



10-601 Introduction to Machine Learning

Machine Learning Department
School of Computer Science
Carnegie Mellon University

Hidden Markov Models

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Lecture 22
April 2, 2018

Reminders

- **Homework 6: PAC Learning / Generative Models**
 - Out: Wed, Mar 28
 - Due: Wed, Apr 04 at 11:59pm
- **Homework 7: HMMs**
 - Out: Wed, Apr 04
 - Due: Mon, Apr 16 at 11:59pm

DISCRIMINATIVE AND GENERATIVE CLASSIFIERS

Generative vs. Discriminative

- **Generative Classifiers:**
 - Example: Naïve Bayes
 - Define a joint model of the observations \mathbf{x} and the labels y : $p(\mathbf{x}, y)$
 - Learning maximizes (joint) likelihood
 - Use Bayes' Rule to classify based on the posterior:
$$p(y|\mathbf{x}) = p(\mathbf{x}|y)p(y)/p(\mathbf{x})$$
- **Discriminative Classifiers:**
 - Example: Logistic Regression
 - Directly model the conditional: $p(y|\mathbf{x})$
 - Learning maximizes conditional likelihood

Generative vs. Discriminative

Whiteboard

- Contrast: To model $p(x)$ or not to model $p(x)$?

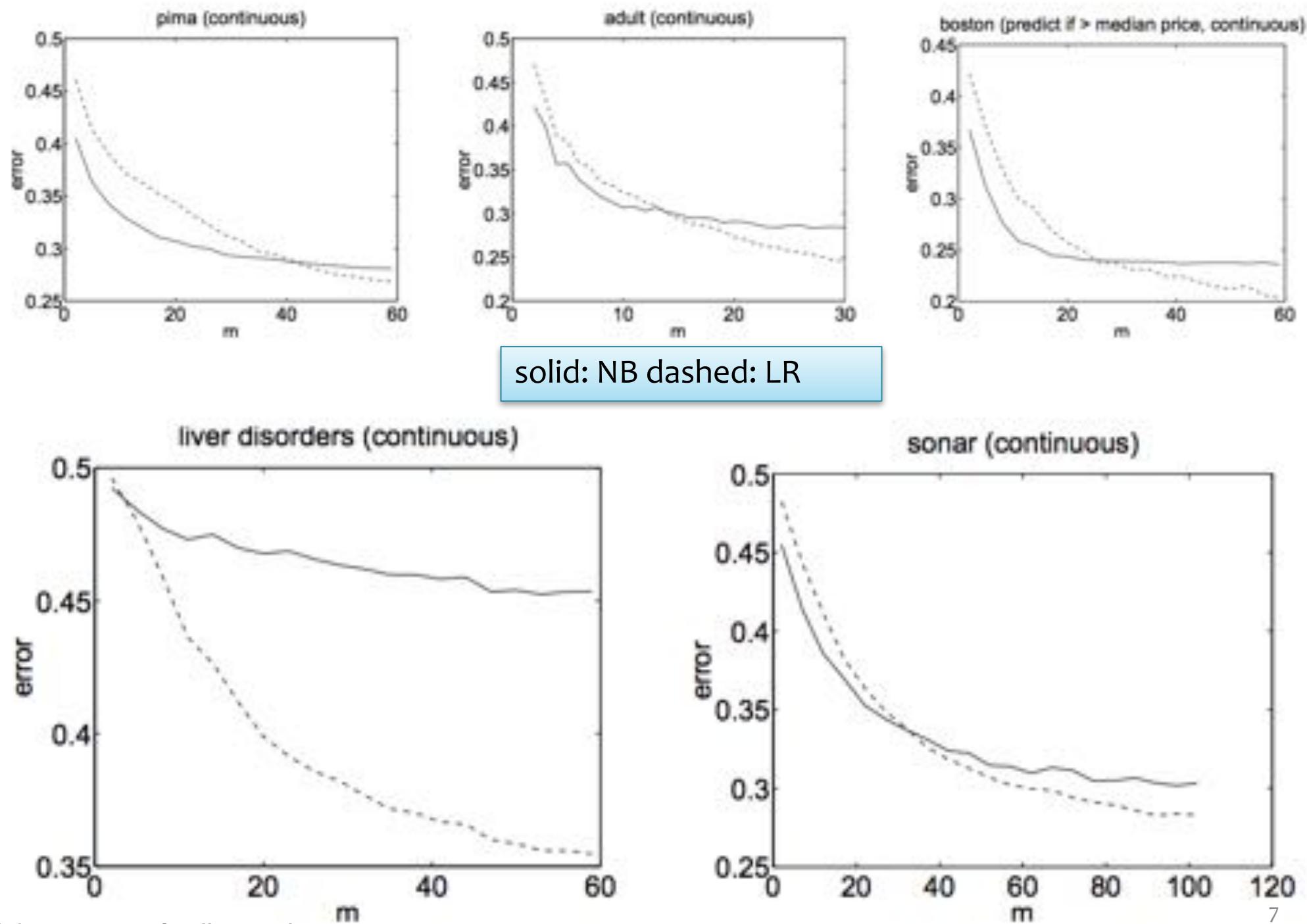
Generative vs. Discriminative

Finite Sample Analysis (Ng & Jordan, 2002)

[Assume that we are learning from a finite training dataset]

