

Computing a basis

Proposition: Mutually orthogonal nonzero vectors are linearly independent.

What happens if we call the `orthogonalize` procedure on a list $\text{vlist} = [\mathbf{v}_0, \dots, \mathbf{v}_n]$ of vectors that are linearly dependent?

$\dim \text{Span } \{\mathbf{v}_0, \dots, \mathbf{v}_n\} < n + 1.$

`orthogonalize`($[\mathbf{v}_0, \dots, \mathbf{v}_n]$) returns $[\mathbf{v}_0^*, \dots, \mathbf{v}_n^*]$

The vectors $\mathbf{v}_0^*, \dots, \mathbf{v}_n^*$ are mutually orthogonal.

They can't be linearly independent since they span a space of dimension less than $n + 1$.

Therefore some of them must be zero vectors.

Leaving out the zero vectors does not change the space spanned...

Let S be the subset of $\{\mathbf{v}_0^*, \dots, \mathbf{v}_n^*\}$ consisting of nonzero vectors.

$\text{Span } S = \text{Span } \{\mathbf{v}_0^*, \dots, \mathbf{v}_n^*\} = \text{Span } \{\mathbf{v}_0, \dots, \mathbf{v}_n\}$

Proposition implies that S is linearly independent.

Thus S is a basis for $\text{Span } \{\mathbf{v}_0, \dots, \mathbf{v}_n\}$.

Computing a basis

Therefore in principle the following algorithm computes a basis for $\text{Span}\{\mathbf{v}_0, \dots, \mathbf{v}_n\}$:

```
def find_basis( $[\mathbf{v}_0, \dots, \mathbf{v}_n]$ ):  
    "Return the list of nonzero starred vectors."  
     $[\mathbf{v}_0^*, \dots, \mathbf{v}_n^*] = \text{orthogonalize}([\mathbf{v}_0, \dots, \mathbf{v}_n])$   
    return  $[\mathbf{v}^* \text{ for } \mathbf{v}^* \text{ in } [\mathbf{v}_0^*, \dots, \mathbf{v}_n^*] \text{ if } \mathbf{v}^* \text{ is not the zero vector}]$ 
```

Example:

Suppose $\text{orthogonalize}([\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6])$ returns $[\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_2^*, \mathbf{v}_3^*, \mathbf{v}_4^*, \mathbf{v}_5^*, \mathbf{v}_6^*]$ and the vectors $\mathbf{v}_2^*, \mathbf{v}_4^*$, and \mathbf{v}_5^* are zero.

Then the remaining output vectors $\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_3^*, \mathbf{v}_6^*$ form a basis for $\text{Span}\{\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6\}$.

Recall

Lemma: Every finite set T of vectors contains a subset S that is a basis for $\text{Span } T$.

What about finding a subset of $\mathbf{v}_0, \dots, \mathbf{v}_n$ that is a basis?

Proposed algorithm:

```
def find_subset_basis( $[\mathbf{v}_0, \dots, \mathbf{v}_n]$ ):
```

Computing a basis

Therefore in principle the following algorithm computes a basis for $\text{Span } \{\mathbf{v}_0, \dots, \mathbf{v}_n\}$:

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Recall

Lemma: Every finite set T of vectors contains a subset S that is a basis for $\text{Span } T$.

What about finding a subset of $\mathbf{v}_0, \dots, \mathbf{v}_n$ that is a basis?

Proposed algorithm:

```
def find_subset_basis( $[\mathbf{v}_0, \dots, \mathbf{v}_n]$ ):  
    "Return the list of original vectors that correspond to nonzero starred vectors."  
     $[\mathbf{v}_0^*, \dots, \mathbf{v}_n^*] = \text{orthogonalize}([\mathbf{v}_0, \dots, \mathbf{v}_n])$   
    Return  $[\mathbf{v}_i \text{ for } i \text{ in } \{0, \dots, n\} \text{ if } \mathbf{v}_i^* \text{ is not the zero vector}]$ 
```

Is this correct?

