

# Pedestrian Safety – Fundamental to a Walkable City

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**Abstract.** In this paper, we present a method to identify urban areas with a higher likelihood of pedestrian safety related events. Pedestrian safety related events are pedestrian—vehicle interactions that result in fatalities, injuries, accidents without injury, or a near-miss between pedestrian and vehicle. To develop a solution to this problem of identifying likely locations of events, we assemble data sets, primarily from the City of Cincinnati, that include safety reports from a 5 year period, geographic information for these events, a citizen survey that identifies pedestrian reported concerns, and a database of all requests for service for any cause in the city. From this assembled data set we complete unsupervised learning along with multivariate linear regression. The results indicate areas with a high potential for safety improvement for prioritized remediation enabling a proactive approach to improved pedestrian safety.

## 1 Introduction

*An early-morning walk is a blessing for the whole day -- Henry David Thoreau [1]. So, begins the choice every day for urban dwellers -- to walk or not to walk — to have a blessing as proposed by Thoreau, or to assess the daily commute — as summarized by Jeff Kober [2]: *My intention is to get done with this commute ... my intention will not be met until I get out of this car* — as just a rather unpleasant means to get from point A to point B.*

A walkable neighborhood is a neighborhood with the following characteristics:a center (either a main street or public space), sufficient population density to support local businesses and public transit, affordable housing, public spaces, streets designed for bicyclists and pedestrians, and schools and workplaces within walking distance for residents [3]. As the modern urban landscape has evolved in the US over the last fifty years, pedestrianism was not often on the list of high priorities for inclusion into the development of urban environments. As a result of this trend, there have been real, and negative, consequences: economically, epidemiologically, and environmentally on the inhabitants of many cities in

western developed countries [4]. Economically, we can observe that the percentage of income spent on transportation for working families has doubled, from one-tenth to one-fifth of household earnings from the 1970s to current era [4]. So much so that working families are currently spending more of their budget on transportation than housing. If we consider the health effects of urban living patterns, we observe that people living in less walkable neighborhoods are nearly twice as likely to be obese than people that live in walkable neighborhoods [4]. This statistic, coupled with the fact that Americans now walk the least of any industrialized nation in the world [5] indicate a growing health problem due in part to a lack of physical activity. When constructed on a per-household basis, carbon mapping clearly demonstrates that suburban dwellers generate nearly twice as much carbon-dioxide, the main pollutant contributing to global warming [6], than do urban dwellers due to longer commutes and larger houses [4].

There is a growing movement in the US and other western nations to promote the concept of walkable cities as healthier places to live - economically, environmentally and physiologically - than the suburban, exurban, drive-till-you-qualify model of modern western development [7] [8] [9]. As identified in the Toronto Pedestrian Charter [10] the six principles for building a vital urban pedestrian environment include: accessibility, equity, health and well-being, environmental sustainability, personal and community safety, and community cohesion and vitality. According to the city of Toronto, this is the first such pedestrian bill of rights in the world and promotes the concept that walking is valued for its social, environmental, and economic benefits.

The US is experiencing an increase in the number of pedestrian fatalities, reaching a 25-year high in 2017, with nearly 6,000 fatalities [11]. Newspaper articles in the Midwest identify fatal occurrences: [12] "An uptick in pedestrians being hit by cars in the Cincinnati and Northern Kentucky area has officials sounding the alarm. Three crashes just this week resulted in the death of three pedestrians."

As one avenue of response, the City of Cincinnati has requested citizen input to identify specific areas in the city which are pedestrian safety concerns. The city created a web-site, which launched in Feb-2018 [13], that allows citizens to specifically identify a location on a map, within a distance of several feet of the area of concern and report the nature of the concern in a functional user interface. The city plans to use this community input to prioritize maintenance and improvement resources.

## 2 Pedestrian Safety

The subject pedestrian safety is supported by terminology specific to this domain. A collection of the terminology that we use in this paper is provided in this section.

Prime measurements that are used to report pedestrian safety events are fatalities, injuries, and near misses. The statistics in these categories are quoted

in number of events and are typically stated on an annualized and per capita basis.

There are a range of severities associated to the outcomes of pedestrian–vehicle accidents. A continuous real valued response variable that accounts for both the severity and the frequency of events can be established by accounting for this relative severity. We implement a response variable that is a multiple of the number of events and the cost of the event. The cost basis that we use is based on average severity costs for 5 levels of events, as established by the National Safety Council [14] as shown in Table 1.

**Table 1.** Event Cost Severity, 2012 [14]

Severity	Unit Cost (\$)
Fatality	10,082,000
Disabling Injury	1,103,000
Evident Injury	304,000
Possible injury	141,000
No Injury Observed	46,600

Table 2 below is presented as a primer on pedestrian safety related terminology along with an explanation of the significance of each term in relation to the evaluation presented in this paper.

**Table 2.** Pedestrian safety terminology

Attribute	Description
Potential for Safety Improvement (PSI)	Im- Measures the actual crash cost minus the expected cost of “similar” sites that can be obtained from the crash cost models. In typical usage, an explanatory model using available features is established to predict some measure of cost (e.g., fatality or injury). [15]
Hotspot	In this context, hotspots are areas with higher density or frequency of pedestrian related accidents [16].

