Time Series

Sudipta Das

Assistant Professor,

Department of Computer Science,
Ramakrishna Mission Vivekananda Educational & Research Institute

Outline I

- Stationary Process
 - Strict Stationary Process
 - (Weak) Stationary Process
 - Linear Process
 - Revisiting ARMA Process



Stationary Process I

- Going beyond i.i.d stochastic process (time series)
- Stationary Process
 - Strict Stationary Process
 - Weak Stationary Process

Strict Stationary Process I

• $\{X_t\}$ is a strictly stationary process if

$$(X_{i_1}, X_{i_2}, \dots, X_{i_n})' \stackrel{D}{=} (X_{i_1+h}, X_{i_2+h}, \dots, X_{i_n+h})'$$

for all integers h and $n \ge 1$.

i.e.

$$f_{X_{i_1},X_{i_2},...,X_{i_n}}(x_1,...,x_n) = f_{X_{i_1+h},X_{i_2+h},...,X_{i_n+h}}(x_1,x_2,...,x_n)$$

for all integers h and $n \ge 1$.

Strict Stationary Process II

- Properties of a Strictly Stationary Process {X_t} :
 - The random variables X_t are identically distributed
 - Not necessarily independent
 - An i.i.d sequence is also strictly stationary
 - $(X_t, X_{t+h})' \stackrel{D}{=} (X_1, X_{1+h})'$ for all integers t and h.

(Weak) Stationary Process I

- $\{X_t\}$ is a (weakly) stationary process if all of the following three conditions hold
 - - Finite second order moment
 - - where $\mu_X(t)$ is the **mean function** of $\{X_t\}$ and is defined as

$$\mu_X(t) = E(X_t)$$

- - where $\gamma(t+h,t)$ is the **covariance function** of $\{X_t\}$ and is defined as

$$\gamma(t+h,t) = \operatorname{Cov}(X_{t+h}, X_t) = E[(X_{t+h} - \mu_X(t+h))(X_t - \mu_X(t))]$$

(Weak) Stationary Process II

Remarks:

- If $\{X_t\}$ is strictly stationary and $E[X_t^2] < \infty$ for all t, then $\{X_t\}$ is also weakly stationary
- In this course, whenever we use the term stationary we shall mean weakly stationary, unless we specifically indicate otherwise.
- We use the term covariance function with reference to a stationary time series $\{X_t\}$ we shall mean the function γ_X of one variable defined by

$$\gamma_X(h) := \gamma_X(h,0) = \gamma_X(t+h,t)$$

• The function $\gamma_X(\cdot)$ will be referred to as the **autocovariance** function (ACVF) of X_t and $\gamma_X(h)$ as its value at $lag\ h$.

(Weak) Stationary Process III

• Formally, the **autocovariance function** (ACVF) of $\{X_t\}$ at lag h is defined as

$$\gamma_X(h) = E\left[(X_{t+h} - \mu_X)(X_t - \mu_X) \right]$$

Note that

$$\gamma_X(0) \geq 0$$

and

$$\gamma_X(h) = \gamma_X(-h)$$

(Weak) Stationary Process IV

• The autocorrelation function (ACF) of $\{X_t\}$ at lag h is defined as

$$\rho_X(h) = \frac{\gamma_X(h)}{\gamma_X(0)}$$

- Basic Properties of $\rho(\cdot)$:
 - $|\rho(h)| \leq 1$
 - $\rho(\cdot)$ is even, i.e., $\rho(h) = \rho(-h)$ for all h.

(Weak) Stationary Process: Examples I

- Some Elementary Stationary processes
 - 1 iid noise: $\{X_t\} \sim IID(0, \sigma^2)$, with $E(X_t^2) = \sigma^2 < \infty$
 - ACVF:

$$\gamma_X(t+h,t) = \gamma_X(h) = \begin{cases} \sigma^2, & \text{if } h = 0, \\ 0 & \text{if } h \neq 0. \end{cases}$$

ACF

$$\rho_X(t+h,t) = \rho_X(h) = \begin{cases} 1, & \text{if } h = 0, \\ 0, & \text{if } h \neq 0. \end{cases}$$

