8.3. Symmetric, Skew-Symmetric, and Orthogonal Matrices

Symmetric, Skew-Symmetric, and Orthogonal Matrices.

A real square matrix $A = [a_{jk}]$ is called

1. symmetric if transposition leaves it unchanged,

$$A^T = A$$
, thus $a_{kj} = a_{jk}$,

2. skew-symmetric if transposition gives the negative of A,

$$A^T = -A$$
, thus $a_{kj} = -a_{jk}$,

3. orthogonal if transposition gives the inverse of A,

$$\mathbf{A}^{\mathrm{T}} = \mathbf{A}^{-1}.$$

Example: The matrices

$$\begin{bmatrix} -3 & 1 & 5 \\ 1 & 0 & -2 \\ 5 & -2 & 4 \end{bmatrix}, \quad \begin{bmatrix} 0 & 9 & -12 \\ -9 & 0 & 20 \\ 12 & -20 & 0 \end{bmatrix}, \quad \begin{bmatrix} \frac{2}{3} & \frac{1}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix}$$

are symmetric, skew-symmetric, and orthogonal, respectively.

Note:

- 1. The determinant of an orthogonal matrix has the value +1 or -1.
- 2. Every square matrix can be expressed as the addition of symmetric and skew-symmetric matrix.

$$A = \frac{A + A^T}{2} + \frac{A - A^T}{2}$$

Eigenvalues of Symmetric and Skew-Symmetric and Orthogonal Matrices:

- (a) The eigenvalues of a symmetric matrix are real.
- **(b)** The eigenvalues of a skew-symmetric matrix are pure imaginary or zero.
- (c) The eigenvalues of an orthogonal matrix **A** are real or complex conjugates in pairs and have absolute value 1.

Example:

The matrix
$$\begin{bmatrix} 5 & 3 \\ 3 & 5 \end{bmatrix}$$
 is symmetric and has eigenvalues 2 and 8.

The matrix
$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$
 is skew-symmetric and has eigenvalues $-i$ and i .

Example: The orthogonal matrix

$$\begin{bmatrix} \frac{2}{3} & \frac{1}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \end{bmatrix}$$

has eigenvalues -1, $(5+i\sqrt{11})/6$ and $(5-i\sqrt{11})/6$, which have absolute value 1.

8.5. Complex Matrices and Different Forms.

Complex Conjugate Matrix

 $\bar{A} = [\bar{a}_{ik}]$ is obtained from $A = [a_{ik}]$ by replacing each entry $a_{jk} = \alpha + i\beta$ (α , β real) with its complex conjugate $\bar{a}_{jk} = \alpha - i\beta$. Also, $\bar{A}^T = [\bar{a}_{kj}]$ is the transpose of \bar{A} , hence the conjugate transpose of A.

Hermitian, Skew-Hermitian, and Unitary Matrices.

A square matrix $A = [a_{ki}]$ is called

1. **Hermitian** if $\bar{A}^T = A$, that is, $\bar{a}_{kj} = a_{jk}$ 2. **skew-Hermitian** if $\bar{A}^T = -A$, that is, $\bar{a}_{kj} = -a_{jk}$ 3. **unitary** if $\bar{A}^T = A^{-1}$.

Note:

- 1. Let A be a unitary matrix. Then its determinant has absolute value one, that is,
- 2. Every complex square matrices can be expressed as the addition of Hermitian and Skew-Hermitian matrices.

$$A = \frac{A + (\overline{A})^T}{2} + \frac{A - (\overline{A})^T}{2}$$

Eigenvalues of Hermitian and Skew-Hermitian and Unitary Matrices.

- (a) The eigenvalues of a Hermitian matrix (and thus of a symmetric matrix) are real.
- (b) The eigenvalues of a skew-Hermitian matrix (and thus of a skew-symmetric matrix) are pure imaginary or zero.
- (c) The eigenvalues of a unitary matrix (and thus of an orthogonal matrix) have absolute value 1.

Example:

The matrix
$$\begin{bmatrix} 4 & 1-3i \\ 1+3i & 7 \end{bmatrix}$$
 is Hermitian and has eigenvalues 9 and 2.

The matrix
$$\begin{bmatrix} 3i & 2+i \\ -2+i & -i \end{bmatrix}$$
 is skew-Hermitian and has eigenvalues $4i$ and $-2i$.

$$\begin{bmatrix} \frac{1}{2}i & \frac{1}{2}\sqrt{3} \\ \frac{1}{2}\sqrt{3} & \frac{1}{2}i \end{bmatrix}$$

 $\begin{bmatrix} \frac{1}{2}i & \frac{1}{2}\sqrt{3} \\ \frac{1}{2}\sqrt{3} & \frac{1}{2}i \end{bmatrix}$ is unitary and has eigenvalues $(\sqrt{3}+i)/2$ and $(-\sqrt{3}+i)/2$, which have absolute value 1.

