



ĐẠI HỌC ĐÀ NẴNG

TRƯỜNG ĐẠI HỌC CÔNG NGHỆ THÔNG TIN VÀ TRUYỀN THÔNG VIỆT - HÀN
VIETNAM - KOREA UNIVERSITY OF INFORMATION AND COMMUNICATION TECHNOLOGY

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Nhân bản – Phụng sự – Khai phóng

Graphs

Data Structures & Algorithms

- Terminology
- Graph Representations
- Graph Traversals

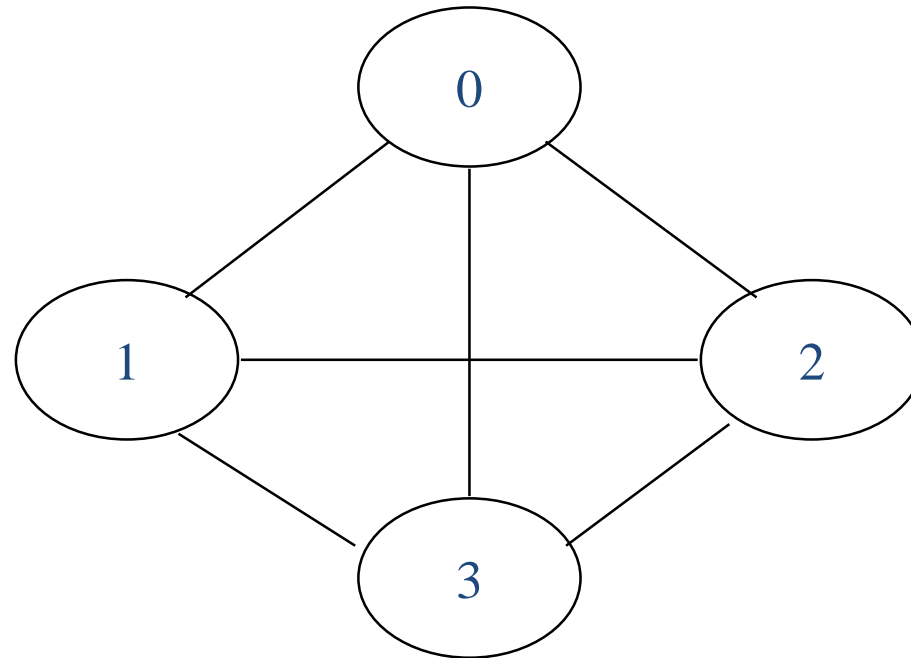
- **Terminology**
- Graph Representations
- Graph Traversals

- **A graph $G=(V,E)$, V and E are two sets**
 - V : finite non-empty set of vertices
 - E : set of edges (pairs of vertices)
- **Undirected graph**
 - The pair of vertices representing any edge is unordered.
Thus, the pairs (u,v) and (v,u) represent the same edge
- **Directed graph**
 - each edge is represented by an ordered pair $\langle u,v \rangle$

- Examples

Graph $G1=(V,E)$:

- $V(G1)=\{0,1,2,3\}$
- $E(G1)=\{(0,1), (0,2), (0,3), (1,2), (1,3), (2,3)\}$



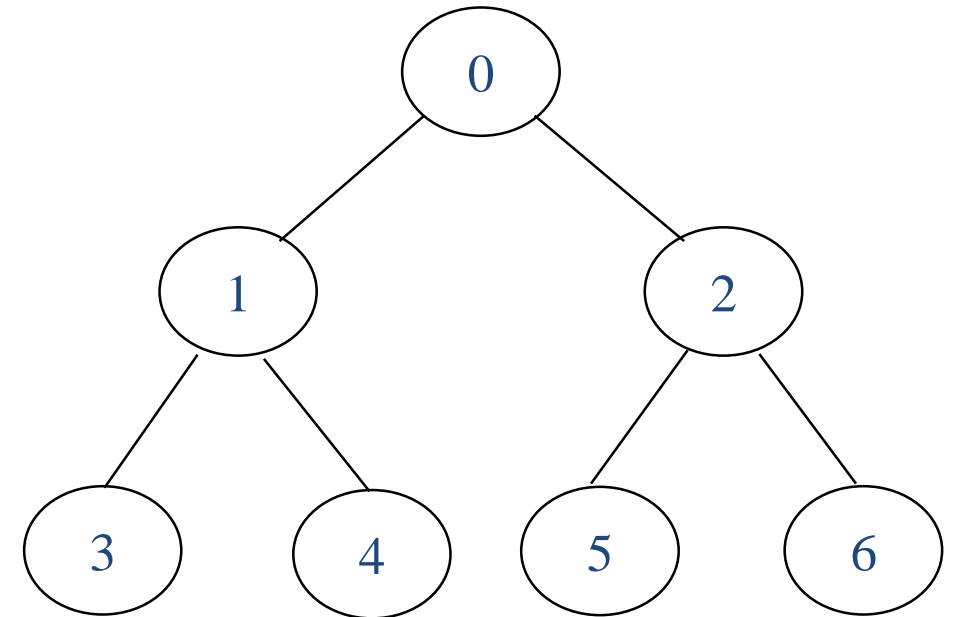
- Examples

Graph $G_2=(V,E)$:

- $V(G_2)=\{0,1,2,3,4,5,6\}$
- $E(G_2)=\{(0,1), (0,2), (1,3), (1,4), (2,5), (2,6)\}$

G_2 is also a tree

Tree is a special case of graph

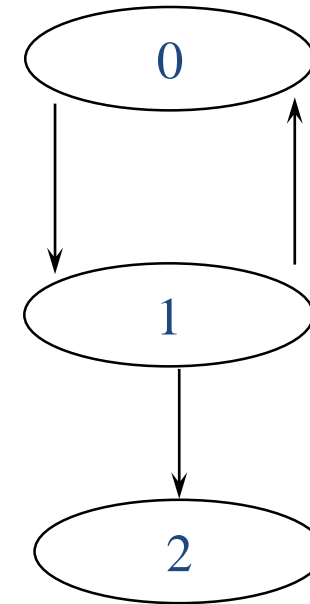


- **Examples**

Graph $G3=(V,E)$:

- $V(G3)=\{0,1,2\}$
- $E(G3)=\{<0,1>, <1,0>, <1,2>\}$

Directed graph (digraph)



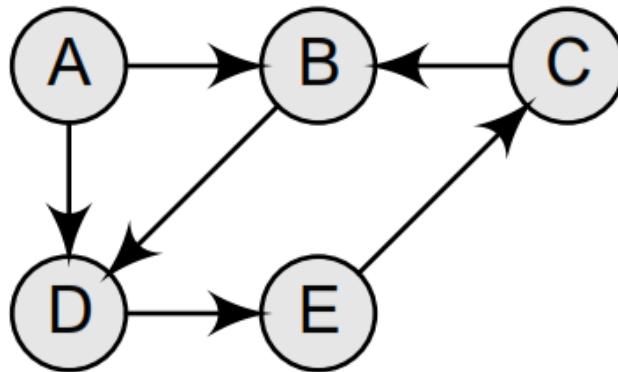
- Examples

Directed graph

a graph with 5 vertices and 6 edges:

$V(G) = \{A, B, C, D, E\}$ and

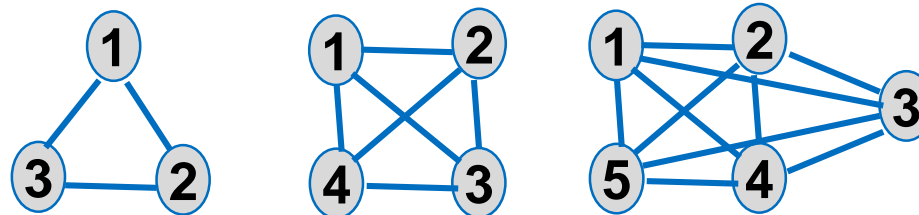
$E(G) = \{ \langle A, B \rangle, \langle C, B \rangle, \langle A, D \rangle, \langle B, D \rangle, \langle D, E \rangle, \langle E, C \rangle \}$.



- **Complete Graph**

- **Complete Graph** is a graph that has the maximum number of edges
- For undirected graph with n vertices, the maximum number of edges is $n(n-1)/2$
- For directed graph with n vertices, the maximum number of edges is $n(n-1)$

Example:

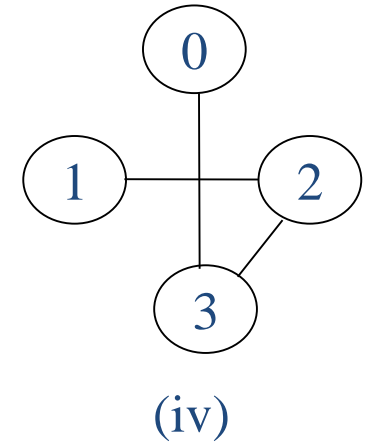
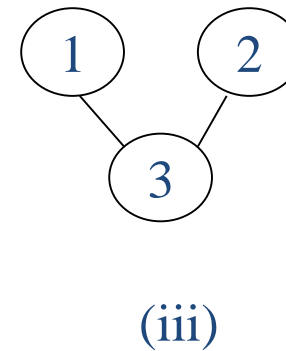
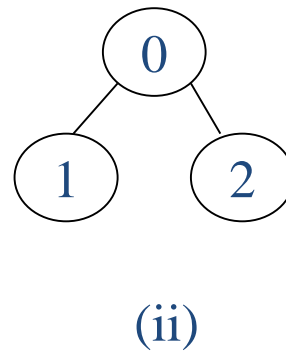
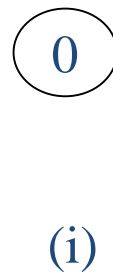
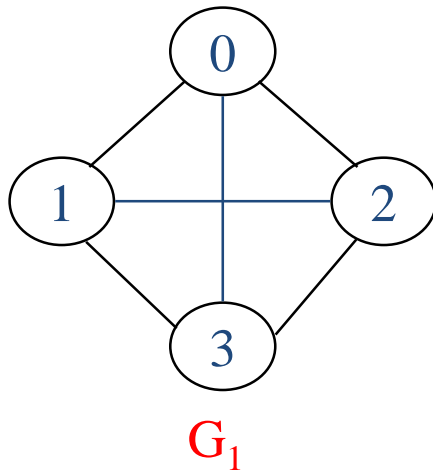


- **Adjacent and Incident**

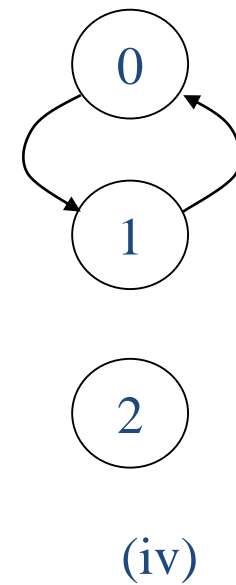
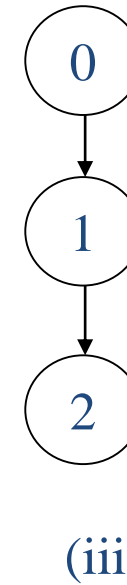
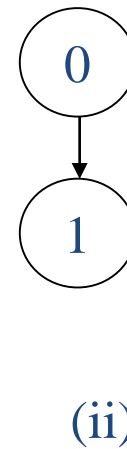
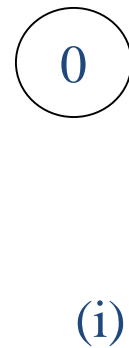
- If (u,v) is an edge in an undirected graph,
 - Adjacent: u and v are adjacent
 - Incident: The edge (u,v) is incident on vertices u and v
- If $\langle u,v \rangle$ is an edge in a directed graph
 - Adjacent: u is adjacent to v , and v is adjacent from u
 - Incident: The edge $\langle u,v \rangle$ is incident on u and v

• Subgraph

- A subgraph of G is a graph G' such that
 - $V(G') \subseteq V(G)$
 - $E(G') \subseteq E(G)$
- Some of the subgraph of G_1



- Some of the subgraphs of G_3



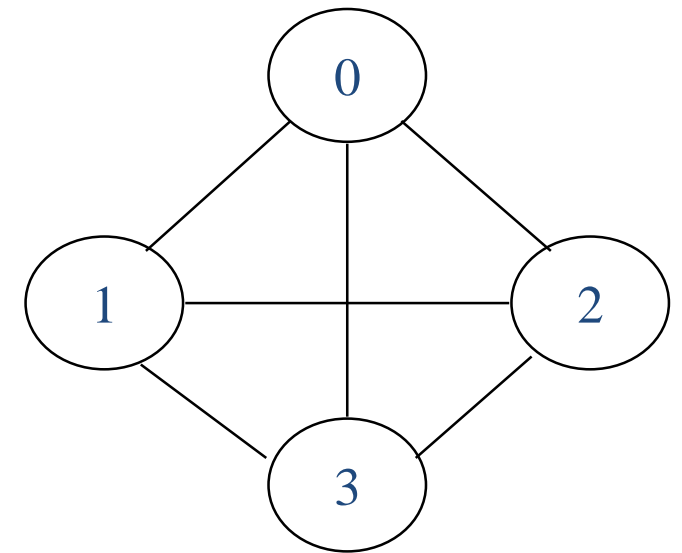
- Path

- Path from u to v in G

- a sequence of vertices $u, i_1, i_2, \dots, i_k, v$
 - If G is undirected: $(u, i_1), (i_1, i_2), \dots, (i_k, v) \in E(G)$
 - If G is directed: $\langle u, i_1 \rangle, \langle i_1, i_2 \rangle, \dots, \langle i_k, v \rangle \in E(G)$

- Length

- The length of a path is the number of edges on it.
 - Length of $0, 1, 3, 2$ is 3



- **Simple Path**

- is a path in which all vertices except possibly the first and last are distinct.

⇒ 0,1,3,2 is simple path

0,1,3,1 is path but not simple

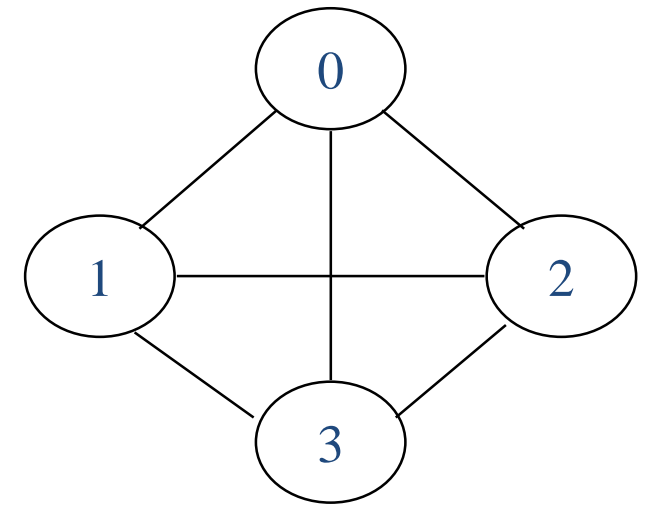
- **Cycle**

- a simple path, first and last vertices are same.

⇒ 0,1,2,0 is a cycle

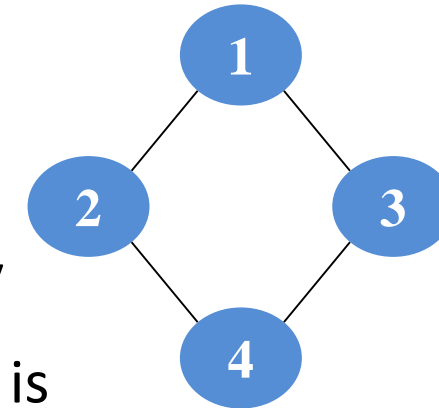
- **Acyclic graph**

- No cycle is in graph

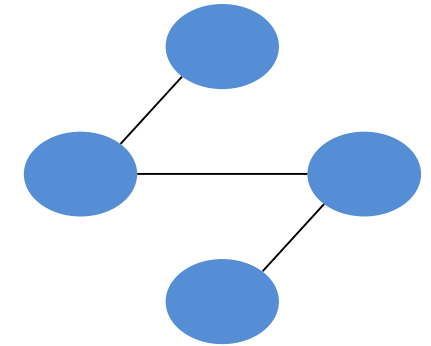


• Connected

- Two vertices u and v are connected if in an undirected graph G , \exists a path in G from u to v
- A graph G is connected, if any vertex pair u, v is connected



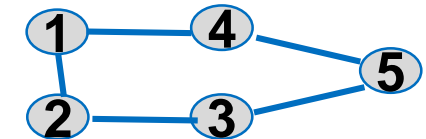
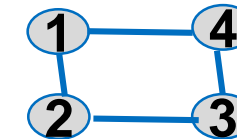
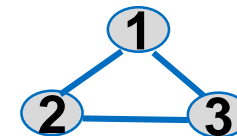
connected



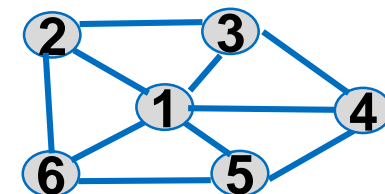
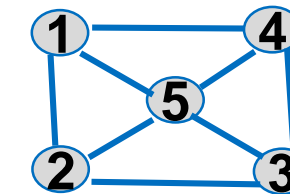
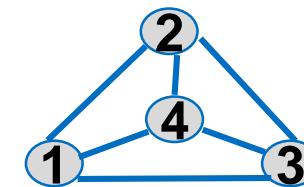
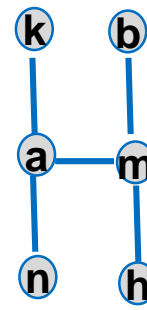
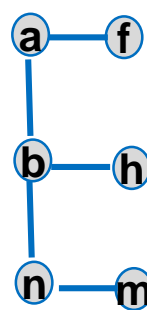
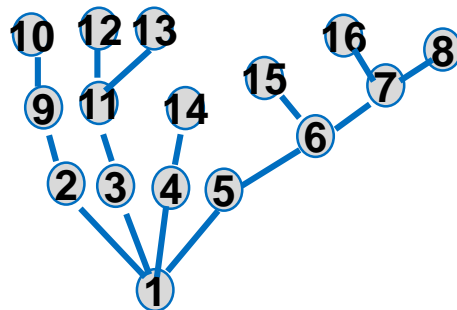
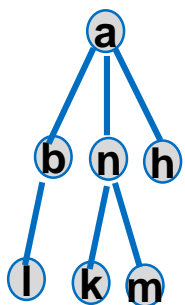
connected

• Connected Component

- a maximal connected subgraph.

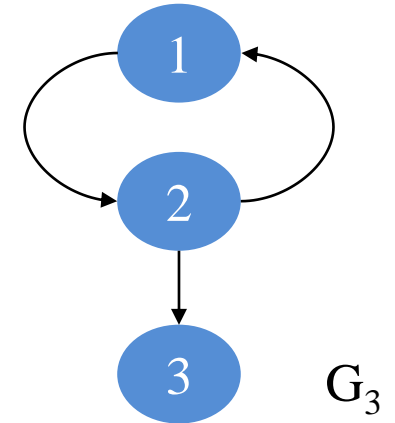


• Tree is a connected acyclic graph



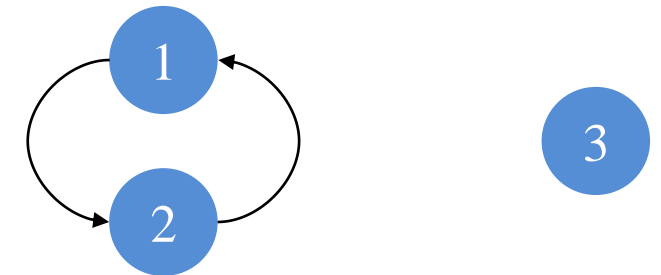
• Strongly Connected

- u, v are strongly connected if in a directed graph (digraph) G , \exists a path in G from u to v .
- A directed graph G is strongly connected, if any vertex pair u, v is connected



• Strongly Connected Component

- a maximal strongly connected subgraph



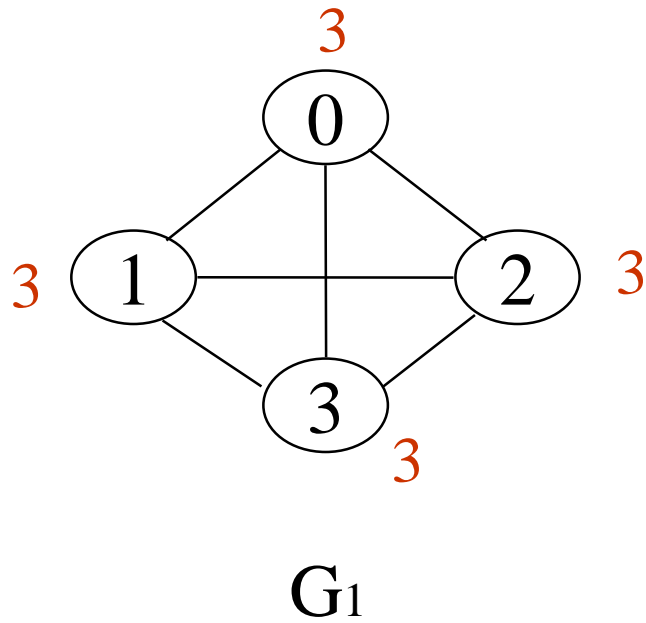
• Degree of Vertex

- is the number of edges incident to that vertex

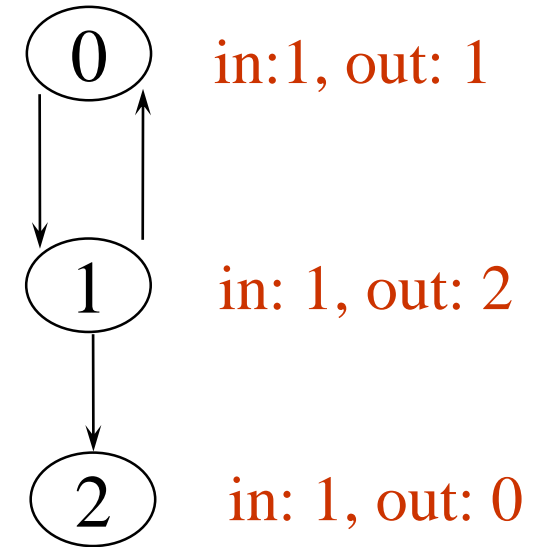
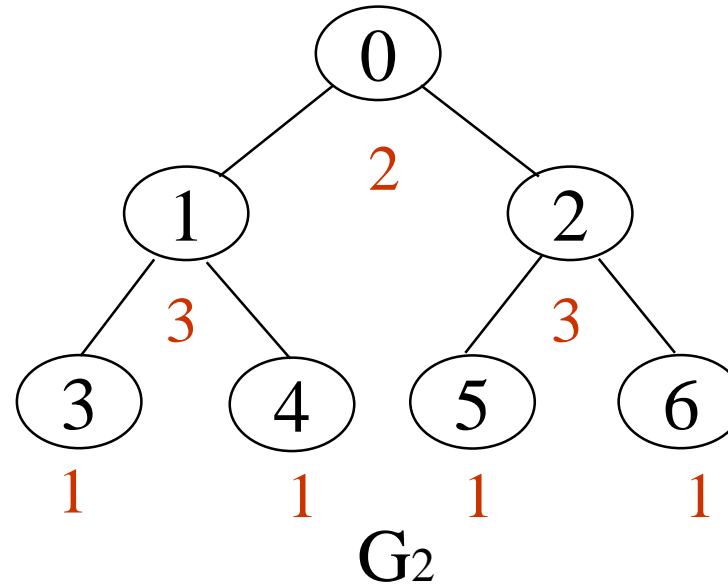
• Degree in directed graph