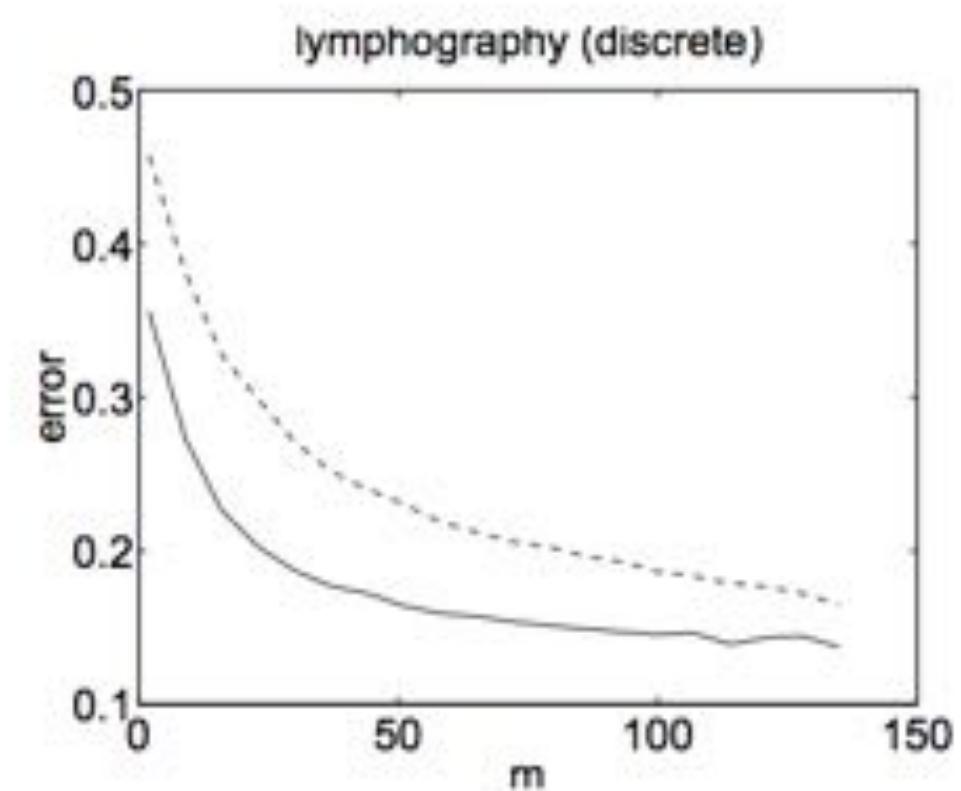
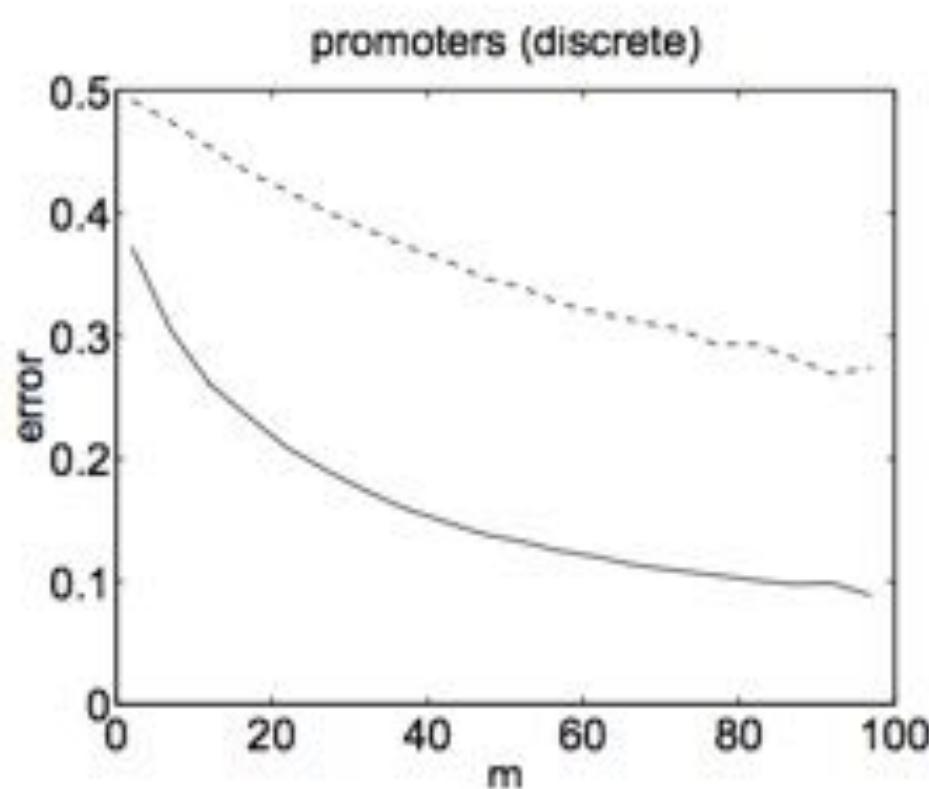
If model assumptions are correct: Naive Bayes is a more efficient learner (requires fewer samples) than Logistic Regression

If model assumptions are incorrect: Logistic Regression has lower asymptotic error, and does better than Naïve Bayes



Slide courtesy of William Cohen

solid: NB dashed: LR



Naïve Bayes makes stronger assumptions about the data
but needs fewer examples to estimate the parameters

“On Discriminative vs Generative Classifiers:” Andrew Ng
and Michael Jordan, NIPS 2001.

Generative vs. Discriminative Learning (Parameter Estimation)

Naïve Bayes:

Parameters are decoupled → Closed form solution for MLE

Logistic Regression:

Parameters are coupled → No closed form solution – must use iterative optimization techniques instead

Naïve Bayes vs. Logistic Reg.

Learning (MAP Estimation of Parameters)

Bernoulli Naïve Bayes:

Parameters are probabilities → Beta prior (usually) pushes probabilities away from zero / one extremes

Logistic Regression:

Parameters are not probabilities → Gaussian prior encourages parameters to be close to zero

(effectively pushes the probabilities away from zero / one extremes)

Naïve Bayes vs. Logistic Reg.

Features

Naïve Bayes:

Features x are assumed to be conditionally independent given y . (i.e. Naïve Bayes Assumption)

Logistic Regression:

No assumptions are made about the form of the features x . They can be dependent and correlated in any fashion.

MOTIVATION: STRUCTURED PREDICTION

Structured Prediction

- Most of the models we've seen so far were for **classification**
 - Given observations: $\mathbf{x} = (x_1, x_2, \dots, x_K)$
 - Predict a (binary) **label**: y
- Many real-world problems require **structured prediction**
 - Given observations: $\mathbf{x} = (x_1, x_2, \dots, x_K)$
 - Predict a **structure**: $\mathbf{y} = (y_1, y_2, \dots, y_J)$
- Some *classification* problems benefit from **latent structure**

Structured Prediction Examples

- **Examples of structured prediction**
 - Part-of-speech (POS) tagging
 - Handwriting recognition
 - Speech recognition
 - Word alignment
 - Congressional voting
- **Examples of latent structure**
 - Object recognition

Dataset for Supervised Part-of-Speech (POS) Tagging

Data: $\mathcal{D} = \{\mathbf{x}^{(n)}, \mathbf{y}^{(n)}\}_{n=1}^N$

Sample 1:	n time	v flies	p like	d an	n arrow	$y^{(1)}$
Sample 2:	n time	n flies	v like	d an	n arrow	$y^{(2)}$
Sample 3:	n flies	v fly	p with	n their	n wings	$y^{(3)}$
Sample 4:	p with	n time	n you	v will	v see	$y^{(4)}$

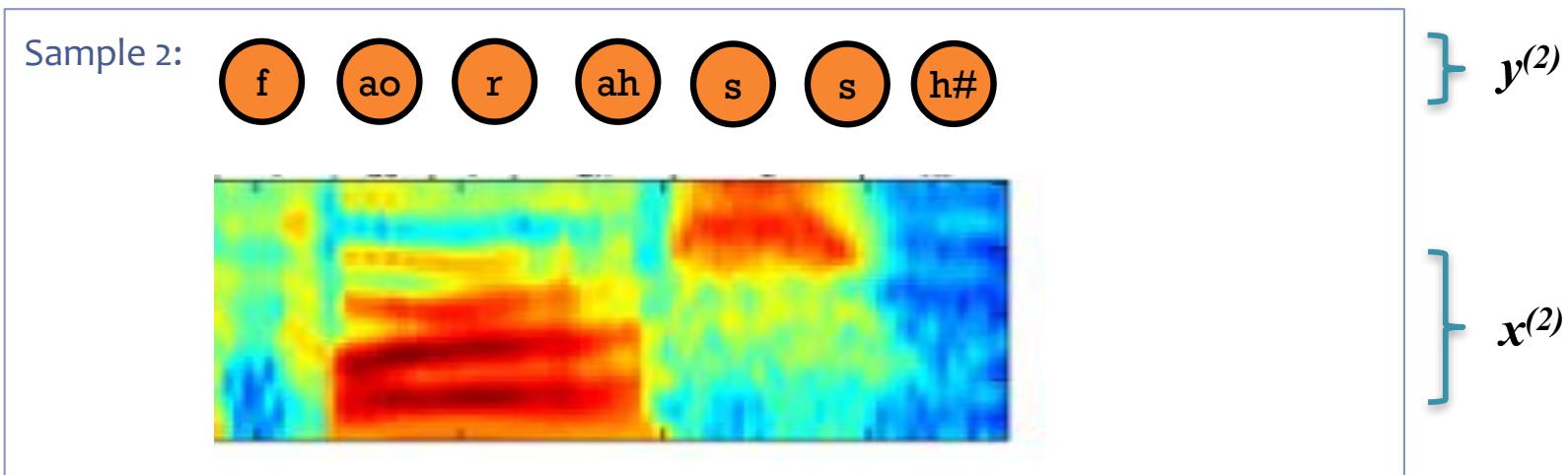
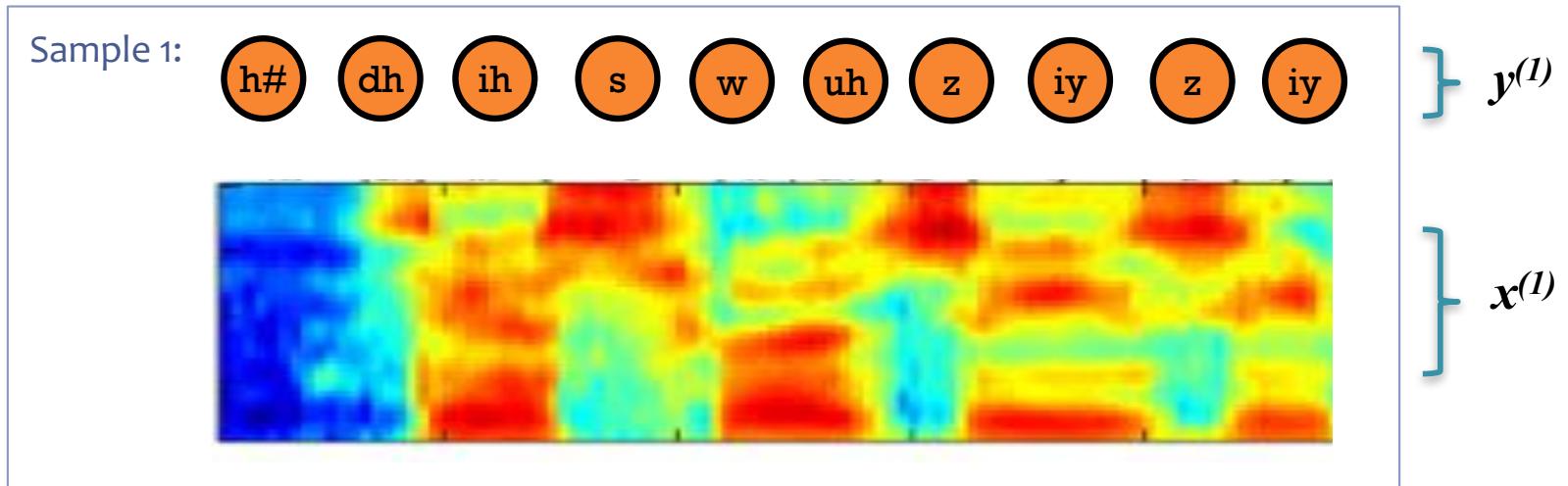
Dataset for Supervised Handwriting Recognition