The focus of many pedestrian safety studies is the interaction between pedestrians and vehicles. Prior works have created statistical models to determine the likelihood of crashes, given information about the time of day, victim’s age, gender, and other features [17] [18] [19] [20] [21] [22]. The study done by Guo [23], et al examined the patterning and structure of road networks as a factor of pedestrian vehicle interactions (PVIs). Zhang et al [24] created a statistical model that classified different types of street crossings to determine which type of crossing

was the safest, and gain insight to the relationships between the factors that contribute to a PVI. In our study, we addressed the issue of pedestrian safety in regard to PVIs by proactively identifying intersections which are of high risk, as opposed to prior studies which have only identified the contributing factors.

### 3 Data Sets

The Cincinnati Area Geographic Information System is an online survey which was available from Feb 2018 to April 2018 for pedestrian safety [13]. Users logged in to <http://cagisonline.hamilton-co.org/pedsafetysurvey/>. The survey screen provided users with view of the city, a drop down of neighborhoods, and a list of issue categories. The user then selected a neighborhood, and selects a pre-defined issue type to report, and writes their comment. If another user selects the same location and issue type, comments are appended as additional comments. This gives an idea of number of users having same issue at a particular location. Survey submissions are anonymous.

Additionally, the date of the issue created, typical mode of user (walk, drive, bicycle), and intersection of the location selected are captured. There are 3788 records in our survey dataset with 8 usable columns. There are missing data and categorical data in incorrect format which require clean-up and updating of missing information. Other than the survey data, we have various sources of data which would be combined to form the dataset for the project. All acquired from the City of Cincinnati are listed in Table 3. Datasets that originated from the Open Data Cincinnati are listed in Table 4. Supplementary data sets from external sources are listed in Table 5.

**Table 3.** Cincinnati based data sets

Data Set	Source	Evaluation summary
Cincinnati open data	<a href="https://data.cincinnati-oh.gov">https://data.cincinnati-oh.gov</a>	Contains economic, neighborhood safety, and health related data for city of Cincinnati Data is not granular
Cincinnati pedestrian safety survey data		Contains survey data from citizens who have reported problems by using the web-page Data is organized at the street intersection level
Pedestrian near miss data		Data was collected from Feb - Apr 2018 A dataset provided by the city of Cincinnati containing latitude and longitudinal data of near-miss incidents within the city
Income and house price	<a href="http://www.city-data.com/nbmaps/neigh-Cincinnati-Ohio.html">http://www.city-data.com/nbmaps/neigh-Cincinnati-Ohio.html</a>	Contains statistics on age, house prices, income and more Data gathered as a collection of public and private sources Data organized at both the neighborhood, and census block group level

**Table 4.** Cincinnati open data datasets

Data Set	Evaluation Summary
Cincinnati 311 non-emergency service requests	This dataset contains records of all non-emergency service requests to the city of Cincinnati from 2012 to 2018. Contains reports from graffiti to relevant traffic information such as roadkill and potholes.
2017 NFIRS Cincinnati Fire Department Incident Data	Cincinnati Fire National Fire Incident Reporting System dataset which reports on the full range of fire department activities with reports of number of employees and vehicles deployed to every incident.
Street Centerline (w/ PCI rating)	City street centerline data with pavement condition index ranking; used to determine road condition and composition.
Traffic Crash Reports (CPD)	The Cincinnati traffic crash reports dataset compiled by the Cincinnati Police Department. It contains records of responses to traffic crashes, containing a wide-range of crash data such as persons involved, injury level, day, time, and weather.

**Table 5.** Supplementary data sets

Data Set	Source	Evaluation summary
Google Maps	<a href="https://developers.google.com/maps">https://developers.google.com/maps</a>	This API gives us granular data on walking and biking - distance, direction and other information Latitude and Longitude information for grid areas can be derived using this API
Walk Score®	<a href="https://www.walkscore.com">https://www.walkscore.com</a>	A scoring scale across US which gives an idea of the current walkability of the city
Zillow	<a href="https://www.quandl.com/">https://www.quandl.com/</a>	The Zillow Home Value Index contains monthly time-series of data which represent Zillow's estimation of the median market value of home sales. Index-Metro-NF-Sales-Cincinnati-OHh

## 4 Methods and Experiments

### 4.1 Data Ingestion and Grid-Cell Aggregation

### 4.2 Random Forest - Binary Model

### 4.3 Multi-Variate Linear Regression - Cost Model

In order to create a linear cost model to predict the cost of a PVI, the data must lend itself to the assumptions of a parametric model. These assumptions include normality, linearity, constant variance, and independence. The response variable within the data has a very abnormal distribution, with nearly 80% of the grid-cells containing no incidents of PVI and having 0 cost associated with them. This positively skewed data does not meet the assumption of normality even after multiple types of transformations, notably including the logarithmic transformation. In order to meet the assumption of normally distributed data, the data is subset to exclude locations where there is no data, and the few events resulting in extreme damage of \$5 million or more. This data subset dramatically reduces the skewness present in the dataset, and allows for linear regression modelling to proceed.

The reduced scope dataset is first run through the 10-fold cross validated stepwise selection of the caret package in R, in order to determine the best full model, ranging from 10 to 35 predictor variables. The function iterates through each number of predictor variables from 10 to 35, performing stepwise 10-fold cross validation for each number of maximum predictor variables. The 10-fold cross validation is a model validation technique used to reduce overfitting and promote the generalizability of the model. Model overfitting can occur when a model is trained on a particular dataset to the degree that it performs extraordinarily well in predicting on the dataset, but it fails to achieve that same level of prediction capability on other datasets. The parameters in an overly fit model do not generalize to the population at large because they are fine tuned to only reflect the dataset on which they were trained. The 10-fold cross validation splits the data into 10 pieces. In each of the 10 iterations, one is selected to be the testing dataset, and the other 9 are used to train the model. This methodology is repeated so that each of the 10 pieces has a chance to be the testing dataset. The result of these 10 trials are averaged and compared against the cross validation results at each other maximum variable value from 10 to 35. The full model chosen is the model with the lowest average root mean square error value, and in our study, was determined to be the model with 30 variables.

