mmWAVE SENSOR EVALUATION SOLUTION

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Joybien Batman BM201 mmWave EVM Kit is a Texas Instruments (TI) IWR6843 ASIC based millimeter-wave (mmWave) Kit with Frequency-Modulated Continuous Wave (FMCW) radar technology capable of operation in the 60GHz to 64GHz band with up to 4 GHz continuous chirp, using 3 Transmission Antennas and 4 Receiving Antennas, for sensing target object's range, velocity, and angle parameters. Batman BM201 mmWave EVM Kit is with a small and compact mmWave Module (with low-power, self-monitored, ultra-accurate, and lighting condition independent versatilities), along with a Pi-Hat Board for simple and direct connectivity to a Raspberry Pi or NVIDIA Jetson Nano computer, suitable for various applications including: Education, Engineering, Science, Industrial, Medical, and Business & Consumer.

### **Applications**

- Education's Practical Radar Introduction
- Engineering & Science's Motion Detection, Displacement, etc.
- Industrial sensor for Displacement & Safe Guard, Factory Automation, Robotics, etc.
- Building Automation sensor for Occupancy Detection, Proximity & Position sensing, People Counting, Security and Surveillance
- Business' Traffic Monitoring, and Proximity Advertisement

#### Specification

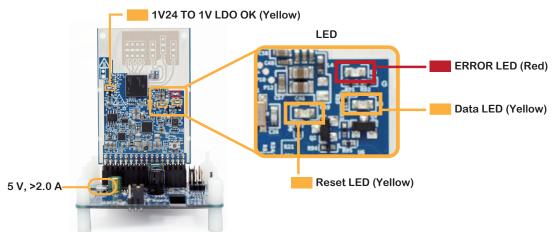
(BM201-LPD) Long-Range People Detection	For a contactless and wearableless Long-Range People Detection (LPD) of 1 meter ~ 50 meters (about 3 ~ 164 feet), for various applications that require people sensing or counting without privacy invasion.	
(BM201-TMD) Traffic Monitoring Detection	For detecting moving objects (such as vehicles) in 5m ~ 50m with FOV of approx. +/- 54 degrees with Position X&Y, Velocity X&Y info. And based on the detected data, a programmer may write a program to define virtual Zones, for mapping objects (vehicles) moving in and out of certain Zones for traffic monitoring applications.	
(BM201-VSD) Vital Signs Detection	For a contactless and wearableless human Vital Signs Detection (VSD) with real-time Heartbeat Rate & Respiration Rate data, for range of 30cm ~ 90cm (about 1~3 feet); along with Status Indicator for sensing the presence of a person, as well as the measurement stability, and whether the person is present but without Vital Signs.	
(BM201-HAM) High Accuracy Measurement	For a wireless High Accuracy Measurement (HAM) of an object distance with range of 30cm ~ 3 meters (about 1~10 feet), having millimeter measurement resolution.	

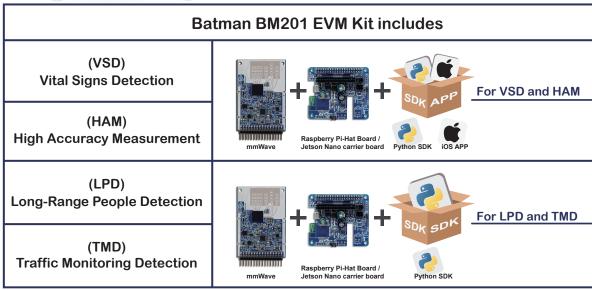
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### Packing List: mmWave Module, Raspberry Pi-Hat Board, Python SDK

Make sure you are using the correct power supply of 5 V, >2.0 A with a Micro USB connection





#### **Features**

•Operating Frequency: 60GHz ~ 64GHz coverage

with 4GHz continuous bandwidth

•Antenna: 3 Tx and 4 Rx Antennas on Module, with:

TX Power: 10 dBm

RX Noise Figure: 14 dB

Processors: ARM R4F based MCU and C674x DSP

for advanced signal processing

On-Chip Memory: 1.75MB

Internal Memories With ECC

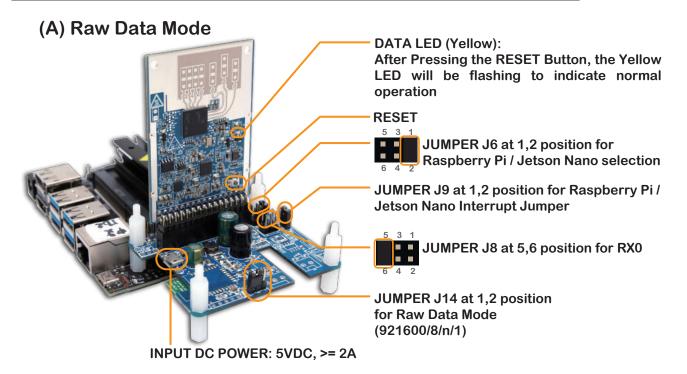
Integrated Peripherals

•Input Power:3.3Vdc, 2.1A

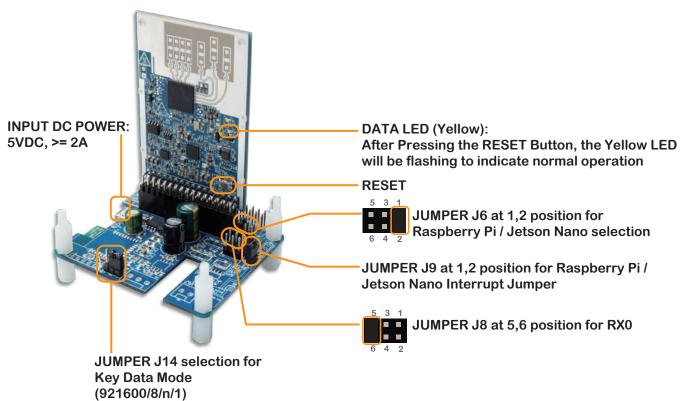
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### Selection: Key Data Mode or Raw Data Mode Application



### (B) Key Data Mode

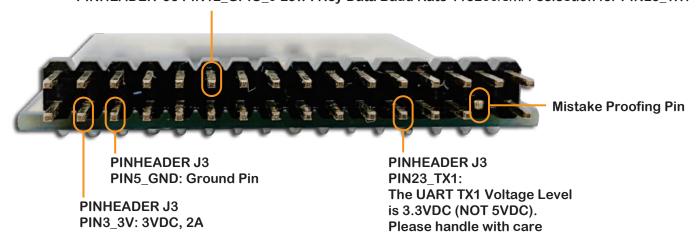


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### Batman BM201 Module J3 Pin Assignment Note

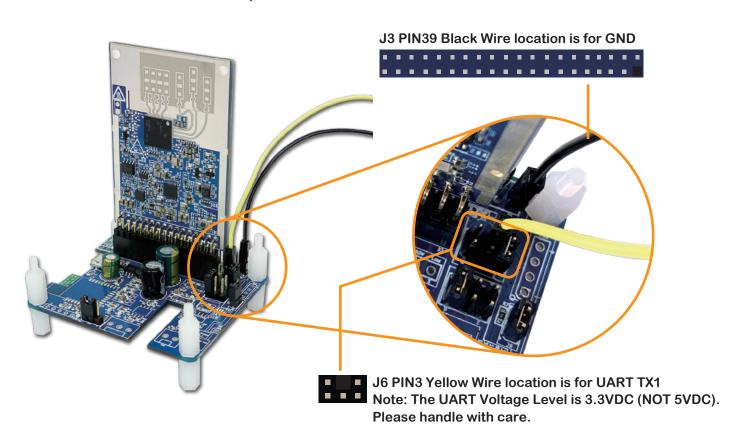
PINHEADER J3 PIN12\_GPIO\_0 High: Raw Data Baud Rate 921600/8/n/1 selection for PIN23\_TX1 PINHEADER J3 PIN12\_GPIO\_0 Low: Key Data Baud Rate 115200/8/n/1 selection for PIN23\_TX1



Alert: All GPIO Pins base on 3.3V System. Pin23\_TX1 is DC 3.3V system.