Data: $\mathcal{D} = \{\mathbf{x}^{(n)}, \mathbf{y}^{(n)}\}_{n=1}^N$



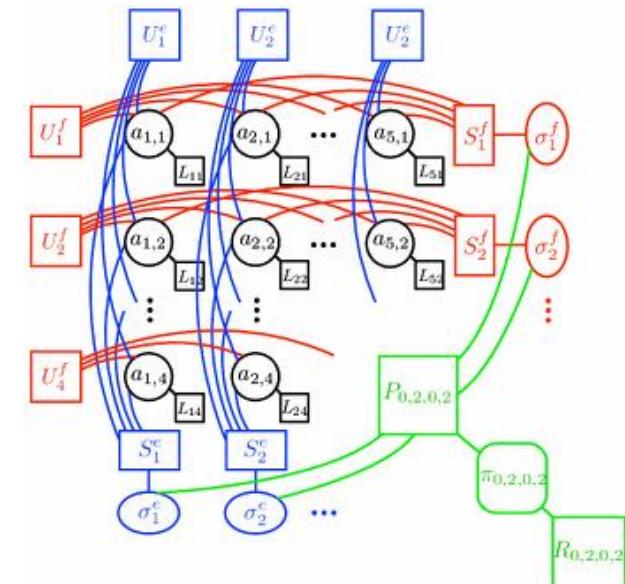
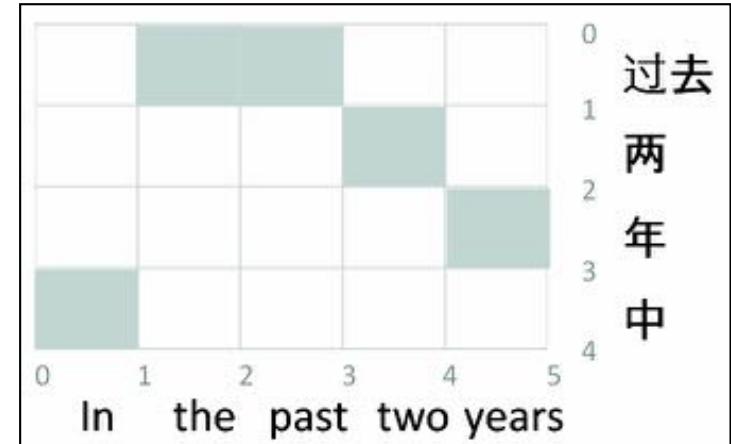
Dataset for Supervised Phoneme (Speech) Recognition