Once the full model is selected, it is then manually pruned based on the variance inflation factor values and significance. Variance inflation factor values larger than 5 signify collinearity between variables, and a violation of one of the parametric assumptions in linear regression. Variable significance is determined by the p-value, and the typical value used is .05. Variables at or below the .05 p-value threshold are determined to be statistically significant to the model, while those above it are not. In spite of this black and white view on p-values, some

variables are left in the model which are not significant at the .05 level, but are suggestive of being significant influences to the model, as shown in Table 7.

With the reduced model, the cost of non-fatality incidents to pedestrians is predicted for each event, and the resulting prediction is compared against the actual cost of incident. The difference between the predicted and actual cost is the residual, and the residuals are then mapped back to the Cincinnati map to visualize areas with potential for safety improvement.

#### 4.4 Non-Supervised Learning - Neighborhood Characterization

For unsupervised learning, a dataset is used which does not contain the response variable and is run through the t-sne algorithm, using perplexities 10 to 500 to obtain optimal cluster groupings. Each perplexity returns its own t-sne outputs of X1 and X2. We picked perplexity 50 to run unsupervised algorithms, as shown in Figure 1. Using the 2 outputs of the t-sne algorithm and combining it with the original dataset, Kmeans and hierarchical clustering approaches were able to be applied. Optimal clusters were chosen based on silhouette score, which is determined that 3 clusters are optimal to use in k-mean clustering. The labels are then plotted on the Cincinnati grid map to create visualization.

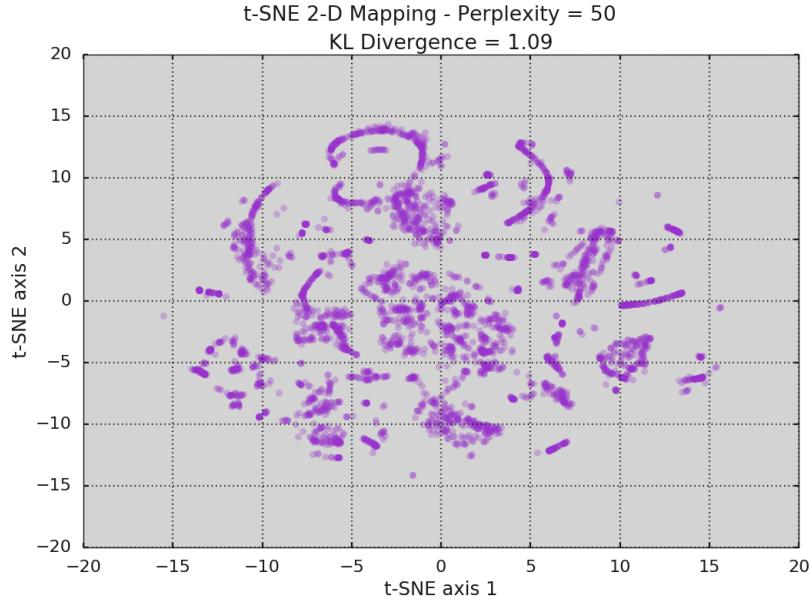


Fig. 1: Spread of data visualized using t-sne.

## 5 Results

### 5.1 Data Aggregation and Grid-Cell Assignment

The results of several of the data sets aggregated and assigned to each respective grid cell are shown in following figures. In summary, the following features were mapped into the grid cells as candidate features to participate in the modeling :

**Table 6.** Feature Definition

Data category	Specific feature definition
Non-pedestrian accidents	Number Events Sum cost (NSC) for events
Pedestrian survey responses	TBD in next update
Reported near misses	Number events Categorical feature counts
Street surface areas	Surface total length Sum lane counts
Walk Scores	Max, Mean, Min
Fire incidents	TBD in next update
Non-emergency service requests	Sum number requests Categorical feature counts
Property values & uses	Median prperty values Number of property transfers in 10-year period
Public transportation accessibility	Distance to nearest bus stop

Figure 2.

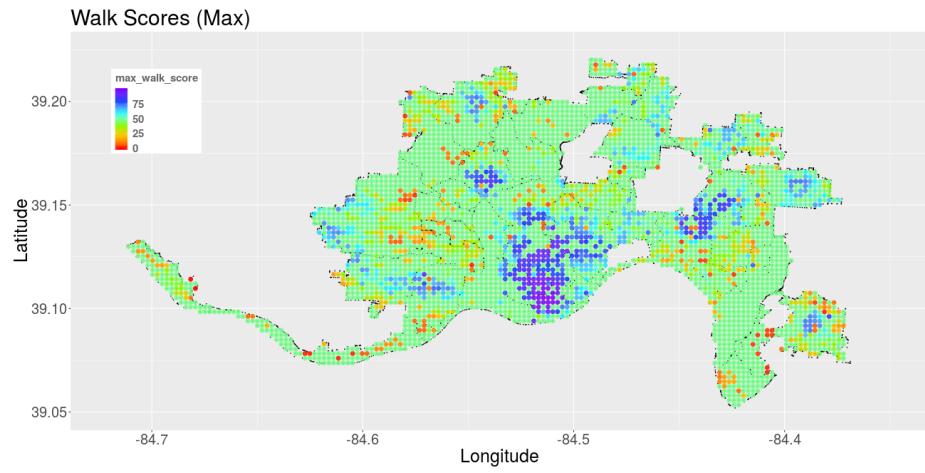


Fig. 2: Walk Score - Max values

Figure 3.