- Indegree
- Outdegree

• Summation of all vertices' degrees are $2|E|$



undirected graph



directed graph

in-degree

out-degree

- **Weighted Edge**

- In many applications, the edges of a graph are assigned weights
- These weights may represent the distance from one vertex to another
- A graph with weighted edges is called a **network**

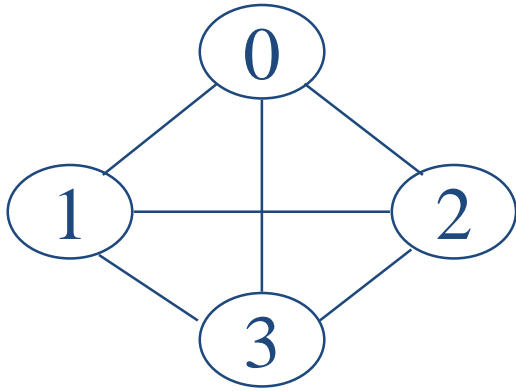
- Terminology
- **Graph Representations**
- Graph Traversals

- **Graph Representations**
 - **Adjacency Matrix**
 - **Adjacency Lists**
 - Adjacency Multi-lists

- **Adjacency Matrix**

- Let $G = (V, E)$ with n vertices, $n \geq 1$. The adjacency matrix of G is a 2-dimensional $n \times n$ matrix, A
 - $A(i, j) = 1$ iff $(v_i, v_j) \in E(G)$
($\langle v_i, v_j \rangle$ for a digraph)
 - $A(i, j) = 0$ otherwise
- The adjacency matrix for an undirected graph is symmetric
- The adjacency matrix for a digraph need not be symmetric

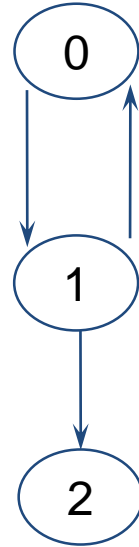
• Example



$$\begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$$

G_1

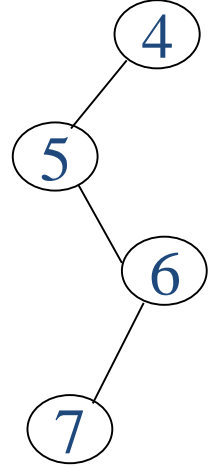
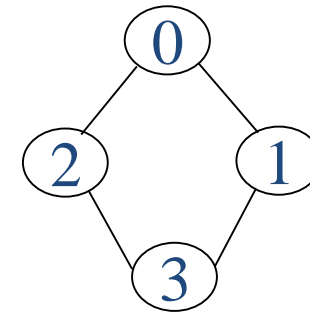
undirected: $n^2/2$
directed: n^2



$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

G_2

symmetric



$$\begin{bmatrix} 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

G_4

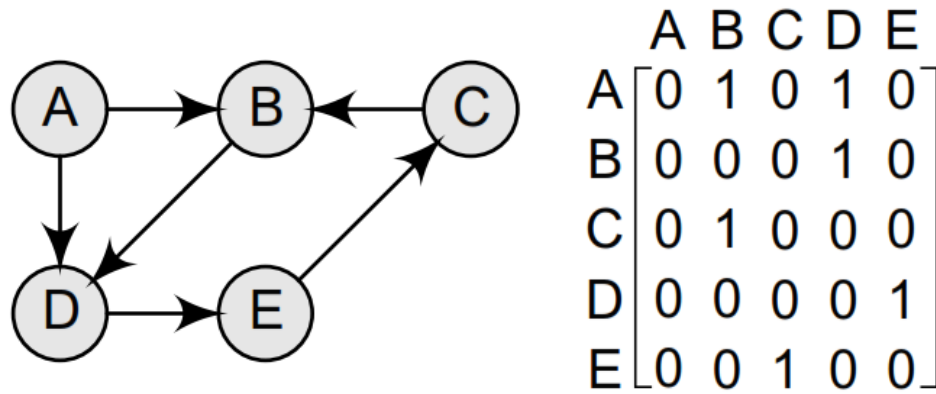
- **Merits of Adjacency Matrix**

- From the adjacency matrix, to determine the connection of vertices is easy
- The degree of a vertex is $\sum_{j=0}^{n-1} adj_mat[i][j]$
- For a digraph, the row sum is the out_degree, while the column sum is the in_degree

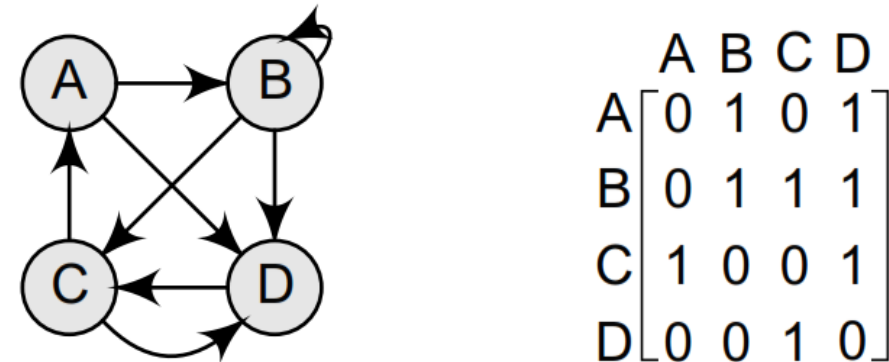
$$ind(vi) = \sum_{j=0}^{n-1} A[j, i]$$

$$outd(vi) = \sum_{j=0}^{n-1} A[i, j]$$

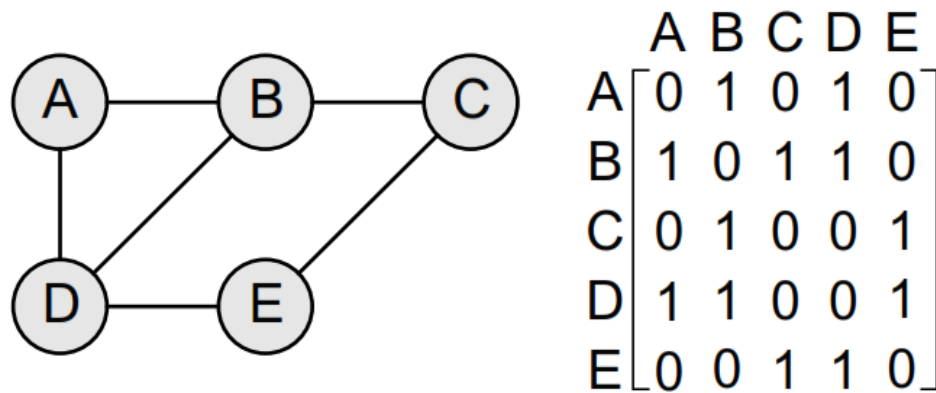
• Adjacency Matrix



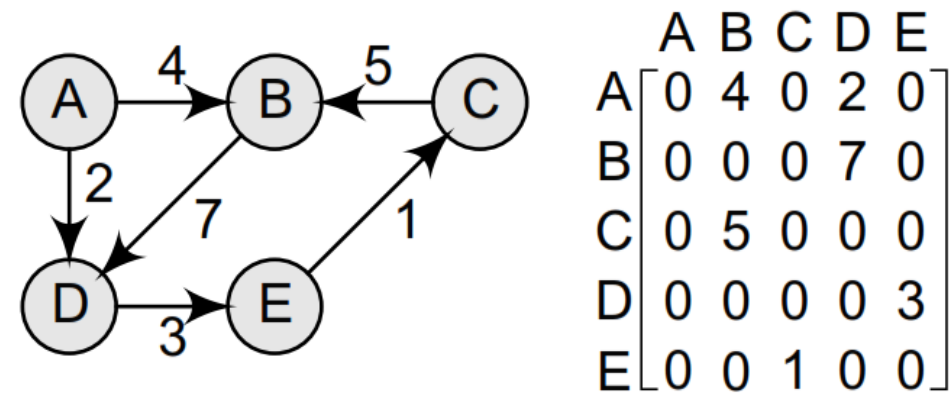
(a) Directed graph



(b) Directed graph with loop

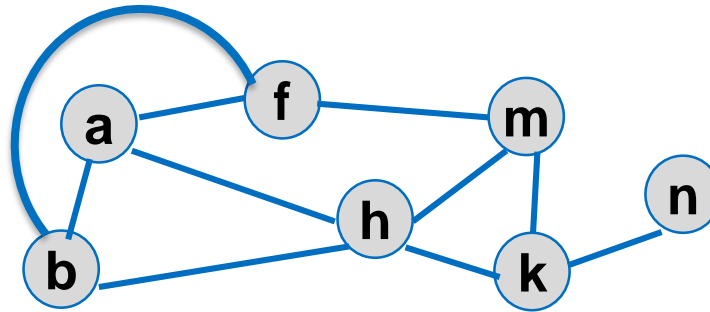


(c) Undirected graph



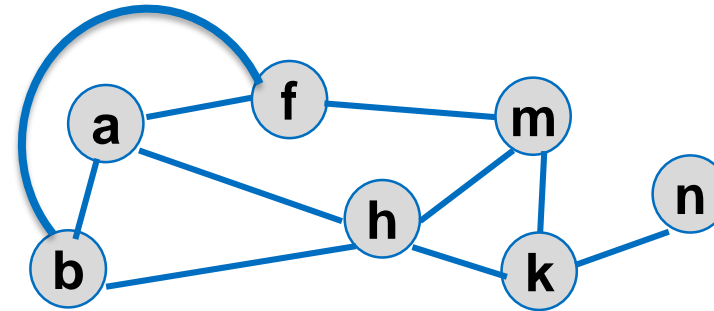
(d) Weighted graph

- Adjacency Matrix

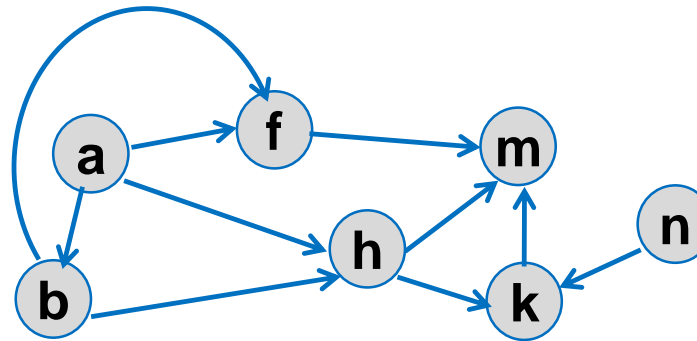


- Adjacency Matrix

	<i>a</i>	<i>b</i>	<i>f</i>	<i>h</i>	<i>m</i>	<i>n</i>	<i>k</i>
<i>a</i>	0	1	1	1	0	0	0
<i>b</i>	1	0	1	1	0	0	0
<i>f</i>	1	1	0	0	1	0	0
<i>h</i>	1	1	0	0	1	0	1
<i>m</i>	0	0	1	1	0	0	1
<i>n</i>	0	0	0	0	0	0	1
<i>k</i>	0	0	0	1	1	1	0



- Adjacency Matrix

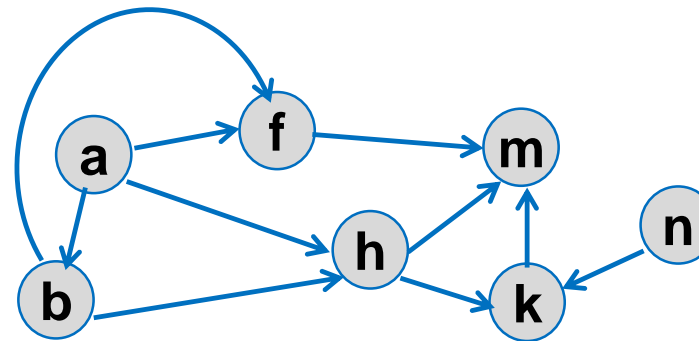


- Adjacency Matrix

-

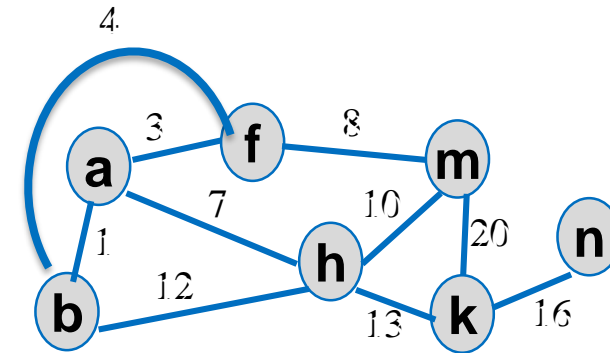
a b f h m n k

$$\begin{array}{c}
 a \\
 b \\
 f \\
 h \\
 m \\
 n \\
 k
 \end{array}
 \begin{bmatrix}
 0 & 1 & 1 & 1 & 0 & 0 & 0 \\
 0 & 0 & 1 & 1 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 1 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 1 \\
 0 & 0 & 0 & 0 & 1 & 0 & 0
 \end{bmatrix}$$



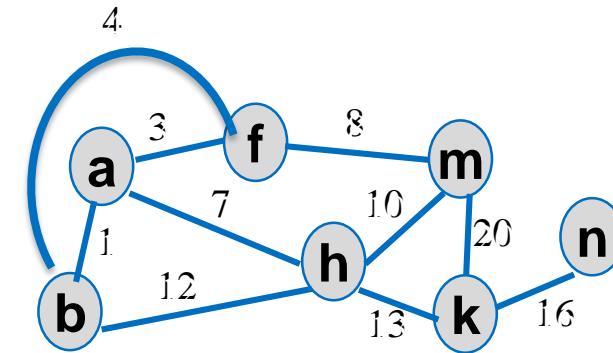
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- Adjacency Matrix



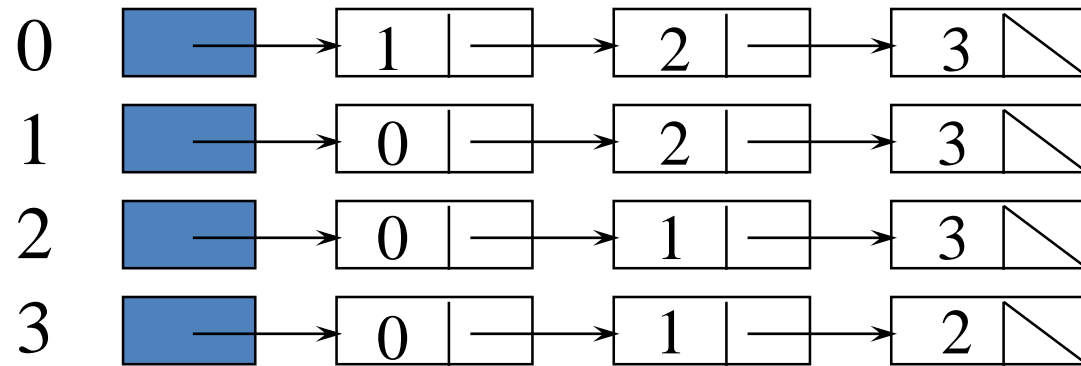
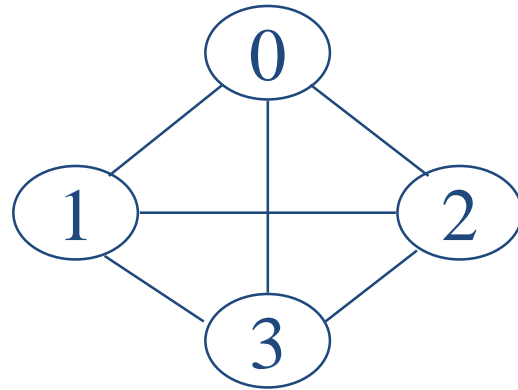
- Adjacency Matrix

	<i>a</i>	<i>b</i>	<i>f</i>	<i>h</i>	<i>m</i>	<i>n</i>	<i>k</i>
<i>a</i>	0	1	3	7	0	0	0
<i>b</i>	1	0	4	12	0	0	0
<i>f</i>	3	4	0	0	8	0	0
<i>h</i>	7	12	0	0	10	0	13
<i>m</i>	0	0	8	10	0	0	20
<i>n</i>	0	0	0	0	0	0	16
<i>k</i>	0	0	0	13	20	16	0

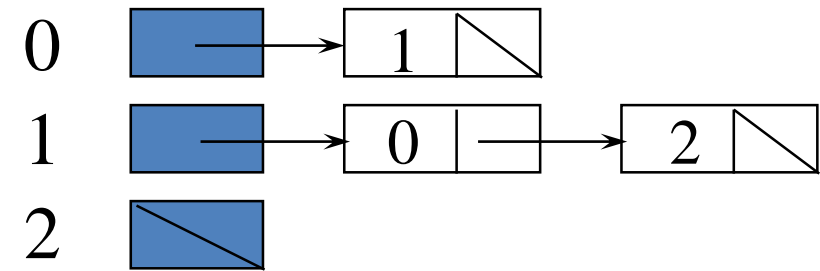
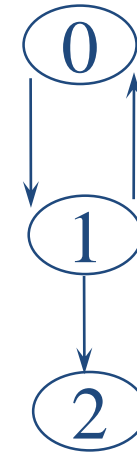


• Adjacency List

- Replace n rows of the adjacency matrix with n linked list
- Example (1)



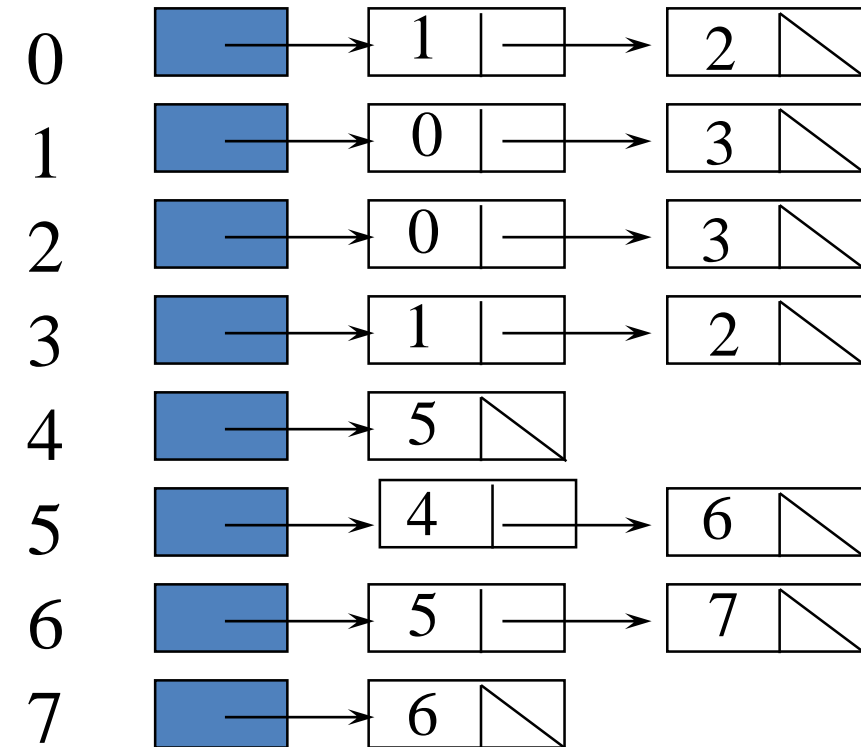
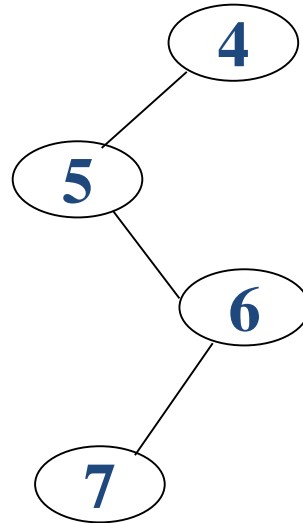
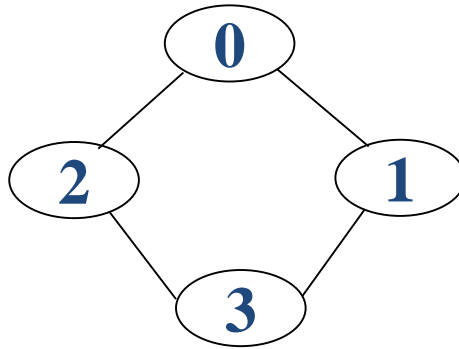
G_1



