

# Packing to fewer dimensions

*(for space compression and query speedup)*

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# Speeding up cosine computation

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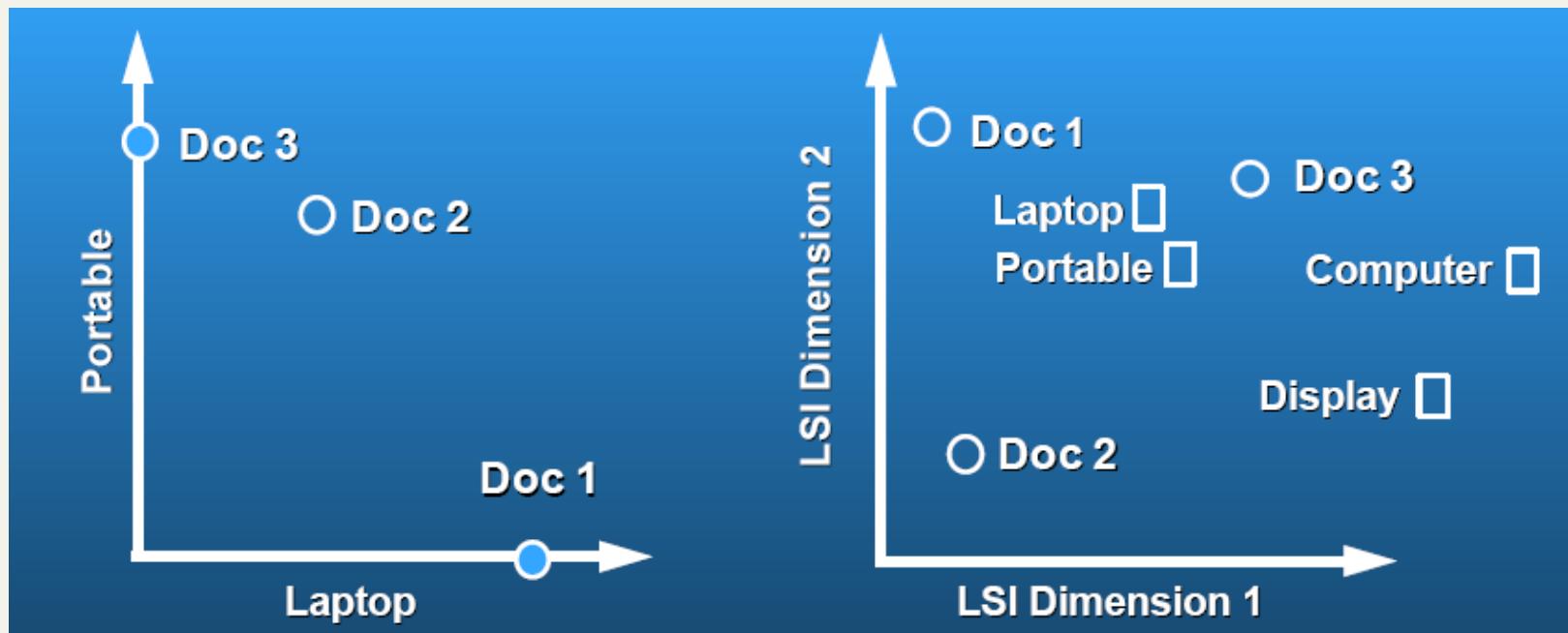
- What if we could take our vectors and “pack” them into fewer dimensions (**say 50,000→100**) while preserving distances?
  - Now,  $O(nm)$  to compute  $\cos(d,q)$  for all n docs
  - Then,  $O(km+kn)$  where  $k \ll n,m$
- Two methods:
  - Latent semantic indexing
  - Random projection

# Briefly

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- LSI is data-dependent
    - Create a k-dim subspace by eliminating redundant axes
    - Pull together “related” axes – hopefully
      - **car** and **automobile**
  - Random projection is data-independent
    - Choose a k-dim subspace that guarantees good *stretching properties with high probability* between any pair of points.
- What about polysemy ?

# Latent Semantic Indexing



*courtesy of Susan Dumais*

# Notions from linear algebra

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- Matrix A, vector v
- Matrix transpose ( $A^t$ )
- Matrix product
- Rank
- Eigenvalues  $\lambda$  and eigenvector v:  $Av = \lambda v$

*Example*

$$\begin{pmatrix} 6 & -2 \\ 4 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

# Overview of LSI

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- Pre-process docs using a technique from linear algebra called Singular Value Decomposition
- Create a new (*smaller*) vector space
- Queries handled (*faster*) in this new space

# Singular-Value Decomposition

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- Recall  $m \times n$  matrix of terms  $\times$  docs,  $A$ .
  - $A$  has rank  $r \leq m, n$
- Define **term-term** correlation matrix  $T = AA^t$ 
  - $T$  is a square, symmetric  $m \times m$  matrix
  - Let  $U$  be  $m \times r$  **matrix of r eigenvectors** of  $T$
- Define **doc-doc** correlation matrix  $D = A^tA$ 
  - $D$  is a square, symmetric  $n \times n$  matrix
  - Let  $V$  be  $n \times r$  **matrix of r eigenvectors** of  $D$

# A's decomposition

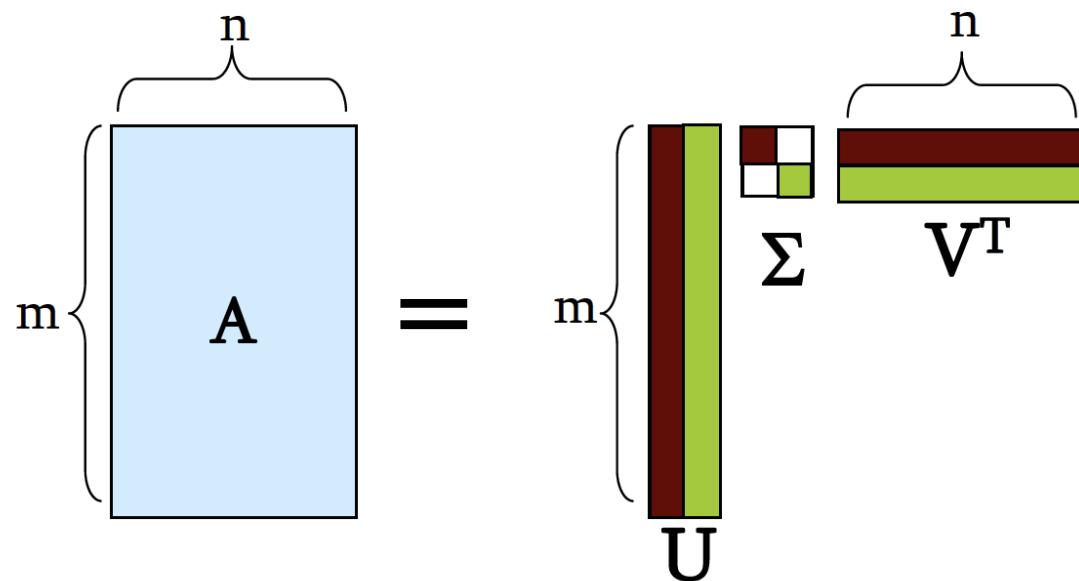
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- Given  $U$  (for T,  $m \times r$ ) and  $V$  (for D,  $n \times r$ ) formed by orthonormal columns (unit dot-product)
- It turns out that  $A = U \Sigma V^t$ 
  - Where  $\Sigma$  is a diagonal matrix with the **singular values** (=square root of the eigenvalues of  $T=AA^t$ ) in **decreasing order**.

