

#### MCTE 4342

## EMBEDDED SYSTEM DESIGN

Semester 2, 2023/2024

Section 1

## Week 2:

## **Comparative Analysis of**

# Microcontrollers, Microprocessors, and Embedded Systems

## in Mechatronics

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# **Contents**

INTRO	DUCTION	3
1.1	Definition of Microcontroller, Microprosessor and Embedded System	3
1.2 Mech	Importance of Microcontrollers, Microprocessors, and Embedded Systems atronics	
MICRO	OCONTROLLERS	6
1.3	Architecture and key features of microcontrollers.	6
1.4	Microcontroller Applications	7
1.5	Advantages of using microcontrollers in embedded systems	8
1.6	Limitations of using microcontrollers in embedded systems.	10
MICRO	PROSESSORS	12
1.7	Architecture and key features of Microprosessors.	12
1.8	Microprocessor Applications	14
1.9	Advantages of using microprocessors in embedded systems.	15
1.10	Limitations of using microprocessors in embedded systems.	16
COMPA	ARISON	18
1.11 funct	Effect of choosing between a microcontroller and a microprocessor to the dionality of an embedded system in mechatronics.	_
	STUDIES	
1.12	Case Study 1: Microcontroller (Autonomous Warehouse System)	
1.13	Case Study 2: Microprocessor (Medical Imaging System)	
CONCI	LUSION	
	ENCE	

#### INTRODUCTION

#### 1.1 Definition of Microcontroller, Microprosessor and Embedded System

Microcontrollers, microprocessors, and embedded systems are integral components of mechatronics, a multidisciplinary field that combines mechanical, electrical, and software engineering.

Microcontrollers are a type of embedded system designed for control of processes and product functions, capturing information about the product and its surroundings, processing the information, and making decisions based on the processed data. A typical microcontroller includes a processor, memory and input/output (I/O) peripherals on a single chip. Microcontroller also can be referred to as an embedded controller or microcontroller unit (MCU). It can be found in various applications such as vehicles, robots, office machines, medical devices and vending machine. Microcontroller are designed as simple personal computer (PCs) without a complex front-end operating system (OS).

Microprocessors, on the other hand, are the central processing units of computers, responsible for executing instructions and performing calculations. It is a controlling unit of a micro-computer, fabricated on a small chip capable of performing ALU (Arithmetic Logical Unit) operations and communicating with the other devices connected to it. Microprocessor is an important part of a computer architecture without it, there nothing be able to be perform on the computer. In simple words, a Microprocessor is a digital device on a chip that can fetch instructions from memory, decode then execute them while give results. It takes a bunch of instructions in machine language and executes them.

Embedded systems are a combination of computer hardware and software designed for a specific function. It is a computer system designed to perform specific tasks within larger systems. The system can be programmable or have a fix functionality. Possible location for and embedded system are airplanes, medical equipment, cameras, household appliances and vending machines. Embedded systems often rely on microcontroller and microprosessor to control and monitor hardware components and interact with the environment.

# 1.2 Importance of Microcontrollers, Microprocessors, and Embedded Systems in Mechatronics

Microcontrollers, microprocessors, and embedded systems are fundamental components in mechatronics, playing crucial roles in integrating mechanical, electrical, and computing elements to create efficient and functional systems. Microcontrollers are self-contained systems with processors, memory, and peripherals integrated onto a single chip, making them ideal for embedded applications. It is also cost-effective by reducing the number of chips and wiring required, microcontrollers decrease the overall cost of embedded systems while increasing efficiency. Microcontrollers are widely used in various applications like automobile control systems, medical devices, appliances, and more due to their compact size and low power consumption. They also have the ability to process data in real-time.

Microprocessors offer higher processing power compared to microcontrollers, making them suitable for complex computations and tasks in mechatronics. Unlike microcontrollers, microprocessors require external memory and peripherals, allowing for more flexibility in system design. Microprocessors excel in handling high computational demands and are commonly used in advanced mechatronic systems that require sophisticated processing capabilities.

Embedded systems are crucial in mechatronics for controlling various tasks within robotic systems, from simple motor movements to complex decision-making processes. They contribute significantly to the efficiency and performance of robots by providing precise control over actuators and sensors. Embedded systems process data in real-time, enabling adaptive and intelligent behavior in robots as they interact with their environment.