G_3

• Adjacency List

- Replace n rows of the adjacency matrix with n linked list
- Example (2)



G_4

An undirected graph with n vertices and e edges \Rightarrow n head nodes and $2e$ list nodes

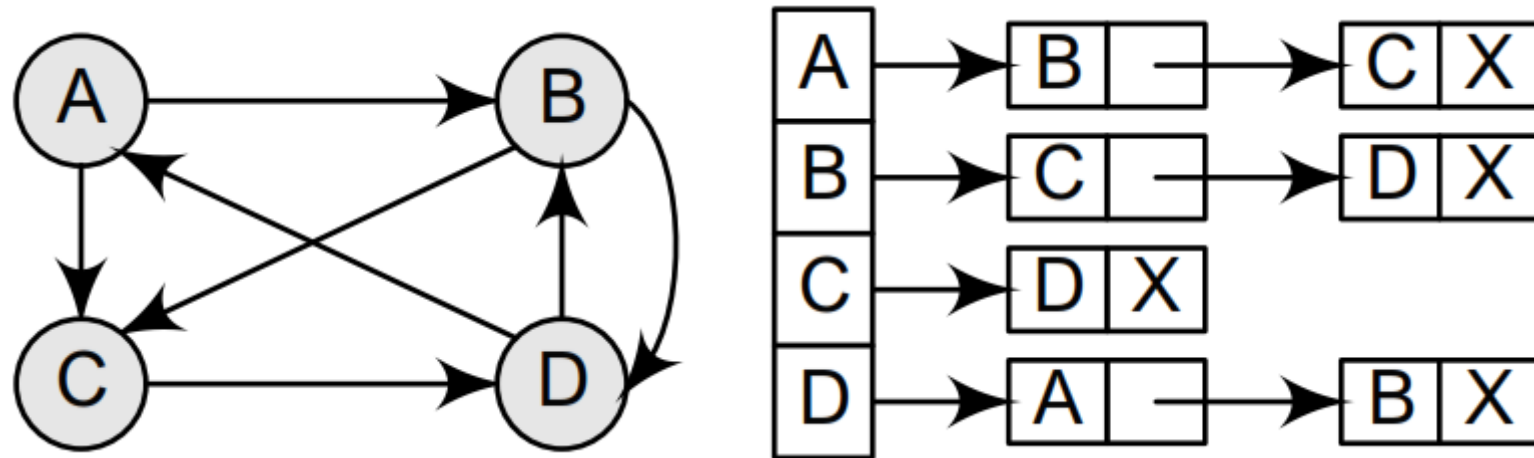
- **Adjacency List**

- Data Structures

- Each row in adjacency matrix is represented as an adjacency list

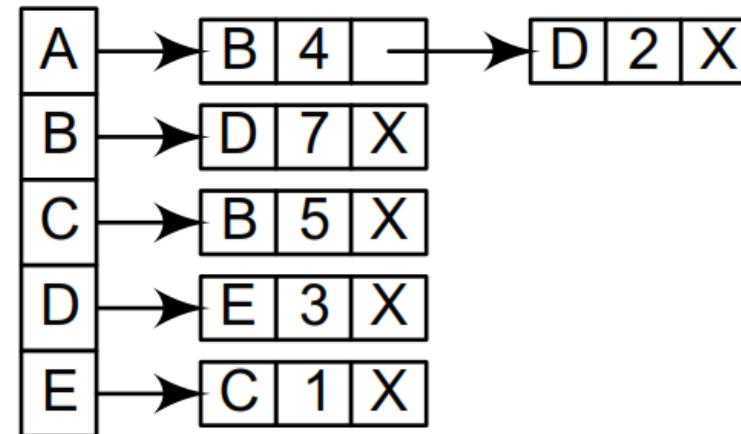
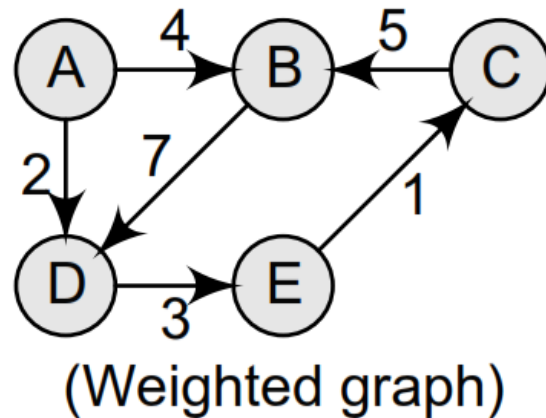
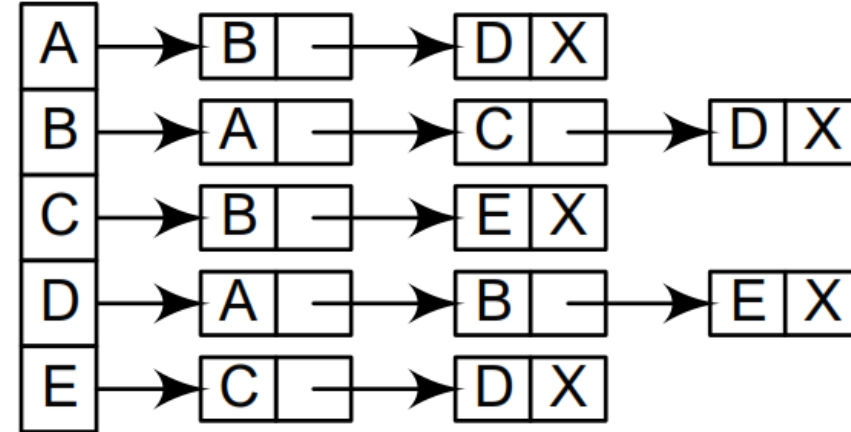
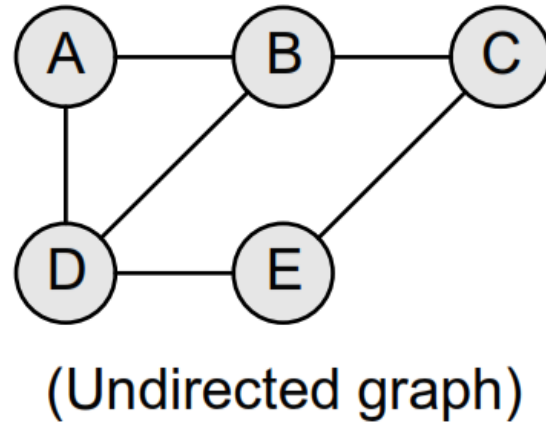
```
#define MAX_VERTICES 50
typedef struct node *node_pointer;
typedef struct node {
    int vertex;
    struct node *link;
};
node_pointer graph[MAX_VERTICES];
int n=0;      /* vertices currently in use */
```

- Adjacency List

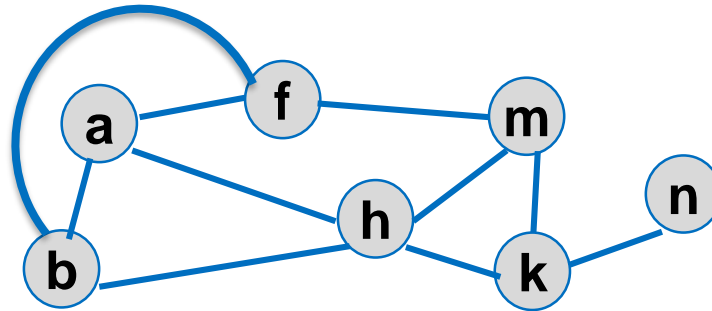


Graph G and its adjacency list

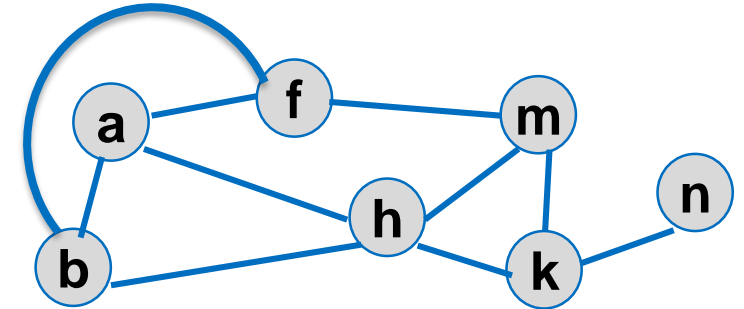
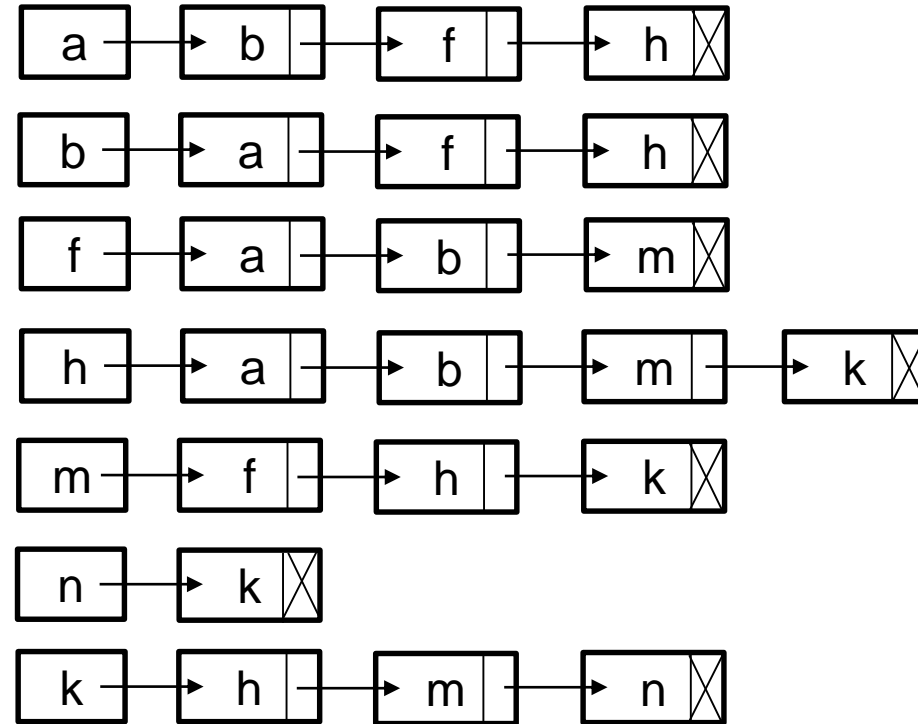
- Adjacency List



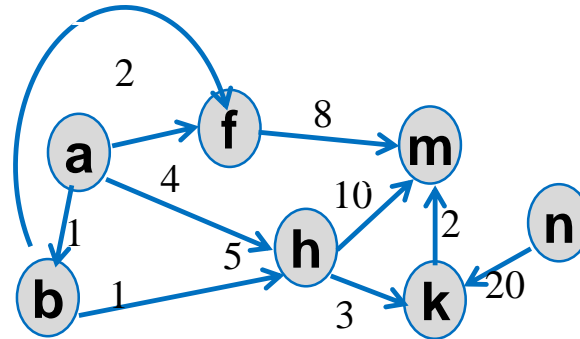
- Adjacency List



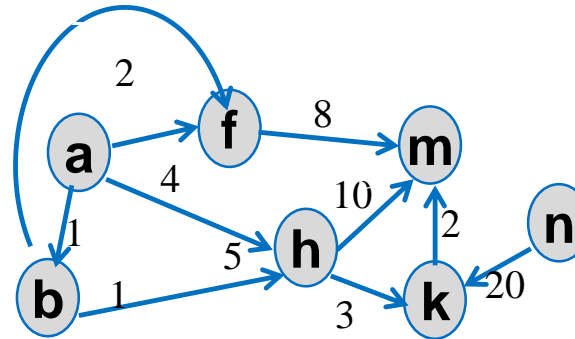
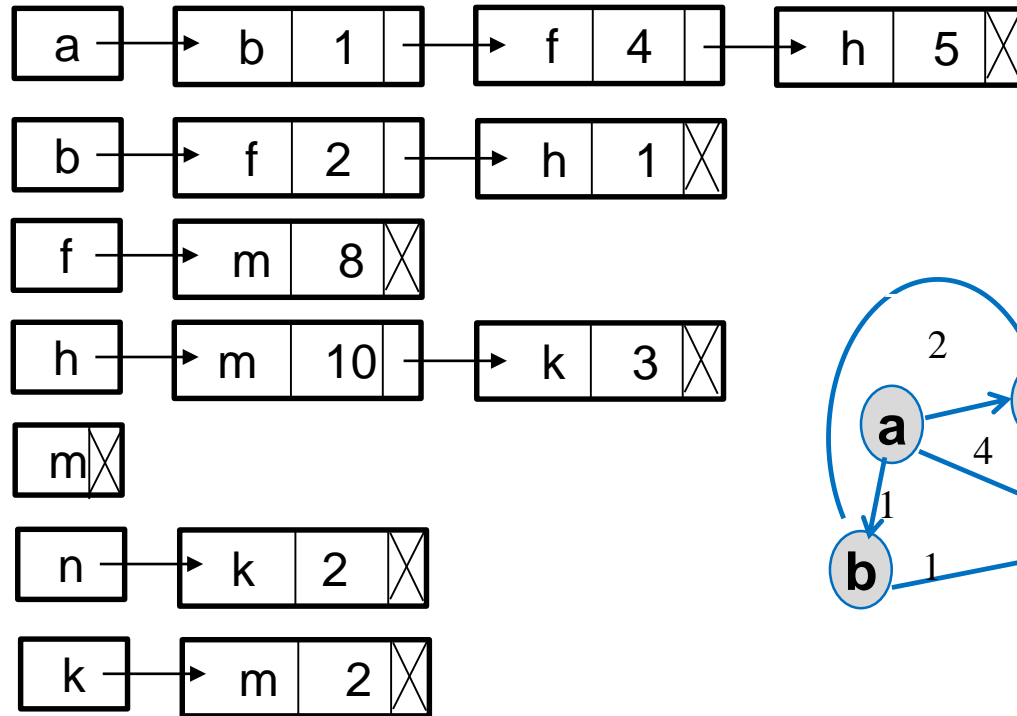
- Adjacency List



- Adjacency List



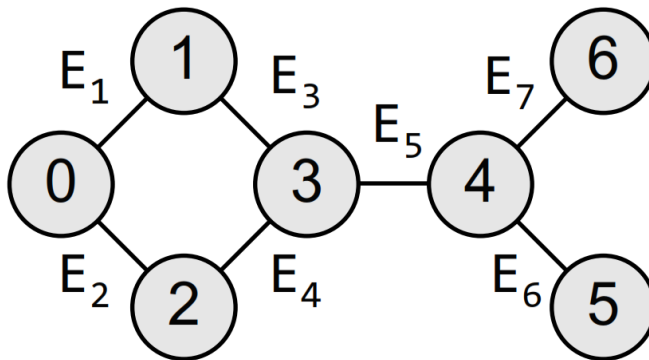
• Adjacency List



• Adjacency Multi-lists

A multi-lists representation basically consists of two parts:

- nodes' information
- linked lists storing information about edges.



VERTEX	LIST OF EDGES
0	Edge 1, Edge 2
1	Edge 1, Edge 3
2	Edge 2, Edge 4
3	Edge 3, Edge 4, Edge 5
4	Edge 5, Edge 6, Edge 7
5	Edge 6
6	Edge 7

- Terminology
- Graph Representations
- **Graph Traversals**

- **Traversal**

Given $G = (V, E)$ and vertex v , find or visit all $w \in V$, such that w connects v

- Depth First Search (DFS)
- Breadth First Search (BFS)

- **Applications**

- Connected component
- Spanning trees
- Biconnected component

- **Depth-First Search (DFS)**

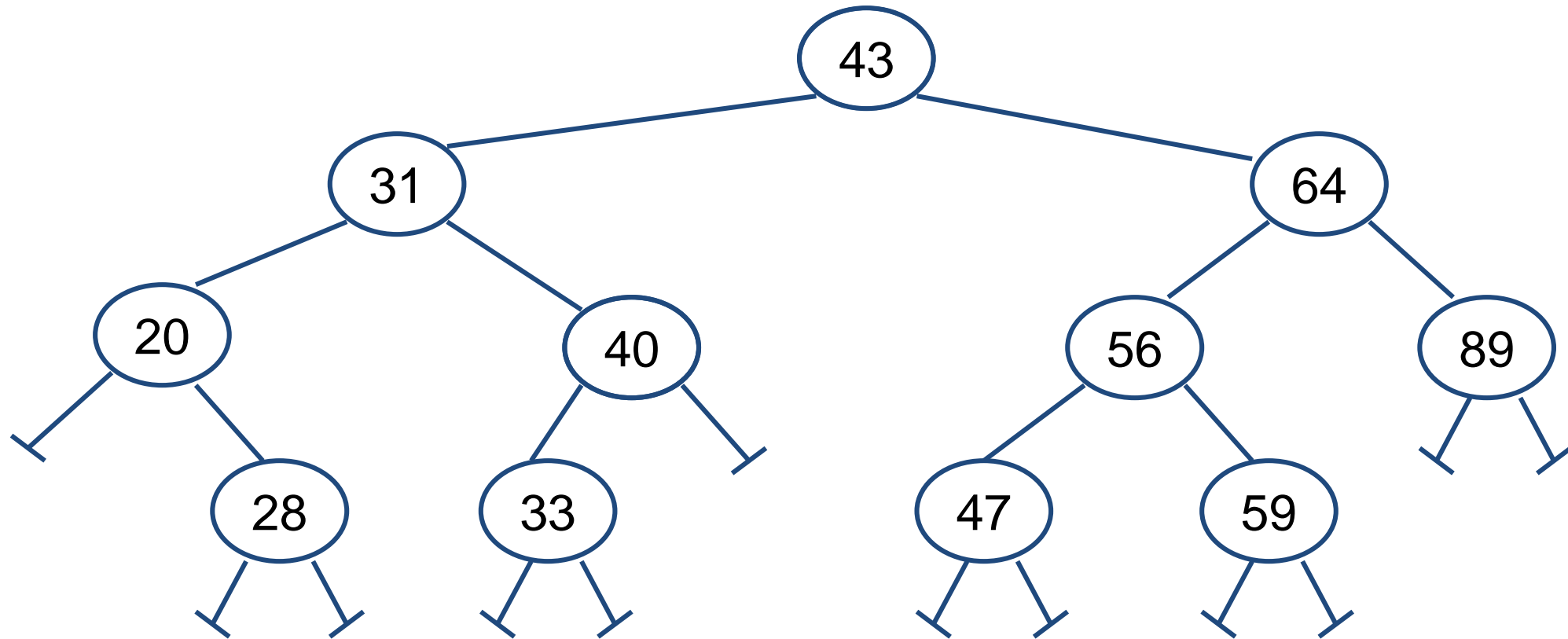
- like depth-first search in a tree, we search **as deeply as possible** by visiting a node, and then recursively performing depth-first search on each adjacent node

- **Breadth-First Search (BFS)**

- like breadth-first search in a tree, we search **as broadly as possible** by visiting a node, and then immediately visiting all nodes adjacent to that node

- Depth First Search (DFS)
 - Begin the search by visiting the start vertex v
 - If v has an unvisited neighbor, traverse it recursively
 - Otherwise, backtrack
 - Very similar to preorder traversal of a binary tree (node, left, right)

- Example: Preorder



43	31	20	28	40	33	64	56	47	59	89
----	----	----	----	----	----	----	----	----	----	----

- **Algorithm**

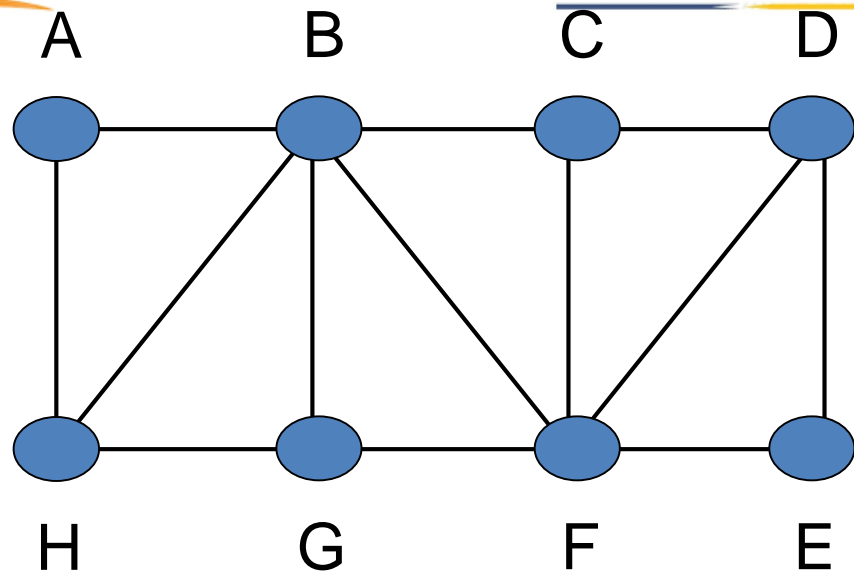
```

Depth_First_Search (VERTEX V){
    Visit V;
    Set the visit flag for the vertex V to TRUE;
    For all adjacent vertices  $V_i$  ( $i = 1, 2, \dots, n$ ) of V
        If ( $V_i$  has not been previously visited)
            Depth_First_Search ( $V_i$ )
    }
    
```