$$A \quad m \times n \quad = \quad U \quad m \times r \quad \Sigma \quad r \times r \quad V^t \quad r \times n$$

# The case of $r = 2$

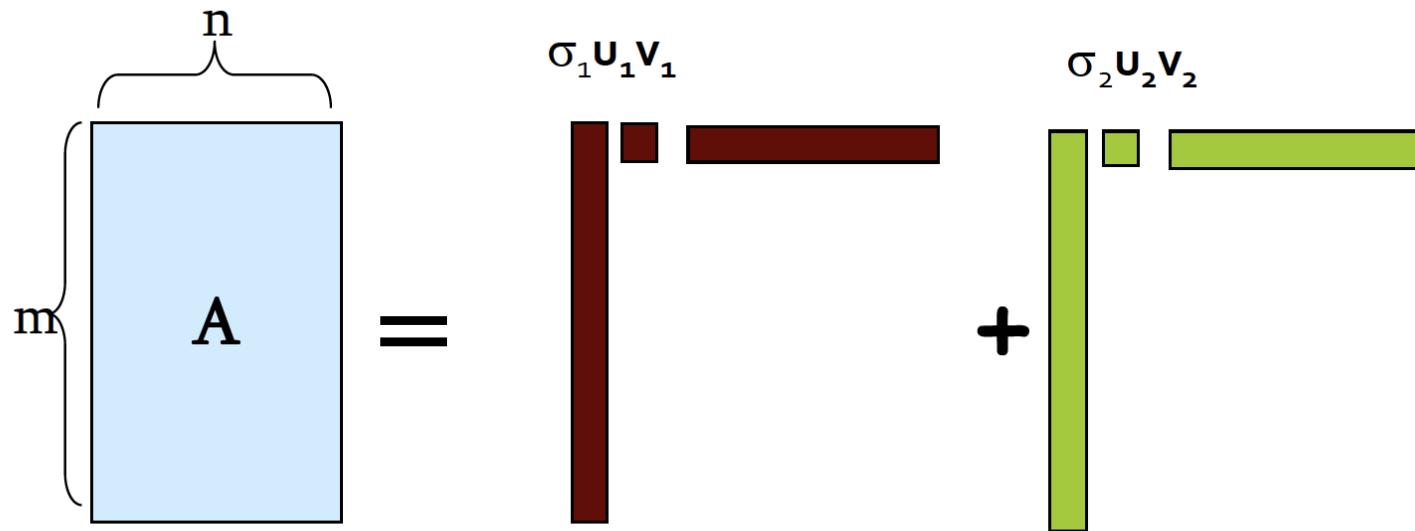
$$\mathbf{A} = \mathbf{U}\Sigma\mathbf{V}^T = \sum_i \sigma_i \mathbf{u}_i \circ \mathbf{v}_i^T$$



*From Jure Leskovec's slides (Stanford), this and next ones*

# The case of $r=2$

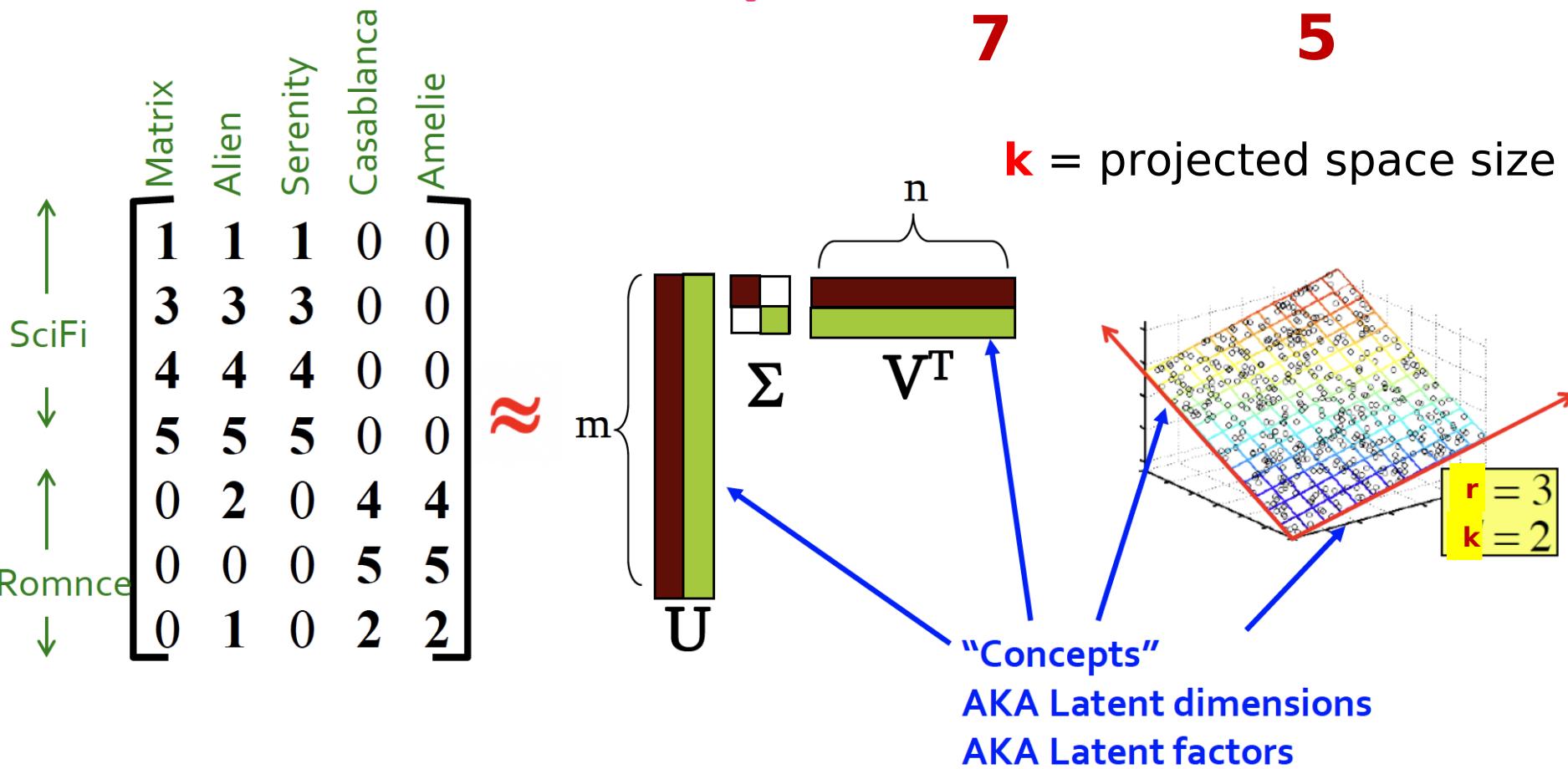
$$\mathbf{A} = \mathbf{U}\Sigma\mathbf{V}^T = \sum_i \sigma_i \mathbf{u}_i \circ \mathbf{v}_i^\top$$