#### Batman BM201 EVM Kit + External Microprocessor

Wire connections for external microprocessor access on the HAT-Board



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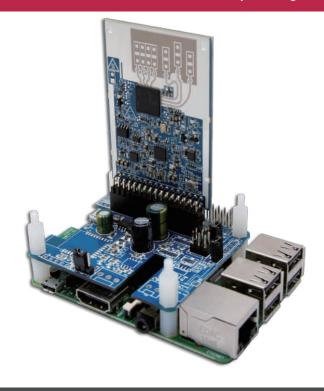
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Batman Kit + NVIDIA Jetson Nano / Batman Kit + Raspberry Pi Please make sure that the JUMPER SETTING is for Raw Data Mode

Batman BM201 EVM Kit + Jetson Nano



### Batman BM201 EVM Kit + Raspberry Pi



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### **Specifications**

### mmWave Sensor Evaluation Module



mmWave ASIC	TI IWR6843 Single Chip mmWave Sensor		
FMCW Transceiver	● Integrated PLL, Transmitter, Receiver, Baseband, and A2D		
	● 60GHz to 64GHz Coverage With 4GHz Continuous Bandwidth		
	Four Receive Channels		
	Three Transmit Channels		
	<ul> <li>Ultra-Accurate Chirp Engine Based on Fractional-N PLL</li> </ul>		
	TX Power: 10 dBm		
	RX Noise Figure: 14 dB		
	● Phase Noise at 1 MHz: –92 dBc/Hz		
	Antenna Type : ISK Antenna		
Built-in Calibration	ARM® Cortex® -R4F-Based Radio Control System		
and Self-Test	Built-in Firmware (ROM)		
(Monitoring)	Self-calibrating System Across Frequency and Temperature		
DSP	C674x DSP for Advanced Signal Processing		
On-Chip Memory	● 1.75MB		
MCU	ARM R4F Microcontroller for Object Detection, and Interface Control		
	<ul> <li>Joybien mmWave Protocol (Per configuration)</li> </ul>		
I/O	Up to 6 ADC Channels (low sample rate monitoring)		
	Up to 2 SPI Ports		
	• Up to 2 UARTs		
	• I2C – GPIOs		
Power Management	Built-in LDO Network for Enhanced PSRR		
<b>3</b>	● I/Os Support Dual Voltage 3.3 V/1.8 V		
Clock Source	40MHz		
Antenna Orientation	4 receive(RX) 3 transmit (TX) antenna with 108° azimuth field of view (FoV) and 44° elevation FoV		
Input Power	3.3VDC, 2.1A source		
Operating Temperature	0°C ~ 40°C		
& Humidity	10% ~ 85% Non-Condensing		
Dimensions & Weight	67mm x 46mm x 2mm ; 15 grams net		

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### Raspberry Pi-Hat Board /

Jetson Nano carrier board



Connector	<ul> <li>Matching mmWave Module Female Connector</li> <li>Matching Raspberry Pi GPIO Female Connector</li> <li>Micro USB Power Connector</li> <li>Jumpers for Bluetooth Tx/Rx or Raspberry Pi Tx/Rx Selection</li> <li>Jumper for mmWave Raw Data or Key Data Selection</li> </ul>	
Bluetooth (optional)	Joybien JBT24M Bluetooth Low Energy Module	
Micro USB Input Power	5VDC, 2Amp. (Note: Power Adapter and Micro USB Cable NOT included)	
Operating Temperature Operating Humidity	<ul> <li>0° to 40° degree Celsius</li> <li>10 ~ 85% Non-Condensing</li> </ul>	
Dimensions & Weight	65.3mm x 56.3mm     30 grams with JBT24M Bluetooth	