- Time is $O(n + e)$ for adjacency lists
- Time is $O(n^2)$ for adjacency matrices

```
#define FALSE 0
#define TRUE 1
short int visited[MAX_VERTICES];

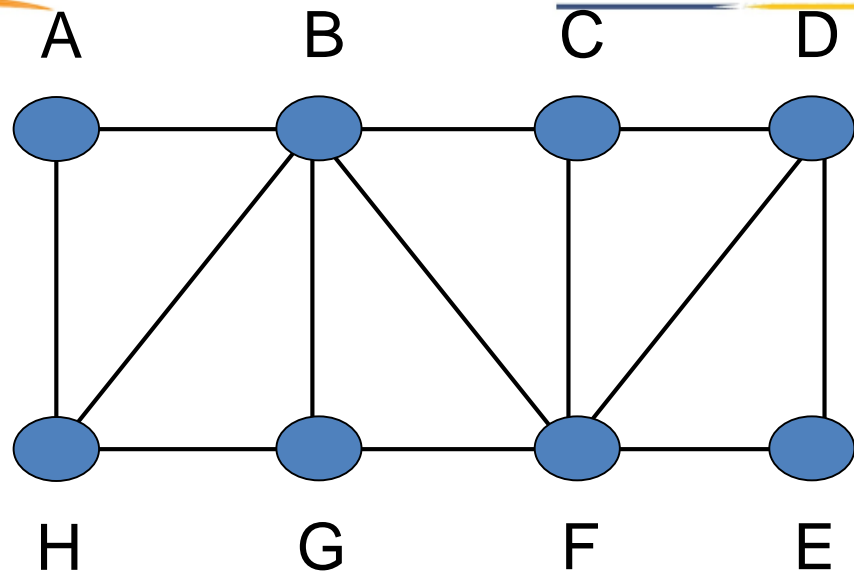
/* graph is represented as an adjacency list */
void dfs(int v){
    node_pointer w;
    visited[v]= TRUE;
    printf("%5d", v);
    for (w=graph[v]; w; w=w->link)
        if (!visited[w->vertex])
            dfs(w->vertex);
}
```



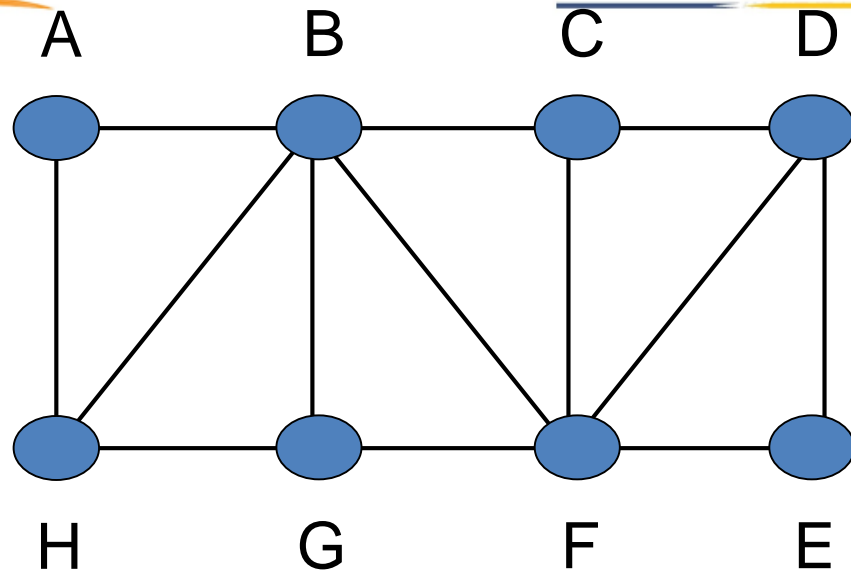
Vertex

Adjacent Vertices

A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G



Vertex (label, visited?)	Adjacent Vertices
A <i>F</i> →	B, H
B <i>F</i> →	A, C, G, F, H
C <i>F</i> →	B, D, F
D <i>F</i> →	C, E, F
E <i>F</i> →	D, F
F <i>F</i> →	B, C, D, E, G
G <i>F</i> →	B, F, H
H <i>F</i> →	A, B, G



Depth_First_Search (VERTEX V)

{
Visit V;

Set the visit flag for the vertex V to TRUE;

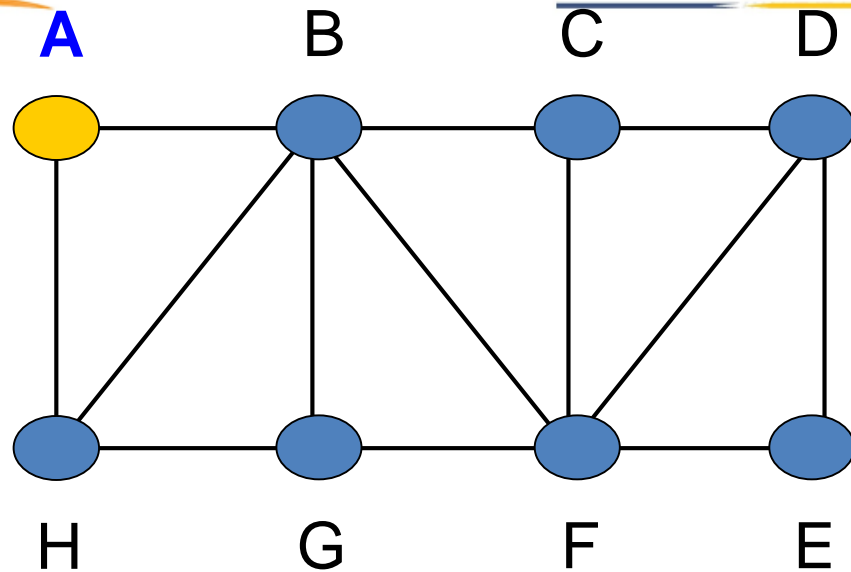
For all adjacent vertices V_i ($i = 1, 2, \dots, n$) of V
if (V_i has not been previously visited)
 Depth_First_Search (V_i)

}

Vertex
(label, visited?)

Adjacent Vertices

A F	→	B, H
B F	→	A, C, G, F, H
C F	→	B, D, F
D F	→	C, E, F
E F	→	D, F
F F	→	B, C, D, E, G
G F	→	B, F, H
H F	→	A, B, G



Depth_First_Search (VERTEX V)

{

Visit V;

Set the visit flag for the vertex V to TRUE;

For all adjacent vertices V_i ($i = 1, 2, \dots, n$) of V
if (V_i has not been previously visited)
 Depth_First_Search (V_i)

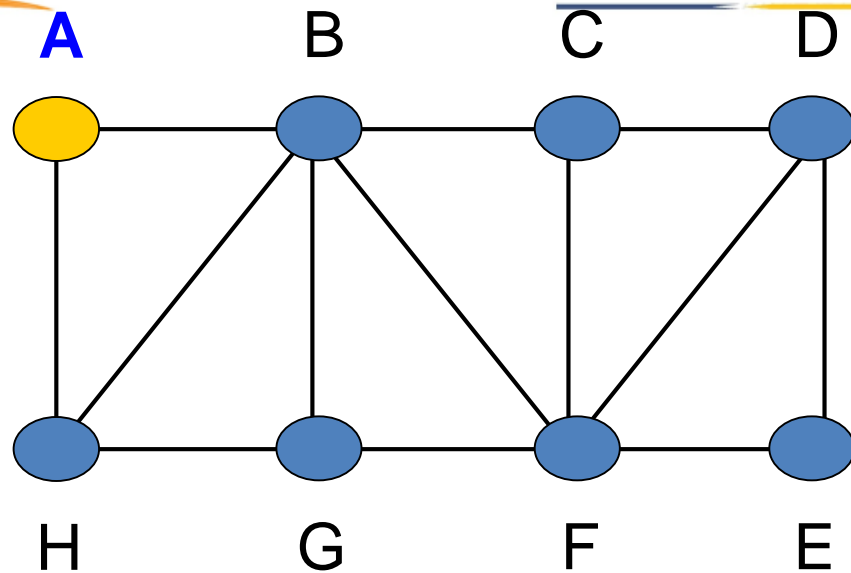
}

Vertex
(label, visited?)

Adjacent Vertices

A F	→	B, H
B F	→	A, C, G, F, H
C F	→	B, D, F
D F	→	C, E, F
E F	→	D, F
F F	→	B, C, D, E, G
G F	→	B, F, H
H F	→	A, B, G

A



Depth_First_Search (VERTEX V)

{
Visit V;

Set the visit flag for the vertex V to TRUE;

For all adjacent vertices V_i ($i = 1, 2, \dots, n$) of V
if (V_i has not been previously visited)
 Depth_First_Search (V_i)

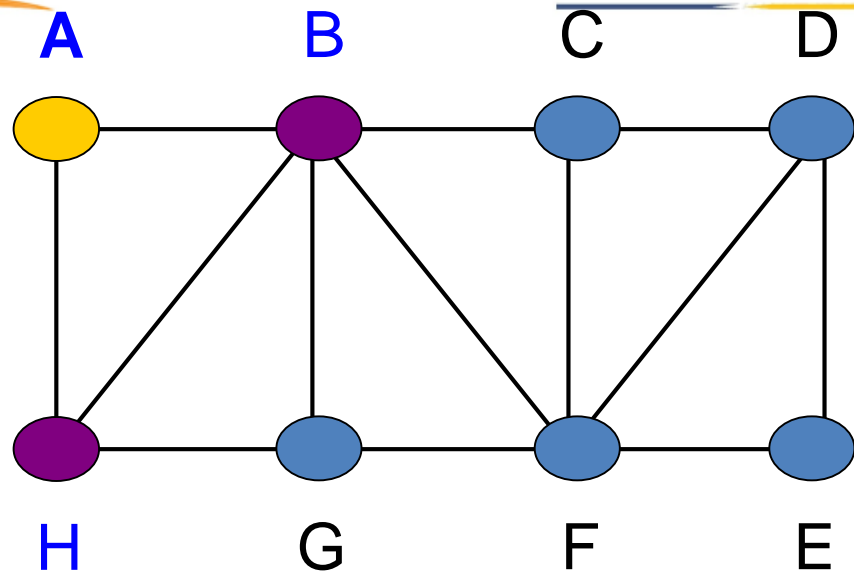
}

Vertex
(label, visited?)

Adjacent Vertices

A <i>T</i>	→	B, H
B <i>F</i>	→	A, C, G, F, H
C <i>F</i>	→	B, D, F
D <i>F</i>	→	C, E, F
E <i>F</i>	→	D, F
F <i>F</i>	→	B, C, D, E, G
G <i>F</i>	→	B, F, H
H <i>F</i>	→	A, B, G

A



Depth_First_Search (VERTEX V)

{
Visit V;

Set the visit flag for the vertex V to TRUE;

For all adjacent vertices V_i ($i = 1, 2, \dots, n$) of V
if (V_i has not been previously visited)
 Depth_First_Search (V_i)

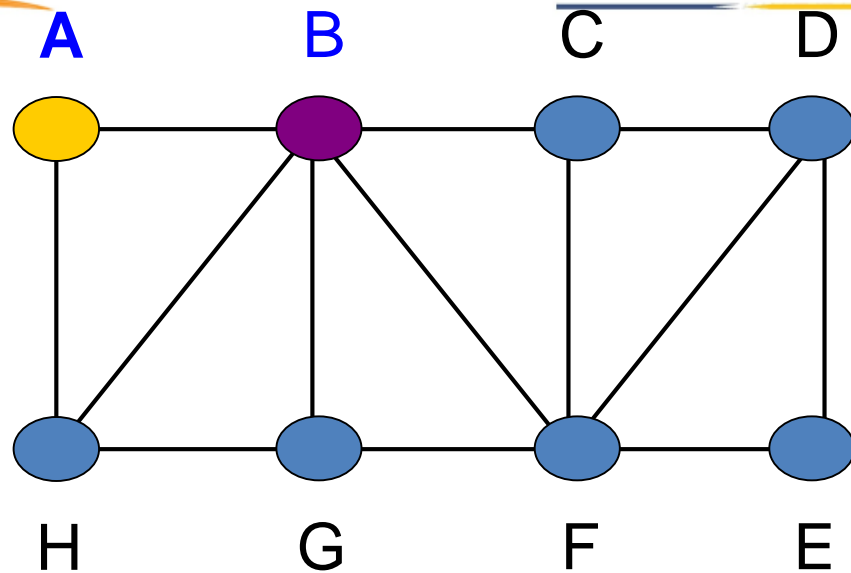
}

Vertex
(label, visited?)

Adjacent Vertices

A <i>T</i>	→	B, H
B <i>F</i>	→	A, C, G, F, H
C <i>F</i>	→	B, D, F
D <i>F</i>	→	C, E, F
E <i>F</i>	→	D, F
F <i>F</i>	→	B, C, D, E, G
G <i>F</i>	→	B, F, H
H <i>F</i>	→	A, B, G

A



```

Depth_First_Search (VERTEX V)
{
    Visit V;

    Set the visit flag for the vertex V to TRUE;

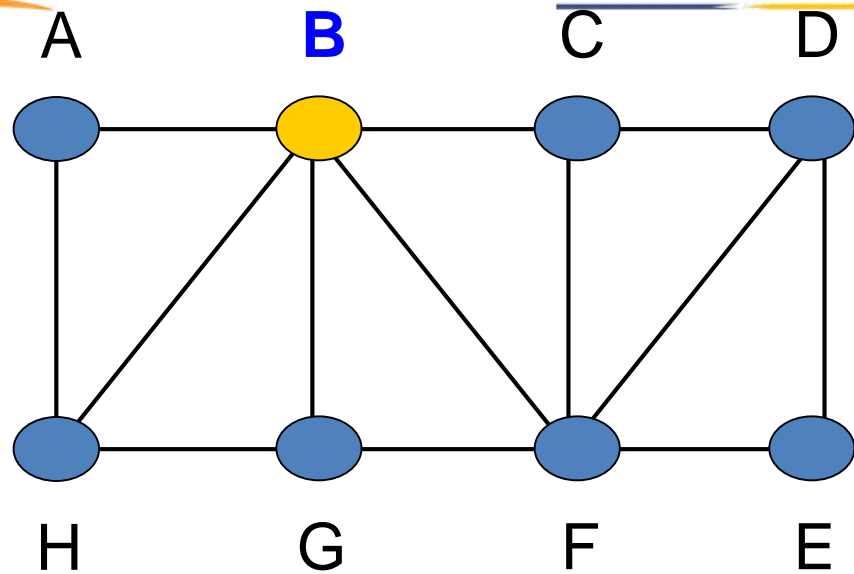
    For all adjacent vertices Vi (i = 1, 2, ....., n) of V
        if (Vi has not been previously visited)
            Depth_First_Search (Vi)
}
    
```

Vertex
(label, visited?)

Adjacent Vertices

A <i>T</i>	→	B , H
B <i>F</i>	→	A, C, G, F, H
C <i>F</i>	→	B, D, F
D <i>F</i>	→	C, E, F
E <i>F</i>	→	D, F
F <i>F</i>	→	B, C, D, E, G
G <i>F</i>	→	B, F, H
H <i>F</i>	→	A, B, G

A



```

Depth_First_Search (VERTEX V)
{
    Visit V;

    Set the visit flag for the vertex V to TRUE;

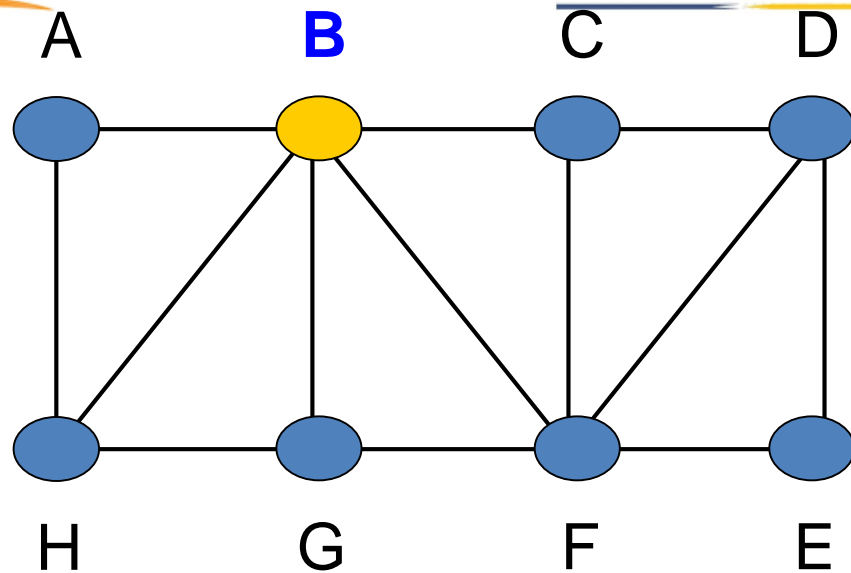
    For all adjacent vertices  $V_i$  ( $i = 1, 2, \dots, n$ ) of V
        if ( $V_i$  has not been previously visited)
            Depth_First_Search ( $V_i$ )
}
    
```

Vertex
(label, visited?)

Adjacent Vertices

A <i>T</i>	→	B, H
B <i>F</i>	→	A, C, G, F, H
C <i>F</i>	→	B, D, F
D <i>F</i>	→	C, E, F
E <i>F</i>	→	D, F
F <i>F</i>	→	B, C, D, E, G
G <i>F</i>	→	B, F, H
H <i>F</i>	→	A, B, G

A



Depth_First_Search (VERTEX V)

{

Visit V;

Set the visit flag for the vertex V to TRUE;

For all adjacent vertices V_i ($i = 1, 2, \dots, n$) of V
if (V_i has not been previously visited)
 Depth_First_Search (V_i)

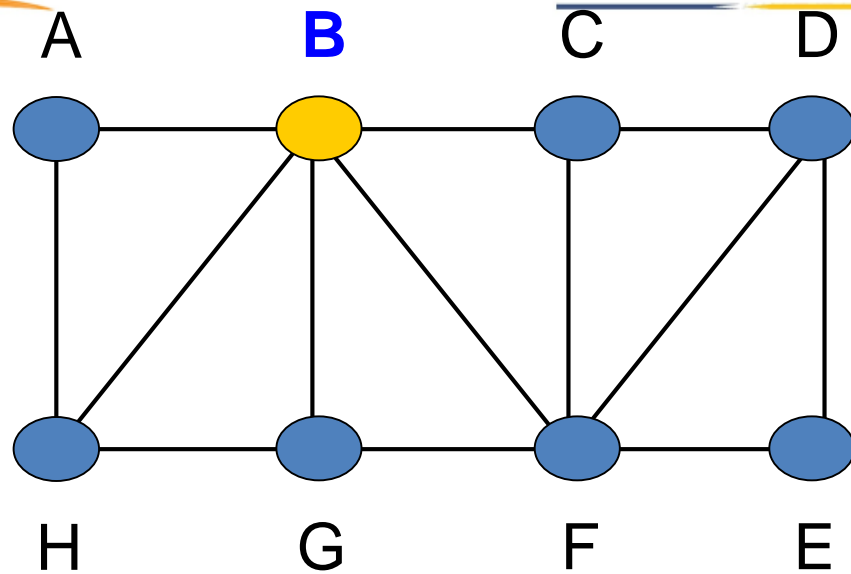
}

Vertex
(label, visited?)

Adjacent Vertices

A <i>T</i>	→	B, H
B <i>F</i>	→	A, C, G, F, H
C <i>F</i>	→	B, D, F
D <i>F</i>	→	C, E, F
E <i>F</i>	→	D, F
F <i>F</i>	→	B, C, D, E, G
G <i>F</i>	→	B, F, H
H <i>F</i>	→	A, B, G

A B



Depth_First_Search (VERTEX V)

{
Visit V;

Set the visit flag for the vertex V to TRUE;

For all adjacent vertices V_i ($i = 1, 2, \dots, n$) of V
if (V_i has not been previously visited)
 Depth_First_Search (V_i)

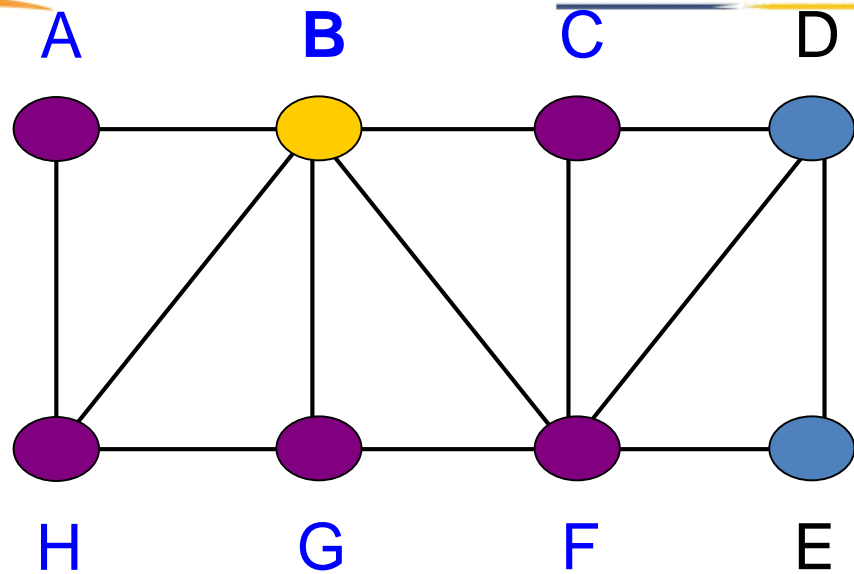
}

Vertex
(label, visited?)

