

New Frontiers In Human-robot Interaction

Author: Kerstin Dautenhahn Joe Saunders / **Category**: Computers / **Total Pages**: 332 pages

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Summary: Free new frontiers in human-robot interaction pdf download - human robot interaction hri considers how people can interact with robots in order to enable robots to best interact with people hri presents many challenges with solutions requiring a unique combination of skills from many fields including computer science artificial intelligence social sciences ethology and engineering we have specifically aimed this work to appeal to such a multi-disciplinary audience this volume presents new and exciting material from hri researchers who discuss research at the frontiers of hri the chapters address the human aspects of interaction such as how a robot may understand provide feedback and act as a social being in interaction with a human to experimental studies and field implementations of human robot collaboration ranging from joint action robots practically and safely helping people in real world situations robots helping people via rehabilitation and robots acquiring concepts from communication this volume reflects current trends in this exciting research field

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using visual attention to evaluate collaborative control ... - architectures for human robot interaction ... in proc. of "new frontiers in human - robot interaction", a symposium at aisb 2009, edinburgh, uk, april 2009, pp 38-43.

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considering the bystander's perspective for indirect human ... - considering the bystander's perspective for indirect human-robot ... role of interaction ... in "new frontiers in human-robot interaction ...

automated prediction of extraversion during human-robot ... - automated prediction of extraversion during human-robot interaction ... new information ... aisb2009 symposium on new frontiers in human-robot interaction pp. 94{101 ...

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a two-day symposium at aisb 2010 (31 march – 1 april 2010 ... - new frontiers in human-robot interaction ... 9:05-10.30 session: multi-modal human-robot interaction (4 contributed papers, 15

min each for presentation, ...

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turn-yielding cues in robot-human conversation - turn-yielding cues in robot-human conversation ... taking cues during human-robot interaction. ... turn-yielding events we developed a new task where the participant

iterative design process for robots with personality - human-robot interaction [3] ... proceedings of the aisb2009 symposium on new frontiers in human-robot interaction edingburgh pp. 94-101. 94.

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how infants perceive the toy robot pleo. an exploratory ... - how infants perceive the toy robot pleo. an exploratory case study on infant-robot-interaction ... treat such new technologies as either x or y?" ...

the impact of robot design approach on product evaluation ... - product usefulness and purchase intention ... design approach for a better human-robot interaction. ... of the new frontiers in human-robot interaction ...

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creating trustworthy robots: lessons and inspirations from ... - creating trustworthy robots: lessons and ... new frontiers in human-robot interaction. creating trustworthy robots: lessons and inspirations from automated systems

improving the modeling of dog-owner interactions for the ... - improving the modeling of dog ... improving the modeling of dog-owner interactions for the design of ... the relevance to the field of human-robot interaction ...

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proceedings of the international workshop on new frontiers ... - the international new frontiers of service robotics for the elderly took place in conjunction with the 23rd ieee international ... and human -robot interaction;

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an autonomous proxemic system for a mobile companion robot - an autonomous proxemic system for a mobile ... field of human-robot interaction ... second international symposium on new frontiers in human-robot interaction, ...

the imhg dataset: a multi-view hand gesture rgb-d dataset ... - ... a multi-view hand gesture rgb-d dataset for human-robot interaction ... communication in human-robot interaction ... interface in hri opens up new frontiers of ...

migrating artificial companions (demonstration) - migrating artificial companions (demonstration) ... intelligence for human-robot interaction, ... new frontiers of human-robot interaction, ...

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a dynamic field approach to goal inference, error ... - 4 selection in human-robot collaboration ... 5 joe (eds), new frontiers in human robots interaction, [advances in interaction 6 studies, 2] 2011. vi, ...

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