



Determining the accessibility of parking spaces in unfavorable conditions

**FINAL PROJECT
OF INTRO2CV**



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PLAN

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INTRODUCTION

- Looking for a parking spot is a *common* and often *stressful activity*; it takes a *large amount of time*.
- Have to pay a high amount in parking fines.
- Imbalance between parking demand and availability because of the *growth of automobile ownership*.
- Consumes around one million barrels of oil every day and contributes to *air pollution*.

⇒ PROJECT: **locate vacant parking spaces** in parking lots based on bird's-eye view photographs acquired by cameras in unfavorable conditions.

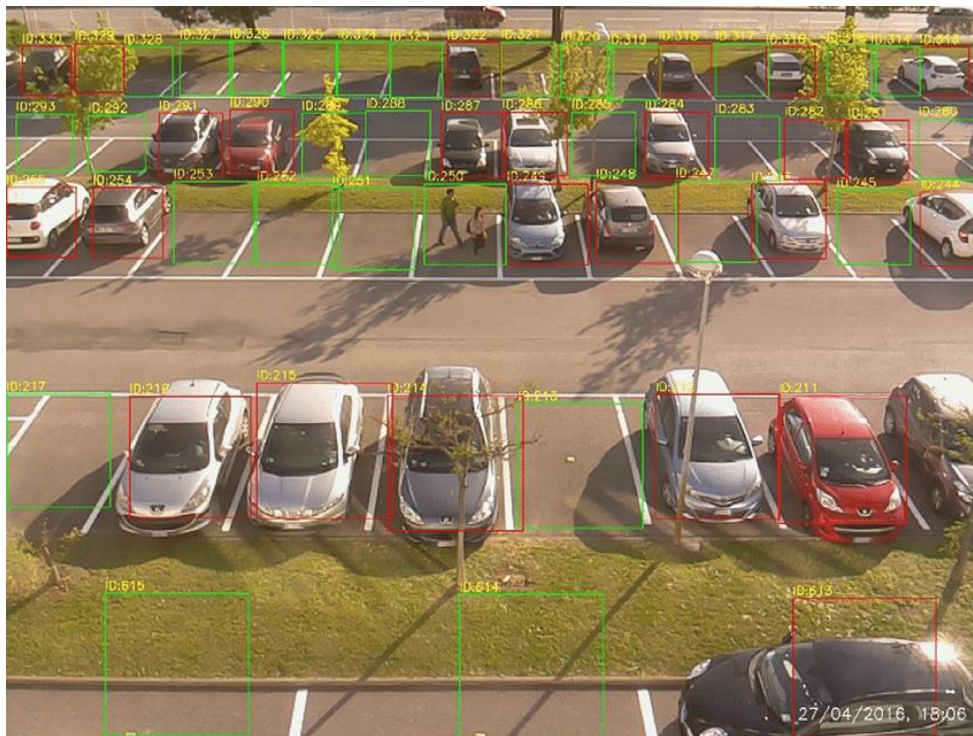
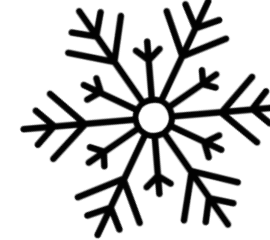


What is the expected value?

- Graphical display of available parking spaces
- Center coordinates
- Occupation status



PROBLEM DESCRIPTION



Ideal case:

- There are parking markings
- The images of the cars are not distorted in any way

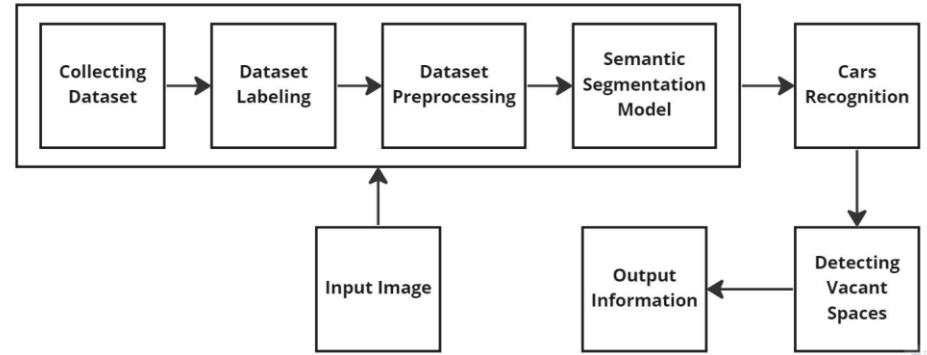
But what about real life?