(Weak) Stationary Process: Examples II

- 2 White Noise: $\{X_t\} \sim WN(0, \sigma^2)$
 - It's a sequence of uncorrelated random variables, each with zero mean and variance σ^2 .
 - ACVF:

$$\gamma_X(h) = \begin{cases} \sigma^2, & \text{if } h = 0, \\ 0 & \text{if } h \neq 0. \end{cases}$$

ACF

$$\rho_X(h) = \left\{ \begin{array}{ll} 1, & \text{if } h = 0, \\ 0, & \text{if } h \neq 0. \end{array} \right.$$

(Weak) Stationary Process: Examples III

Note that every $IID(0, \sigma^2)$, sequence is $WN(0, \sigma^2)$ but the converse is not true, e.g.

Let $\{Z_t\}$ be iid $\sim N(0,1)$ noise and define

$$X_t = \left\{ egin{array}{ll} Z_t, & ext{if } t ext{ is even}, \ (Z_{t-1}^2 - 1)/\sqrt{2} & ext{if } t ext{ is odd}. \end{array}
ight.$$

Here, that $\{X_t\}$ is WN(0,1) but not iid(0,1).

(Weak) Stationary Process: Examples IV

First-order moving average or MA(1) process:

$$X_t = Z_t + \theta Z_{t-1}, t = 0, \pm 1, \ldots,$$

where $\{Z_t\} \sim WN(0, \sigma^2)$ and θ is real valued constant

- $EX_t = 0$
- ACVF

$$\gamma_X(h) = \begin{cases} \sigma^2(1+\theta^2), & \text{if } h = 0, \\ \sigma^2\theta, & \text{if } h = \pm 1 \\ 0, & \text{if } |h| \ge 2. \end{cases}$$

ACF

$$\rho_X(h) = \begin{cases} 1, & \text{if } h = 0, \\ \theta/(1 + \theta^2), & \text{if } h = \pm 1, \\ 0, & \text{if } |h| \ge 2. \end{cases}$$

(Weak) Stationary Process: Examples V

First-order autoregressive or AR(1) process:

$$X_t = \phi X_{t-1} + Z_t, t = 0, \pm 1, \ldots,$$

where $\{Z_t\} \sim WN(0, \sigma^2), |\phi| < 1$ and Z_t is uncorrelated with X_s for each s < t

- $EX_t = 0$
- ACVF

$$\gamma(h) = \phi^{|h|} \frac{\sigma^2}{1 - \phi^2}$$

ACF

$$\rho(h) = \phi^{|h|}$$

(Weak) Stationary Process: Examples VI

First-order ARMA or ARMA(1,1) process:

$$X_t = \phi X_{t-1} + Z_t + \theta Z_{t-1}, t = 0, \pm 1, \dots,$$

where $\{Z_t\} \sim WN(0, \sigma^2), |\phi| < 1, Z_t$ is uncorrelated with X_s for each s < t and $\phi + \theta \neq 0$

- EX_t = 0 ACVF

$$\gamma_X(h) = \begin{cases} \sigma^2 \left[1 + \frac{(\theta + \phi)^2}{1 - \phi^2} \right], & \text{if } h = 0, \\ \sigma^2 \left[\theta + \phi + \frac{(\theta + \phi)^2 \phi}{1 - \phi^2} \right], & \text{if } h = \pm 1 \\ \phi^{|h| - 1} \gamma_X(1), & \text{if } |h| \ge 2. \end{cases}$$

(Weak) Stationary Process: Examples VII

Is Random Walk a stationary process?

$$X_t = X_{t-1} + Z_t,$$

where $Z_t \sim \textit{IID}(\mu, \sigma^2)$

(Weak) Stationary Process: Examples VIII

- NO
 - $\mu_X(t) = \mu t$
 - $Cov(X_m, X_n) = min(m, n) \times \sigma^2$



(Weak) Stationary Process: Examples IX

- Three higher order stationary processes
 - \bigcirc *q*-order moving average or MA(*q*) process:

$$X_t = Z_t + \theta_1 Z_{t-1} + \ldots + \theta_q Z_{t-q}, t = 0, \pm 1, \ldots,$$

where $\{Z_t\} \sim WN(0, \sigma^2)$ and $\theta_1, \dots, \theta_q$ are real valued constants

2 p-order autoregressive or AR(p) process:

$$X_t = \phi_1 X_{t-1} + \ldots + \phi_p X_{t-p} + Z_t, t = 0, \pm 1, \ldots,$$

where $\{Z_t\} \sim WN(0, \sigma^2)$, Z_t is uncorrelated with X_s for each s < t and all roots of the polynomial $(1 - \phi_1 z - \phi_2 z^2 - \cdots - \phi_p z^p)$ lie outside the unit circle.

