mice and identify the purpose of each one.
- Explain why it is not possible for mice to be eaten by cats under your synchronization technique.

Justify whether it is not possible for cats or mice to starve under your synchronization technique.

Sol

### The Cat and Mice problem

Problem:

- Multiple cats can't eat simultaneously  
i.e.  $cat_1, cat_2, \dots, cat_n$  X
- Multiple mice can eat simultaneously  
i.e.  $m_1, m_2, \dots, m_n$  ✓
- Both cat and mice are not allowed  
i.e. cat, mouse X

Sol<sup>n</sup> to the cat and mice problem

```
semaphore cat = 1;  
semaphore mctx = 1;  
int no_of_mouse = 0;
```

```
cat: while(1)  
{  
    wait(cat);  
    /* Eating is performed */  
    signal(cat);  
}
```



Module:

while (1)

{

wait(mutex);

no\_of\_processes ++;

if (no\_of\_processes == 1)

wait(cat);

signal(mutex);

/\* eating is performed \*/

wait(mutex);

no\_of\_processes --;

if (no\_of\_processes == 0)

signal(cat);

signal(mutex);

}

Q.N  
0:3

- a) Which process states diagram would you propose for system which requires neither any I/O operations nor any other process suspension? (2 marks)
- b) Consider process arrival as given below where N = right most significant digit of your Roll No. (ex:- for Roll No. 190854, N=4):

Process	CPU Burst Time(ms)	Arrival Time	Priority
A	4	0	2
B	3	6	3
C	6	N	6
D	5	3	N
E	1	4	4

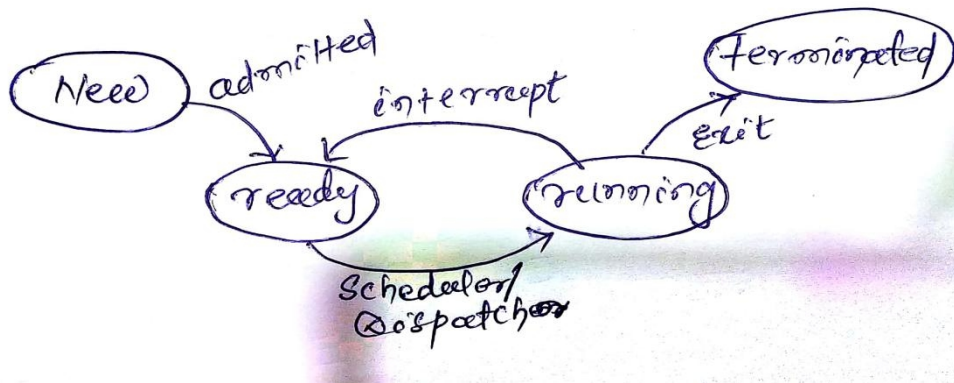
Calculate the following for *priority (non preemptive)* and *round robin* (time quantum = 2 ms) CPU scheduling algorithm:

- Average waiting time
- Turnaround time for each process
- Order of completion

(hints:-higher digits indicate higher priority) (8marks)

Sol

A)

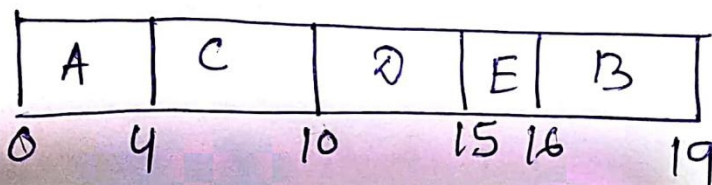


B)

Consider collno. 190854, i.e.  $N=4$

(i) Non-preemptive priority

Process	BT	AT	priority	CT	TAT	WT
A	4	0	2	4	4	0
B	3	6	3	19	13	10
C	6	4	6	10	6	0
D	5	3	4	15	12	7
E	1	4	4	16	12	11
						<u>5.6</u>



(i) Avg. WT = 5.6

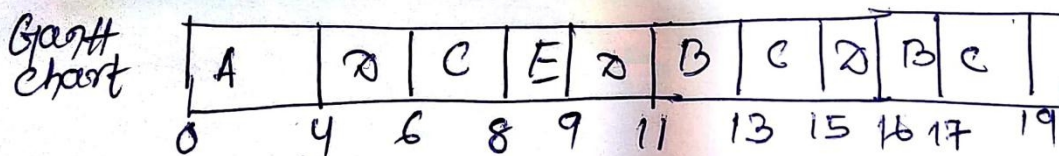
(ii)  $TAT(A, B, C, D, E) = (4, 13, 6, 12, 12)$