Data: $\mathcal{D} = \{\mathbf{x}^{(n)}, \mathbf{y}^{(n)}\}_{n=1}^N$

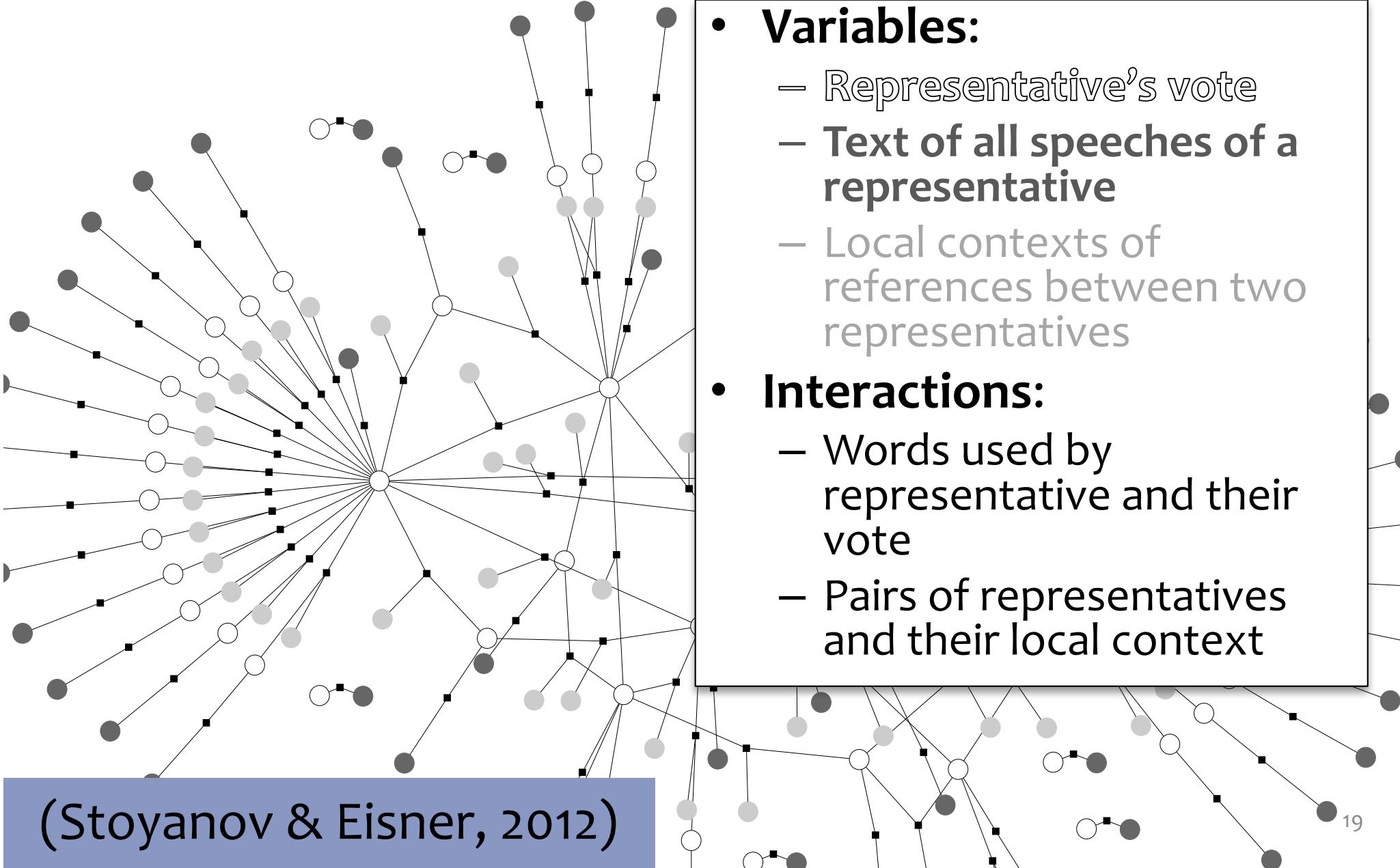


Word Alignment / Phrase Extraction

- **Variables (boolean):**
 - For each (Chinese phrase, English phrase) pair, are they linked?
- **Interactions:**
 - Word fertilities
 - Few “jumps” (discontinuities)
 - Syntactic reorderings
 - “ITG constraint” on alignment
 - Phrases are disjoint (?)



Congressional Voting



Structured Prediction Examples

- **Examples of structured prediction**
 - Part-of-speech (POS) tagging
 - Handwriting recognition
 - Speech recognition
 - Word alignment
 - Congressional voting
- **Examples of latent structure**
 - Object recognition

Case Study: Object Recognition

Data consists of images x and labels y .



pigeon

$$\left. \begin{array}{c} x^{(1)} \\ y^{(1)} \end{array} \right\}$$



rhinoceros

$$\left. \begin{array}{c} x^{(2)} \\ y^{(2)} \end{array} \right\}$$



leopard

$$\left. \begin{array}{c} x^{(3)} \\ y^{(3)} \end{array} \right\}$$



llama

$$\left. \begin{array}{c} x^{(4)} \\ y^{(4)} \end{array} \right\}$$

Case Study: Object Recognition

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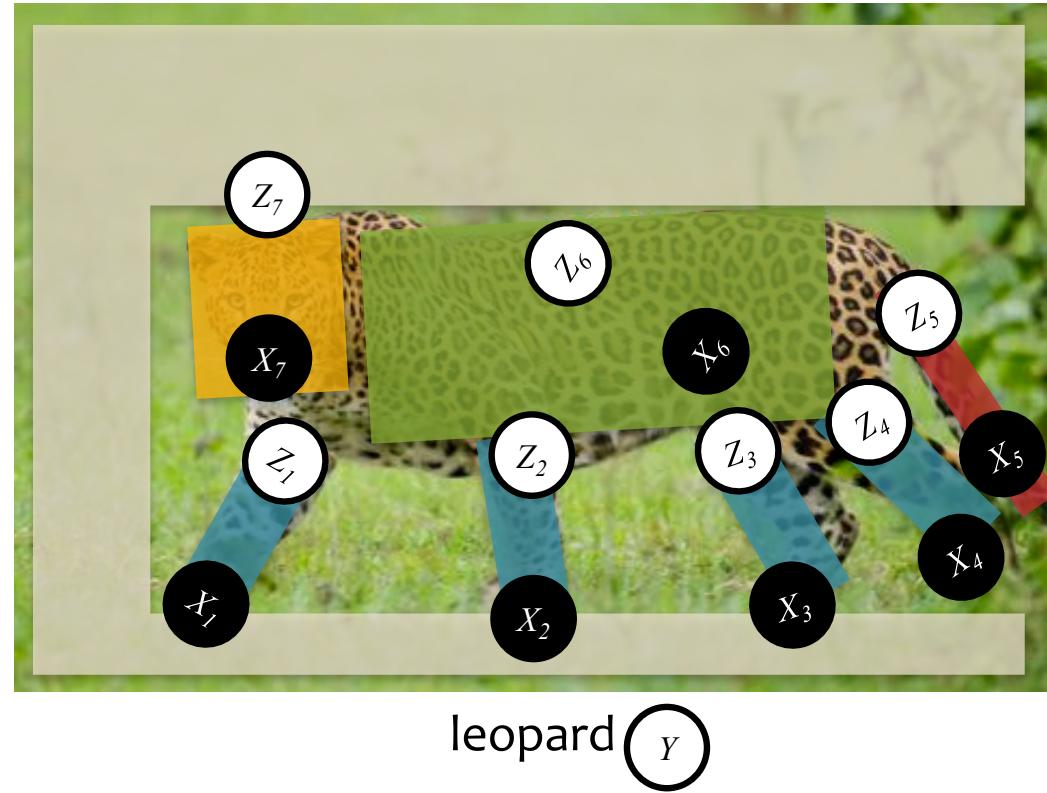
- Preprocess data into “patches”
- Posit a latent labeling z describing the object’s parts (e.g. head, leg, tail, torso, grass)
- Define graphical model with these latent variables in mind
- z is not observed at train or test time



Case Study: Object Recognition

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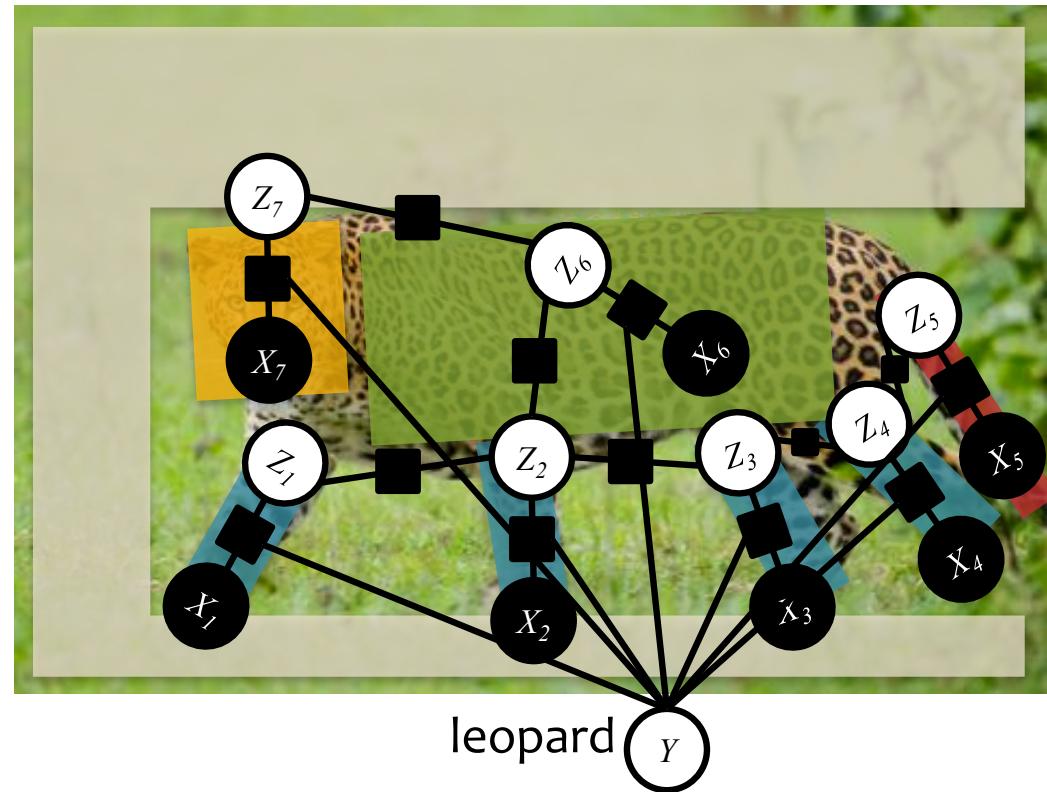
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Structured Prediction

Preview of challenges to come...