#### MICROCONTROLLERS

# 2.1 Architecture and key features of microcontrollers.

- Microcontrollers typically consist of a CPU core, volatile and non-volatile memory (RAM and ROM/Flash), input/output (I/O) ports, timers/counters, analog-to-digital converters (ADCs), communication interfaces (UART, SPI, I2C), and sometimes specialized peripherals like PWM (Pulse Width Modulation) controllers or CAN (Controller Area Network) interfaces.
- Use volatile memory types such as random access memory (<u>RAM</u>) and non-volatile memory types -- this includes <u>flash memory</u>, erasable programmable read-only memory (EPROM) and electrically erasable programmable read-only memory (EEPROM).
- Designed to be readily usable without additional computing components because they are designed with sufficient onboard memory as well as offering pins for general I/O operations.
- Language:
  - Assembly language (when first become available)
  - C
  - Python
  - JavaScript
- Input output pin functions:
  - Analog-digital converter
  - LCD controllers
  - Real time clock (RTC)
  - o universal synchronous/asynchronous receiver transmitter (USART)
  - o universal asynchronous receiver transmitter (UART)

- Timers
- O Universal serial bus (USB) connectivity.

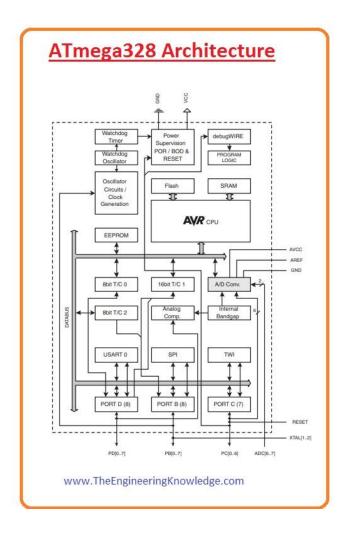


Figure 1: Atmega 328 microcontroller architecture that usually use with development board Arduino UNO R3

# 2.2 Microcontroller Applications

Microcontrollers are widely used in mechatronics for tasks such as motor control in robotics, sensor data acquisition and processing, embedded system control in automotive applications (e.g., engine management systems), home automation systems, industrial automation, and medical devices.

The example of microcontroller applications:

#### Industrial Automation

Microcontrollers are commonly used in industrial automation to control machinery, robotic arms, conveyor belts, and other manufacturing equipment.

They enable precise control over industrial processes, ensuring efficiency and safety in manufacturing environments.

#### • Automotive System

In automobiles, microcontrollers are utilized to control critical systems like the engine, transmission and brakes. Microcontrollers play a vital role in enhancing vehicle performance, fuel efficiency, and overall safety through intelligent control systems.

## Home Appliances

Many household appliances such as washing machines, refrigerators, and microwave ovens incorporate microcontrollers for controlling various functions. Microcontrollers optimize the operation of home appliances, offering advanced features and energy efficiency.

#### Robotics

In robotics, microcontrollers play a crucial role in controlling robot movements, sensors, actuators, and overall system behavior. They facilitate precise control over robotic functions for automation and intelligent decision-making.

## 2.3 Advantages of using microcontrollers in embedded systems.

## • Low Power Consumption

Microcontrollers operate at lower speeds and require less power, making them ideal for embedded applications where energy efficiency is crucial. This feature enhances the battery life of electronic devices and systems, contributing to their longevity and sustainability.

#### Cost-Effectiveness

Microcontrollers are cost-effective solutions for embedded systems due to their compact size and integrated functionalities. Their affordability makes them a preferred choice for manufacturers looking to optimize costs without compromising performance.

#### • Real-Time Processing

Microcontrollers are designed for real-time processing, ensuring rapid response times to external events within strict timing constraints. This feature is essential for applications like automotive control systems and medical devices that require immediate and precise actions.

#### Compact Size

Microcontrollers are small and compact, making them suitable for integration into small electronic devices and systems. Their size advantage allows for the development of portable and space-efficient embedded solutions.

#### Ease of Use

Microcontrollers are easy to use, troubleshoot, and maintain, simplifying system development and maintenance processes. They offer a user-friendly

interface for programming and customization, enhancing their usability in various applications.