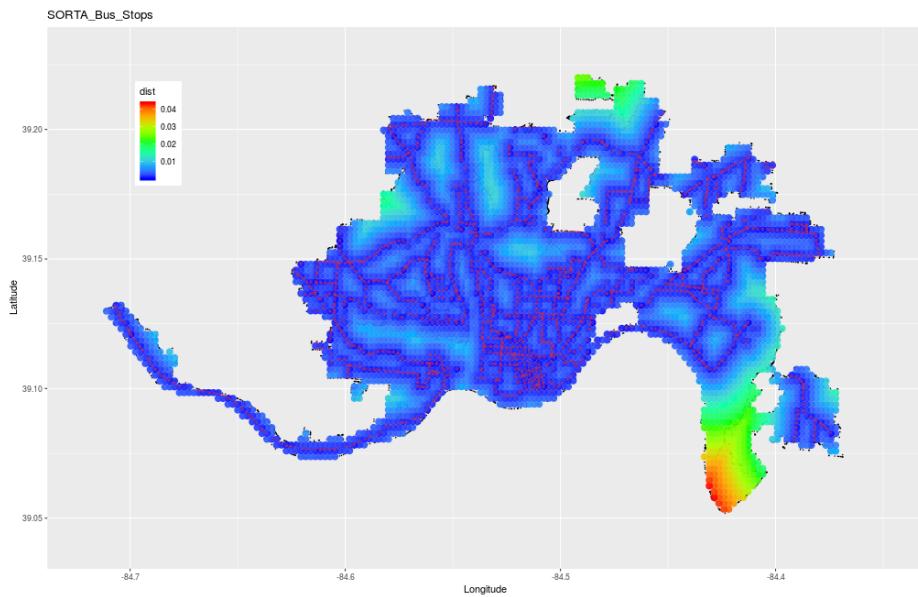


Fig. 3: Public Transportaton accessibility

Figure 4.

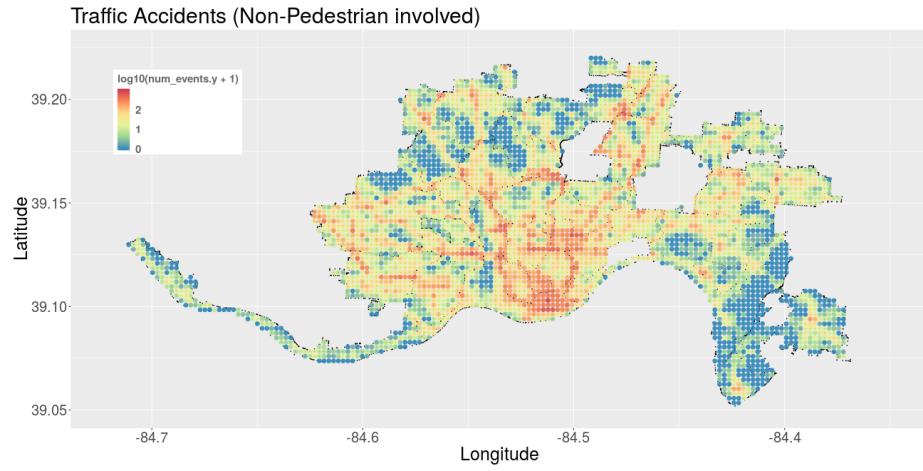


Fig. 4: Number of Traffic Accidents (Non-pedestrian involved)

## 5.2 Random Forest - Binary Model

The random forest model which we deployed to estimate occurrence of pedestrian related events produces the result of 75% true positive, 20% false positive with a detection threshold set at 0.20. This result provides a balanced compromise between true positive and false positive, as depicted in the following Figure 5.