- Consider the task of finding the **most probable assignment** to the output

Classification

$$\hat{y} = \operatorname{argmax}_y p(y|\mathbf{x})$$

where $y \in \{+1, -1\}$

Structured Prediction

$$\hat{\mathbf{y}} = \operatorname{argmax}_{\mathbf{y}} p(\mathbf{y}|\mathbf{x})$$

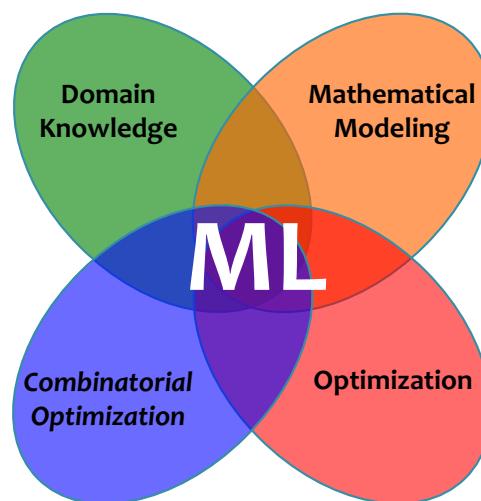
where $\mathbf{y} \in \mathcal{Y}$
and $|\mathcal{Y}|$ is very large

Machine Learning

The **data** inspires the structures we want to predict

Inference finds {best structure, marginals, partition function} for a new observation

(**Inference** is usually called as a subroutine in learning)



Our **model** defines a score for each structure

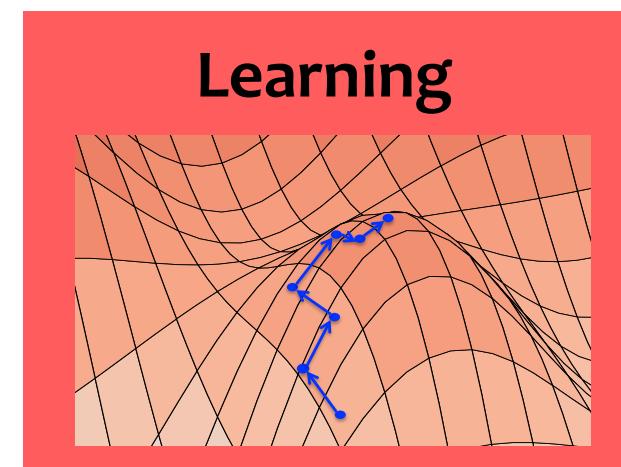
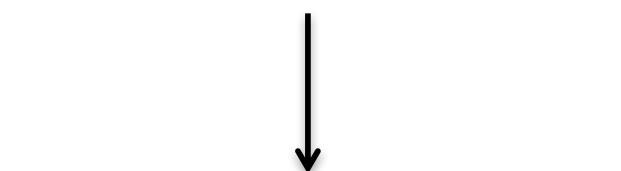
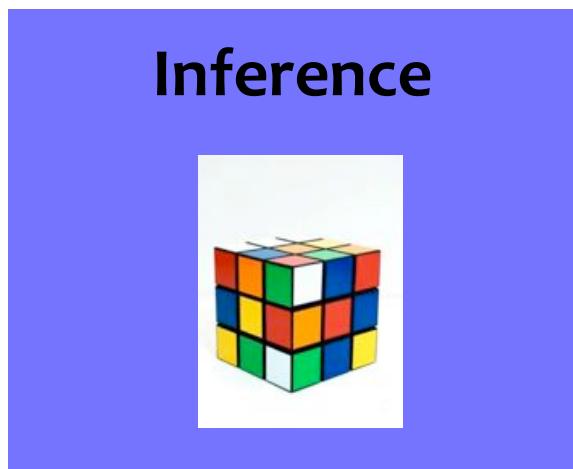
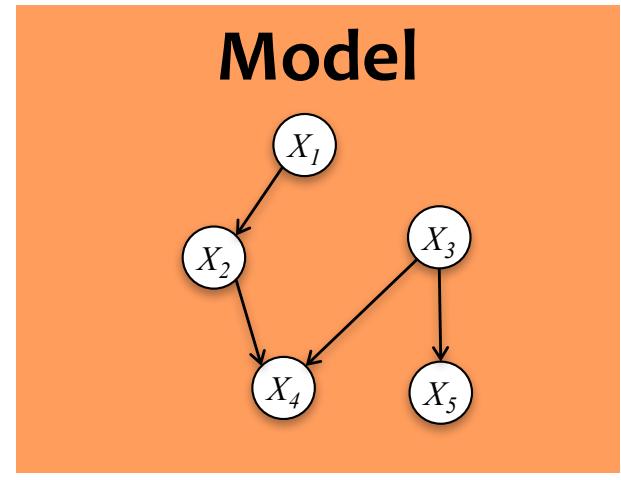
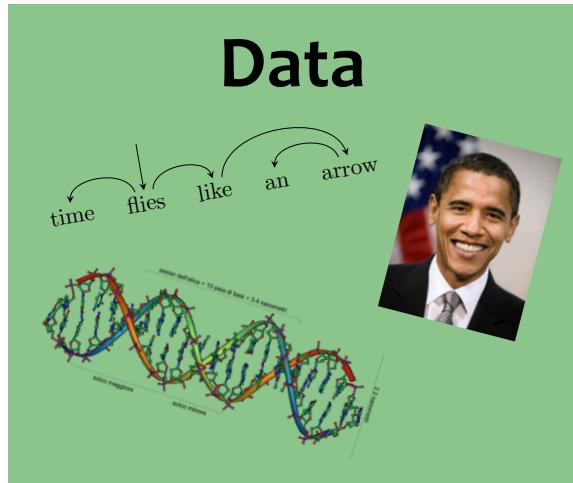
It also tells us what to optimize



Learning tunes the parameters of the model



Machine Learning



(Inference is usually called as a subroutine in learning)

BACKGROUND

Background

Whiteboard

- Chain Rule of Probability
- Conditional Independence

Background: Chain Rule of Probability

For random variables A and B :

$$P(A, B) = P(A|B)P(B)$$

For random variables X_1, X_2, X_3, X_4 :

$$P(X_1, X_2, X_3, X_4) = P(X_1|X_2, X_3, X_4)$$

$$P(X_2|X_3, X_4)$$

$$P(X_3|X_4)$$

$$P(X_4)$$

Background: Conditional Independence

Random variables A and B are conditionally independent given C if:

$$P(A, B|C) = P(A|C)P(B|C) \quad (1)$$

or equivalently:

$$P(A|B, C) = P(A|C) \quad (2)$$

We write this as:

$$A \perp\!\!\!\perp B | C$$

Later we will also
write: $I<math>A, \{C\}, B>$

HIDDEN MARKOV MODEL (HMM)

HMM Outline

- **Motivation**
 - Time Series Data
- **Hidden Markov Model (HMM)**
 - Example: Squirrel Hill Tunnel Closures
[courtesy of Roni Rosenfeld]
 - Background: Markov Models
 - From Mixture Model to HMM
 - History of HMMs
 - Higher-order HMMs
- **Training HMMs**
 - (Supervised) Likelihood for HMM
 - Maximum Likelihood Estimation (MLE) for HMM
 - EM for HMM (aka. Baum-Welch algorithm)
- **Forward-Backward Algorithm**
 - Three Inference Problems for HMM
 - Great Ideas in ML: Message Passing
 - Example: Forward-Backward on 3-word Sentence
 - Derivation of Forward Algorithm
 - Forward-Backward Algorithm
 - Viterbi algorithm