(Weak) Stationary Process: Examples X

 \bigcirc ARMA(p, q) process:

$$X_{t} = \phi_{1}X_{t-1} + \ldots + \phi_{p}X_{t-p} + Z_{t} + \theta_{1}Z_{t-1} + \ldots + \theta_{q}Z_{t-q}, t = 0, \pm 1, \ldots,$$

where $\{Z_t\} \sim WN(0, \sigma^2)$, with all roots of the polynomial $(1 - \phi_1 z - \phi_2 z^2 - \cdots - \phi_p z^p)$ lie outside the unit circle and the polynomials $(1 - \phi_1 z - \phi_2 z^2 - \cdots - \phi_p z^p)$ and $(1 + \theta_1 z + \ldots + \theta_q z^q)$ have no common factors.

Linear Process I

- Linear processes: It includes the class of autoregressive moving-average (ARMA) process,
- Definition: The process $\{X_t\}$ is a linear process if it has the representation

$$X_t = \sum_{j=-\infty}^{\infty} \psi_j Z_{t-j},$$

for all t, where $\{Z_t\} \sim WN(0,\sigma^2)$ and $\{\psi_j\}$ is a sequence of constants with $\sum_{j=-\infty}^{\infty} |\psi_j| < \infty$

Linear Process II

Alternate representation by backward shift operator:

$$X_t = \Psi(B)Z_t$$

where
$$\Psi(B) = \sum_{j=-\infty}^{\infty} \psi_j B^j$$

- The operator $\Psi(B)$ can be thought of as a linear filter, which when applied to the white noise "input" series $\{Z_t\}$ produces the "output" $\{X_t\}$
- Note: every second-order stationary process is either a linear process or can be transformed to a linear process by subtracting a deterministic component.

Linear Process III

Remarks

• The condition $\sum_{j=-\infty}^{\infty} |\psi_j| < \infty$ (absolute summability) ensures that

the infinite sum

$$X_t = \sum_{j=-\infty}^{\infty} \psi_j Z_{t-j},$$

converges (with probability one)

Linear Process IV

Sketch of proof:-

Let
$$X_t^n = \sum_{j=-n}^n \psi_j Z_{t-j}$$
, and for small $\epsilon > 1$, define

$$A_n(\epsilon) = \left\{ |X_t^n - X_t| > \epsilon \right\} = \left\{ \left| \sum_{|j| > n} \psi_j Z_{t-j} \right| > \epsilon \right\}.$$

By Chebyshev's inequality,

$$P(A_n) \le E\left[\left|\sum_{|j|>n} \psi_j Z_{t-j}\right|^2\right]/\epsilon^2.$$

Linear Process V

Thus,

$$\begin{split} \sum_{n=1}^{\infty} P(A_n) & \leq & \frac{1}{\epsilon^2} \sum_{n=1}^{\infty} E \left| \sum_{|j| > n} \psi_j Z_{t-j} \right|^2 \\ & < & \sum_{n=1}^{\infty} E \left| \sum_{|j| > n} \psi_j Z_{t-j} \right|^2 \\ & = & \sum_{n=1}^{\infty} E \left| \sum_{|i| > n} \sum_{|k| > n} \psi_i \psi_k \left(Z_{t-i} Z_{t-k} \right) \right|; \text{ as } |ab| = |a||b| \\ & \leq & \sum_{n=1}^{\infty} \left[\sum_{|i| > n} \sum_{|k| > n} |\psi_i| |\psi_k| E \left| \left(Z_{t-i} Z_{t-k} \right) \right| \right]; \text{ by triangular inequality} \\ & \leq & \sum_{n=1}^{\infty} \left[\sum_{|i| > n} \sum_{|k| > n} |\psi_i| |\psi_k| E \left| \left(Z_{t-i}^2 \right)^{1/2} \right| E \left| \left(Z_{t-k}^2 \right)^{1/2} \right| \right]; \text{ by Cauchy-Schwarz inequality} \\ & \leq & \sigma^2 \sum_{n=1}^{\infty} \left[\sum_{|i| > n} \sum_{|k| > n} |\psi_i| |\psi_k| \right]; \text{ Stationarity} \\ & = & \sigma^2 \sum_{n=1}^{\infty} \left[\sum_{|i| > n} \sum_{|k| > n} |\psi_i| |\psi_k| \right] < \infty; \text{ absolute summability} \end{split}$$