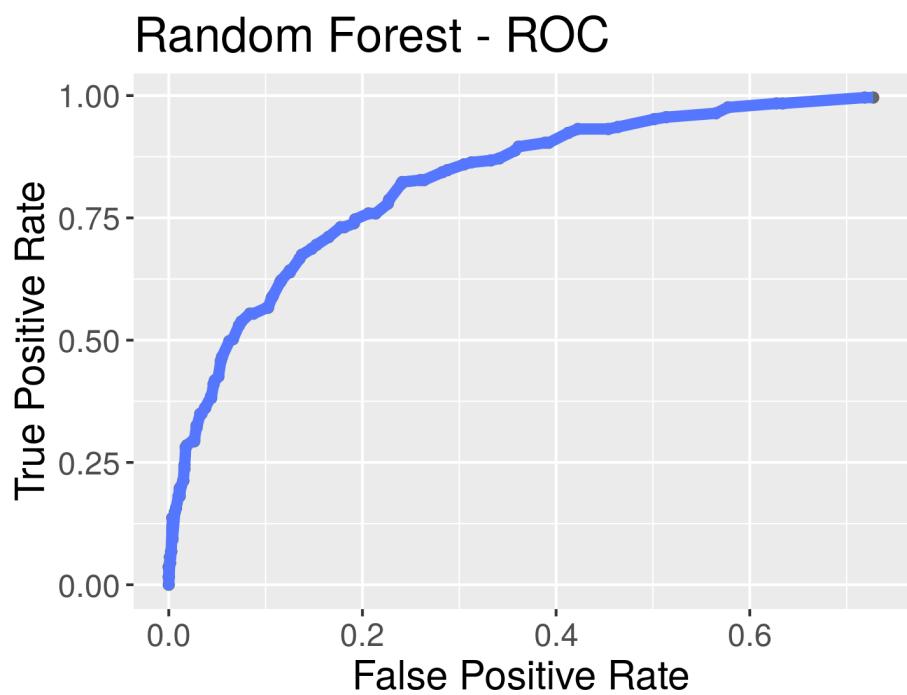


Fig. 5: Random forest - binary model - ROC curve

As visualized on the map of the city, Figure 6, we observe that (a) the regions of true positive (green) and true negative (light grey) comprise the large majority of the surface area, generally represented by contiguous areas, and confirm the high overall accuracy of the model, (b) that the false positive (darker grey) and false negative (red dots) are consistently along the border regions between otherwise true positive or true negative regions, and (c) the false negative regions are distinct non-connected grid cells at somewhat widely distributed locations around the city.

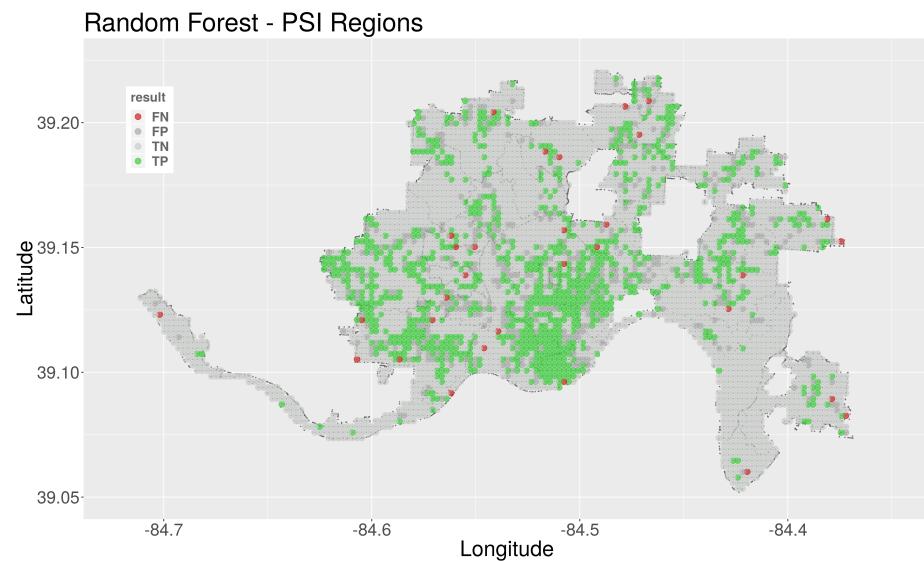


Fig. 6: Distribution of random forest model results visualized on city map

### 5.3 Multi-Variate Linear Regression - Cost Model

**Table 7.** Analysis of reduced model regression variables.

Variable	Estimate (\$)	Std. Error (\$)	t-value	p-value
Intercept	310,397	90,519	3.429	0.00064
Sum Cost of Damage to 267		31.8	8.391	< 2e-16
People in Non-Pedestrian				
Accidents				
Unsanitary Food Operations	39,796	8,189	4.86	1.40E-06
Intercept	310,397	90,519	3.429	0.00064
Maximum Walk Score	5,638	1758	3.207	0.00139
Water Leaks and Breaks	-72,140	24,776	-2.912	0.00369
Crosswalk Needed	117,618	45,848	2.565	0.01048
Number of Police Proper- ties	14,442	5,850	2.469	0.01377
Vehicles Running Red Lights / Stop Signs	50,332	24,291	2.072	0.03856
Unkempt Flora	3,998	2,158	1.853	0.06429
Speeding	-62,700	34,132	-1.837	0.06658
Parking Close to Intersec- tion	-146,340	82,879	-1.766	0.07781
Parking on Sidewalk	257,246	147,334	1.746	0.08117

Table 7 shows the explanatory variables for the reduced multiple linear regression model. This model had an R2 value of .2021 and an adjusted R2 value of .1917.

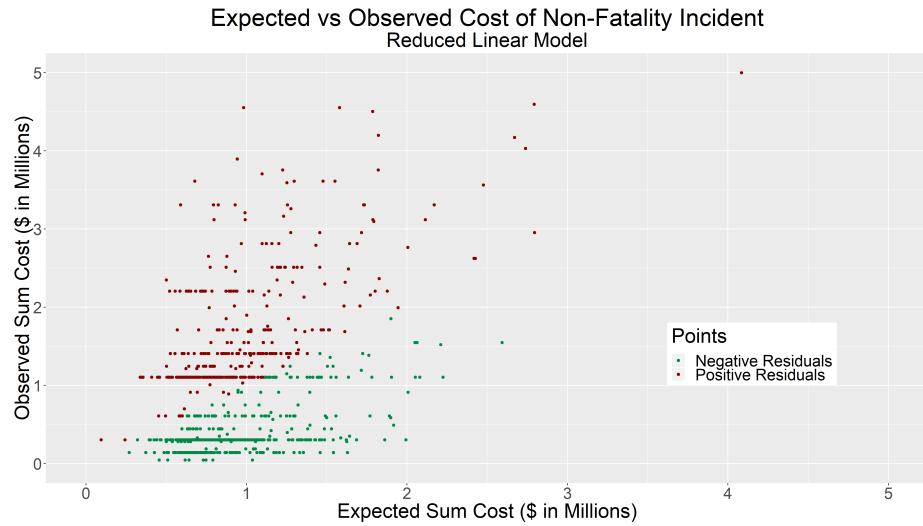


Fig. 7: Comparison of expected and observed non-fatality pedestrian incident costs.