## 2.4 Limitations of using microcontrollers in embedded systems.

## • Limited Processing Power

Microcontrollers generally have limited processing power compared to other computer chips, which can restrict their ability to handle complex tasks. This limitation may impact the performance of applications that require high computational capabilities.

#### • Limited Memory

Microcontrollers typically have limited memory capacity, which can constrain the size and complexity of programs that can be run on them. The memory limitation may restrict the functionality of applications that demand extensive data storage or processing.

## Limited Connectivity

Microcontrollers may lack the ability to connect to external networks or devices, limiting their communication capabilities. This limitation can hinder applications that require extensive connectivity for data exchange or remote control.

## • Limited Software Support

Microcontrollers may have limited software support compared to other computer chips, posing challenges in programming and development

processes. The scarcity of software resources may complicate the implementation of complex functionalities in embedded systems.

#### **MICROPROSESSORS**

# 3.1 Architecture and key features of Microprosessors.

Microprocessors are the central processing units of computers, responsible for
executing instructions and performing calculations. They are an essential
component of embedded systems, which are computer systems designed to
perform specific tasks within larger systems.

#### • Key Features:

#### • CPU

The CPU, or central processing unit, is the primary component of a microprocessor. It executes instructions, performs calculations, and manages data processing.

#### Memory

Microprocessors have memory, which can be programmed to store data and perform calculations. They typically have two types of memory: volatile memory (RAM) for data storage and non-volatile memory (ROM, EPROM, EEPROM, or Flash memory) for program and operating parameter storage.

## • Input/Output (I/O)

Microprocessors have discrete input and output bits, allowing control or detection of the logic state of an individual package pin. They also have serial input/output interfaces like UARTs, I<sup>2</sup>C, Serial Peripheral Interface, and Controller Area Network for system interconnect.

## • Peripherals

Microprocessors often include peripherals such as timers, event counters, PWM generators, and watchdogs. These peripherals help manage various aspects of the system, such as timing and event handling.

#### Clock Generator

Microprocessors have a clock generator, which is often an oscillator for a quartz timing crystal, resonator, or RC circuit. The clock generator helps regulate the timing and synchronization of the system.

# • Analog-to-Digital Converters (ADCs)

Some microprocessors include analog-to-digital converters, which allow them to process and interpret analog signals.

## • In-Circuit Programming and Debugging Support

Many microprocessors have built-in support for in-circuit programming and debugging, which simplifies the development and testing of embedded systems

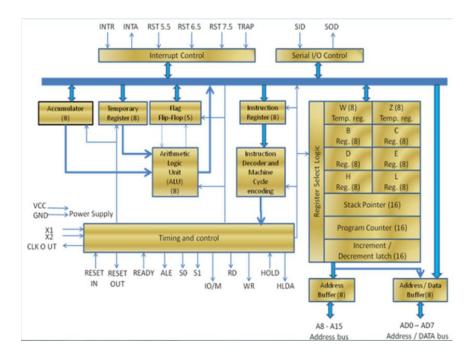


Figure 2: Architecture of Intel 8085 Microprosessors.

## 3.2 Microprocessor Applications

# Stepper Motors

Microprocessors are used to control stepper motors, which convert a train of input pulses into a precisely defined increment in the shaft position. They are used in positioning systems and can be controlled using microcontrollers.

#### Education

Microprocessors are used in mechatronics education to teach students about the integration of electrical, electronic, and computer engineering. They are used in designing control algorithms, signal conditioning, and power electronics, as well as in developing modularized systems for experimental learning and fast prototype design.

#### Health Care

Microprocessors are used in medical devices such as pacemakers, insulin pumps, and blood glucose meters to monitor and control the health of patients. They are also used in robotic surgery, which has been around since 2000 and provides benefits such as being less invasive, leading to faster recovery, and reducing the risk of infection.

#### Manufacturing

Microprocessors are used in industrial control systems such as SCADA (Supervisory Control and Data Acquisition) systems, programmable logic controllers (PLCs), and robotics to control and monitor various processes. They enable manufacturers to keep up with demand while reducing costs.