$\sigma_i$  ... scalar  
 $\mathbf{u}_i$  ... vector  
 $\mathbf{v}_i$  ... vector

# SVD – Example: Users-to-Movies

- $A = U \Sigma V^T$  - example: Users to Movies



# SVD – Example: Users-to-Movies

- $A = U \Sigma V^T$  - example: Users to Movies

Matrix

	Alien	Serenity	Casablanca	Amelie	
SciFi	1	1	1	0	0
	3	3	3	0	0
	4	4	4	0	0
	5	5	5	0	0
Romance	0	2	0	4	4
	0	0	0	5	5
	0	1	0	2	2

=

0.13	0.02	-0.01
0.41	0.07	-0.03
<b>0.55</b>	0.09	-0.04
<b>0.68</b>	0.11	-0.05
0.15	<b>-0.59</b>	<b>0.65</b>
0.07	<b>-0.73</b>	<b>-0.67</b>
0.07	<b>-0.29</b>	<b>0.32</b>

$r = 3$

$\times$   $\begin{bmatrix} 12.4 & 0 & 0 \\ 0 & 9.5 & 0 \\ 0 & 0 & 1.3 \end{bmatrix}$   $\times$

0.56	0.59	0.56	0.09	0.09
0.12	-0.02	0.12	<b>-0.69</b>	<b>-0.69</b>
0.40	<b>-0.80</b>	0.40	0.09	0.09

# SVD – Example: Users-to-Movies

- $A = U \Sigma V^T$  - example: Users to Movies

Matrix

	Alien	Serenity	Casablanca	Amelie
SciFi	1	1	1	0
Romance	3	3	3	0
	4	4	4	0
	5	5	5	0
	0	2	0	4
	0	0	0	5
	0	1	0	2

SciFi-concept      Romance-concept

$$= \begin{bmatrix} 0.13 & 0.02 & -0.01 \\ 0.41 & 0.07 & -0.03 \\ 0.55 & 0.09 & -0.04 \\ 0.68 & 0.11 & -0.05 \\ 0.15 & -0.59 & 0.65 \\ 0.07 & -0.73 & -0.67 \\ 0.07 & -0.29 & 0.32 \end{bmatrix} \times \begin{bmatrix} 12.4 & 0 & 0 \\ 0 & 9.5 & 0 \\ 0 & 0 & 1.3 \end{bmatrix} \times \begin{bmatrix} 0.56 & 0.59 & 0.56 & 0.09 & 0.09 \\ 0.12 & -0.02 & 0.12 & -0.69 & -0.69 \\ 0.40 & -0.80 & 0.40 & 0.09 & 0.09 \end{bmatrix}$$

# SVD – Example: Users-to-Movies

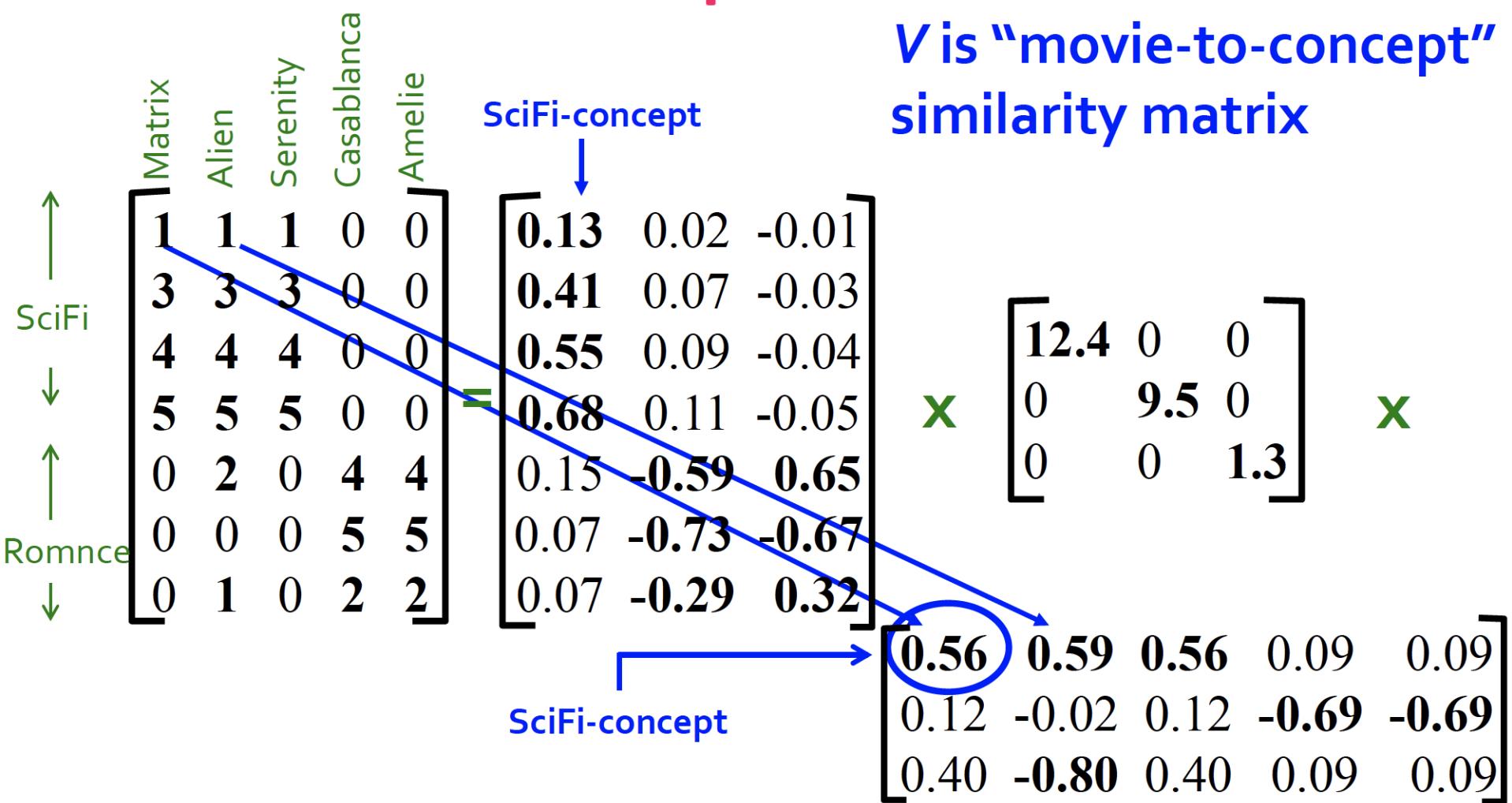
- $A = U \Sigma V^T$  - example:

Matrix

$$\begin{array}{c}
 \begin{array}{l} \uparrow \\ \text{SciFi} \\ \downarrow \\ \uparrow \\ \text{Romance} \\ \downarrow \end{array} & 
 \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} & 
 \begin{array}{l} \text{SciFi-concept} \\ \downarrow \\ \begin{bmatrix} 0.13 & 0.02 & -0.01 \\ 0.41 & 0.07 & -0.03 \\ 0.55 & 0.09 & -0.04 \\ 0.68 & 0.11 & -0.05 \\ 0.15 & -0.59 & 0.65 \\ 0.07 & -0.73 & -0.67 \\ 0.07 & -0.29 & 0.32 \end{bmatrix} \end{array} & 
 \begin{array}{l} \text{"strength" of the SciFi-concept} \\ \downarrow \\ \begin{bmatrix} 12.4 & 0 & 0 \\ 0 & 9.5 & 0 \\ 0 & 0 & 1.3 \end{bmatrix} \end{array} \\
 \times & & \times & 
 \begin{bmatrix} 0.56 & 0.59 & 0.56 & 0.09 & 0.09 \\ 0.12 & -0.02 & 0.12 & -0.69 & -0.69 \\ 0.40 & -0.80 & 0.40 & 0.09 & 0.09 \end{bmatrix}
 \end{array}$$

# SVD – Example: Users-to-Movies

- $A = U \Sigma V^T$  - example:



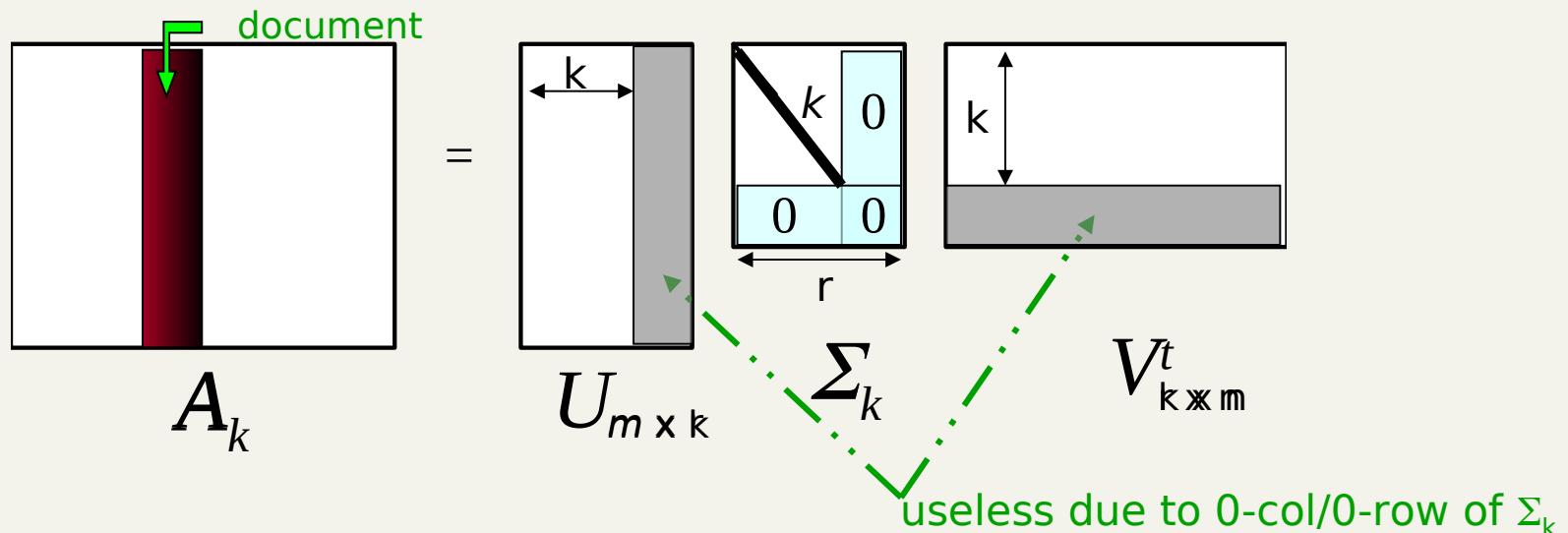
# SVD - Interpretation #1

‘movies’, ‘users’ and ‘concepts’:

- $U$ : user-to-concept similarity matrix
- $V$ : movie-to-concept similarity matrix
- $\Sigma$ : its diagonal elements:  
‘strength’ of each concept

# Dimensionality reduction

- Fix some  $k \ll r$ , zero out all but the  $k$  biggest eigenvalues in  $\Sigma$  [*choice of  $k$  is crucial*]
  - Denote by  $\Sigma_k$  this new version of  $\Sigma$ , having rank  $k$
  - Typically  $k$  is about 100, while  $r$  ( $A$ 's rank) is  $> 10,000$



# Guarantee

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- $A_k$  is a pretty good approximation to  $A$ :
  - Relative distances are (approximately) preserved
  - Of all  $m \times n$  matrices of rank  $k$ ,  $A_k$  is the best approximation to  $A$  wrt the following measures:
    - $\min_{B, \text{rank}(B)=k} \|A-B\|_2 = \|A-A_k\|_2 = \sigma_{k+1}$
    - $\min_{B, \text{rank}(B)=k} \|A-B\|_F^2 = \|A-A_k\|_F^2 = \sigma_{k+1}^2 + \sigma_{k+2}^2 + \dots + \sigma_r^2$
- Frobenius norm  $\|A\|_F^2 = \sigma_1^2 + \sigma_2^2 + \dots + \sigma_r^2$ 