Figure 7 is a comparison between the observed and actual cost of a non-fatality incident in Cincinnati.

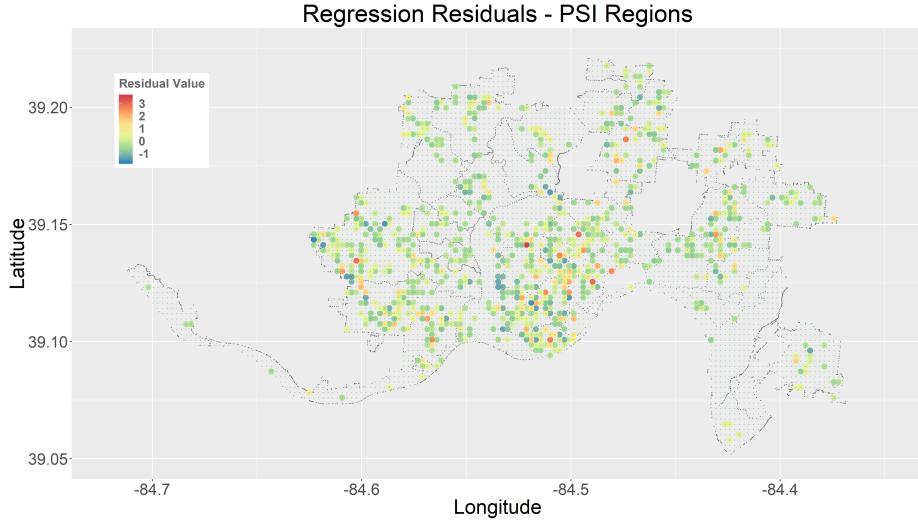


Fig. 8: A map of Cincinnati identifying areas with PSI in the darkest red.

Figure 8 shows the residuals mapped back to the map of Cincinnati.

#### 5.4 Non-Supervised Learning - Neighborhood Characterization

For each attribute, distribution and scatter plots are generated to visualize the impact of it in the cluster. Attributes like property type commercial was heavily clustered in 1 or the green areas as in Figure 11, while residential and industrial were lot more distributed. Issues like metal trash were more in industrial areas which was in the cluster 2 or red neighborhoods. Water leak was more an issue in cluster 0 or blue areas.

Combining attribute behavior and clusters on the map, pedestrian safety issues in each cluster are identified. These issues are then mapped to the actual locality or neighborhood to draw conclusions.

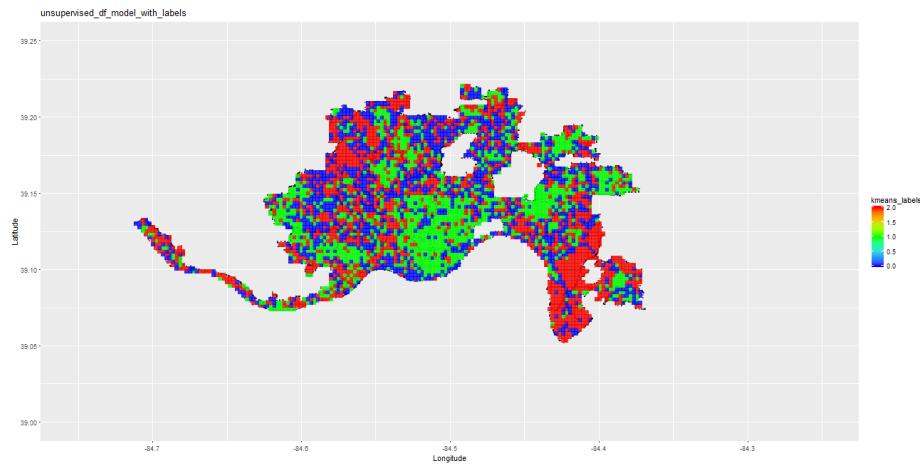


Fig. 9: Cluster results on map of Cincinnati

Initial results from part 1 of our methodology have produced graphs as shown in Figure 10.