#### 3.3 Advantages of using microprocessors in embedded systems.

#### • High Speed

Microprocessors can perform tasks at a very high speed, allowing for efficient processing of data and real-time control of systems.

#### • Low Power Consumption

Microprocessors are designed to operate efficiently with minimal power, making them ideal for battery-powered devices and systems with limited power resources.

#### Cost-Effective

Microprocessors are available at a low cost due to integrated circuit technology, which allows for mass production and economies of scale.

## Versatility

Microprocessors can be used in a wide range of applications, from controlling household appliances to driving industrial automation and enhancing medical devices.

## • Compact Size

Microprocessors are fabricated using metal oxide semiconductor technology, which results in a small footprint, reducing the size of the system.

## • Real-Time Processing

Microprocessors are well-suited for real-time processing, which is essential in many embedded systems applications.

# 3.4 Limitations of using microprocessors in embedded systems.

## • Size and Complexity

Microprocessors are generally larger in size and more complex than microcontrollers, requiring external support chips for memory and peripherals.

This can lead to increased system complexity and higher costs

## • Power Consumption

Microprocessors consume more power due to their higher processing capabilities and external components. This can be a disadvantage in battery-powered applications where power consumption is a critical factor

#### Cost

Microprocessors are generally more expensive than microcontrollers due to their higher processing capabilities and specialized design for specific applications

## Heating Issues

Microprocessors can generate more heat due to their higher processing capabilities, which can be a disadvantage in certain applications

 Performance: While microprocessors offer superior performance and flexibility, they may not be as well-suited for real-time applications as microcontrollers, which are designed for specific tasks and can operate independently

# • Integration

Microprocessors require external memory and peripherals, which can make integration more complex and potentially less reliable than microcontrollers with integrated features

# **COMPARISON**

	Microcontrollers	Microprcessors
Purpose	Process and control the	Process the general task only
	specific task	
Complexity	Less complex, less number	More complex, Large
	of instructions	number of instructions
I/O	Programmable digital and	Need external peripherals
	analog I/O pins	with I/O pins
Memory	Internal – limited size	External – Flexible,
		Expandable
Power Consumption	Lower	Higher
Cost	Cheaper	Expensive
Efficiency	More	Less
Price	Cheaper	Expensive
Applications	Embedded devices, control	Advanced data processing,
	systems, smartphones,	video, computer vision,
	consumer electronics.	personal computers, fast
		communications, multi-core
		computation

- 4.1 Effect of choosing between a microcontroller and a microprocessor to the design and functionality of an embedded system in mechatronics.
- Integration and Complexity

Microcontrollers are self-contained systems on a single chip, integrating a CPU, memory, I/O ports, and other peripherals. This integration simplifies hardware design, reduces complexity, and lowers costs compared to microprocessors that require external support chips for memory and I/O capabilities.

# • Functionality

Microcontrollers are designed specifically for control applications, making them ideal for embedded systems where the controller is physically located in the equipment being controlled. They are optimized for low-power operation and real-time tasks, enhancing their suitability for mechatronic applications. Microprocessors offer more versatility and computational power, making them suitable for applications requiring high processing capabilities, complex computations, or running full-fledged operating systems. However, this comes at the cost of higher power consumption and complexity in system design.

#### Cost and Power Consumption

Microcontrollers are generally more cost-effective than microprocessors due to their integrated design and simplified hardware requirements. They are also optimized for low-power operation, making them ideal for battery-powered devices in mechatronics. Microprocessors may be more expensive due to their higher processing capabilities and external component requirements. They consume more power compared to microcontrollers, which can be a disadvantage in power-constrained embedded systems.

#### **CASE STUDIES**

## 5.1 Case Study 1: Microcontroller (Autonomous Warehouse System)

The autonomous warehouse system is designed to optimize inventory management and streamline order fulfillment processes. It consists of automated guided vehicles (AGVs) equipped with sensors, conveyor belts, and robotic arms for material handling. The system employs a microcontroller-based control system to coordinate the movement of AGVs, manage inventory, and ensure efficient routing within the warehouse. Rationale Behind Microcontroller Selection:

#### • Real-Time Control

The primary requirement for the autonomous warehouse system is real-time control to ensure safe and efficient operation. Microcontrollers offer deterministic control over AGV movements, conveyor belt speed, and robotic arm actions, allowing the system to respond quickly to dynamic changes in warehouse conditions and incoming orders.