### **Python SDK**



**Python SDK** 

 Available on GitHub Note: Please refer to README.md file first for proper configuration

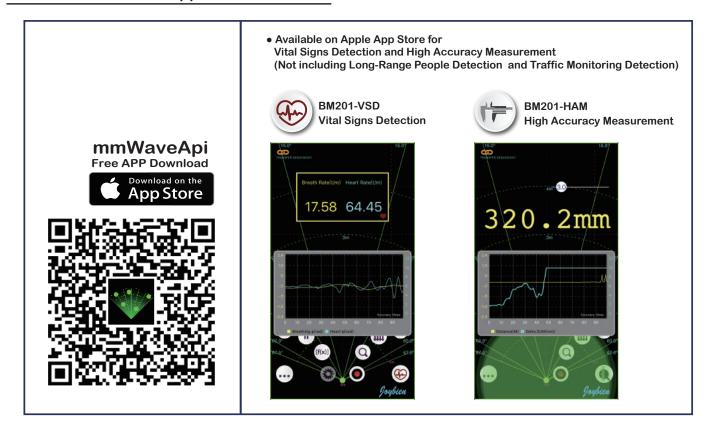




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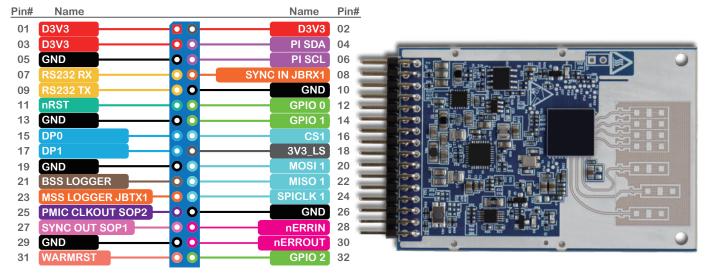
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### iOS mmWave Demo App: VSD and HAM



# mmWave Pin Assignment





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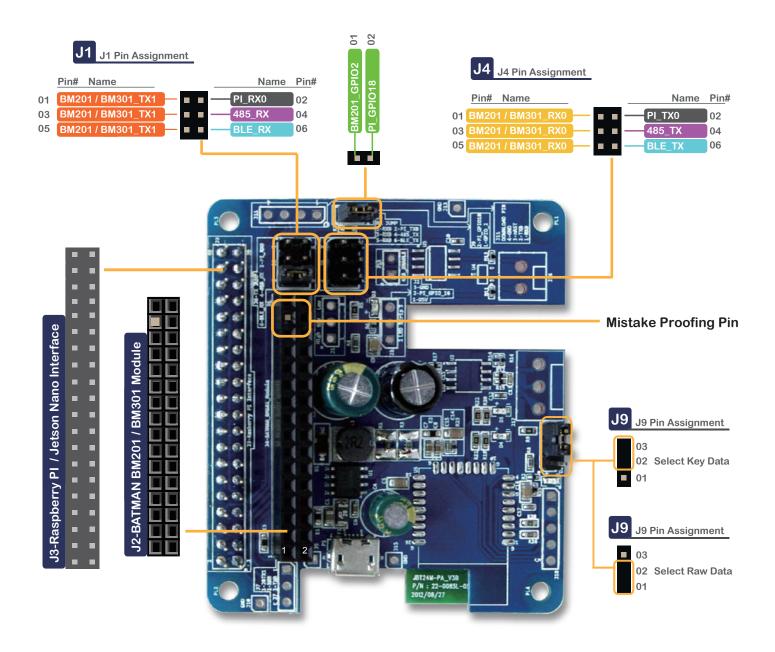
### J3 Pin Assignment