Markov Models

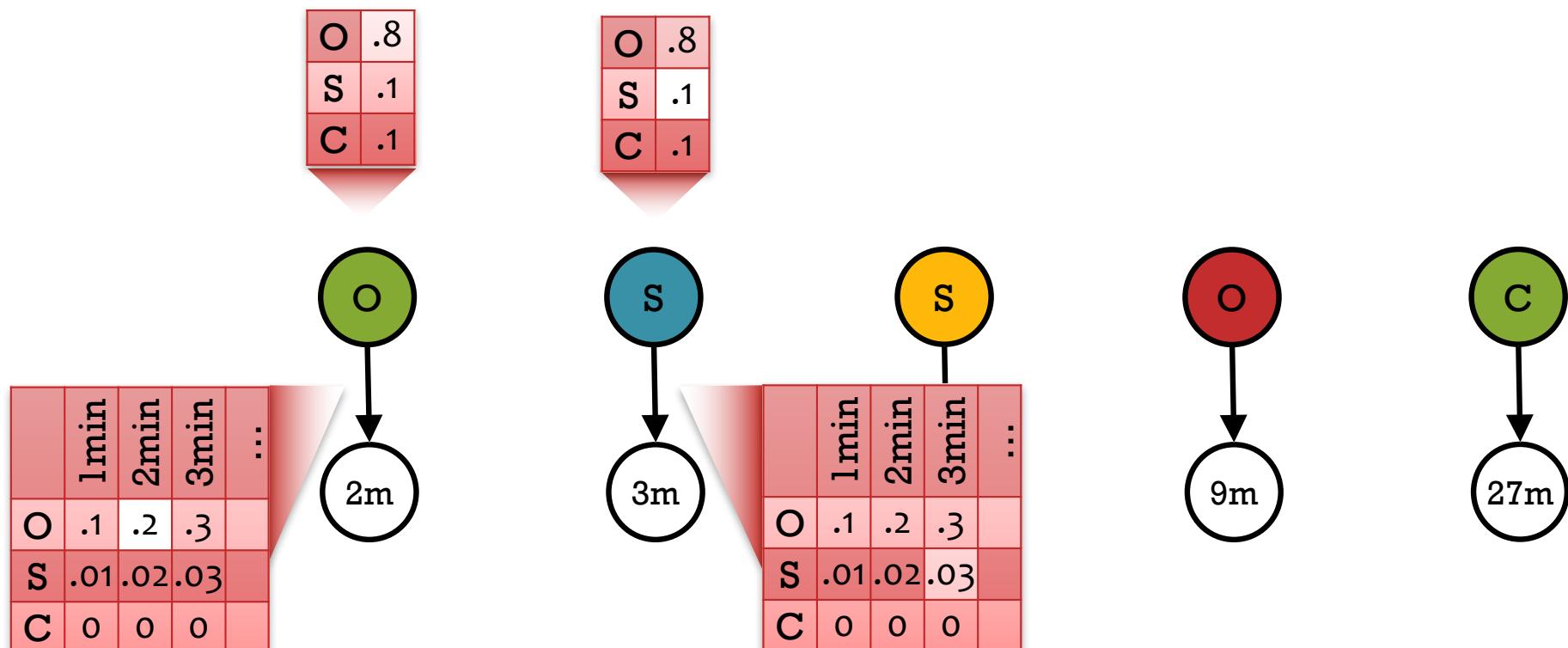
Whiteboard

- Example: Squirrel Hill Tunnel Closures
[courtesy of Roni Rosenfeld]
- First-order Markov assumption
- Conditional independence assumptions

Mixture Model for Time Series Data

We could treat each (tunnel state, travel time) pair as independent. This corresponds to a Naïve Bayes model with a single feature (travel time).

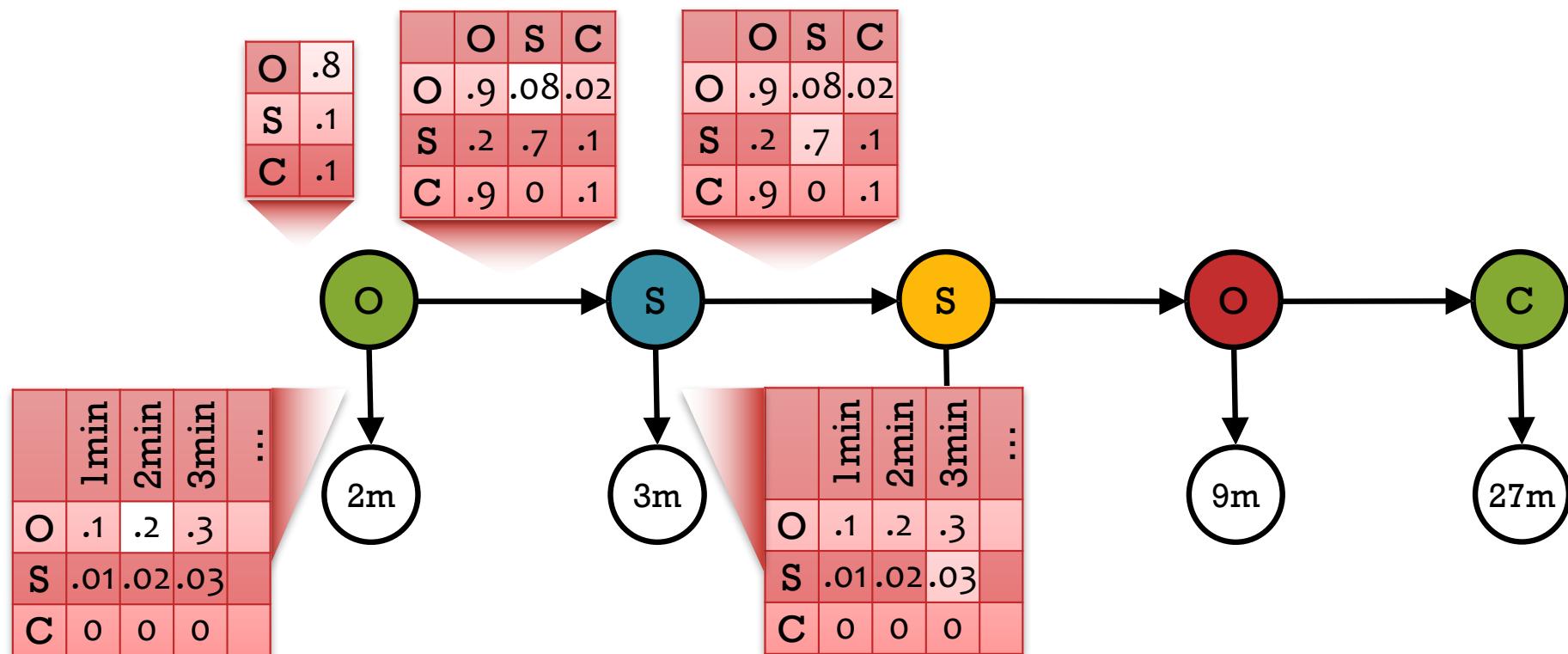
$$p(O, S, S, O, C, 2m, 3m, 18m, 9m, 27m) = (.8 * .2 * .1 * .03 * \dots)$$



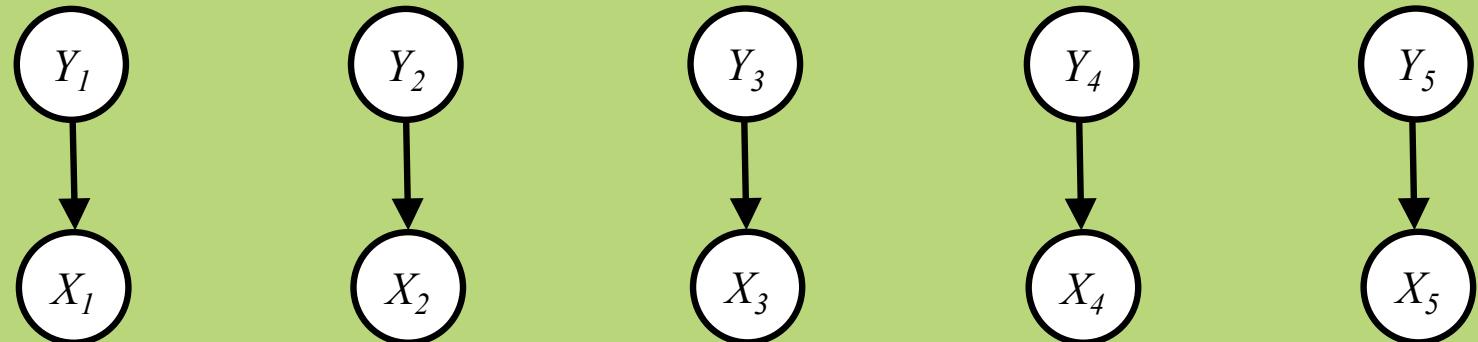
Hidden Markov Model

A Hidden Markov Model (HMM) provides a joint distribution over the tunnel states / travel times with an assumption of dependence between adjacent tunnel states.