#### • Low Power Consumption

AGVs are powered by batteries, making power efficiency a critical consideration.

Microcontrollers are designed for low power consumption, prolonging the battery life of AGVs and reducing the frequency of recharging or battery replacement, thereby maximizing uptime and operational efficiency.

#### • Integrated Peripherals

Microcontrollers integrate various peripherals such as motor drivers, encoder interfaces, and communication modules on a single chip. These built-in features simplify hardware design, reduce component count, and lower production costs, making microcontrollers an economical choice for large-scale deployment in warehouse automation systems.

#### • Deterministic Behavior

Microcontrollers offer deterministic behavior, ensuring precise timing and synchronization of AGV movements and interactions with other warehouse equipment. This reliability is essential for preventing collisions, optimizing traffic flow, and maintaining high throughput in busy warehouse environments, thereby enhancing safety and productivity.

#### Cost-Effectiveness

Microcontrollers are cost-effective solutions suitable for mass-produced warehouse automation systems. Their affordability enables manufacturers to offer competitive pricing while maintaining profitability, making them an ideal choice for commercial applications in logistics and supply chain management.

## 5.2 Case Study 2: Microprocessor (Medical Imaging System)

The medical imaging system is designed for non-invasive diagnosis and visualization of internal organs and tissues. It comprises imaging modalities such as computed tomography (CT), magnetic resonance imaging (MRI), and ultrasound, each equipped with sophisticated sensors and signal processing capabilities. The system utilizes a microprocessor-based control unit to acquire, process, and reconstruct medical images with high resolution and accuracy. Rationale Behind Microprocessor Selection:

#### Processing Power

Medical imaging requires intensive computational tasks, including signal processing, image reconstruction, and analysis. Microprocessors offer high processing power and

parallel processing capabilities, enabling the system to handle large datasets and complex algorithms efficiently, resulting in faster image acquisition and diagnosis.

#### • Memory Requirements

Microprocessors provide extensive memory options, essential for storing raw sensor data, intermediate processing results, and image reconstructions. This enables the system to maintain a comprehensive database of patient scans, facilitate comparison and trend analysis, and support advanced visualization techniques such as 3D rendering and virtual reality.

# Flexibility and Software Support

Microprocessors support multitasking operating systems (OS) and high-level programming languages, facilitating software development and integration of advanced functionalities. The use of an OS enables concurrent execution of multiple tasks, such as image acquisition, reconstruction, and analysis, leading to improved workflow efficiency and user experience.

#### • Communication Interfaces

Medical imaging systems often require seamless integration with hospital information systems (HIS), picture archiving and communication systems (PACS), and electronic medical records (EMR). Microprocessors offer a wide range of communication interfaces, including Ethernet, DICOM, and HL7 protocols, enabling seamless data exchange and interoperability with other healthcare IT systems.

#### • Scalability and Future Expansion

As medical imaging technology advances, the demand for higher resolution, faster processing, and new imaging modalities will increase. Microprocessors provide scalability in terms of processing power, memory, and software capabilities, allowing the system to adapt and evolve over time to incorporate new imaging techniques and address emerging clinical needs.

#### **CONCLUSION**

In conclusion, Microcontrollers and microprocessors play crucial roles in the development of efficient and effective embedded systems in mechatronics. Microcontrollers are like tiny brains that control simple tasks quickly and cheaply, while microprocessors are like bigger brains that can handle more complex jobs but use more power.

Microcontrollers are good for things that need to happen in real-time, like controlling robots or sensors. They're also great for gadgets that need to be small and run on batteries, like smartwatches or remote controls. Microprocessors are better for tasks that need lots of thinking power, like analyzing data or running complicated software. They're often used in things like computers or medical devices where speed and accuracy are really important.

Even though they do different jobs, both microcontrollers and microprocessors play a big role in making things work smoothly in mechatronics. They help machines understand what's happening around them, make decisions, and respond quickly to changes. Without them, many of the smart gadgets and machines we rely on today wouldn't be possible.

Understanding the differences and similarities between microcontrollers and microprocessors is essential for designing and implementing successful mechatronic systems.

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