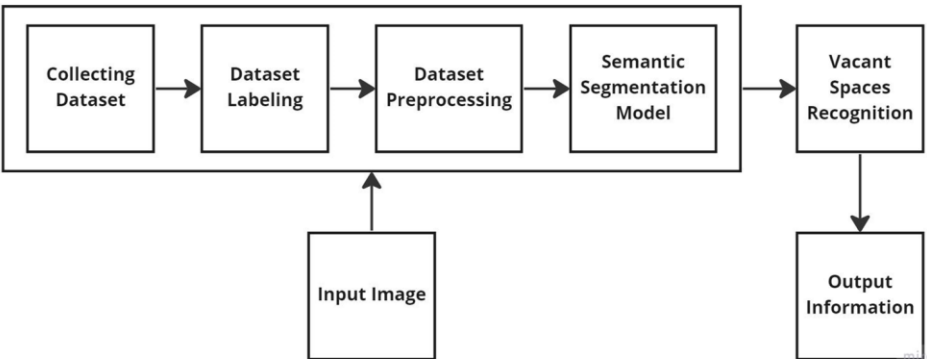
Real case:

- There are **no** parking markings
- Cars are **covered** with snow

Proposed methods



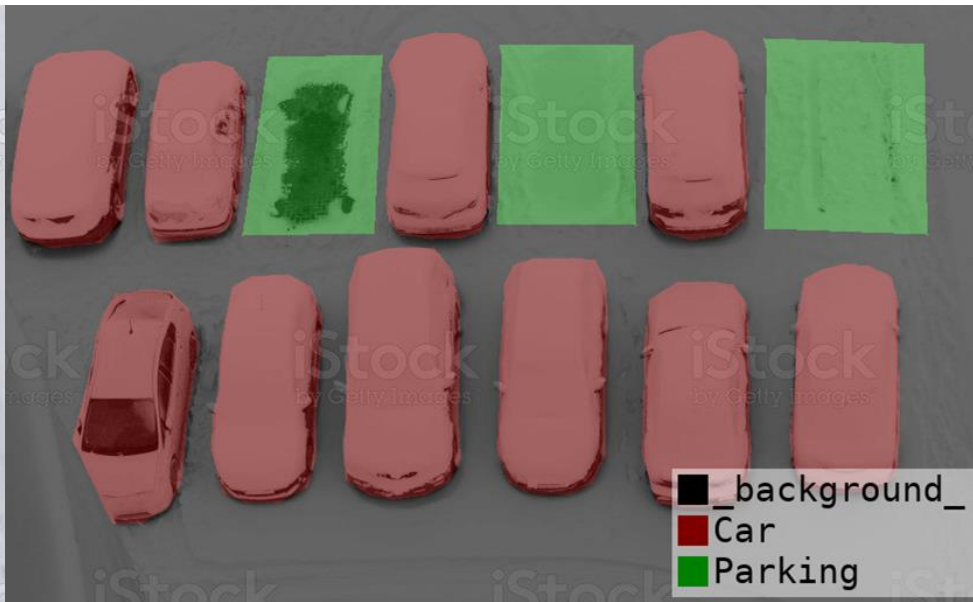
First method



Second method



Dataset - 2 DESCRIPTION





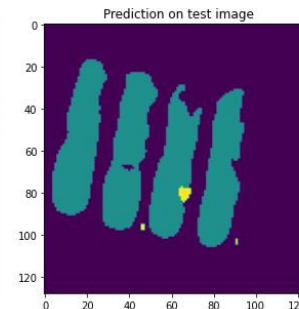
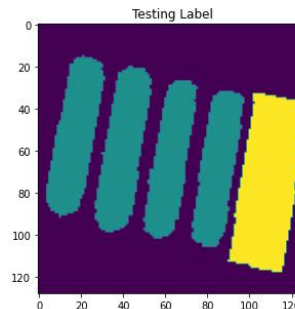