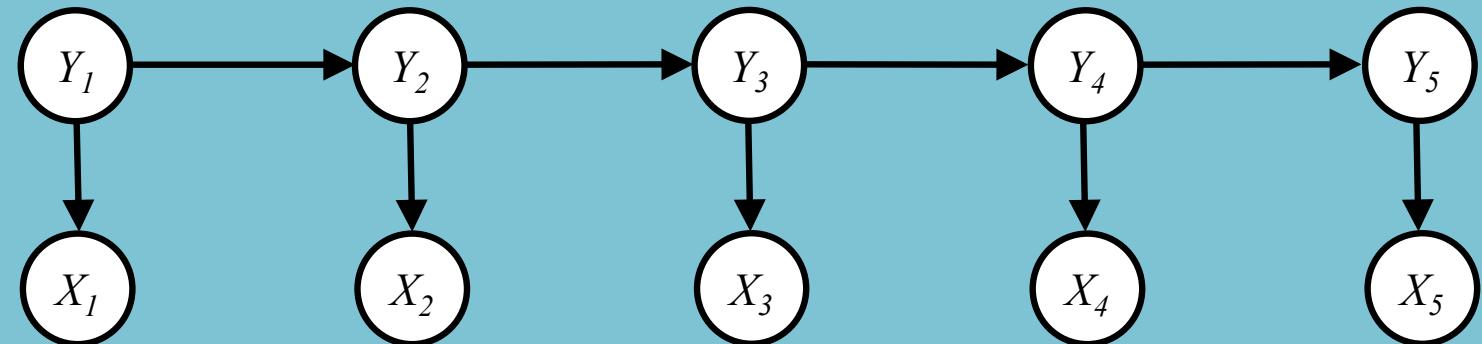
$$p(O, S, S, O, C, 2m, 3m, 18m, 9m, 27m) = (.8 * .08 * .2 * .7 * .03 * \dots)$$



From Mixture Model to HMM



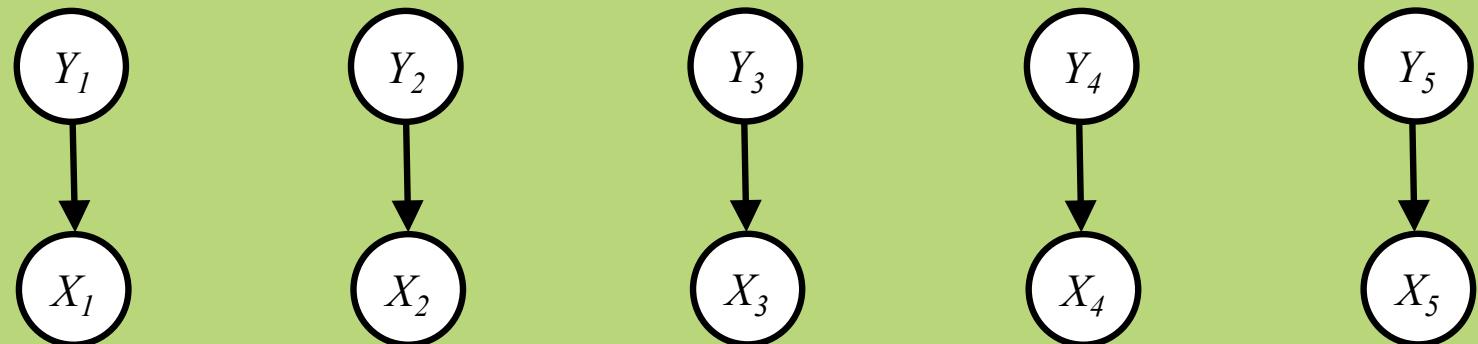
“Naïve Bayes”: $P(\mathbf{X}, \mathbf{Y}) = \prod_{t=1}^T P(X_t|Y_t)p(Y_t)$



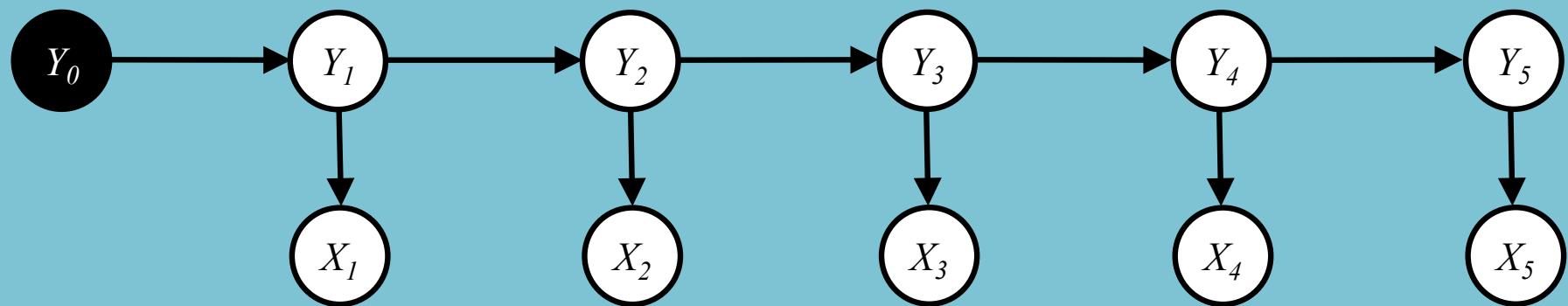
HMM:

$$P(\mathbf{X}, \mathbf{Y}) = P(Y_1) \left(\prod_{t=1}^T P(X_t|Y_t) \right) \left(\prod_{t=2}^T p(Y_t|Y_{t-1}) \right)$$