Adjacent Vertices

A <i>T</i>	→	B, H
B <i>T</i>	→	A, C, G, F, H
C <i>F</i>	→	B, D, F
D <i>F</i>	→	C, E, F
E <i>F</i>	→	D, F
F <i>F</i>	→	B, C, D, E, G
G <i>F</i>	→	B, F, H
H <i>F</i>	→	A, B, G

A B



```

Depth_First_Search (VERTEX V)
{
    Visit V;

    Set the visit flag for the vertex V to TRUE;

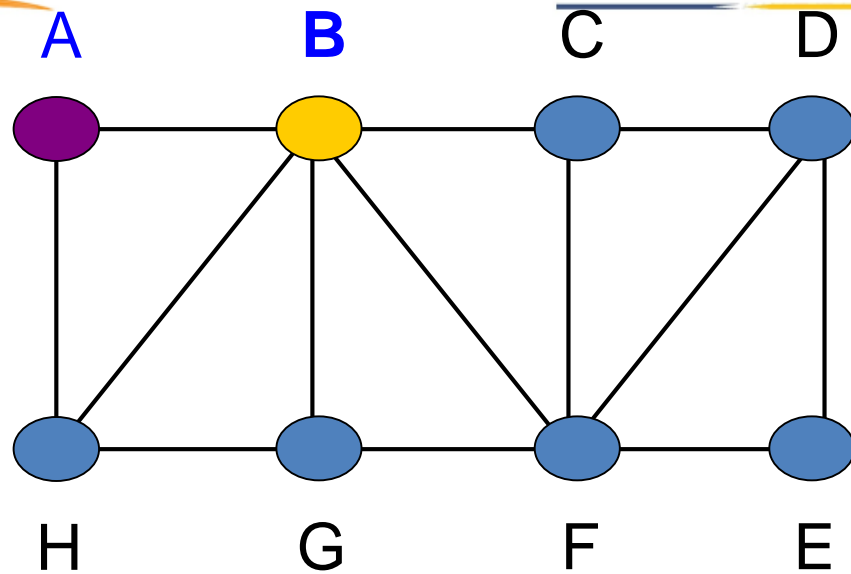
    For all adjacent vertices Vi (i = 1, 2, ....., n) of V
        if (Vi has not been previously visited)
            Depth_First_Search (Vi)
}
    
```

Vertex
(label, visited?)

Adjacent Vertices

A	T	→	B, H
B	T	→	A, C, G, F, H
C	F	→	B, D, F
D	F	→	C, E, F
E	F	→	D, F
F	F	→	B, C, D, E, G
G	F	→	B, F, H
H	F	→	A, B, G

A B



```

Depth_First_Search (VERTEX V)
{
    Visit V;

    Set the visit flag for the vertex V to TRUE;

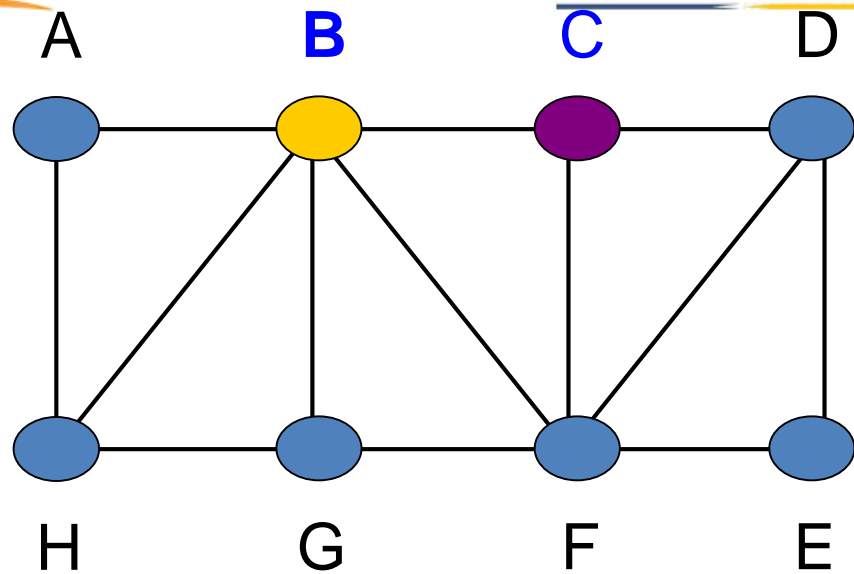
    For all adjacent vertices  $V_i$  ( $i = 1, 2, \dots, n$ ) of V
        if ( $V_i$  has not been previously visited)
            Depth_First_Search ( $V_i$ )
}
    
```

Vertex
(label, visited?)

Adjacent Vertices

A T	→	B, H
B T	→	A, C, G, F, H
C F	→	B, D, F
D F	→	C, E, F
E F	→	D, F
F F	→	B, C, D, E, G
G F	→	B, F, H
H F	→	A, B, G

A B



```

Depth_First_Search (VERTEX V)
{
    Visit V;

    Set the visit flag for the vertex V to TRUE;

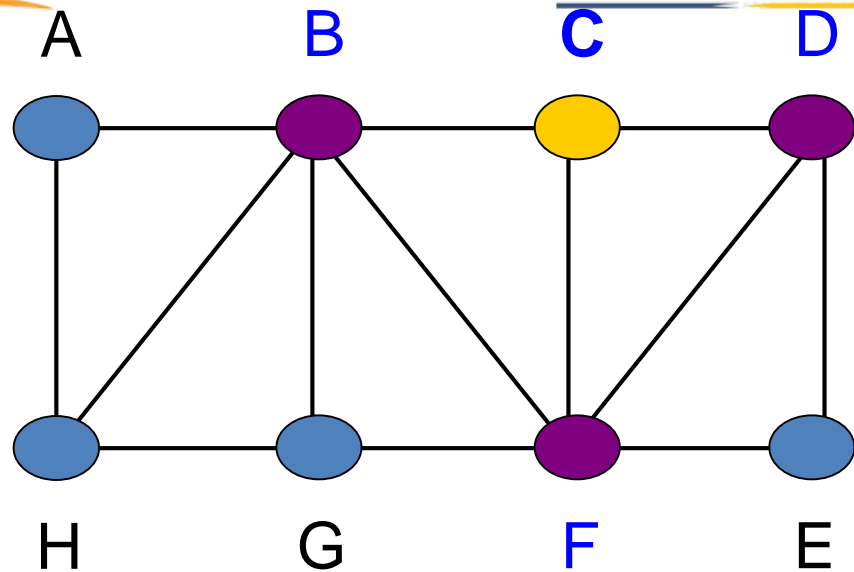
    For all adjacent vertices Vi (i = 1, 2, ....., n) of V
        if (Vi has not been previously visited)
            Depth_First_Search (Vi)
}
    
```

Vertex
(label, visited?)

Adjacent Vertices

A	T	→	B, H
B	T	→	A, C, G, F, H
C	F	→	B, D, F
D	F	→	C, E, F
E	F	→	D, F
F	F	→	B, C, D, E, G
G	F	→	B, F, H
H	F	→	A, B, G

A B



```

Depth_First_Search (VERTEX V)
{
    Visit V;

    Set the visit flag for the vertex V to TRUE;

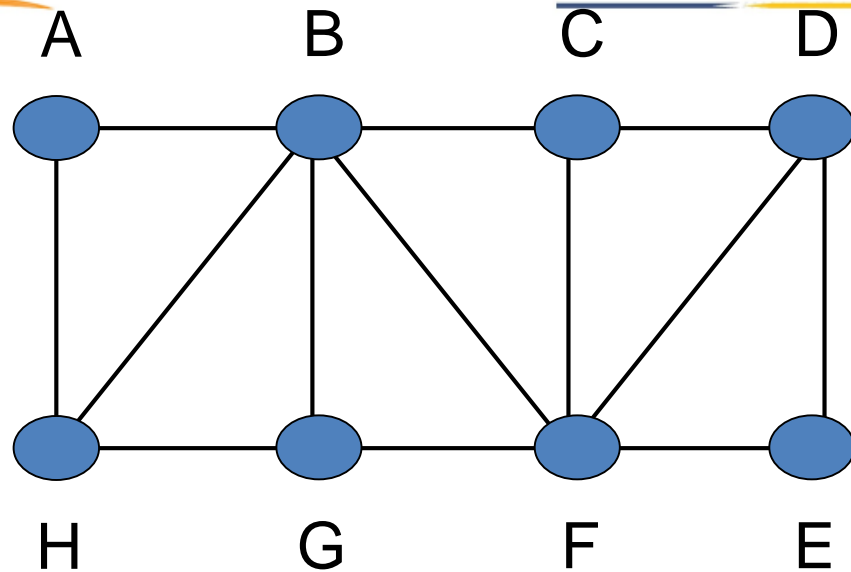
    For all adjacent vertices  $V_i$  ( $i = 1, 2, \dots, n$ ) of V
        if ( $V_i$  has not been previously visited)
            Depth_First_Search ( $V_i$ )
}
    
```

Vertex
(label, visited?)

Adjacent Vertices

A	T	→	B, H
B	T	→	A, C, G, F, H
C	T	→	B, D, F
D	F	→	C, E, F
E	F	→	D, F
F	F	→	B, C, D, E, G
G	F	→	B, F, H
H	F	→	A, B, G

A B C



```

Depth_First_Search (VERTEX V)
{
    Visit V;

    Set the visit flag for the vertex V to TRUE;

    For all adjacent vertices  $V_i$  ( $i = 1, 2, \dots, n$ ) of V
        if ( $V_i$  has not been previously visited)
            Depth_First_Search ( $V_i$ )
}
    
```

Vertex
(label, visited?)

Adjacent Vertices

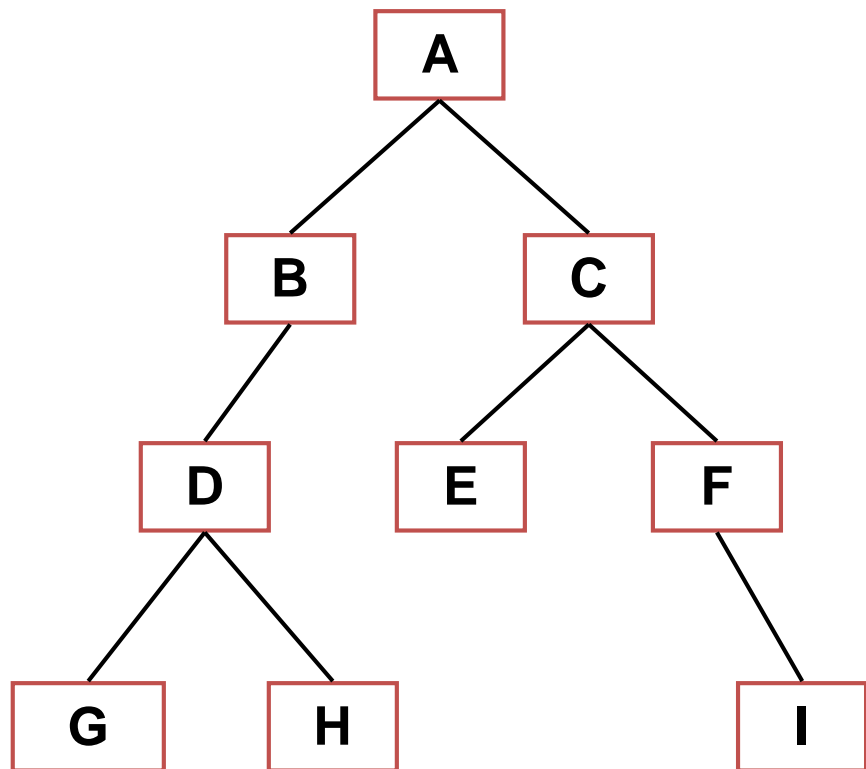
A T	→	B, H
B T	→	A, C, G, F, H
C T	→	B, D, F
D T	→	C, E, F
E T	→	D, F
F T	→	B, C, D, E, G
G T	→	B, F, H
H T	→	A, B, G

A B C D E F G H

- **Breadth First Search (BFS)**
 - Very similar to level-order traversal of a binary tree (left, node, right)
 - Use a *queue* to track unvisited nodes
 - For each node that is deleted from the queue,
 - add each of its children to the queue
 - until the queue is empty

...Graph Traversals – Breadth First Search

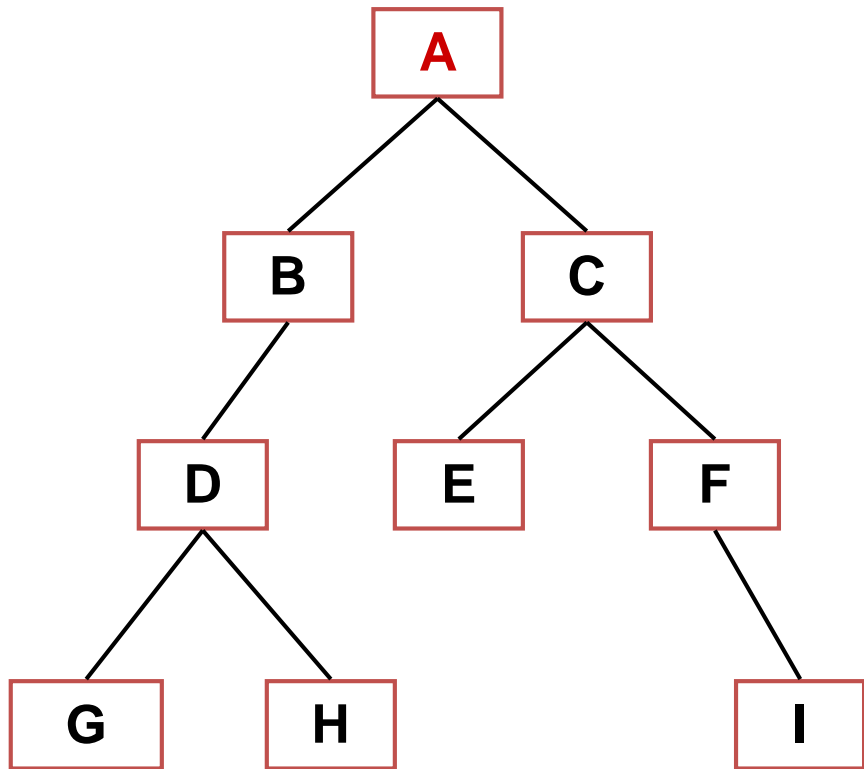
Level-Order



Queue

Output

Level-Order

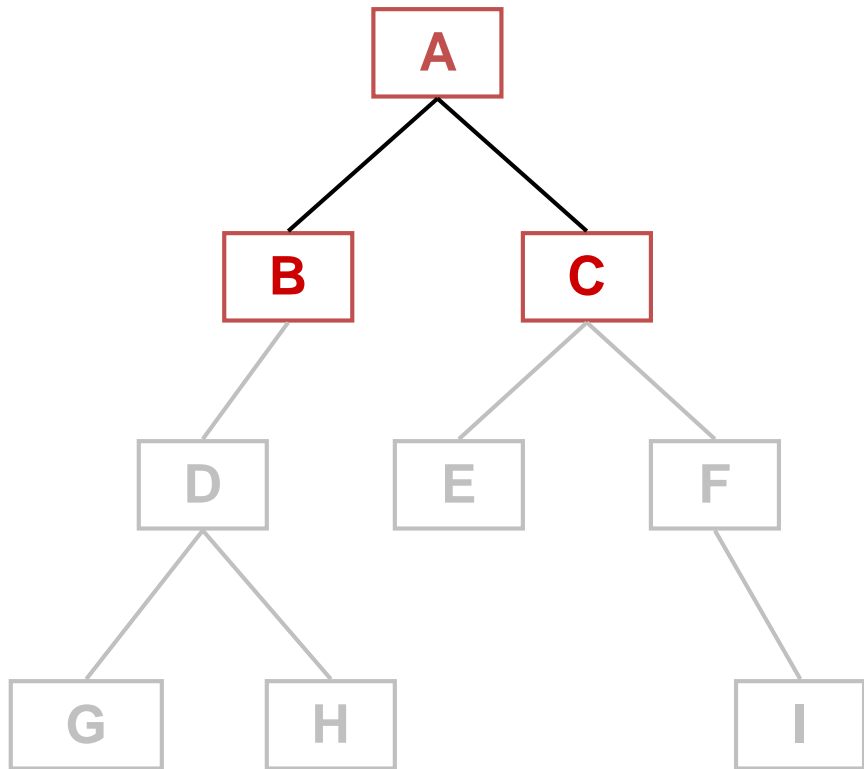


Init

Queue
[**A**]