Different Forms

1. Quadratic Form

Quadratic form is an expression of the form

$$Q = x^{T} A x$$
Where $A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}$ and $x = \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{n} \end{bmatrix}$

$$\Rightarrow Q = x^T A x = a_{11} x_1^2 + a_{12} x_1 x_2 + \dots + a_{1n} x_1 x_n + a_{21} x_1 x_2 + a_{22} x_2^2 + \dots + a_{n1} x_1 x_n + \dots + a_{nn} x_n^2$$

$$\Rightarrow Q = x^T A x = a_{11} x_1^2 + a_{22} x_2^2 + \dots + a_{nn} x_n^2 + (a_{12} + a_{21}) x_1 x_2 + (a_{13} + a_{31}) x_1 x_3 + \dots + (a_{1n} + a_{n1}) x_1 x_n$$
In particular

Let
$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$
 and $A = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$

$$\begin{bmatrix} a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_3 \end{bmatrix}$$

$$\Rightarrow Q = x^T A x = a_{11} x_1^2 + a_{22} x_2^2 + a_{33} x_3^2 + (a_{12} + a_{21}) x_1 x_2 + (a_{13} + a_{31}) x_1 x_3 + (a_{23} + a_{32}) x_2 x_3$$

Determination of Symmetric matrix from Quadratic form

From the given Quadratic form $Q = x^T A x$ we can obtain symmetric matrix as follows:

- Place coefficients of x_i^2 diagonally. I.
- Divide the coefficients of $x_i x_j$, $i \neq j$ equally and place equal values at a_{ij} and a_{ji} II. places respectively.

Example: Find the symmetric matrix from the following quadratic form

$$Q = 2x_1^2 + 4x_2^2 + 3x_3^2 + 10x_1x_2 + 12x_2x_3 + 8x_3x_1$$

Solution: In case of symmetric matrix $a_{ij} = a_{ji}$

$$\Rightarrow Q = 2x_1^2 + 4x_2^2 + 3x_3^2 + (5+5)x_1x_2 + (6+6)x_2x_3 + (4+4)x_3x_1$$

The symmetric matrix is

$$A = \begin{bmatrix} 2 & 5 & 4 \\ 5 & 4 & 6 \\ 4 & 6 & 3 \end{bmatrix}$$

2. Hermitian Form

Hermitian form H is given by

$$H = \bar{x}^T A x$$

Where A is a Hermitian matrix and x is a column matrix.

Note: Hermitian form is always real.

Example: Is the following matrix Hermitian or Skew-Hermitian matrix? Find the Hermitian form or Skew-Hermitian form.

$$A = \begin{bmatrix} 4 & 3 - 2i \\ 3 + 2i & -4 \end{bmatrix}, x = \begin{bmatrix} -2i \\ 1 + i \end{bmatrix}$$
Solution: $\bar{A} = \begin{bmatrix} 4 & 3 + 2i \\ 3 - 2i & -4 \end{bmatrix}, \bar{A}^T = \begin{bmatrix} 4 & 3 - 2i \\ 3 + 2i & -4 \end{bmatrix} = A$

Since $\bar{A}^T = A$, so A is Hermitian.

Hermitian form is $H = \bar{x}^T A x$

Here
$$x = \begin{bmatrix} -2i \\ 1+i \end{bmatrix}$$
 $\Rightarrow \bar{x} = \begin{bmatrix} 2i \\ 1-i \end{bmatrix}$
 $\Rightarrow H = \bar{x}^T A x = \begin{bmatrix} 2i \\ 1-i \end{bmatrix} \begin{bmatrix} 4 & 3-2i \\ 3+2i & -4 \end{bmatrix} \begin{bmatrix} -2i \\ 1+i \end{bmatrix} = \begin{bmatrix} 7i+5 & 10i \end{bmatrix} \begin{bmatrix} -2i \\ 1+i \end{bmatrix} = 4$

3. Skew-Hermitian Form

Skew-Hermitian form S is given by

$$H = \bar{x}^T A x$$

Where A is a Skew-Hermitian matrix and x is a column matrix.

Note: Skew-Hermitian form is always 0 or purely imaginary.

Example: Is the following matrix Hermitian or Skew-Hermitian matrix? Find the Hermitian form or Skew-Hermitian form.

$$A = \begin{bmatrix} i & -2+3i \\ 2+3i & 0 \end{bmatrix}, x = \begin{bmatrix} i \\ 4 \end{bmatrix}$$
Solution: $\overline{A} = \begin{bmatrix} -i & -2-3i \\ 2-3i & 0 \end{bmatrix}, \overline{A}^T = \begin{bmatrix} -i & 2-3i \\ -2-3i & 0 \end{bmatrix} = -\begin{bmatrix} i & -2+3i \\ 2+3i & 0 \end{bmatrix} = -A$

Since $\overline{A}^T = -A$, so A is Skew-Hermitian.

Skew-Hermitian form is
$$S = \overline{x}^T A x$$
. Here $\begin{bmatrix} i \\ 4 \end{bmatrix} \implies \overline{x} = \begin{bmatrix} -i \\ 4 \end{bmatrix}$

$$\Rightarrow S = \overline{x}^T A x = \begin{bmatrix} -i \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ 2+3i \end{bmatrix} \begin{bmatrix} i \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$