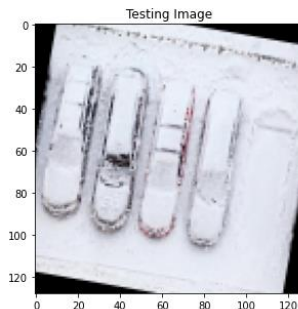
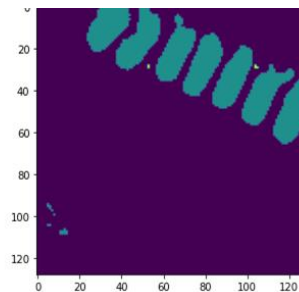
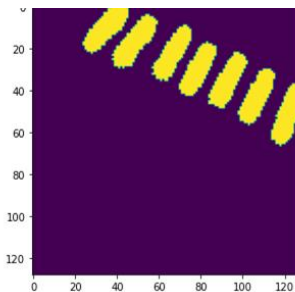
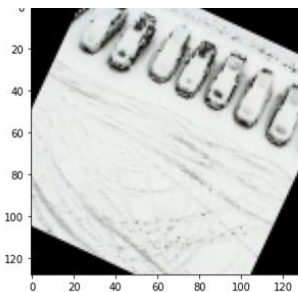
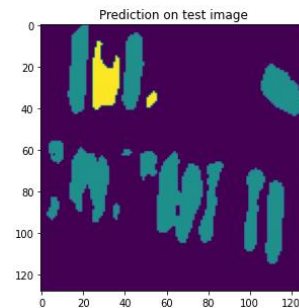
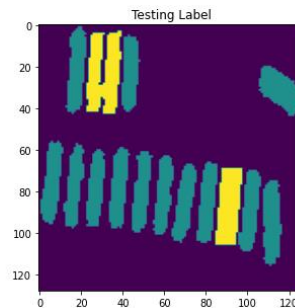
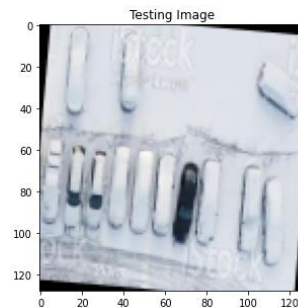
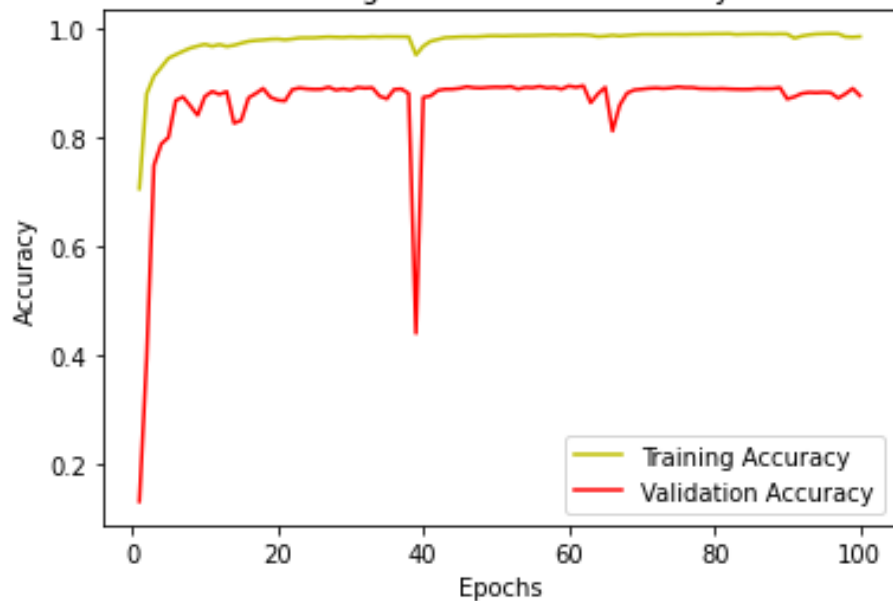
COMPUTER VISION PIPELINE