**Q: How many  $\sigma_s$  to keep?**

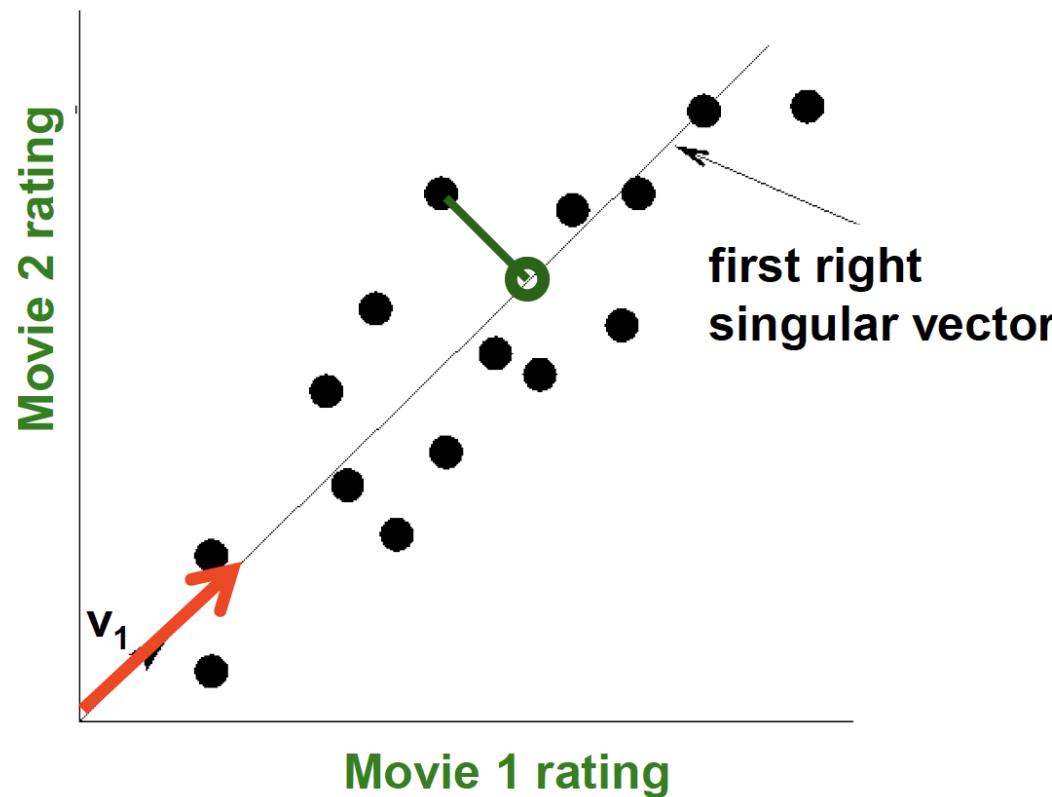
**A: Rule-of-a thumb:**

**keep 80-90% of 'energy' =  $\sum_i \sigma_i^2$**

# SVD - Complexity

- **To compute SVD:**
  - $O(nm^2)$  or  $O(n^2m)$  (whichever is less)
- **But:**
  - Less work, if we just want singular values
  - or if we want first  $k$  singular vectors
  - or if the matrix is sparse
- **Implemented in** linear algebra packages like
  - LINPACK, Matlab, SPlus, Mathematica ...

# SVD – Dimensionality Reduction



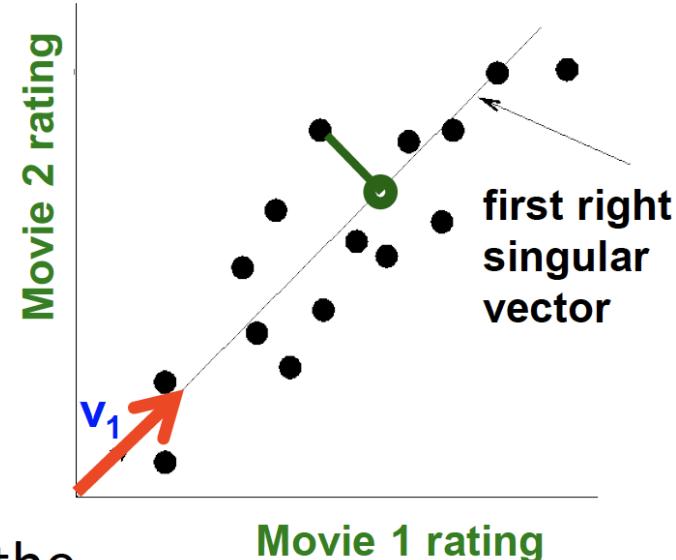
- Instead of using two coordinates  $(x, y)$  to describe point locations, let's use only one coordinate
- Point's position is its location along vector  $v_1$
- How to choose  $v_1$ ? **Minimize reconstruction error**

# SVD – Dimensionality Reduction

- **Goal:** Minimize the sum of reconstruction errors:

$$\sum_{i=1}^N \sum_{j=1}^D \|x_{ij} - z_{ij}\|^2$$

- where  $x_{ij}$  are the “old” and  $z_{ij}$  are the “new” coordinates



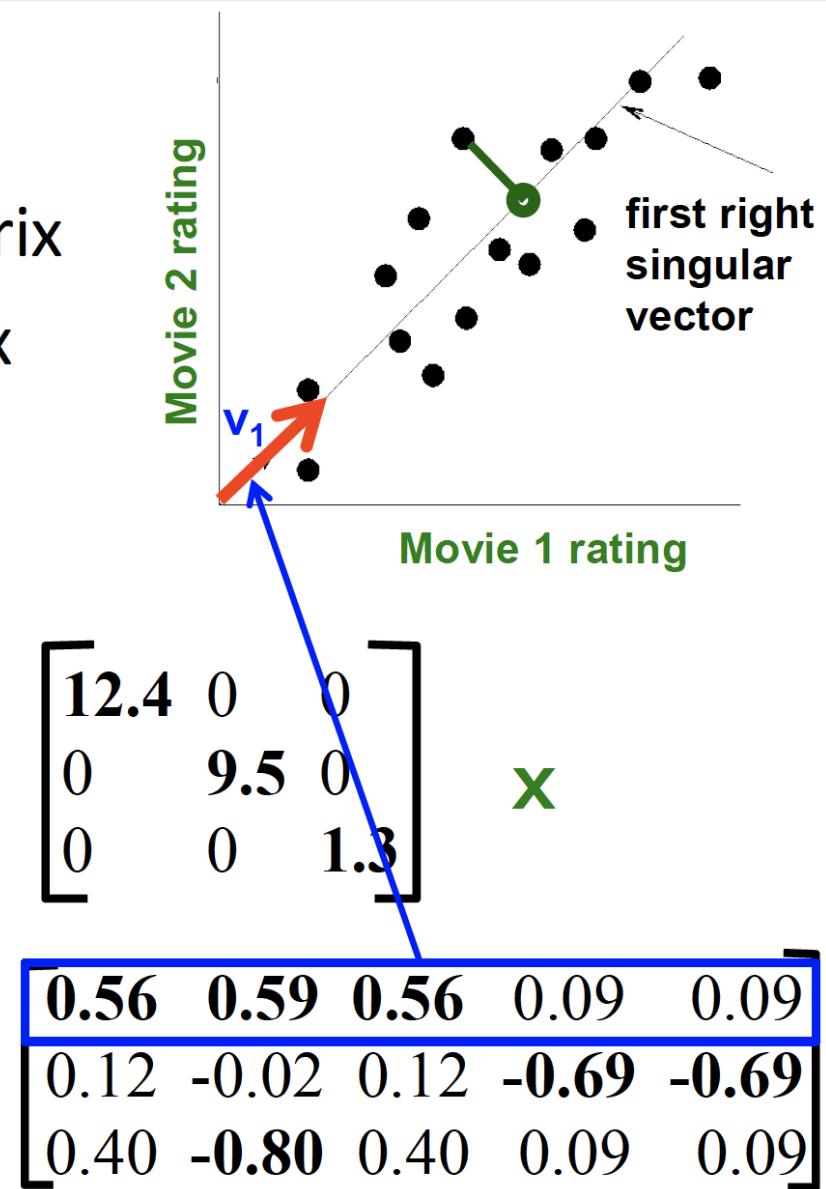
- **SVD gives ‘best’ axis to project on:**
  - ‘best’ = minimizing the sum of reconstruction errors
- **In other words, minimum reconstruction error**