Output
-

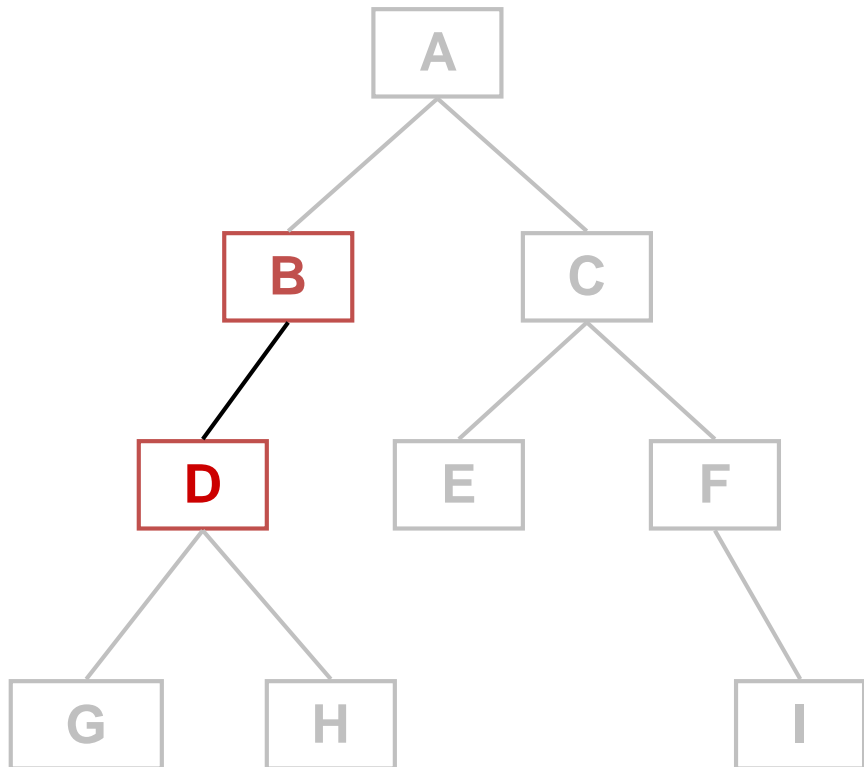
Level-Order



	Queue	Output
Init	[A]	-
Step 1	[B,C]	A

Dequeue A
Print A
Enqueue children of A

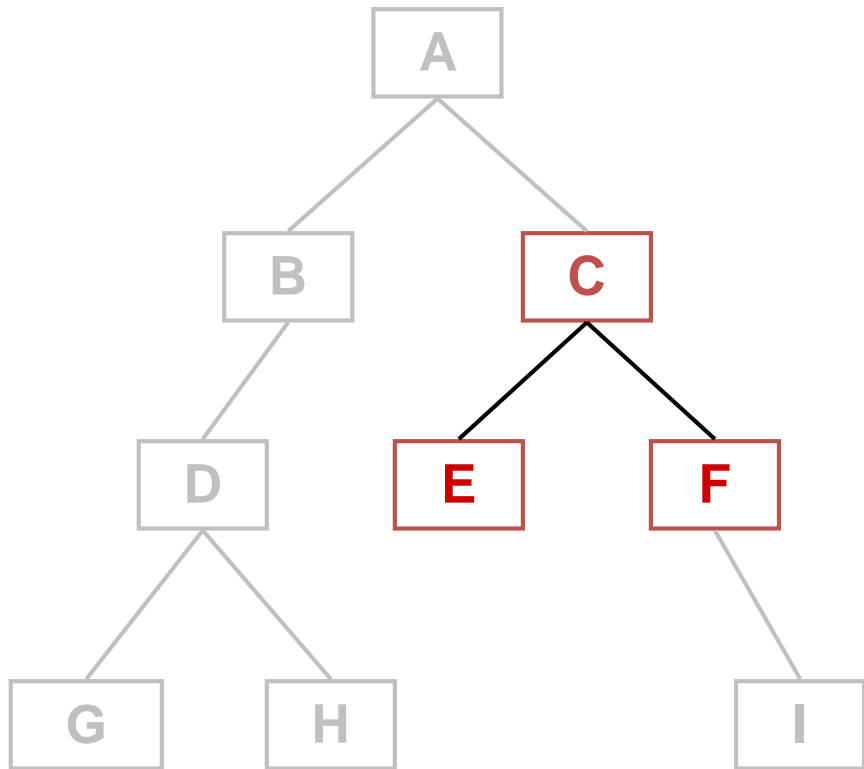
Level-Order



	Queue	Output
Init	[A]	-
Step 1	[B ,C]	A
Step 2	[C, D]	A B

Dequeue B
Print B
Enqueue children of B

Level-Order

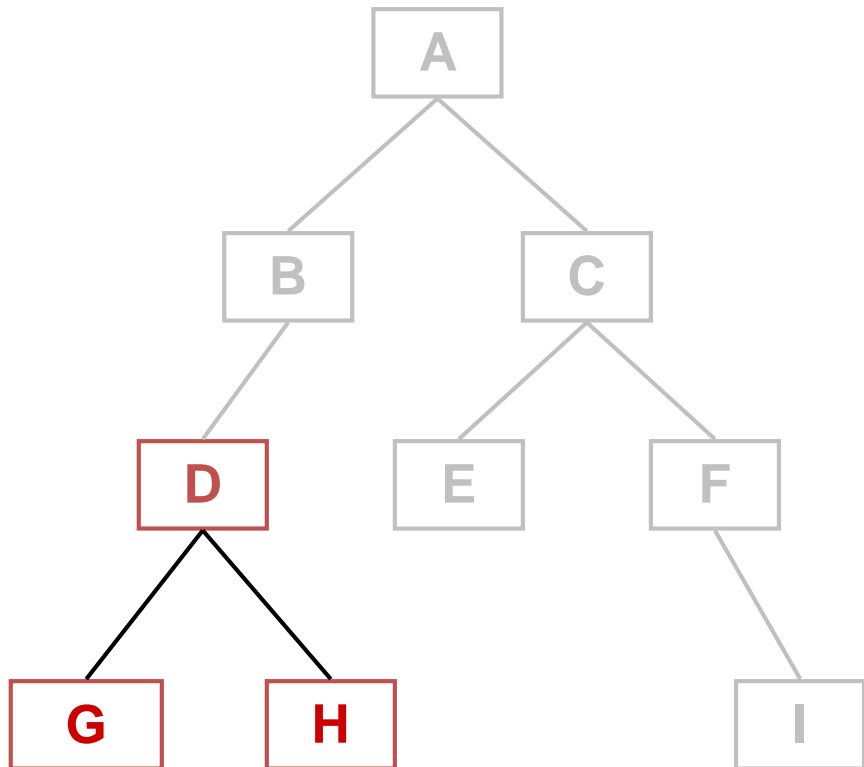


	Queue	Output
Init	[A]	-
Step 1	[B,C]	A
Step 2	[C ,D]	A B
Step 3	[D, E , F]	A B C

Dequeue C
Print C
Enqueue children of C

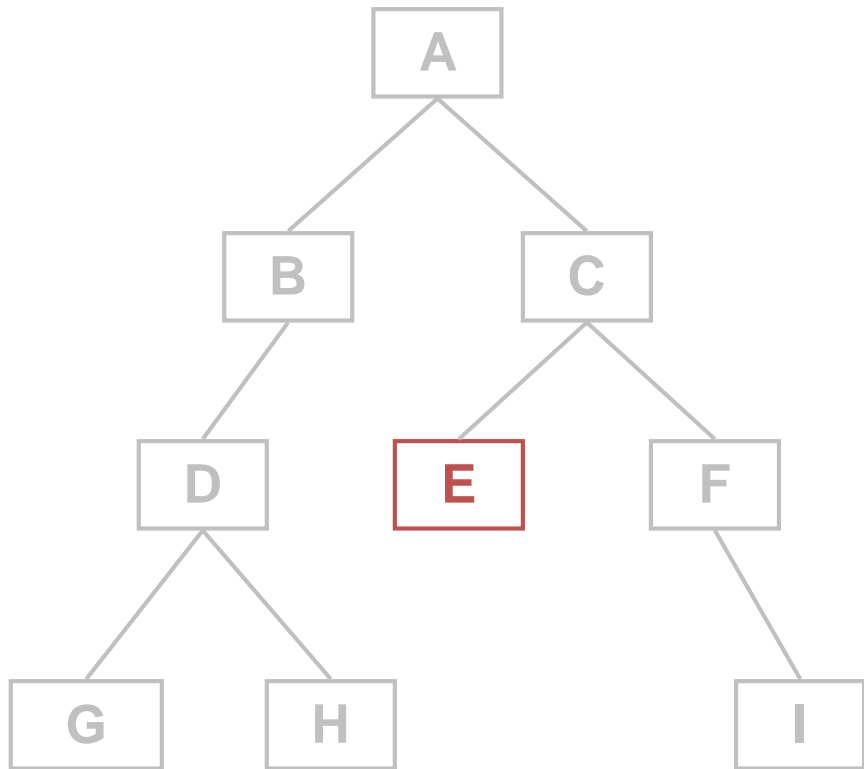
...

Level-Order



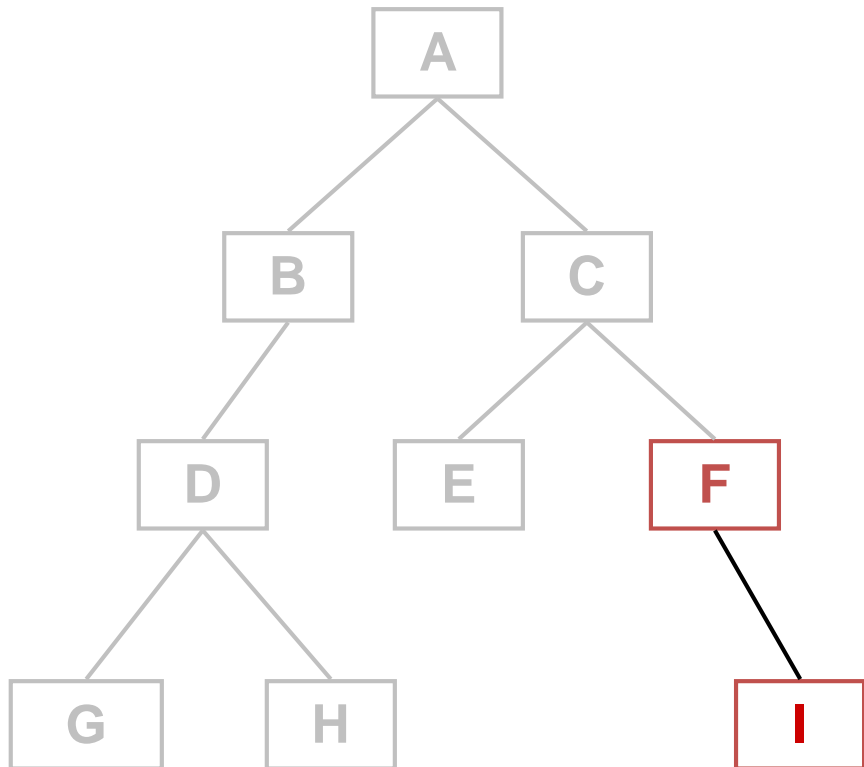
	Queue	Output
Init	[A]	-
Step 1	[B,C]	A
Step 2	[C,D]	A B
Step 3	[D ,E,F]	A B C
Step 4	[E,F, G , H]	A B C D

Level-Order



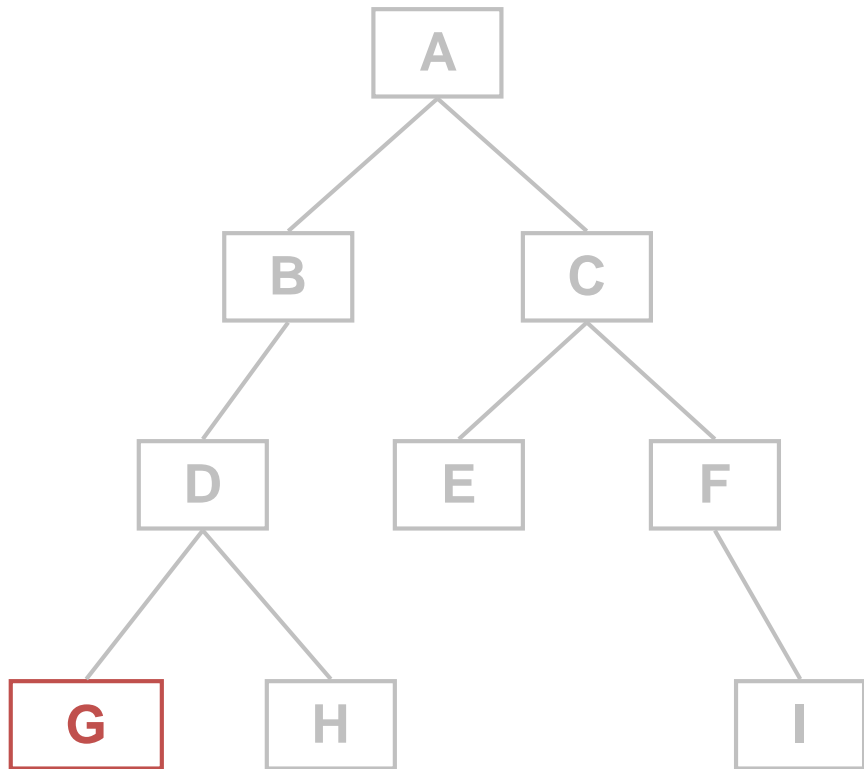
	Queue	Output
Init	[A]	-
Step 1	[B,C]	A
Step 2	[C,D]	A B
Step 3	[D,E,F]	A B C
Step 4	[E ,F,G,H]	A B C D
Step 5	[F,G,H]	A B C D E

Level-Order



	Queue	Output
Init	[A]	-
Step 1	[B,C]	A
Step 2	[C,D]	A B
Step 3	[D,E,F]	A B C
Step 4	[E,F,G,H]	A B C D
Step 5	[F,G,H]	A B C D E
Step 6	[G,H,I]	A B C D E F

Level-Order



	Queue	Output
Init	[A]	-
Step 1	[B,C]	A
Step 2	[C,D]	A B
Step 3	[D,E,F]	A B C
Step 4	[E,F,G,H]	A B C D
Step 5	[F,G,H]	A B C D E
Step 6	[G ,H,I]	A B C D E F
Step 7	[H,I]	A B C D E F G

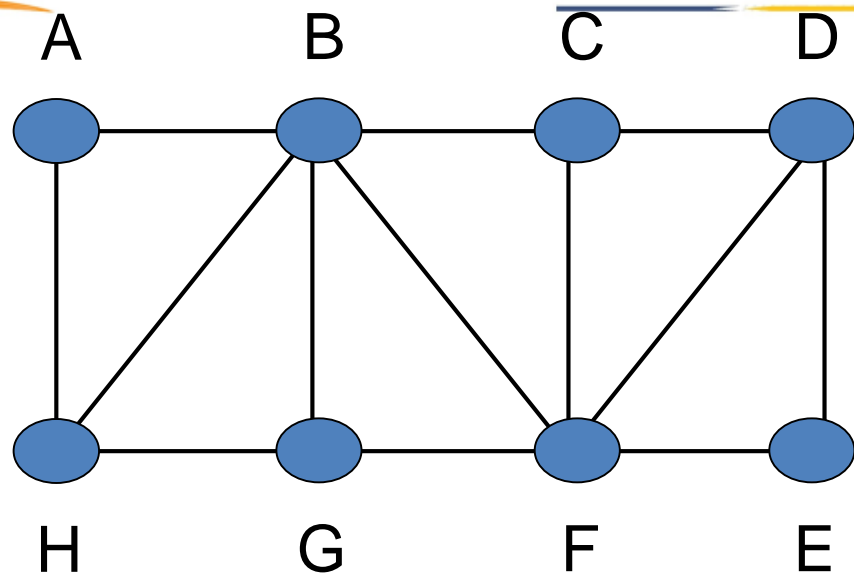
- **Algorithm**

```
bfs(v) { /* v is the starting vertex */  
    push v into an empty queue Q;  
    while Q is not empty do  
        v = delete(Q);  
        if v is not visited {  
            mark v as visited;  
            push v's neighbors into Q;  
        }  
    }  
}
```

- Time is $O(e)$ for adjacency lists and $O(n^2)$ for adjacency matrices

```
typedef struct queue *queue_pointer;  
typedef struct queue {  
    int vertex;  
    queue_pointer link;  
};  
void addq(queue_pointer *, queue_pointer *, int);  
int deleteq(queue_pointer *);
```

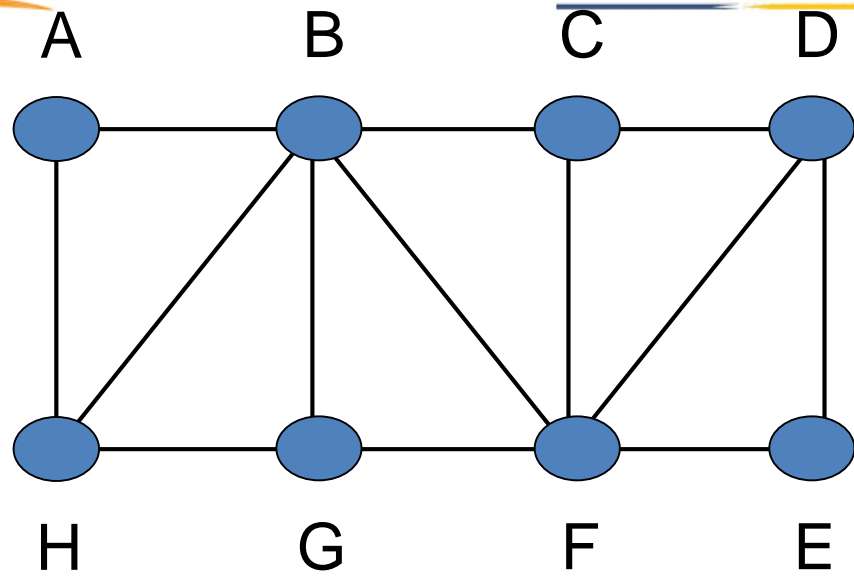
```
void bfs(int v){
    node_pointer w;
    queue_pointer front, rear;
    front = rear = NULL;
    printf("%5d", v);
    visited[v] = TRUE;
    addq(&front, &rear, v);
    while (front) {
        v = deleteq(&front);
        for (w=graph[v]; w; w=w->link)
            if (!visited[w->vertex]) {
                printf("%5d", w->vertex);
                addq(&front, &rear, w->vertex);
                visited[w->vertex] = TRUE;
            }
    }
}
```



Vertex

Adjacent Vertices

A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G



Vertex

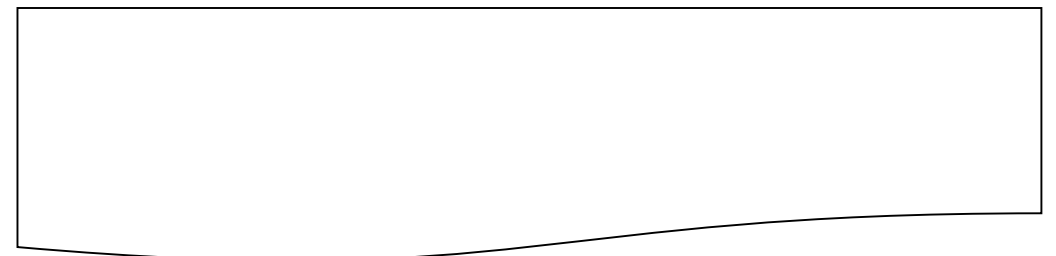
Adjacent Vertices

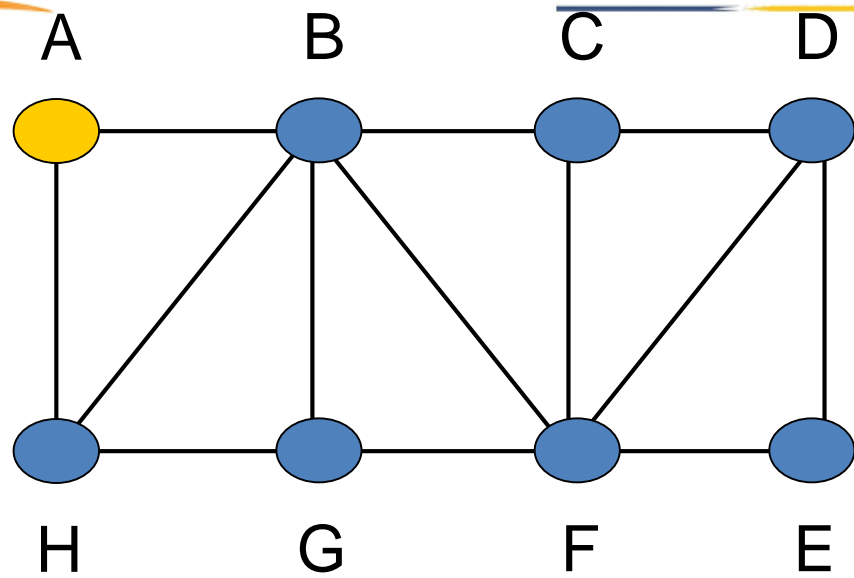
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [F, F, F, F, F, F, F, F]

Q: []

V:





Vertex

Adjacent Vertices

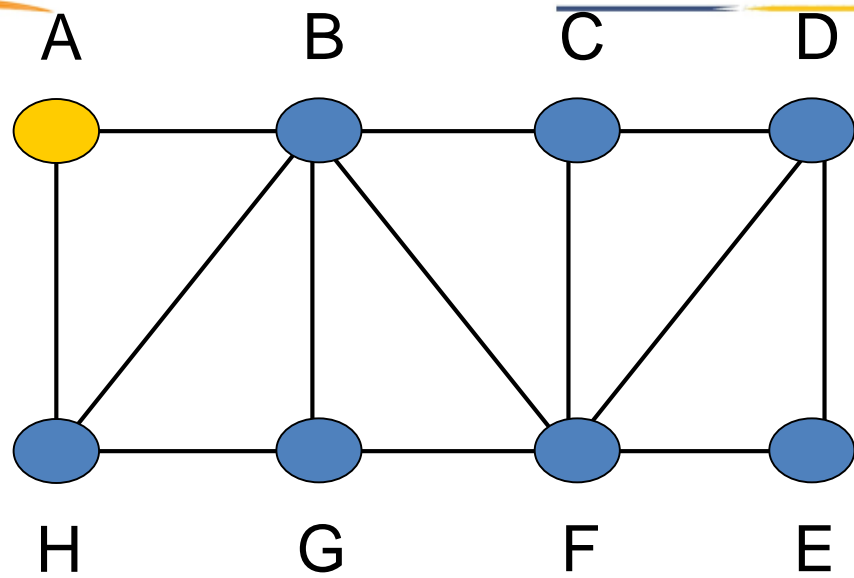
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, F, F, F, F, F, F, F]

Q: [**A**]

V:

A



Vertex

Adjacent Vertices

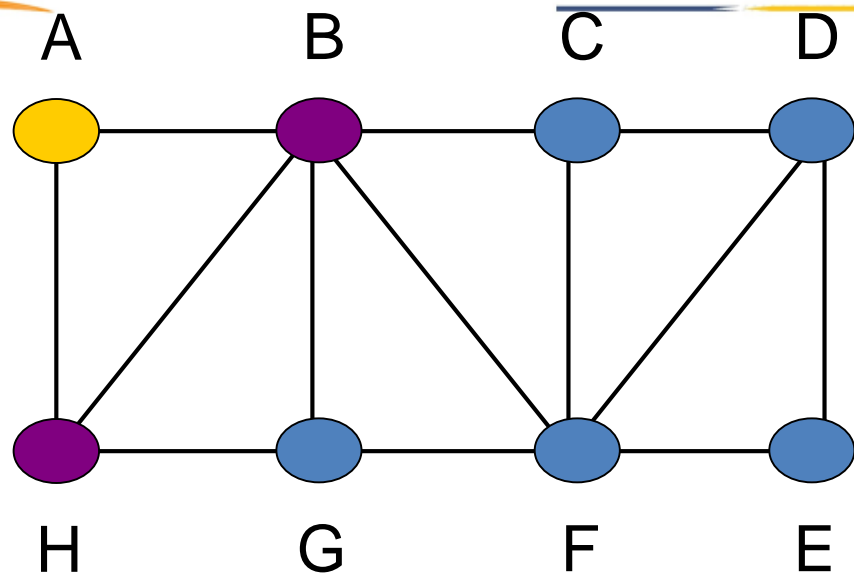
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, F, F, F, F, F, F, F]

Q: []

v: **A**

A



Vertex

Adjacent Vertices

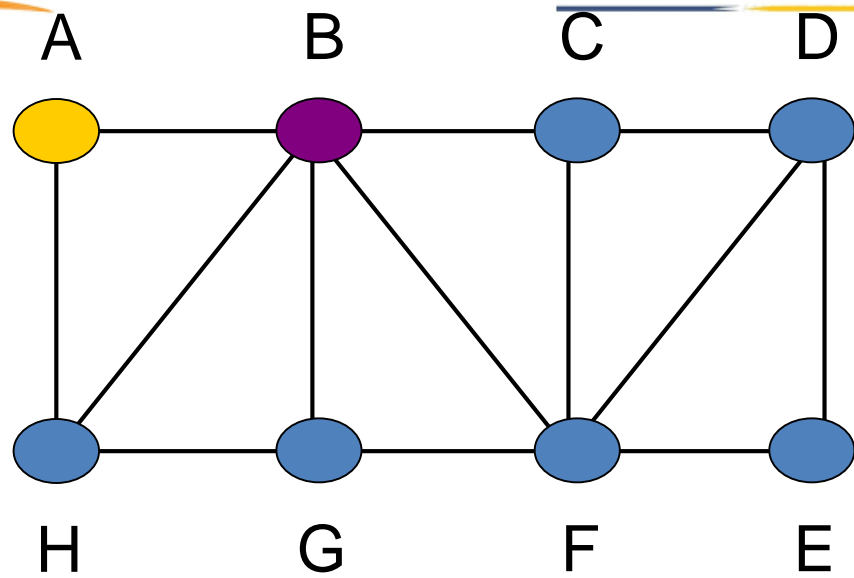
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, F, F, F, F, F, F, F]