Correctness of find_subset_basis

```
def find_subset_basis([ $\mathbf{v}_0, \dots, \mathbf{v}_n$ ]):  
    [ $\mathbf{v}_0^*, \dots, \mathbf{v}_n^*$ ] = orthogonalize([ $\mathbf{v}_0, \dots, \mathbf{v}_n$ ])  
    Return [ $\mathbf{v}_i$  for  $i$  in  $\{0, \dots, n\}$  if  $\mathbf{v}_i^*$  is not  
           the zero vector]
```

```
def orthogonalize(vlist):  
    vstarlist = []  
    for v in vlist:  
        vstarlist.append(  
            project_orthogonal(v, vstarlist))  
    return vstarlist
```

Example: `orthogonalize([$\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6$])` returns [$\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_2^*, \mathbf{v}_3^*, \mathbf{v}_4^*, \mathbf{v}_5^*, \mathbf{v}_6^*$]

Suppose \mathbf{v}_2^* , \mathbf{v}_4^* , and \mathbf{v}_5^* are zero vectors.

In third iteration of `orthogonalize`, `project_orthogonal($\mathbf{v}_3, [\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_2^*]$)` computes \mathbf{v}_3^* :

- ▶ subtract projection of \mathbf{v}_3 along \mathbf{v}_0^* ,
- ▶ subtract projection along \mathbf{v}_1^* ,
- ▶ subtract projection along \mathbf{v}_2^* —but since $\mathbf{v}_2^* = \mathbf{0}$, the projection is the zero vector

Result is the same as `project_orthogonal($\mathbf{v}_3, [\mathbf{v}_0^*, \mathbf{v}_1^*]$)`. Zero starred vectors are ignored.

Thus `orthogonalize([$\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6$])` would return [$\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_3^*, \mathbf{v}_6^*$].

Since [$\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_3^*, \mathbf{v}_6^*$] is a basis for $\mathcal{V} = \text{Span}\{\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6\}$
and [$\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6$] spans the same space, and has the same cardinality

Correctness of find_subset_basis

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def find_subset_basis([ $\mathbf{v}_0, \dots, \mathbf{v}_n$ ]):  
    [ $\mathbf{v}_0^*, \dots, \mathbf{v}_n^*$ ] = orthogonalize([ $\mathbf{v}_0, \dots, \mathbf{v}_n$ ])  
    Return [ $\mathbf{v}_i$  for  $i$  in  $\{0, \dots, n\}$  if  $\mathbf{v}_i^*$  is not  
           the zero vector]
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def orthogonalize(vlist):  
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Example: `orthogonalize([$\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6$])` returns [$\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_2^*, \mathbf{v}_3^*, \mathbf{v}_4^*, \mathbf{v}_5^*, \mathbf{v}_6^*$]

Suppose \mathbf{v}_2^* , \mathbf{v}_4^* , and \mathbf{v}_5^* are zero vectors.

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Thus `orthogonalize([$\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6$])` would return [$\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_3^*, \mathbf{v}_6^*$].

Since [$\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_3^*, \mathbf{v}_6^*$] is a basis for $\mathcal{V} = \text{Span}\{\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6\}$
and [$\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6$] spans the same space, and has the same cardinality