# SVD - Interpretation #2

## ■ $A = U \Sigma V^T$ - example:

- $V$ : “movie-to-concept” matrix
- $U$ : “user-to-concept” matrix

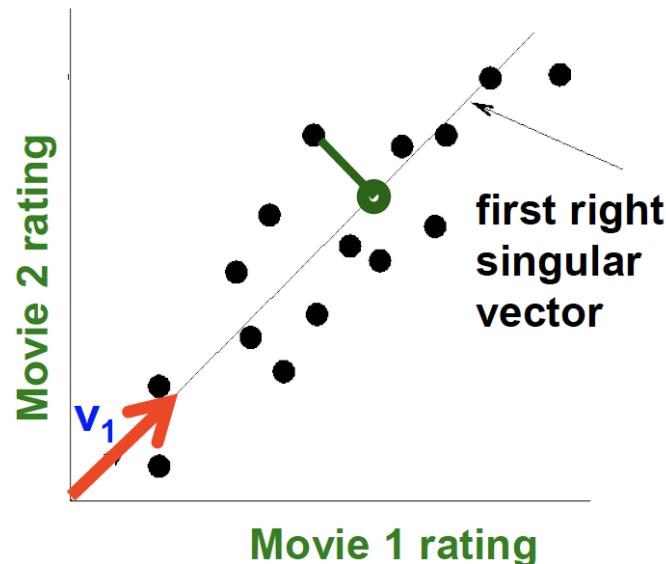
$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} = \begin{bmatrix} 0.13 & 0.02 & -0.01 \\ 0.41 & 0.07 & -0.03 \\ 0.55 & 0.09 & -0.04 \\ 0.68 & 0.11 & -0.05 \\ 0.15 & -0.59 & 0.65 \\ 0.07 & -0.73 & -0.67 \\ 0.07 & -0.29 & 0.32 \end{bmatrix} \times \begin{bmatrix} 12.4 & 0 & 0 \\ 0 & 9.5 & 0 \\ 0 & 0 & 1.3 \end{bmatrix}$$



# SVD - Interpretation #2

- $A = U \Sigma V^T$  - example:

variance ('spread')  
on the  $v_1$  axis



$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} = \begin{bmatrix} 0.13 & 0.02 & -0.01 \\ 0.41 & 0.07 & -0.03 \\ 0.55 & 0.09 & -0.04 \\ 0.68 & 0.11 & -0.05 \\ 0.15 & -0.59 & 0.65 \\ 0.07 & -0.73 & -0.67 \\ 0.07 & -0.29 & 0.32 \end{bmatrix} \times \begin{bmatrix} 12.4 & 0 & 0 \\ 0 & 9.5 & 0 \\ 0 & 0 & 1.3 \end{bmatrix} \times \begin{bmatrix} 0.56 & 0.59 & 0.56 & 0.09 & 0.09 \\ 0.12 & -0.02 & 0.12 & -0.69 & -0.69 \\ 0.40 & -0.80 & 0.40 & 0.09 & 0.09 \end{bmatrix}$$

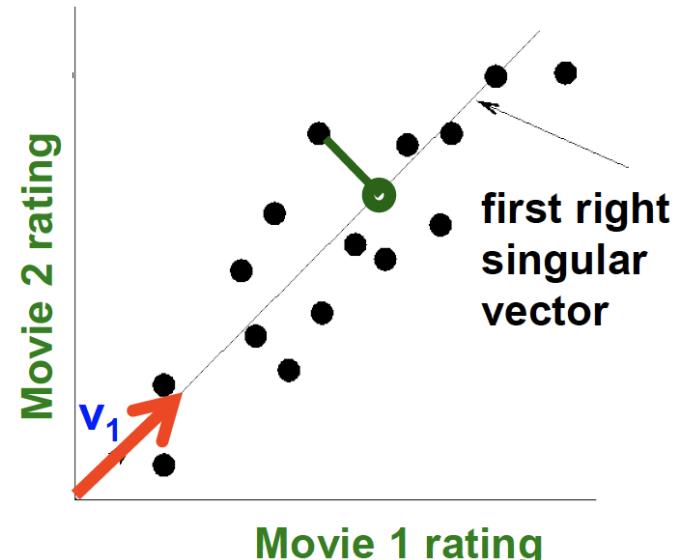
# SVD - Interpretation #2

$A = U \Sigma V^T$  - example:

- $U \Sigma$ : Gives the coordinates of the points in the projection axis

1	1	1	0	0
3	3	3	0	0
4	4	4	0	0
5	5	5	0	0
0	2	0	4	4
0	0	0	5	5
0	1	0	2	2

Projection of users on the “Sci-Fi” axis  
 $(U \Sigma)^T$ :



1.61	0.19	-0.01
5.08	0.66	-0.03
6.82	0.85	-0.05
8.43	1.04	-0.06
1.86	-5.60	0.84
0.86	-6.93	-0.87
0.86	-2.75	0.41

# SVD - Interpretation #2

## More details

- Q: How exactly is dim. reduction done?