(iii) Order of completion of processes are  
(A, C, D, E, B)

(ii) RR with time quantum = 2ms

Process	BT	AT	CT	TAT	WT
A	4/20	0	4	4	0
B	3/10	6	17	11	8
C	6/4	4	19	15	9
D	5/3	3	16	13	8
E	10	4	9	5	4
					<u>5.8</u>

Queue ~~A~~ ~~D~~ ~~E~~ ~~B~~ ~~C~~ ~~D~~ ~~B~~ ~~C~~



(i) Avg. WT = 5.8

(ii) TAT(A, B, C, D, E) = (4, 11, 15, 13, 5)

(iii) Order of completion is (A, E, D, B, C)

**Q.N**  
**0:4**

Let there is an array of size  $n$ , which is used for storing both stack data and heap data. The stack data is stored from the left end of the array, i.e. from  $0^{\text{th}}$  index, towards right end of the array, and the heap data is stored from the right end of the array, i.e. from  $(n-1)^{\text{th}}$  index, towards left end of the array. In this system, there are 4 kinds of processes such as stack producer, heap producer, stack consumer and heap consumer. The stack producers store the data sequentially one after another from the left to right and the heap producers store the data sequentially one after another from the right to left. The stack consumer consumes the last inserted data into the stack and heap consumer consumes the last inserted data into the heap side. The stack producer and stack consumer will be identified through even process id(pid), and the heap producer and heap consumer will be identified through odd process id(pid). Write the synchronization method for producer and consumer that satisfies the following:

- Two producer, one belongs to stack and another belongs to heap, can access the array simultaneously.
- Two consumer, one belongs to stack and another belongs to heap, can access the array simultaneously.
- One producer belongs to stack and another another consumer belongs to heap can access the array simultaneously.

One producer belongs to heap and another another consumer belongs to stack can access the array simultaneously. (10 marks)

<b>Sol</b>	Semaphore empty=n, full=0, mutex_stack=1, mutex_heap=1, count_stack=0, count_heap=0; int st_i=0, hp_i=n-1; int arr[n];	
	<b>Producer</b>	<b>Consumer</b>
	<pre> p(empty) if(pid%2){     p(mutex_heap)     arr[hp_i--]=heap_item     v(mutex_heap)     v(count_heap) }else{     p(mutex_stack)     arr[st_i++]=stack_item     v(mutex_stack)     v(count_stack) } v(full) </pre>	<pre> if(pid%2){     p(count_heap)     p(full)     p(mutex_heap)     heap_receive=arr[++hp_i]     v(mutex_heap) }else{     p(count_stack)     p(full)     p(mutex_stack)     stack_receive=arr[--st_i]     v(mutex_stack) } v(empty) </pre>

Q.N  
o:5

Consider process arrival as given below where (10 marks)  
 $Z = 11 * (1 + (\text{right most significant digit of your Roll No \% } 9))$ . ( Ex:- for Roll No. 190560,  $M=11 * (1+(0\%9)) = 11$ )

Process	CPU Burst Time(ms)	Arrival Time
P <sub>1</sub>	30	0
P <sub>2</sub>	40	Z
P <sub>3</sub>	50	10
P <sub>4</sub>	Z	20
P <sub>5</sub>	10	30

Calculate the following for *round robin* (time quantum = 15 ms) CPU scheduling algorithm:

a) Average waiting time

b) Turnaround time for each process

c) Order of completion

<b>Sol</b>	Consider the example:- for Roll No. 190560, $M=11 * (1+(0\%9)) = 11$ :					
	Proces s	CPU Burst Time(ms)	Arrival Time	Wait Time	TA T	Execution Time
	P <sub>1</sub>	30 15 0	0 15 <b>60</b>	0+30 =30	60	0+15+15+15
	P <sub>2</sub>	40 25 10 0	Z=11 45 111 <b>136</b>	19+51+15=85	125	+ 15+11+10+15

P <sub>3</sub>	50 35 20 5 0	10 30 96 126 <b>141</b>	5+51+15+10=81	131	+15+15+10+ 5 =141
P <sub>4</sub>	Z=11 0	20 <b>71</b> –	40	51	
P <sub>5</sub>	10– 0	30 <b>81</b>	41	51	
			Avg. Wait = 277/5 = 55.4		

P <sub>1</sub>	P <sub>3</sub>	P <sub>2</sub>	P <sub>1</sub>	P <sub>4</sub>	P <sub>5</sub>	P <sub>3</sub>	P <sub>2</sub>	P <sub>3</sub>	P <sub>2</sub>	P <sub>3</sub>	
0	15	30	45	60	71	81	96	111	126	136	141