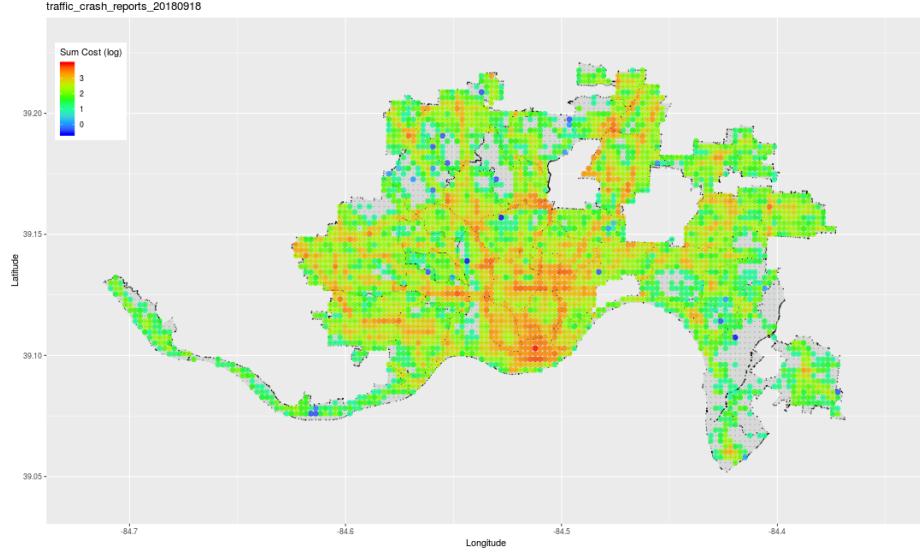


Fig. 10: Sum cost of traffic crashes reported from 2012 to October 2018 involving pedestrians by grid cells.

## 6 Analysis

### 6.1 Random Forest - Binary Model

The focus of this effort is to identify locations within the city that indicate highest potential for safety improvement. Consistent with the concept as defined and implemented in other works, the model incidents for which the observed experience exceeds the expected (model output) response are the regions with potential for safety improvement. In the context of a binary model, as was completed here with the random forest model, the regions of PSI are the false negative points on the grid map, as presented in Figure 6. For these grid cells, the model result was no expected pedestrian events, yet the observed experience exceeded this expected response. In this case, there are 31 grid cells identified with potential for safety improvement. In the next update to this draft, we will present what are the unique characteristics of these grid cells, where they are located geographically within the city (street and intersection identification) and what was the ac

### 6.2 Multi-Variate Regression - Cost Model

The results from the prior section provide a numerical and visual way to interpret the model. Because the regression model was subset based on the total cost of damage to the pedestrian excluding events resulting in \$5 million or more in damages, this results in the scope of the model being limited to non-fatality

incidents. The regression model is able to explain 20% of the variance in the cost of a non-fatality incident. This model consists of many significant variables, such as reports of crosswalks needed and reports of vehicles not obeying traffic signs, and some suggestively significant variables which make sense practically, but do not meet the p-value threshold of .05 such as speeding (p-value = .066), parking close to an intersection (p-value = .077), and parking on the sidewalk (p-value = .081). Most variables present within the model are reports to the non-emergency police telephone number, or the city's online safety survey. For each incident of report within the grid-cell, the predicted total cost of non-fatal incident changes by the estimated amount. Other non-report variables include the number of police properties present within the grid-cell, the maximum Walk Score value of properties within the grid-cell, and the total cost of damage to people involved in non-pedestrian related (motor vehicle) accidents.

Figure 7 illustrates the model's predictive capability as compared to the cost of incident in reality. Points which are colored in red have positive residuals, meaning the model has underestimated the cost. Green points have negative residuals, which mean the model has overestimated the cost. The further away a point is, the larger its absolute residual value is. These distances are displayed on Figure 8, where the red colored areas correspond to the distant red points. These areas within the city in which the model has underestimated the cost the most have the most potential for safety improvement, because all other factors being equal, there is something about that area which is causing a higher amount of damage to pedestrians.

### 6.3 Non-Supervised Learning - Neighborhood Characterization

For each attribute, distribution and scatter plots are generated to visualize the impact of it within the cluster. Attributes like property type: commercial were heavily clustered in 1, or the green areas as in Figure 11, while residential and industrial were lot more distributed. Issues like metal trash were more in industrial areas which was in the cluster 2 or red neighborhoods. Water leak was more an issue in cluster 0 or blue areas.

Combining attribute behavior and clusters on the map, pedestrian safety issues in each cluster are identified. These issues are then mapped to the actual locality or neighborhood to draw conclusions.

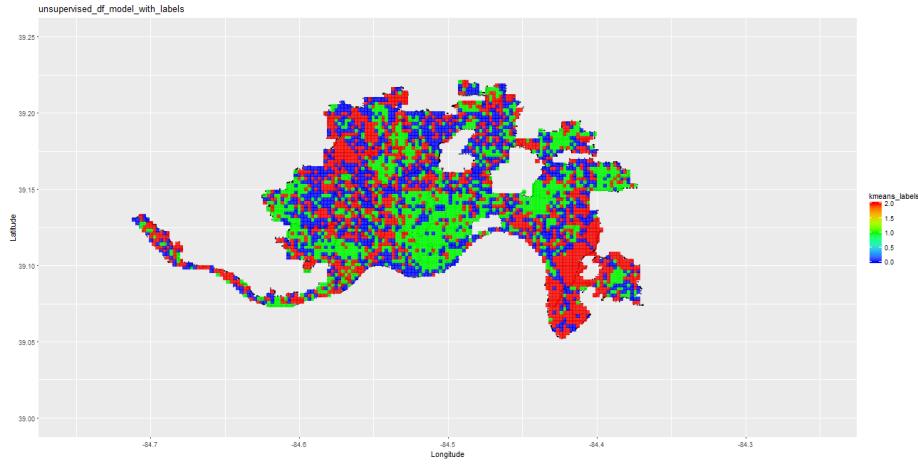


Fig. 11: Cluster results on map of Cincinnati

## 7 Ethics

As a means to evaluate compliance with ethical considerations, we use the model of the ACM Code of Ethics (the Code). Within the Code, there are four primary sections, e.g., General Ethical Principles, Professional Leadership Principles, etc., with each primary section providing additional subsections for self-assessment compliance to the Code. For each sub-section, we self-scored categorically as either Y, n/a, or D, where Y indicates that the work completed for this project rather obviously complies with the Code, n/a indicates that that section of the Code is less obviously significant for this project, and D indicates that that section of the Code identifies a potential ethical dilemma that is worthy of additional discussion to demonstrate compliance or at least point out the potential ethical challenge identified from this self-assessment. The most significant elements that we self-assess as D are: §1.2 - Avoid harm; §1.4 - Be fair and take action not to discriminate; and §3.7 - Recognize and take special care of systems that become integrated into the infrastructure of society.