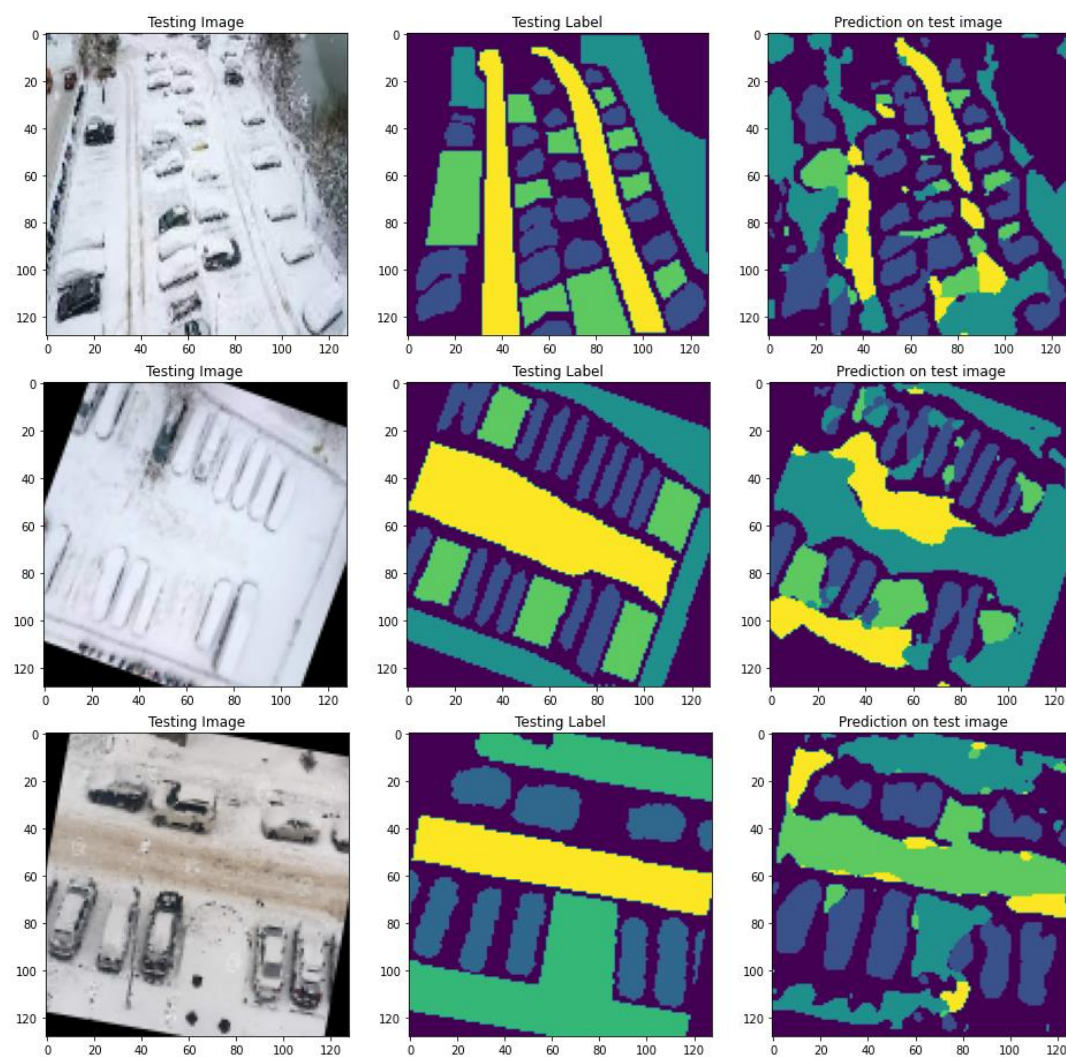
1. Manually collect images for train dataset (22 images)
2. Train **resnet34** model for semantic segmentation (cars, parking, road, mud)
3. Apply morphological operations to labeled image
4. Using the contours, draw a rectangle for each “car area” that borders it
5. Retreating from the car at equal distances to the side, check whether the space is free or occupied