Linear Process VI

Therefore, by Borel Cantelli Lemma

$$\sum_{n=1}^{\infty} P(A_n) < \infty \Rightarrow P\left(A^{(S)}\right) = 0, \text{ where } A^{(S)} = \cap_{n=1}^{\infty} \cup_{m=n}^{\infty} A_m = \limsup_{n} A_n$$

- Event $A^{(S)}$ is called the lim sup event of the infinite sequence $\{A_n\}$.
- Event $A^{(S)}$ occurs if and only if for all $n \ge 1$, there exists an $m \ge n$ such that A_m occurs,
- lacktriangle equivalently, Event $A^{(S)}$ occurs if and only if infinitely many of the A_n occur.

By definition of limit, $\omega \in \left\{ \lim_n X_n = X \right\}$ if and only if for all $u \geq 1$ there exists $n \geq 1$ such that for every $m \geq n, |X_m(\omega) - X(\omega)| \leq \frac{1}{u}$. Equivalently, it holds if and only if

$$\omega \in \cap_{u=1}^{\infty} \cup_{n=1}^{\infty} \cap_{m=n}^{\infty} \left[A_m \left(\frac{1}{u} \right) \right]^c = \left(\cup_{u=1}^{\infty} \limsup_{n} A_n \left(\frac{1}{u} \right) \right)^c.$$

Thus,

$$P\left(\omega : \lim_{n} X_{t}^{n}(\omega) = X_{t}(\omega)\right) = P\left(\left(\bigcup_{u=1}^{\infty} \limsup_{n} A_{n}(1/u)\right)^{c}\right) = 1 - P\left(\bigcup_{u=1}^{\infty} \limsup_{n} A_{n}(1/u)\right)$$

$$\geq 1 - \sum_{u=1}^{\infty} P\left(\limsup_{n} A_{n}(1/u)\right) = 1$$

Hence, $X_t^n \stackrel{a.s.}{\to} X_t$.



Linear Process VII

 $\text{ The condition } \sum_{j=-\infty}^{\infty} |\psi_j| < \infty \text{ ensures that } \sum_{j=-\infty}^{\infty} \psi_j^2 < \infty \text{ therefore,}$ the series $\sum_{j=-\infty}^{\infty} |\psi_j| < \infty$ therefore, the series $\sum_{j=-\infty}^{\infty} |\psi_j| < \infty$ therefore,

$$X_t^n = \sum_{t=0}^n \psi_j Z_{t-j} \stackrel{m.s.}{\to} X_t$$

Linear Process VIII

③ In generally, let $\{Y_t\}$ be a stationary process with mean 0 and covariance function γ_Y . If $\sum_{i=-\infty}^{\infty} |\psi_i| < \infty$, then the process

$$X_t = \Psi(B)Y_t = \sum_{j=-\infty}^{\infty} \psi_j Y_{t-j},$$

is also stationary with mean 0 and autocovariance function as

$$\gamma_{X}(h) = \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \psi_{j} \psi_{k} E[Y_{t-j} Y_{t+h-k}]$$

$$= \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \psi_{j} \psi_{k} \gamma_{Y}(h-k+j)$$

$$= \sum_{j=-\infty}^{\infty} \psi_{j} \psi_{j+h} \sigma^{2}, \text{ (if } X_{t} \text{ is linear)}$$