Q: []

v: **A → B, H**

A



Vertex

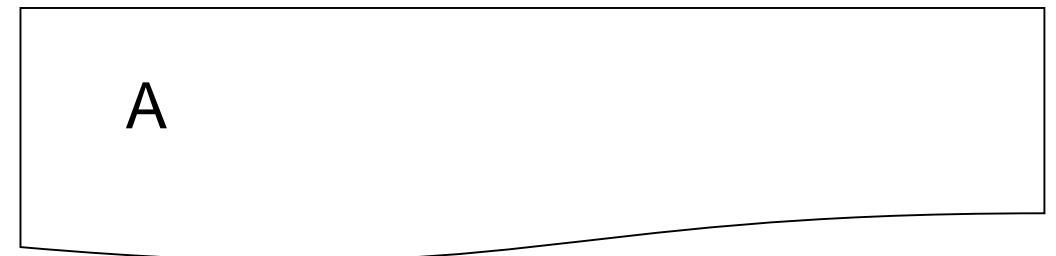
Adjacent Vertices

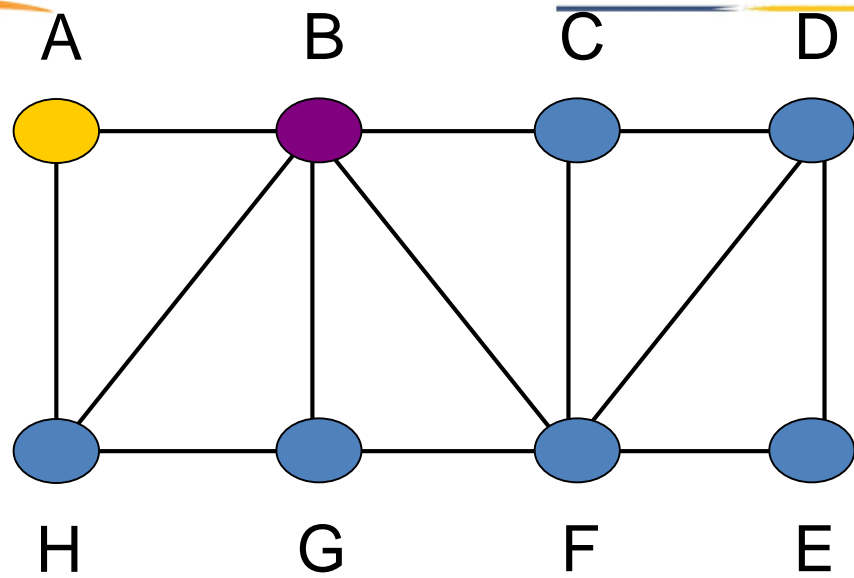
A	→	B , H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, F, F, F, F, F, F, F]

Q: []

v: A → **B**, H





Vertex

Adjacent Vertices

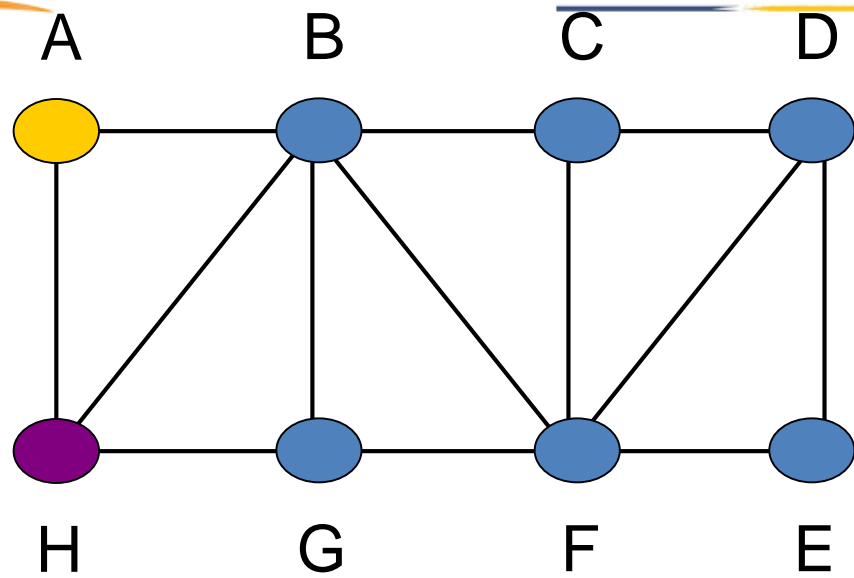
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, **T**, F, F, F, F, F, F]

Q: [**B**]

v: A → **B**, H

A **B**



Vertex

Adjacent Vertices

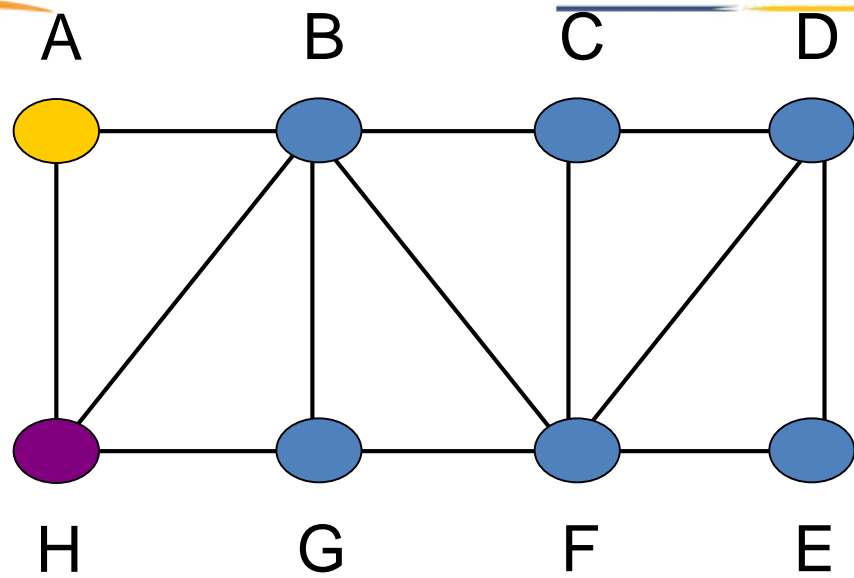
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, F, F, F, F, F, F]

Q: [B]

v: A → B, **H**

A B



Vertex

Adjacent Vertices

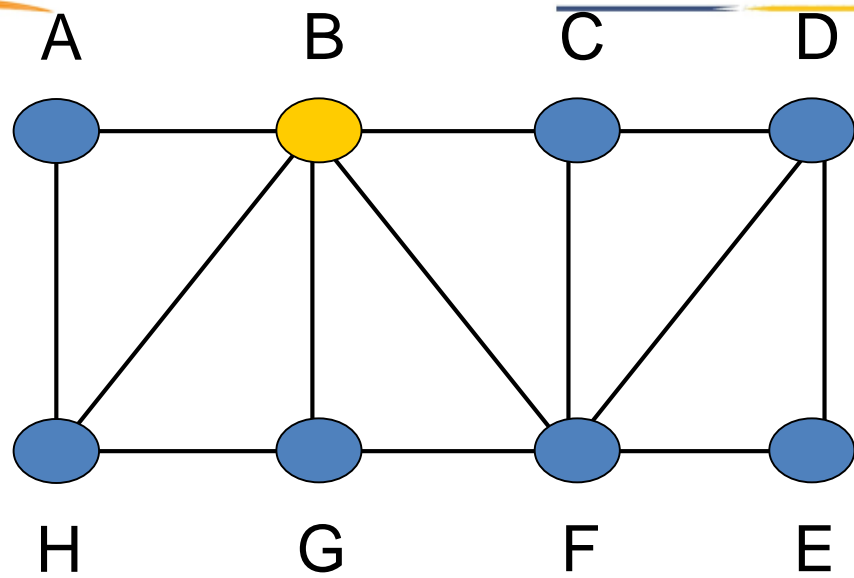
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, F, F, F, F, F, **T**]

Q: [B, **H**]

v: A → B, **H**

A B H



Vertex

Adjacent Vertices

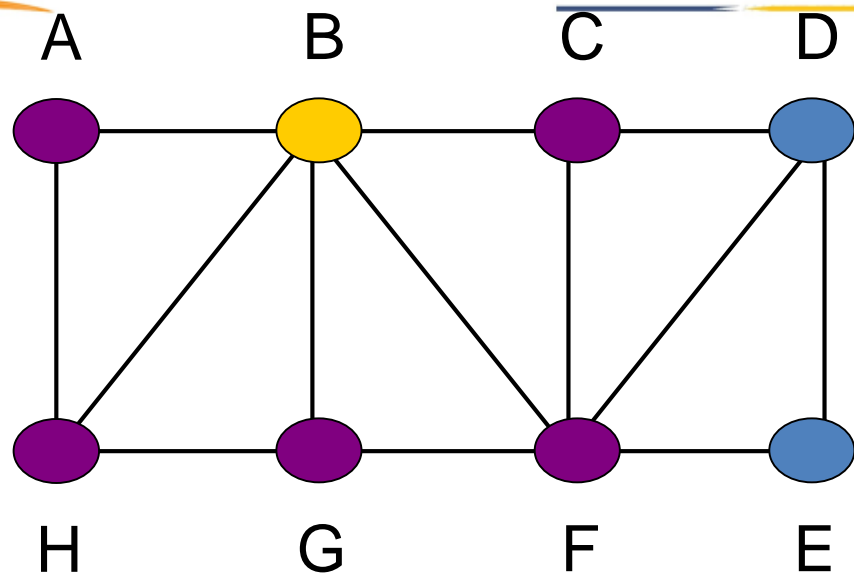
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, F, F, F, F, F, T]

Q: [H]

v: **B**

A B H



Vertex

Adjacent Vertices

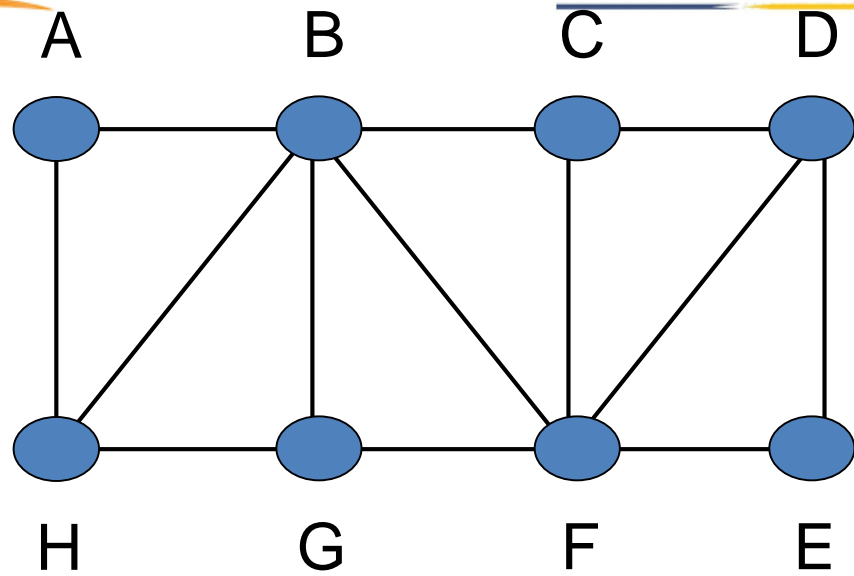
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, F, F, F, F, F, T]

Q: [H]

v: **B → A, C, G, F, H**

A B H



Vertex

Adjacent Vertices

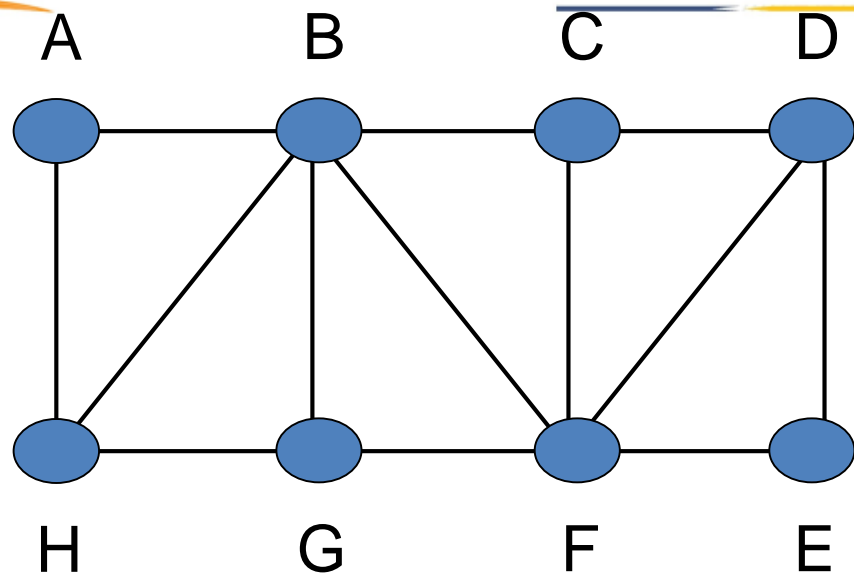
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, F, F, F, F, F, T]

Q: [H]

v: B → A, C, G, F, H

A B H



Vertex

Adjacent Vertices

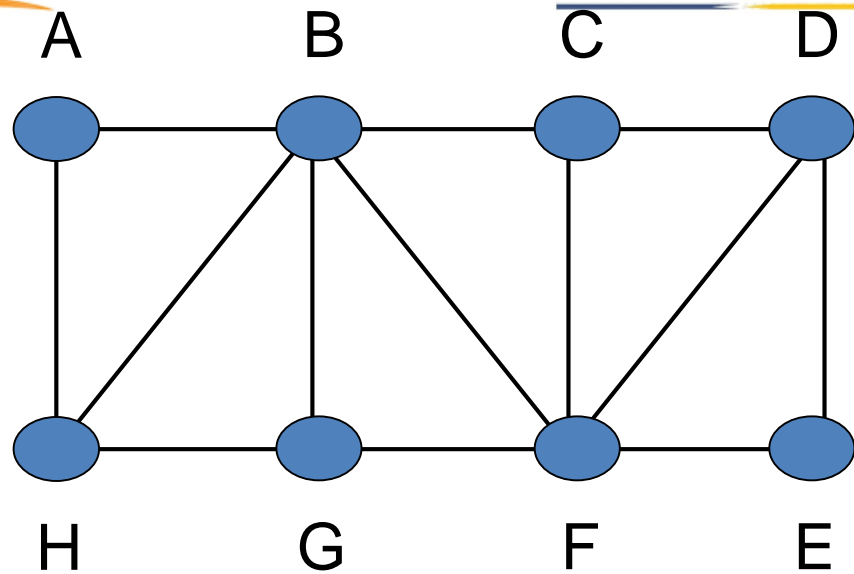
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, F, F, F, F, F, T]

Q: [H]

v: B → A, C, G, F, H

A B H



Vertex

Adjacent Vertices

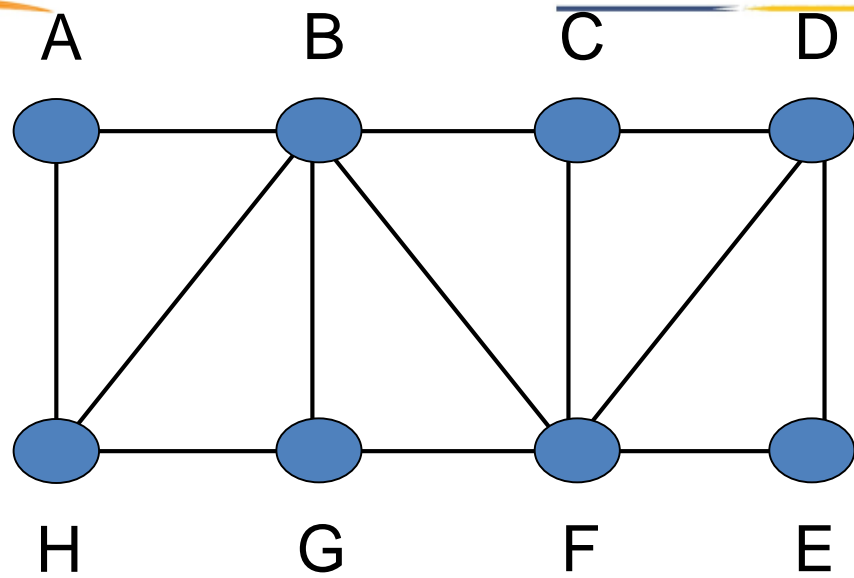
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, F, F, T]

Q: [H, C]

v: B → A, C, G, F, H

A B H C



Vertex

Adjacent Vertices

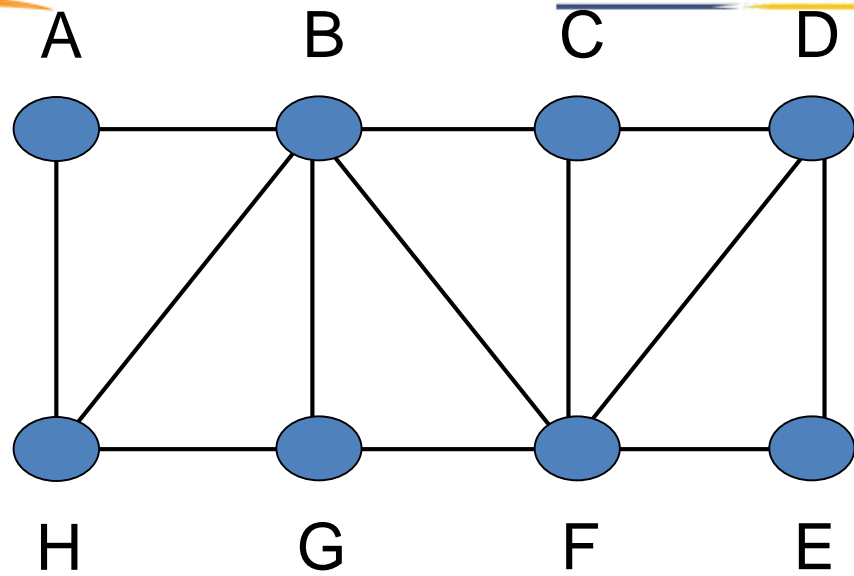
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, F, F, T]

Q: [H, C]

v: B → A, C, G, F, H

A B H C



Vertex

Adjacent Vertices

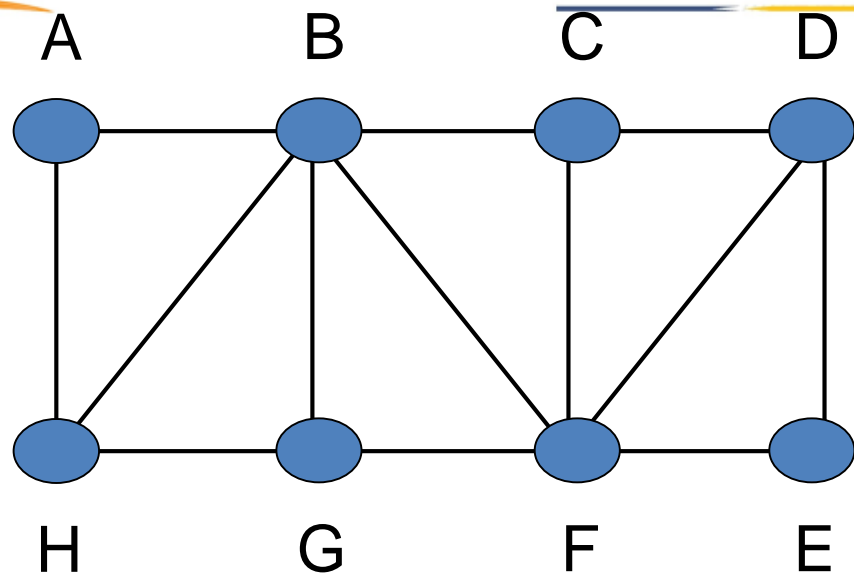
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, F, T, T]

Q: [H, C, G]

v: B → A, C, G, F, H

A B H C G



Vertex

Adjacent Vertices

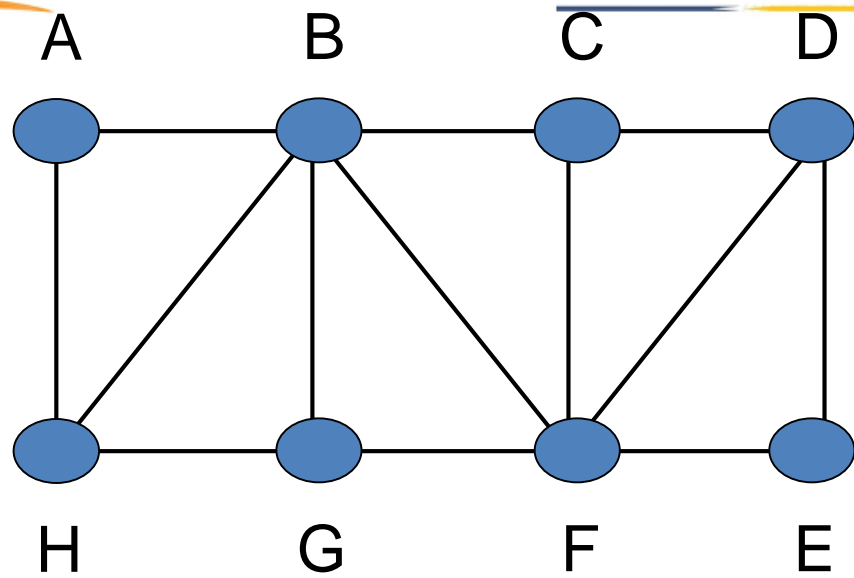
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, **F**, T, T]

Q: [H, C, G]

v: B → A, C, G, F, H

A B H C G



Vertex

Adjacent Vertices

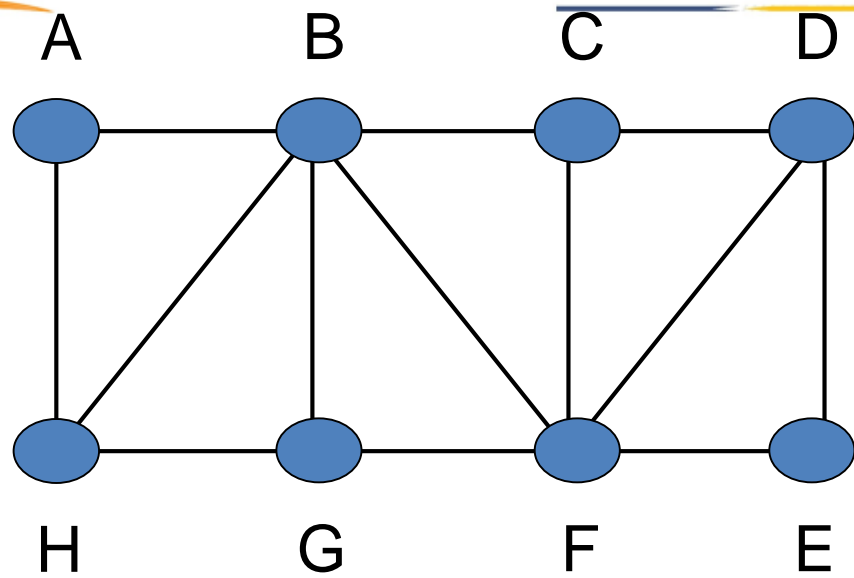
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, T, T, T]