**Q.N  
o:6**

(a) The two processes execution part defined within if and else statement of the following code. Assume that the execution of *scanf* statement is delayed for long time. The *printf* statement is completed prior to *scanf* statement. What will be the process state of child process when it will gets terminated? Give a suitable reason. (2 marks)

```
i=fork();
if(i>0){

    scanf("%d",&j);
    wait(NULL);
}else if(i==0){
    printf("ABC\n");
}
```

(b) Consider the set of 4 processes whose priority(lower value becomes more priority), arrival time, and burst time are given below:

Process No.	Arrival Time	Priority	Burst Time		
			CPU Burst	I/O Burst	CPU Burst
P1	0	2	3	1	2
p2	1	x	1	4	3
P3	3	3	2	2	1
P4	2	y	2	1	2

Here

y= (Your roll no) % 2

x= ((Your roll no) / 100) % 2

For example, if roll no is **2106653**, then x=0 and y=1.

If the OS uses priority based(with preemption) Scheduling, then draw the gantt chart for the whole scheduling and calculate the response time, waiting time, and completion time of each process. (Lower number means higher priority) (8 marks)

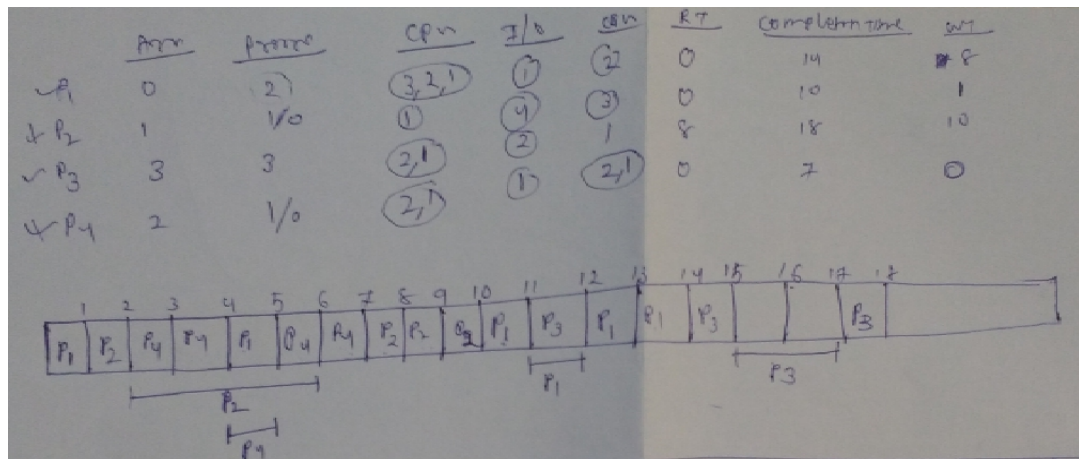
**Sol**

(a) Zombie process

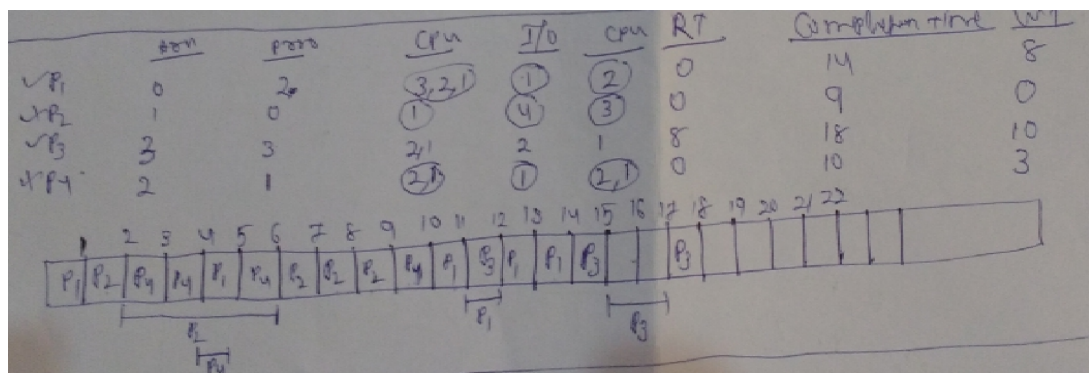
(b)

For (x=0, y=0), (x=1, y=1), (x=1, y=0)





For (x=0, y=1)



**Controller of Examinations**