Linear Process IX

1 The filters of the form $\alpha(B) = \sum_{j=-\infty}^{\infty} \alpha_j B^j$ and $\beta(B) = \sum_{j=-\infty}^{\infty} \beta_j B^j$ with

absolutely summable coefficients can be applied successively to a stationary series $\{Y_t\}$ to generate a new stationary series

$$W_{t} = \sum_{j=-\infty}^{\infty} \alpha_{j} \left(\sum_{k=-\infty}^{\infty} \beta_{k} Y_{(t-j)-k} \right) = \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \alpha_{j} \beta_{k} Y_{(t-j)-k}$$

$$= \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \alpha_{j-k} \beta_{k} Y_{t-j}, \text{replacing } j \text{ by } j-k$$

$$= \sum_{j=-\infty}^{\infty} \psi_{j} Y_{t-j}$$

- Therefore, $\psi_j = \sum_{k=-\infty}^{\infty} \alpha_{j-k} \beta_k = \sum_{k=-\infty}^{\infty} \alpha_k \beta_{j-k}$
- Alternate form $W_t = \alpha(B)\beta(B)Y_t = \beta(B)\alpha(B)Y_t = \psi(B)Y_t$

Linear Process X

- Forms of (stable) linear process:
 - Causal: A linear process $\{X_t\}$ is causal if X_t can be expressed in terms of the current and past values Z_s , $s \le t$,

$$X_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j}.$$

• Invertible: A linear process $\{X_t\}$ is invertible if Z_t can be expressed in terms of the current and past values X_s , $s \le t$,

$$Z_t = \sum_{j=0}^{\infty} \pi_j X_{t-j}.$$

Revisiting ARMA Proces I

• Let X_t be an ARMA(p,q) process

$$X_t - \phi_1 X_{t-1} - \dots - \phi_p X_{t-p} = Z_t + \theta_1 Z_{t-1} + \dots + \theta_q Z_{t-q}$$

where $\{Z_t\} \sim WN(0, \sigma^2)$, and the polynomials $(1 - \phi_1 z - \phi_2 z^2 - \dots - \phi_p z^p)$ and $(1 + \theta_1 z + \dots + \theta_q z^q)$ have no common factors.

• Representing X_t as linear process

$$X_t = (1 - \phi_1 B - \dots - \phi_p B^p)^{-1} (1 + \theta_1 B + \dots + \theta_q B^q) Z_t$$

Revisiting ARMA Proces II

- Condition for stability of X_t :
 - The coefficients of linear process expression of X_t (= $\sum_{j=-\infty}^{\infty} \psi_j Z_{t-j}$) are absolutely summable.
- Equivalent Condition:

$$\phi(z) = 1 - \phi_1 z - \cdots - \phi_p z^p \neq 0$$
 for all $|z| = 1$

• No roots of $\phi(z)$ on the unit circle

Revisiting ARMA Proces III

Example: AR(1)

$$X_t - \phi X_{t-1} = Z_t$$

- ullet if $|\phi|<1$, $X_t=\sum_{j=0}^{\infty}\phi^jZ_{t-j}$ is stable
- if $|\phi|>1$, $X_t=\sum_{j=1}^{\infty}\phi^{-j}Z_{t+j}$ is stable



Revisiting ARMA Proces IV

• Condition for causality of X_t : Process X_t can be expressed in terms of the current and past values $Z_s, s \leq t$, (i.e., $X_t = \sum_{i=1}^{\infty} \psi_i Z_{t-j}$)

Equivalent Condition

$$\phi(z) = 1 - \phi_1 z - \dots - \phi_p z^p \neq 0$$
 for all $|z| < 1$

• No roots of $\phi(z)$ inside the unit circle

Revisiting ARMA Proces V

Example: AR(1)

$$X_t - \phi X_{t-1} = Z_t$$

- ullet if $|\phi| <$ 1, $X_t = \sum_{j=0}^{\infty} \phi^j Z_{t-j}$ is stable and causal
- if $|\phi|>1$, $X_t=\sum_{j=1}^{\infty}\phi^{-j}Z_{t+j}$ is stable but non-causal

Revisiting ARMA Proces VI

• Condition for invertibility of X_t : Process Z_t can be expressed in terms of the current and past values $X_s, s \le t$, (i.e., $Z_t = \sum_{j=0}^{\infty} \pi_j X_{t-j}$)

Equivalent Condition

$$\theta(z) = 1 + \theta_1 z + \dots + \theta_q z^q \neq 0 \text{ for all } |z| < 1$$

• No roots $\theta(z)$ inside the unit circle