Q: [H, C, G, F]

v: B → A, C, G, F, H

A B H C G F



Vertex

Adjacent Vertices

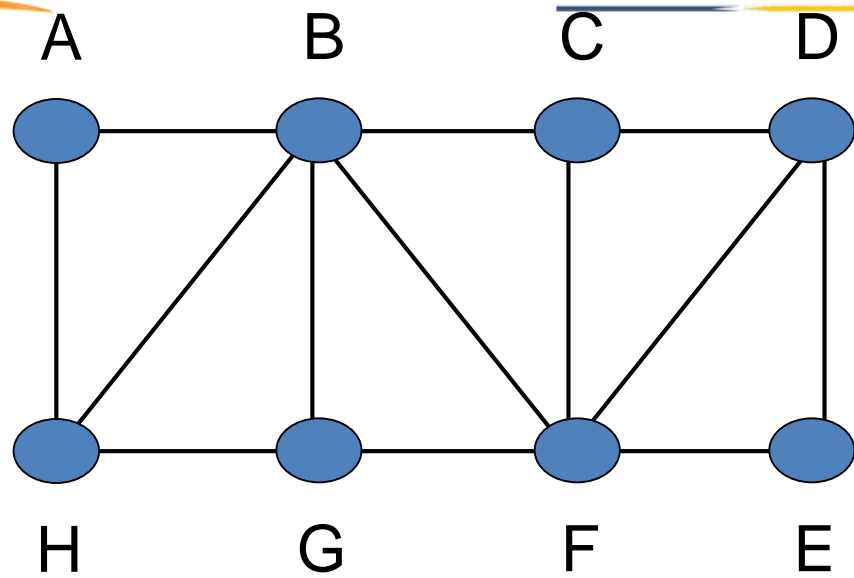
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, T, T, T]

Q: [H, C, G, F]

v: B → A, C, G, F, H

A B H C G F



Vertex

Adjacent Vertices

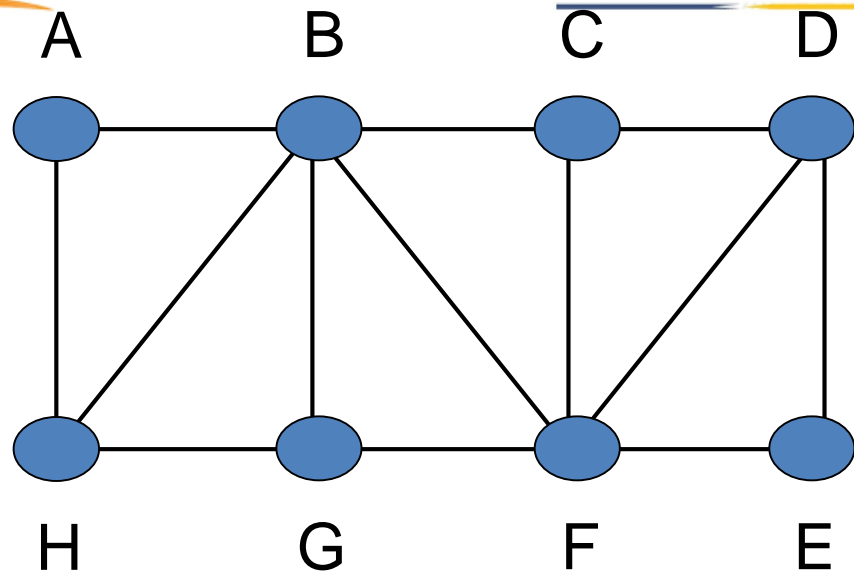
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, T, T, T]

Q: [C, G, F]

v: H

A B H C G F



Vertex

Adjacent Vertices

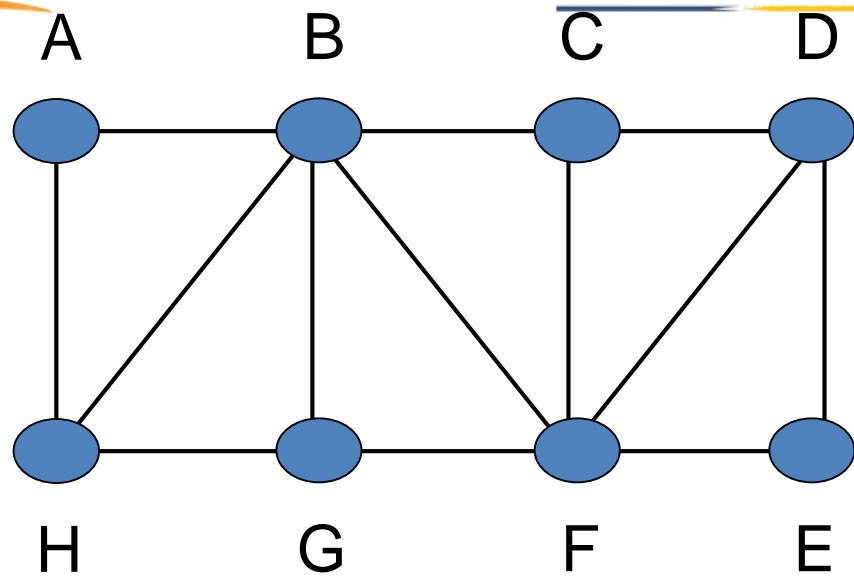
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, T, T, T]

Q: [C, G, F]

v: H → A, B, G

A B H C G F



Vertex

Adjacent Vertices

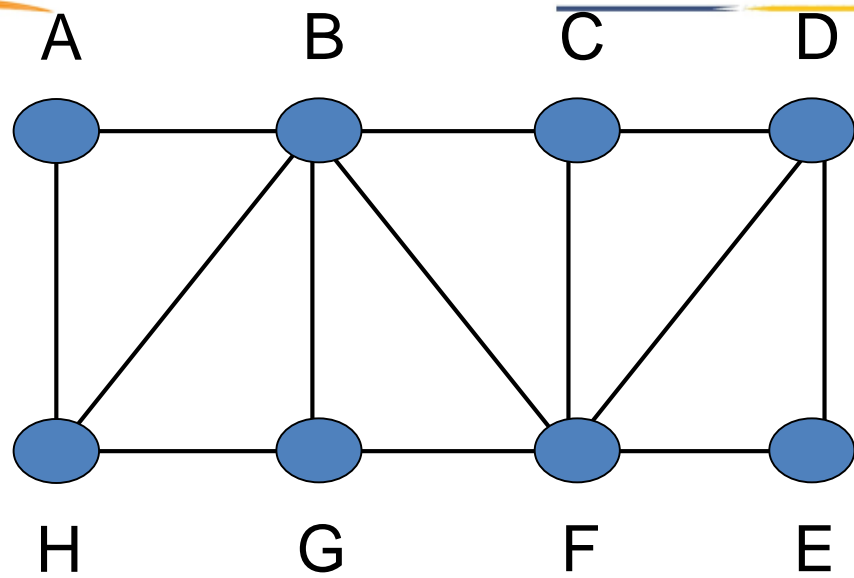
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, T, T, T]

Q: [C, G, F]

v: H → A, B, G

A B H C G F



Vertex

Adjacent Vertices

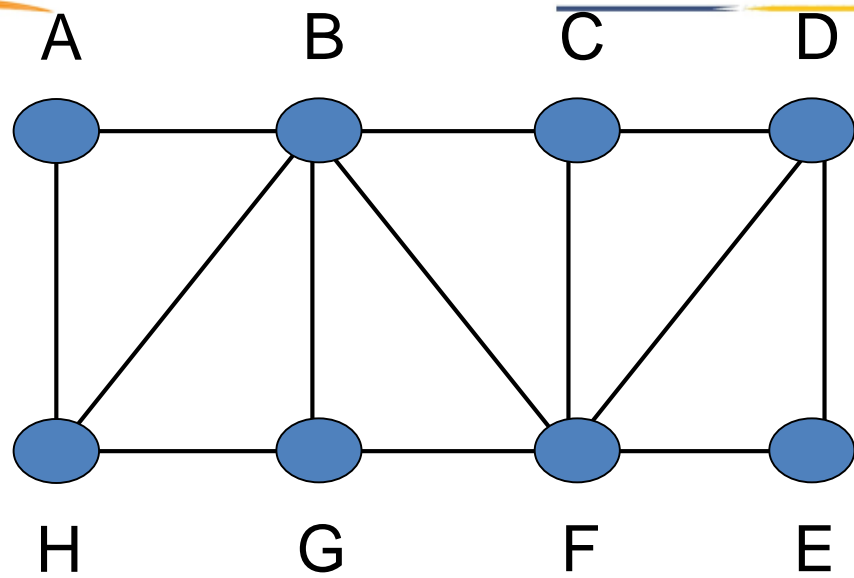
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, T, T, T]

Q: [C, G, F]

v: H → A, B, G

A B H C G F



Vertex

Adjacent Vertices

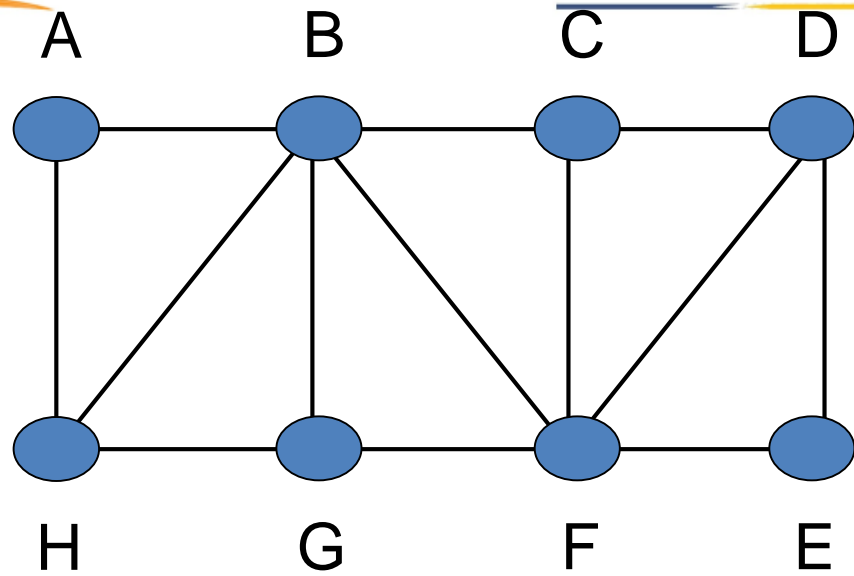
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, T, T, T]

Q: [C, G, F]

v: H → A, B, G

A B H C G F



Vertex

Adjacent Vertices

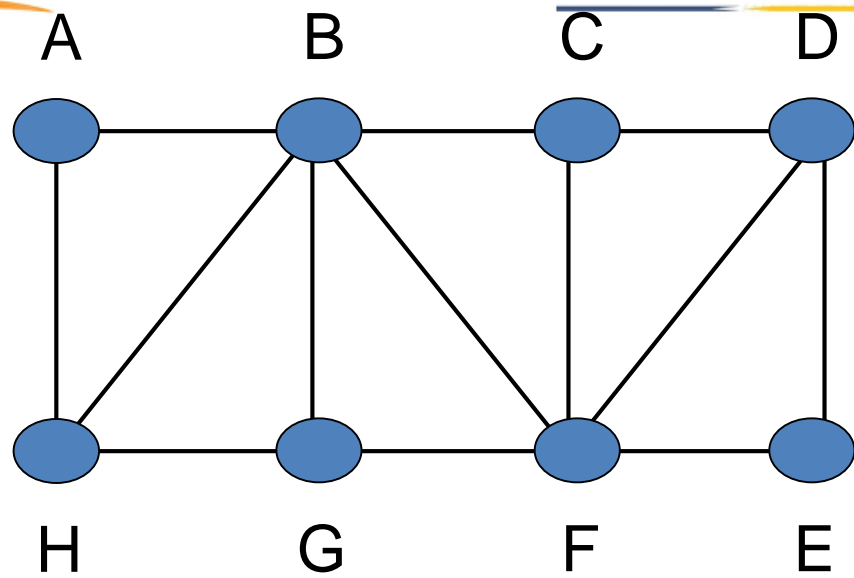
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, T, T, T]

Q: [C, G, F]

V:

A B H C G F



Vertex

Adjacent Vertices

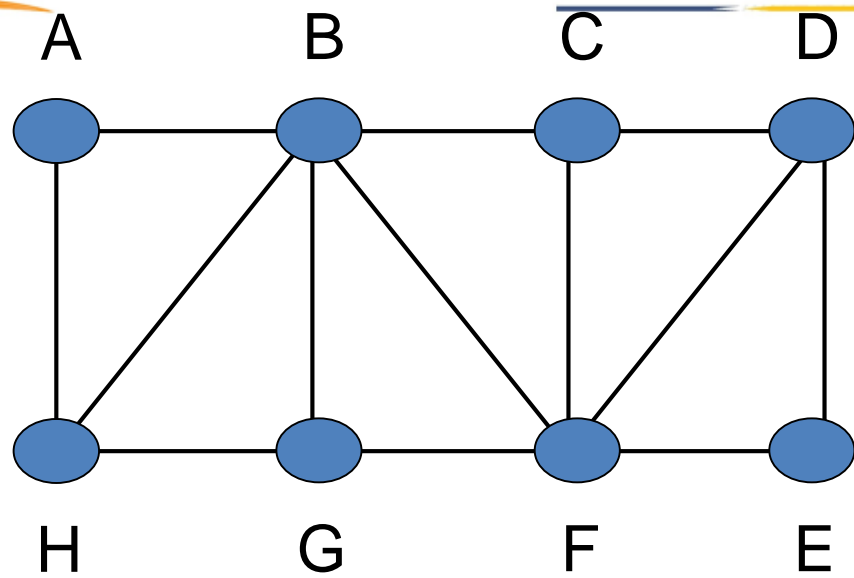
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, T, T, T]

Q: [G, F]

v: C → B, D, F

A B H C G F



Vertex

Adjacent Vertices

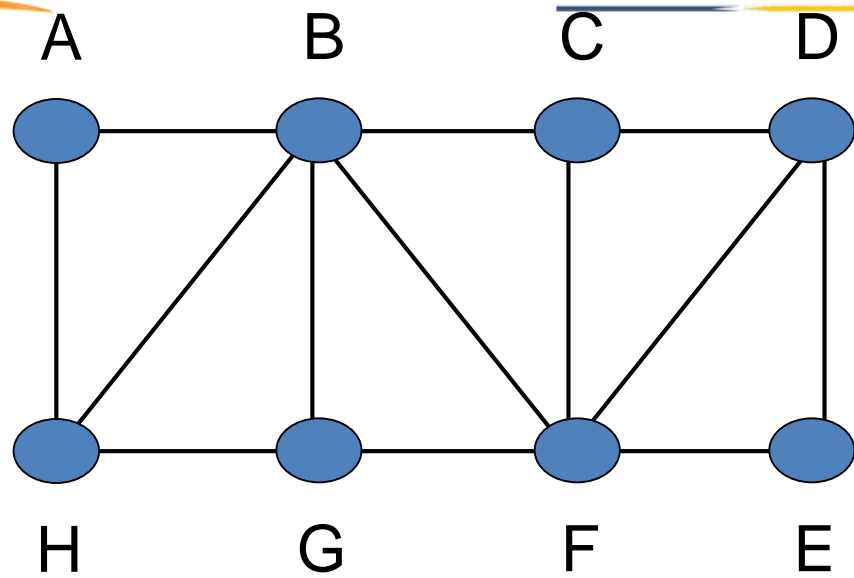
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, T, T, T]

Q: [G, F]

v: C → B, D, F

A B H C G F



Vertex

Adjacent Vertices

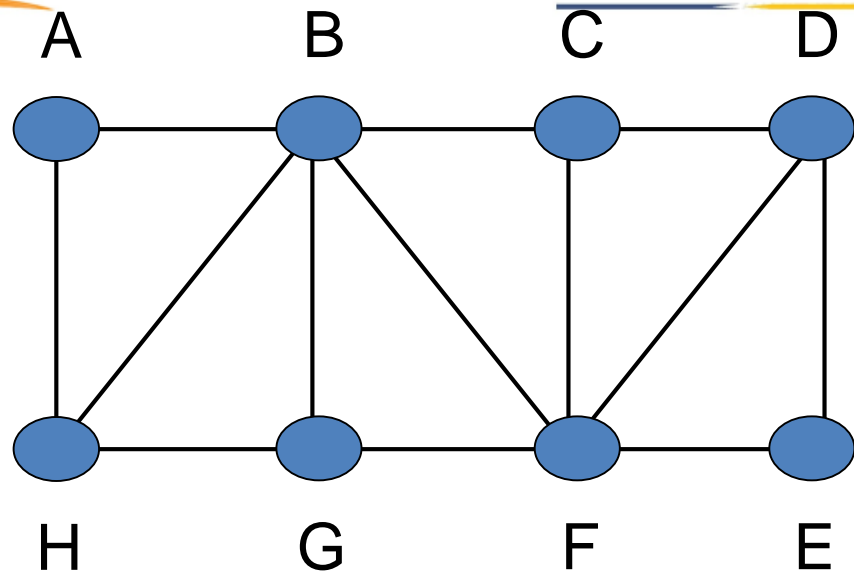
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, F, F, T, T, T]

Q: [G, F]

v: C → B, D, F

A B H C G F



Vertex

Adjacent Vertices

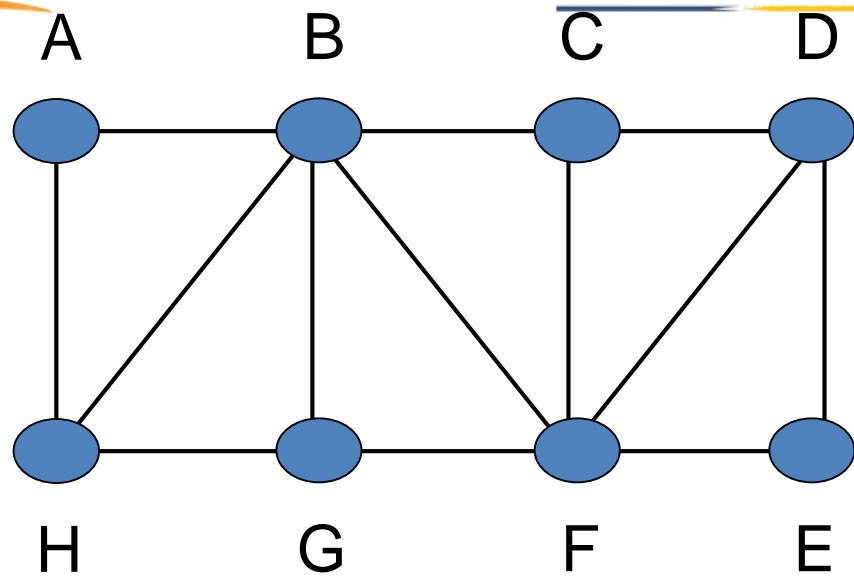
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, T, F, T, T, T]

Q: [G, F, D]

v: C → B, D, F

A B H C G F D



Vertex

Adjacent Vertices

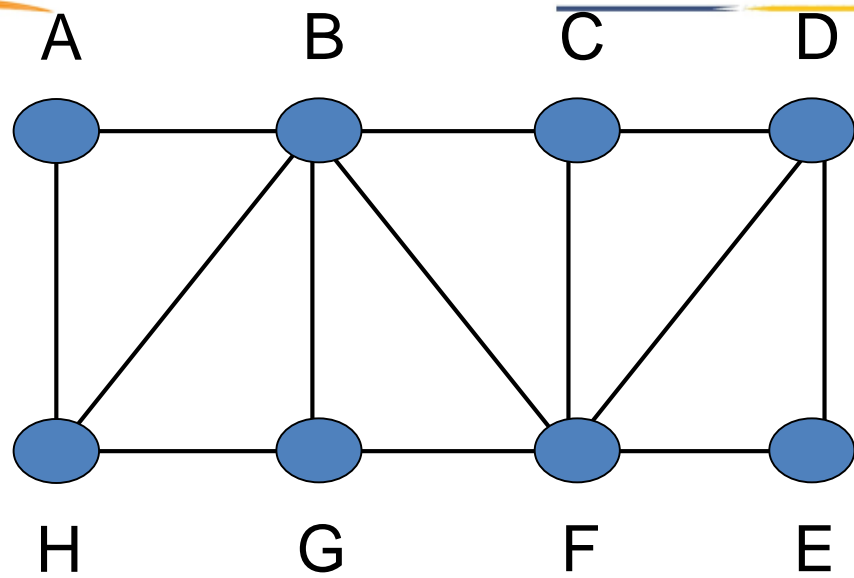
A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, T, F, T, T, T]

Q: [G, F, D]

v: C → B, D, F

A B H C G F D



Vertex

Adjacent Vertices

A	→	B, H
B	→	A, C, G, F, H
C	→	B, D, F
D	→	C, E, F
E	→	D, F
F	→	B, C, D, E, G
G	→	B, F, H
H	→	A, B, G

Visit [T, T, T, T, T, T, T, T]

Q: []

V:

A B H C G F D E

- Terminology
- Graph Representations
- Graph Traversals



Nhân bản – Phụng sự – Khai phóng



Enjoy the Course...!