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} = \begin{bmatrix} 0.13 & 0.02 & -0.01 \\ 0.41 & 0.07 & -0.03 \\ 0.55 & 0.09 & -0.04 \\ 0.68 & 0.11 & -0.05 \\ 0.15 & -0.59 & 0.65 \\ 0.07 & -0.73 & -0.67 \\ 0.07 & -0.29 & 0.32 \end{bmatrix} \times \begin{bmatrix} 12.4 & 0 & 0 \\ 0 & 9.5 & 0 \\ 0 & 0 & 1.3 \end{bmatrix} \times \begin{bmatrix} 0.56 & 0.59 & 0.56 & 0.09 & 0.09 \\ 0.12 & -0.02 & 0.12 & -0.69 & -0.69 \\ 0.40 & -0.80 & 0.40 & 0.09 & 0.09 \end{bmatrix}$$

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# SVD - Interpretation #2

This is Rank 2 approximation to A.  
We could also do Rank 1 approx.  
The larger the rank the more accurate the approximation.

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$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} \approx \begin{bmatrix} 0.92 & 0.95 & 0.92 & 0.01 & 0.01 \\ 2.91 & 3.01 & 2.91 & -0.01 & -0.01 \\ 3.90 & 4.04 & 3.90 & 0.01 & 0.01 \\ 4.82 & 5.00 & 4.82 & 0.03 & 0.03 \\ 0.70 & 0.53 & 0.70 & 4.11 & 4.11 \\ -0.69 & 1.34 & -0.69 & 4.78 & 4.78 \\ 0.32 & 0.23 & 0.32 & 2.01 & 2.01 \end{bmatrix}$$

Frobenius norm:

$$\|M\|_F = \sqrt{\sum_{ij} M_{ij}^2}$$

$$\|A-B\|_F = \sqrt{\sum_{ij} (A_{ij}-B_{ij})^2}$$

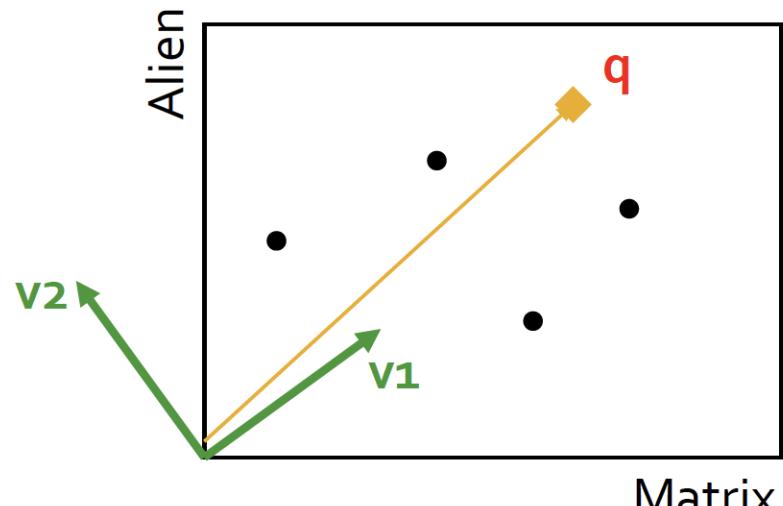
is “small”

# Case study: How to query?

- Q: Find users that like ‘Matrix’
- A: Map query into a ‘concept space’ – how?

$$q = \begin{bmatrix} \text{Matrix} \\ \text{Alien} \\ \text{Serenity} \\ \text{Casablanca} \\ \text{Amelie} \end{bmatrix} \quad \begin{bmatrix} 5 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

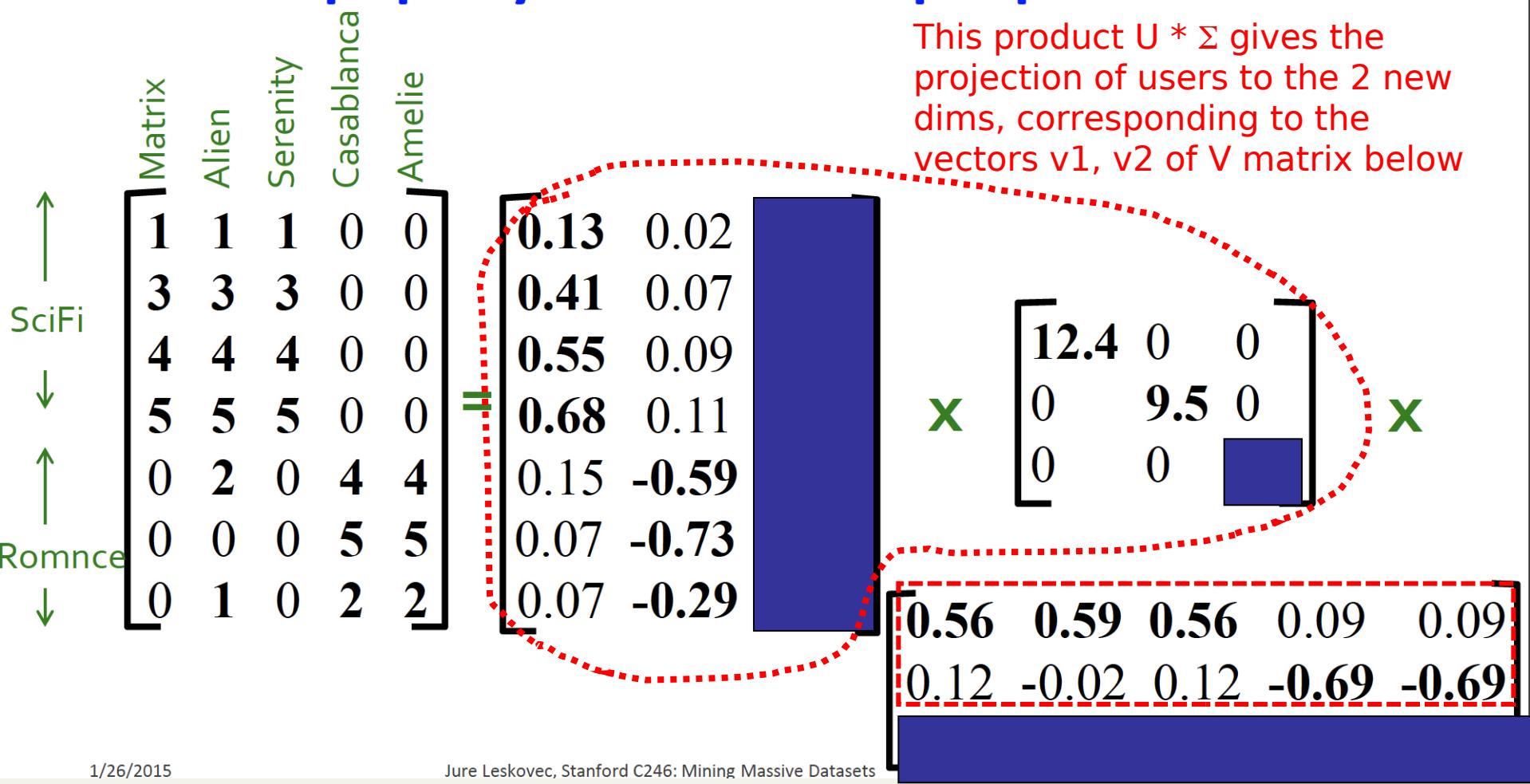
Project into concept space:  
Inner product with each  
'concept' vector  $v_i$



Interpret as another row in the matrix

# Case study: How to query?

- Q: Find users that like ‘Matrix’
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# Case study: How to query?