From Mixture Model to HMM



“Naïve Bayes”: $P(\mathbf{X}, \mathbf{Y}) = \prod_{t=1}^T P(X_t|Y_t)p(Y_t)$



HMM:

$$P(\mathbf{X}, \mathbf{Y}|Y_0) = \prod_{t=1}^T P(X_t|Y_t)p(Y_t|Y_{t-1})$$

SUPERVISED LEARNING FOR HMMS

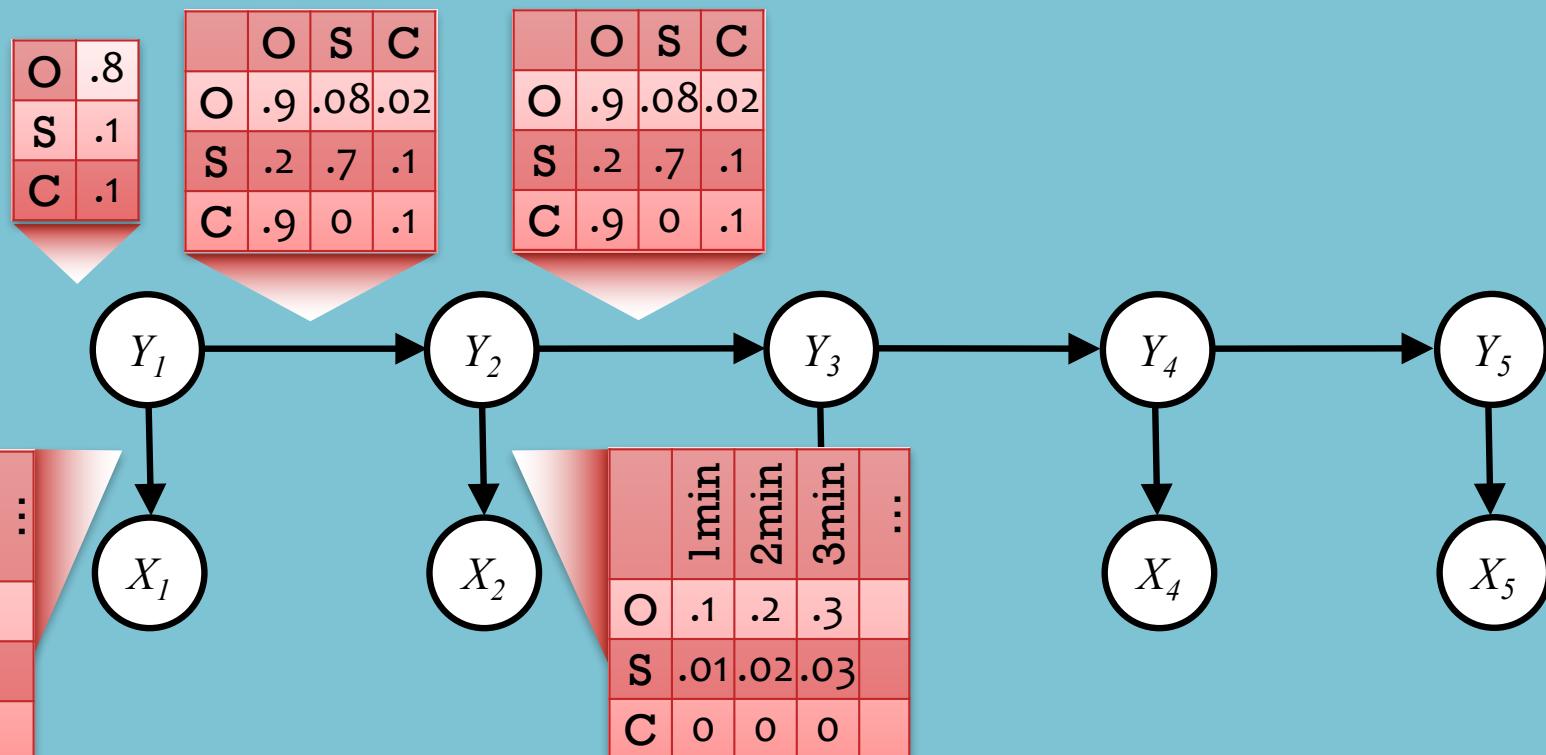
Hidden Markov Model

HMM Parameters:

Emission matrix, \mathbf{A} , where $P(X_t = k|Y_t = j) = A_{j,k}, \forall t, k$

Transition matrix, \mathbf{B} , where $P(Y_t = k|Y_{t-1} = j) = B_{j,k}, \forall t, k$

Initial probs, \mathbf{C} , where $P(Y_1 = k) = C_k, \forall k$



Hidden Markov Model

HMM Parameters:

Emission matrix, \mathbf{A} , where $P(X_t = k|Y_t = j) = A_{j,k}, \forall t, k$

Transition matrix, \mathbf{B} , where $P(Y_t = k|Y_{t-1} = j) = B_{j,k}, \forall t, k$

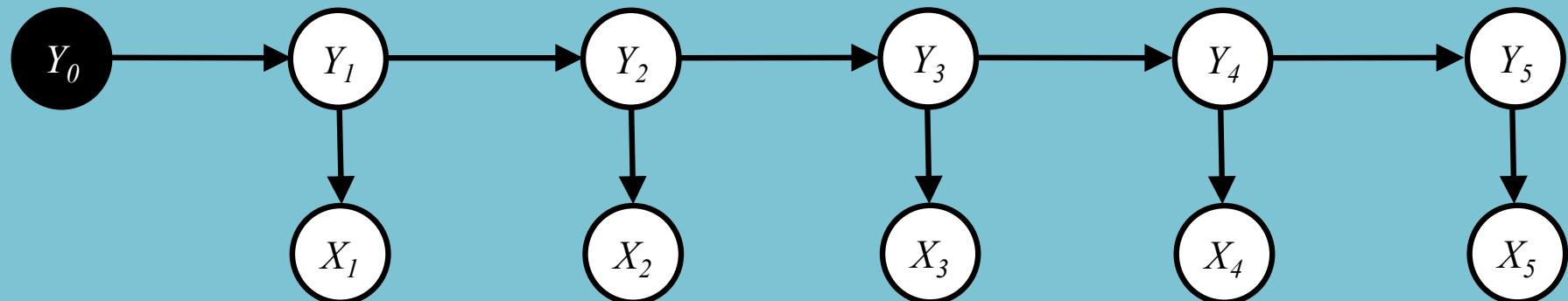
Assumption: $y_0 = \text{START}$

Generative Story:

$Y_t \sim \text{Multinomial}(\mathbf{B}_{Y_{t-1}}) \quad \forall t$

$X_t \sim \text{Multinomial}(\mathbf{A}_{Y_t}) \quad \forall t$

For notational convenience, we fold the initial probabilities \mathbf{C} into the transition matrix \mathbf{B} by our assumption.

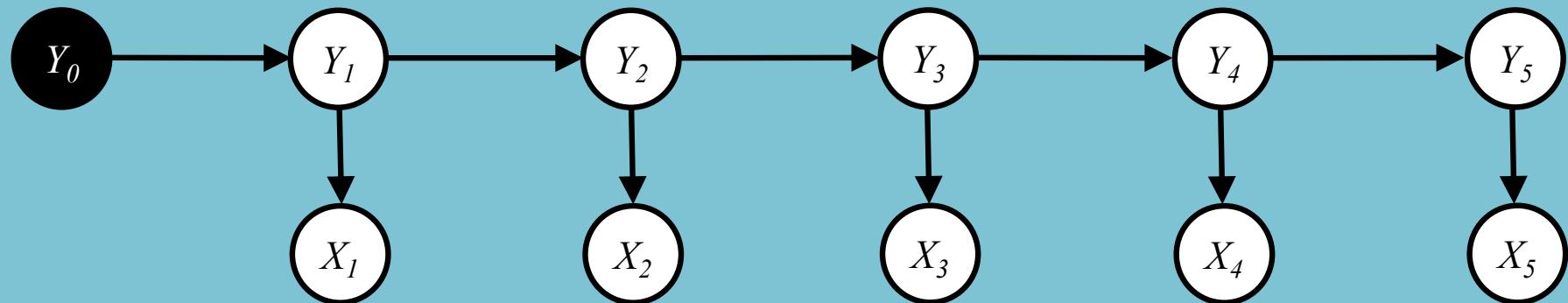


Hidden Markov Model

Joint Distribution:

$y_0 = \text{START}$

$$\begin{aligned} p(\mathbf{x}, \mathbf{y}|y_0) &= \prod_{t=1}^T p(x_t|y_t)p(y_t|y_{t-1}) \\ &= \prod_{t=1}^T A_{y_t, x_t} B_{y_{t-1}, y_t} \end{aligned}$$



Training HMMs

Whiteboard

- (Supervised) Likelihood for an HMM
- Maximum Likelihood Estimation (MLE) for HMM