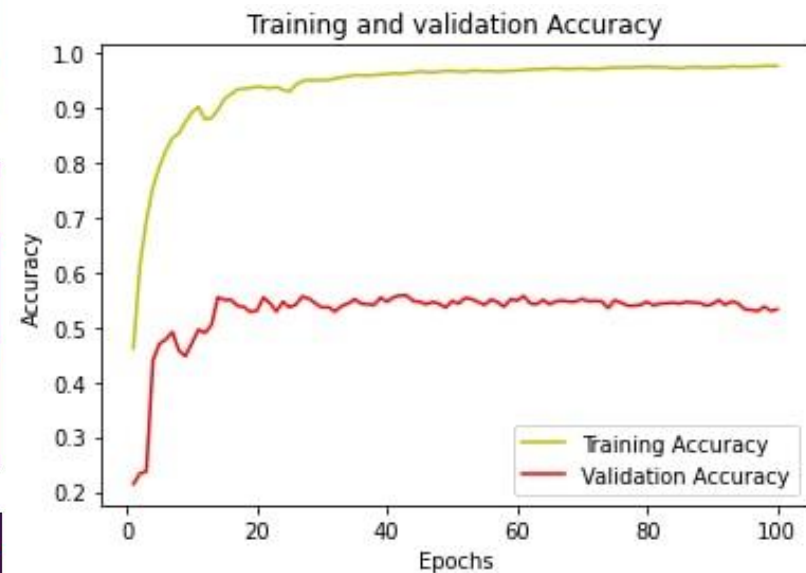
METHOD on Dataset-2

Training and validation Accuracy

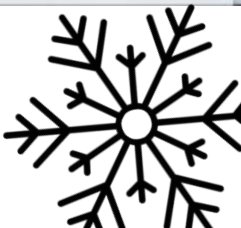
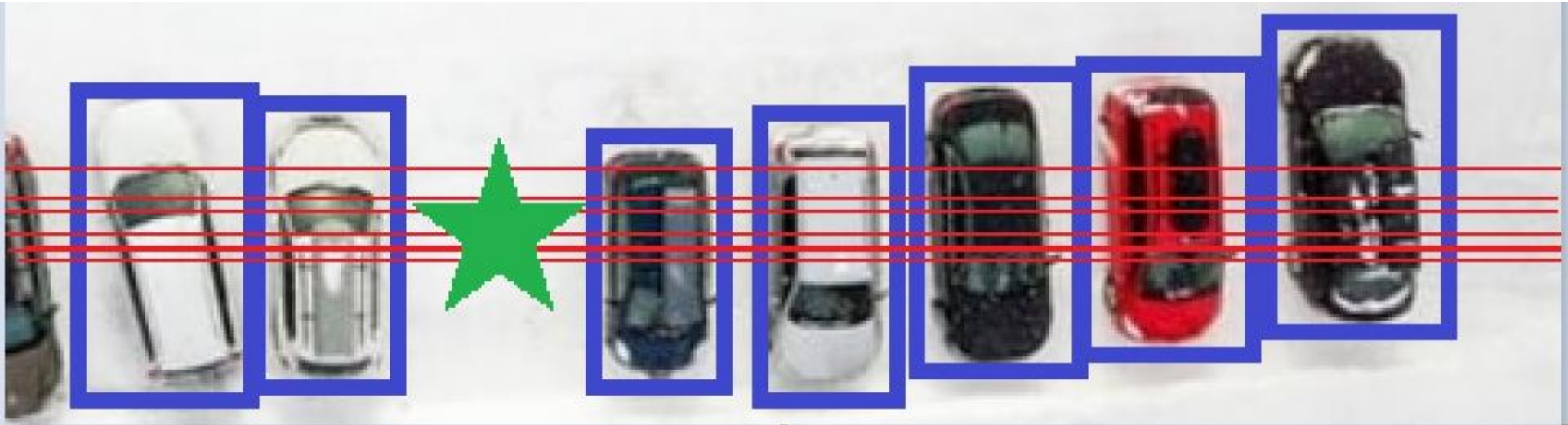




METHOD on Dataset-1



How does algorithm look?



RESULTS

To test the algorithm, we used a test dataset consisting of 6 images.



TPR	FPR	Mean error
0,54	0,14	0,6

Estimate quality metrics



RESULTS: GOOD EXAMPLES



RESULTS: BAD EXAMPLES

False negative



False positive





CONCLUSION

1. Using **semantic segmentation** to detect **parking spaces** as a class is **unreasonable**, because in winter conditions in most cases a free parking space (covered with snow) is no different from a road (covered with snow) or an environment (covered with snow).
2. A common sense approach is to use **semantic segmentation** to detect **snow-covered cars** and work with that information.
3. In such non-trivial tasks, the **data** set must be collected **manually**, and its size must be **large** and cover all **commonality**.





Thank
you!



References



Semantic segmentation model



Dataset Labeling