Compactly, we have:

$$q_{\text{concept}} = q \vee$$

E.g.:

$$q = \begin{bmatrix} \text{Matrix} \\ 5 \\ \text{Alien} \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \times \begin{bmatrix} 0.56 & 0.12 \\ 0.59 & -0.02 \\ 0.56 & 0.12 \\ 0.09 & -0.69 \\ 0.09 & -0.69 \end{bmatrix} = \begin{bmatrix} 2.8 \\ 0.6 \end{bmatrix}$$

SciFi-concept

movie-to-concept  
similarities ( $V$ )

# Case study: How to query?

- How would the user  $d$  that rated ('Alien', 'Serenity') be handled?

$\mathbf{d}_{\text{concept}} = \mathbf{d} \mathbf{V}$  This is a new user that expresses preferences on-the-fly at query time

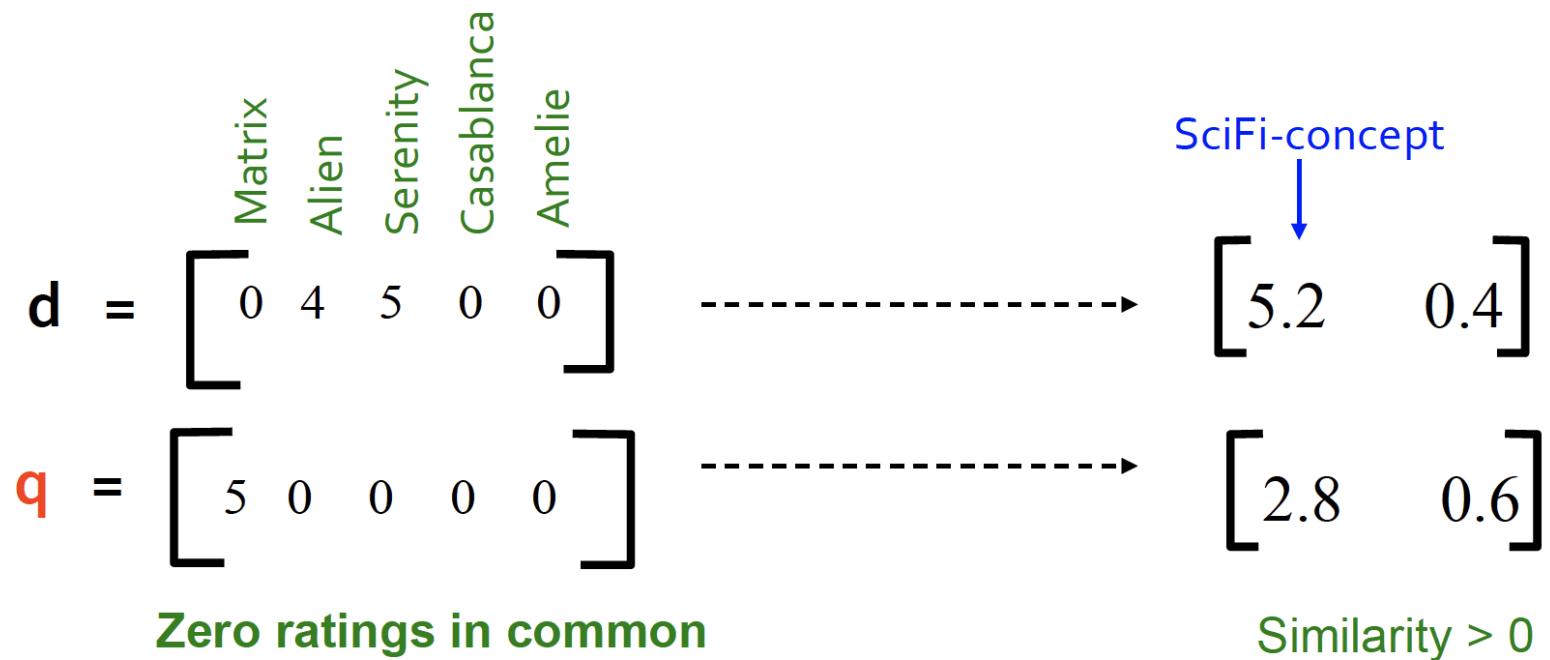
E.g.:

$$\begin{bmatrix} \text{Matrix} \\ 0 & 4 & 5 & 0 & 0 \end{bmatrix} \mathbf{d} \times \begin{bmatrix} \text{Alien} \\ \text{Serenity} \\ \text{Casablanca} \\ \text{Amelie} \end{bmatrix} \mathbf{X} \begin{bmatrix} 0.56 & 0.12 \\ 0.59 & -0.02 \\ 0.56 & 0.12 \\ 0.09 & -0.69 \\ 0.09 & -0.69 \end{bmatrix} \text{SciFi-concept} = \begin{bmatrix} 5.2 \\ 0.4 \end{bmatrix}$$

movie-to-concept  
similarities ( $\mathbf{V}$ )

# Case study: How to query?

- **Observation:** User  $d$  that rated ('Alien', 'Serenity') will be **similar** to user  $q$  that rated ('Matrix'), although  $d$  and  $q$  have **zero ratings in common!**



# SVD: Drawbacks

- + **Optimal low-rank approximation**  
in terms of Frobenius norm
- **Interpretability problem:**
  - A singular vector specifies a linear combination of all input columns or rows
- **Lack of sparsity:**
  - Singular vectors are **dense!**

$$\begin{matrix} \cdot & \cdot \\ \vdots & \vdots \\ \cdot & \cdot \\ \cdot & \cdot \end{matrix} = \begin{matrix} \cdot & \cdot \\ \vdots & \vdots \\ \cdot & \cdot \\ \cdot & \cdot \end{matrix} U \begin{matrix} \Sigma \\ \vdots \end{matrix} V^T$$

# Recap

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- c-th concept = c-th col of  $U_k$  (*which is  $m \times k$* )
  - $U_k[i][c]$  = strength of association between c-th concept and i-th row (term/user/...)
  - $V^t_k[c][j]$  = strength of association between c-th concept and j-th column (document/movie/...)
- Projected query:  $q' = q V_k$ 
  - $q'[c] = \text{strength of concept } c \text{ in } q$
- Projected column (doc/movie):  $d'_j = d_j V_k$ 
  - $d'_j[c] = \text{strength of concept } c \text{ in } d_j$