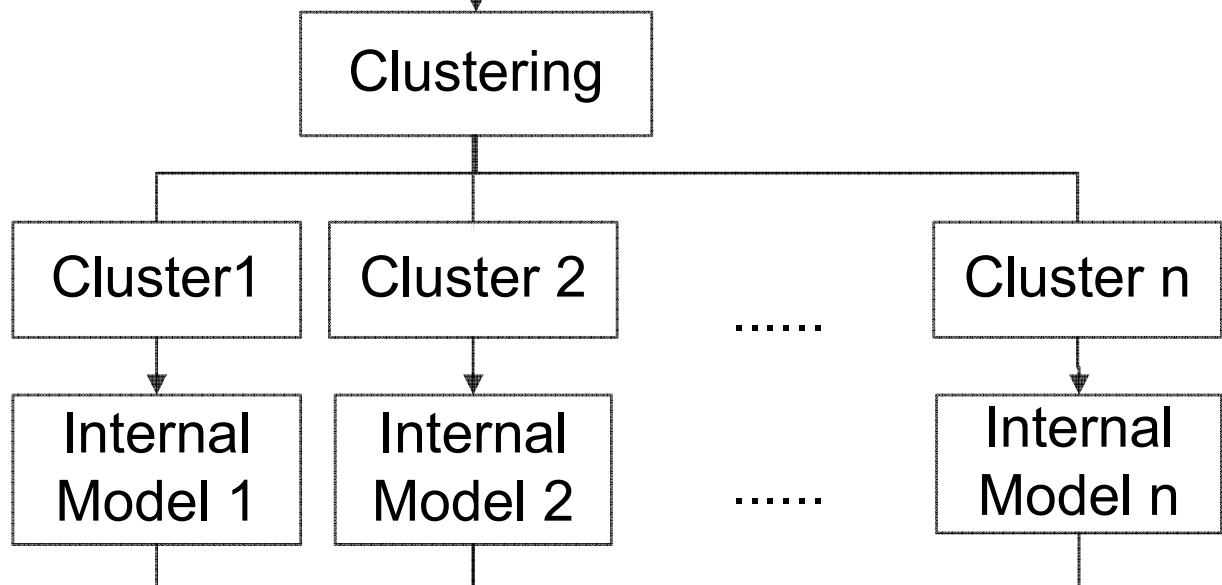


# 1. Human Demonstration



Object level exert Force /  
Object movement

# 2. Model Learning



# 3. Robot Control

Object level exert force  
(converted to robot joint torque)