Correctness of find_subset_basis

```
def find_subset_basis([ $\mathbf{v}_0, \dots, \mathbf{v}_n$ ]):  
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    Return [ $\mathbf{v}_i$  for  $i$  in  $\{0, \dots, n\}$  if  $\mathbf{v}_i^*$  is not  
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def orthogonalize(vlist):  
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```

Suppose \mathbf{v}_2^* , \mathbf{v}_4^* , and \mathbf{v}_5^* are zero vectors.

In third iteration of orthogonalize, `project_orthogonal(\mathbf{v}_3 , [$\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_2^*$])` computes \mathbf{v}_3^* :

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Result is the same as `project_orthogonal(\mathbf{v}_3 , [$\mathbf{v}_0^*, \mathbf{v}_1^*$])`. Zero starred vectors are ignored.

Thus `orthogonalize([$\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6$])` would return [$\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_3^*, \mathbf{v}_6^*$].

Since [$\mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_3^*, \mathbf{v}_6^*$] is a basis for $\mathcal{V} = \text{Span}\{\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6\}$ and [$\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6$] spans the same space, and has the same cardinality [$\mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6$] is also a basis for \mathcal{V} .

Correctness of find_subset_basis

Another way to justify `find_subset_basis`...

Here's the matrix equation expressing original vectors in terms of starred vectors:

$$\begin{bmatrix} \mathbf{v}_0 & \mathbf{v}_1 & \mathbf{v}_2 & \cdots & \mathbf{v}_n \end{bmatrix} = \begin{bmatrix} \mathbf{v}_0^* & \mathbf{v}_1^* & \mathbf{v}_2^* & \cdots & \mathbf{v}_n^* \end{bmatrix} \begin{bmatrix} 1 & \alpha_{01} & \alpha_{02} & & \alpha_{0n} \\ & 1 & \alpha_{12} & & \alpha_{1n} \\ & & 1 & & \alpha_{2n} \\ & & & \ddots & \\ & & & & 1 \end{bmatrix}$$

Correctness of find_subset_basis

$$\left[\begin{array}{c|c|c|c|c|c|c} \mathbf{v}_0 & \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 & \mathbf{v}_4 & \mathbf{v}_5 & \mathbf{v}_6 \end{array} \right]$$

$$= \left[\begin{array}{c|c|c|c|c|c|c} \mathbf{v}_0^* & \mathbf{v}_1^* & \mathbf{v}_2^* & \mathbf{v}_3^* & \mathbf{v}_4^* & \mathbf{v}_5^* & \mathbf{v}_6^* \end{array} \right]$$

Let $\mathcal{V} = \text{Span} \{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6 \}$.

Suppose \mathbf{v}_2^* , \mathbf{v}_4^* , and \mathbf{v}_5^* are zero vectors.

$$\left[\begin{array}{ccccccc} 1 & \alpha_{01} & \alpha_{02} & \alpha_{03} & \alpha_{04} & \alpha_{05} & \alpha_{06} \\ & 1 & \alpha_{12} & \alpha_{13} & \alpha_{14} & \alpha_{15} & \alpha_{16} \\ & & 1 & \alpha_{23} & \alpha_{24} & \alpha_{25} & \alpha_{26} \\ & & & 1 & \alpha_{34} & \alpha_{35} & \alpha_{36} \\ & & & & 1 & \alpha_{45} & \alpha_{46} \\ & & & & & 1 & \alpha_{56} \\ & & & & & & 1 \end{array} \right]$$

Delete zero columns and the corresponding rows of the triangular matrix. Shows

$$\text{Span} \{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6 \} \subseteq \text{Span} \{ \mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_3^*, \mathbf{v}_6^* \}$$

so $\{ \mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_3^*, \mathbf{v}_6^* \}$ is a basis for \mathcal{V}

Delete corresponding original columns \mathbf{v}_2 , \mathbf{v}_4 , \mathbf{v}_5 .

Resulting triangular matrix is invertible. Move it to other side.

Shows $\text{Span} \{ \mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_2^*, \mathbf{v}_6^* \} \subseteq \text{Span} \{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6 \}$ so $\{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6 \}$ is basis for \mathcal{V} .

Correctness of find_subset_basis

$$\left[\begin{array}{c|c|c|c|c|c|c} \mathbf{v}_0 & \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 & \mathbf{v}_4 & \mathbf{v}_5 & \mathbf{v}_6 \end{array} \right]$$

Let $\mathcal{V} = \text{Span} \{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6 \}$.

Suppose \mathbf{v}_2^* , \mathbf{v}_4^* , and \mathbf{v}_5^* are zero vectors.

$$= \left[\begin{array}{c|c|c|c} \mathbf{v}_0^* & \mathbf{v}_1^* & \mathbf{v}_3^* & \mathbf{v}_6^* \end{array} \right]$$