From these three elements, we consider that the significant question to evaluate is: how may these research findings be interpreted and used?

The result of this project provides a recommended prioritization for the allocation of municipal resources for the purpose of improving a pedestrian safety problem. Allocation of public resources is often as much a political challenge as it is a scientific challenge. There is no global objective function that assigns absolute social value to any decision of resource allocation. That is, in fact, the work and challenge of public officials. Within the general framework of public decision making it is recognized that facts, reports, and recommendations which are or were essentially the result of objective research are frequently interpreted in a way that suits the interpreter for their own agenda – in some cases for personal gain – financially or politically. We have to admit for this case, then, that

this evaluation is potentially subject to a personally motivated interpretation. The debate about using scientific research to guide public policy is long and continuing. With that recognition, the task falls to us to identify what steps are taken to reduce the risk of unintended uses of this report.

First, the report as written has limited scope for direct application to policy. The recommendations included are applicable to the specific time period and data evaluation associated to the City of Cincinnati. The methods presented here can be widely applied (and in fact, that is the goal of this research), but in current form it would be difficult to justify using these results for direct resource allocation in any other municipality. The model developed here used very specific local experiences – accidents, reported near accidents, local conditions survey, property valuations, social media, and all other elements that contributed to this model are local and specific to the City of Cincinnati and to the current time period. As such, the specific recommendations are not generalizable. The method is generalizable; the specific results may provide indications of what local elements in other municipalities may prove indicative or at least useful for a similar exercise, but in any rational discourse, it would be difficult to extend the specific recommendations from this study to municipalities beyond the extent of this study.

Secondly, this report is submitted to representatives of the Cincinnati City Council and the Department of Safety . By distributing the results to more than one department and to a reasonably broad audience reduces risk of information being used for narrowly scoped or interests which are not generally aligned with good public discussion, debate, and utilization. Further, the data and methods deployed here were developed based on early and continuing input from representatives of these multiple departments within the City. Thus, early and often participation of multiple stakeholders provided the opportunity to have balanced input to the research, thus improving likelihood of balanced output and utilization. And, by respecting and incorporating the input from multiple perspectives from within the City provides higher likelihood of acceptance (and perhaps adoption) of the resulting recommendations.

Thirdly, within the City of Cincinnati, there are currently several on-going initiatives dedicated to improving pedestrian safety. The other initiatives are, in some cases, significantly funded, and are the work product of several departments within the City, predominantly the Department of Safety, that are the prime stakeholders in promoting public safety in the City. These other initiatives are an order of magnitude more significant, both from resource commitment, and for intended impact, than is this study. It is not our aim to minimize the potential impact of the recommendations from this study, but we are cognizant of the relative significance of this study within the larger context of the on-going programs within the City. In any decision making forum for the City, we consider the likelihood of these results having the capability to be used for unintended or inappropriate outcomes to be sufficiently unlikely.

The ethical considerations associated to this project are adequately assessed in the spirit of the ACM Code. The identified risks are appropriately mitigated.

## 8 Conclusions (and Future Work)

This study demonstrates a methodology to identify areas within the city of Cincinnati, Ohio with the largest potential for safety improvement, based on many open-source datasets made public by the city. Over twenty 250 meter by 250 meter plots of land within the city have been identified for further investigation to determine why the cost of incident within that area are abnormally high as compared to our models. These locations include several areas in the Westwood neighborhood, Clifton, Avondale, Walnut Hills, Bond Hill, and more. Our unsupervised learning techniques... Placeholder sentences about how our unsupervised learning techniques have outlined areas which have potential for safety improvement. These areas demonstrate these qualities which are related to pedestrian safety in the city of Cincinnati, Ohio.

For our unsupervised learning we look at the top pedestrian safety issues in each cluster. Vehicles running red lights or stop signs is a concern for the blue cluster neighborhoods, including: Westwood, Mt. Washington and East End. Heavy traffic is a prominent issue in the green cluster and affects Over-The-Rhine, Mt. Auburn and Central Business District neighborhoods. There is a need for increased number of sidewalks in Clifton, Madisonville, Walnut Hills and Mt. Washington. Over-the-Rhine, Downtown and Clifton need more bike friendly zones.

Future work to further this project could involve the use of other regression modelling techniques to improve accuracy, such as tobit models. Other improvements which could be made include Stuff goes here from Patrick and Preeti about ways to improve your techniques and models.

Aside from improving the models through the use of different techniques, the study itself can be improved by ingesting more data. This study is carried out using publicly available data, if private data exists which can improve the study, it can easily be adapted for use due to only requiring a street address or latitude longitude coordinates which would allow the data to be integrated into the grid-cell aggregation function. Examples of data which may be useful but are not publicly available would be the race, gender and age of the perpetrator and pedestrian victim, data which the city of Cincinnati may have, though the ethical implications of using this data must be weighed.

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