$$\left[\begin{array}{ccccccc} 1 & \alpha_{01} & \alpha_{02} & \alpha_{03} & \alpha_{04} & \alpha_{05} & \alpha_{06} \\ & 1 & \alpha_{12} & \alpha_{13} & \alpha_{14} & \alpha_{15} & \alpha_{16} \\ & & & 1 & \alpha_{34} & \alpha_{35} & \alpha_{36} \\ & & & & & & 1 \end{array} \right]$$

Delete zero columns and the corresponding rows of the triangular matrix. Shows

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Shows $\text{Span} \{ \mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_2^*, \mathbf{v}_6^* \} \subseteq \text{Span} \{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6 \}$ so $\{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6 \}$ is basis for \mathcal{V} .

Correctness of find_subset_basis

$$\left[\begin{array}{c|c|c|c} \mathbf{v}_0 & \mathbf{v}_1 & \mathbf{v}_3 & \mathbf{v}_6 \end{array} \right]$$

Let $\mathcal{V} = \text{Span} \{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6 \}$.

Suppose \mathbf{v}_2^* , \mathbf{v}_4^* , and \mathbf{v}_5^* are zero vectors.

$$= \left[\begin{array}{c|c|c|c} \mathbf{v}_0^* & \mathbf{v}_1^* & \mathbf{v}_3^* & \mathbf{v}_6^* \end{array} \right]$$

$$\begin{bmatrix} 1 & \alpha_{01} & \alpha_{03} & \alpha_{06} \\ & 1 & \alpha_{13} & \alpha_{16} \\ & & 1 & \alpha_{36} \\ & & & 1 \end{bmatrix}$$

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Shows $\text{Span} \{ \mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_2^*, \mathbf{v}_6^* \} \subseteq \text{Span} \{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6 \}$ so $\{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6 \}$ is basis for \mathcal{V} .

Correctness of find_subset_basis

$$\left[\begin{array}{c|c|c|c} \mathbf{v}_0 & \mathbf{v}_1 & \mathbf{v}_3 & \mathbf{v}_6 \end{array} \right] \left[\begin{array}{cccc} 1 & \alpha_{01} & \alpha_{03} & \alpha_{06} \\ & 1 & \alpha_{13} & \alpha_{16} \\ & & 1 & \alpha_{36} \\ & & & 1 \end{array} \right]^{-1}$$

Let $\mathcal{V} = \text{Span} \{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5, \mathbf{v}_6 \}$.

Suppose \mathbf{v}_2^* , \mathbf{v}_4^* , and \mathbf{v}_5^* are zero vectors.

$$= \left[\begin{array}{c|c|c|c} \mathbf{v}_0^* & \mathbf{v}_1^* & \mathbf{v}_3^* & \mathbf{v}_6^* \end{array} \right]$$

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Resulting triangular matrix is invertible. Move it to other side.

Shows $\text{Span} \{ \mathbf{v}_0^*, \mathbf{v}_1^*, \mathbf{v}_2^*, \mathbf{v}_6^* \} \subseteq \text{Span} \{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6 \}$ so $\{ \mathbf{v}_0, \mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_6 \}$ is basis for \mathcal{V} .

Correctness of find_subset_basis

$$\left[\begin{array}{c|c|c|c} \mathbf{v}_0 & \mathbf{v}_1 & \mathbf{v}_3 & \mathbf{v}_6 \end{array} \right] \left[\begin{array}{cccc} 1 & \alpha_{01} & \alpha_{03} & \alpha_{06} \\ & 1 & \alpha_{13} & \alpha_{16} \\ & & 1 & \alpha_{36} \\ & & & 1 \end{array} \right]^{-1}$$

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$$= \left[\begin{array}{c|c|c|c} \mathbf{v}_0^* & \mathbf{v}_1^* & \mathbf{v}_3^* & \mathbf{v}_6^* \end{array} \right]$$

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Roundoff error in computing a basis

In principle the following algorithm computes a basis for $\text{Span} \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$:

```
def find_basis( $[\mathbf{v}_1, \dots, \mathbf{v}_n]$ )
```

Use **orthogonalize** to compute $[\mathbf{v}_1^*, \dots, \mathbf{v}_n^*]$

Return the list consisting of the nonzero vectors in this list.

However: the computer uses floating-point calculations.



Due to round-off error, the vectors that are supposed to be zero won't be exactly zero.

Instead, consider a vector \mathbf{v} to be zero if $\mathbf{v} * \mathbf{v}$ is very small (e.g. smaller than 10^{-20}):

```
def find_basis( $[\mathbf{v}_1, \dots, \mathbf{v}_n]$ )
```

Use orthogonalize to compute $[\mathbf{v}_1^*, \dots, \mathbf{v}_n^*]$

Return the list consisting of vectors in this list
whose squared norms are greater than 10^{-20}

Can use this procedure in turn to define **rank(vlist)** and **is_independent(vlist)**.

Use same idea in other procedures such as **find_subset_basis**