O9		Assigninent		
D3V3	Pin No	Name	Pin Type	Function Description
03	01	D3V3	ı	POWER DC 3V3 Input
04 SDA IO I2C Pin 05 GND GROUND Digital ground 06 SCL IO I2C Pin 07 RS232 RX0 I UART A Receive 08 SYNC IN JBRX1 I Low frequency Synchronization signal input, UART B Receive 09 RS232 TX0 O UART A Transmit 10 GND GROUND Digital ground 11 nRST I Power on reset for chip. Active low 12 GOIO 0 I Select KeyData or RawData 13 GND GROUND Digital ground 14 GPIO 1 I Reserved 15 DPO IO GPIO Pin 16 CS1 IO SPI Channel A - chip Select 17 DP1 IO GPIO Pin 18 3V3 O For meaurement only 19 GND GROUND Digital ground 20 MOSI 1 IO SPI Channel A - Master Out Slave In 21 BSS LOGGER IO BSS LOGGER 22 MISO 1 IO SPI Channel A - Master In Slave Out 23 MSS LOGGER JBTX1 O UART B Transmit 24 SPICLK 1 IO SPI Channel A - Clock 25 SOP2 I SOP2 26 GND GROUND Digital ground 27 SOP1 I SOP1 28 nERRIN I Failsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware. 29 GND GROUND Mistake Proofing Pin Open drain fail safe output signal. Can be driven from	02	D3V3	ı	POWER DC 3V3 Input
05	03	D3V3	ı	POWER DC 3V3 Input
06 SCL IO I2C PIN 07 RS232 RX0 I UART A Receive 08 SYNC IN JBRX1 I Low frequency Synchronization signal input, UART B Receive 09 RS232 TX0 O UART A Transmit 10 GND GROUND Digital ground 11 nRST I Power on reset for chip. Active low 12 GOIO 0 I Select KeyData or RawData 13 GND GROUND Digital ground 14 GPIO 1 I Reserved 15 DPO IO GPIO Pin 16 CS1 IO SPI Channel A - chip Select 17 DP1 IO GPIO Pin 18 3V3 O For meaurement only 19 GND GROUND Digital ground 20 MOSI 1 IO SPI Channel A - Master Out Slave In 21 BSS LOGGER IO SPI Channel A - Master In Slave Out 22 MISO 1 IO SPI Channel A - Clock 23 MSS LOGGER JBTX1 O UART B Transmit 24 SPICLK 1 IO SPI Channel A - Clock 25 SOP2 I SOP2 26 GND GROUND Digital ground 27 SOP1 I SOP1 28 nERRIN I Failsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware. 29 GND GROUND Mistake Proofing Pin Open drain fail safe output signal. Connected to PMIC/Processor/MCU to indicate that some severe criticatlif fault has happened. Recovery would be through reset. Open drain fail safe warm reset signal. Can be driven from	04	SDA	10	I2C Pin
O7 RS232 RX0	05	GND	GROUND	Digital ground
SYNC IN JBRX1	06	SCL	10	I2C Pin
09 RS232 TX0	07	RS232 RX0	ı	UART A Receive
10 GND GROUND Digital ground 11 nRST I Power on reset for chip. Active low 12 GOIO 0 I Select KeyData or RawData 13 GND GROUND Digital ground 14 GPIO 1 I Reserved 15 DPO IO GPIO Pin 16 CS1 IO SPI Channel A - chip Select 17 DP1 IO GPIO Pin 18 3V3 O For meaurement only 19 GND GROUND Digital ground 20 MOSI 1 IO SPI Channel A - Master Out Slave In 21 BSS LOGGER IO BSS LOGGER 22 MISO 1 IO SPI Channel A - Master In Slave Out 23 MSS LOGGER JBTX1 O UART B Transmit 24 SPICLK 1 IO SPI Channel A - Clock 25 SOP2 I SOP2 26 GND GROUND Digital ground 27 SOP1 I SOP1 28 nERRIN I Failsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware.  10 Open drain fail safe output signal. Connected to PMIC/Processor/MCU to indicate that some severe criticallifalt has happened. Recovery would be through reset.  29 Open drain fail safe warm reset signal. Can be driven from	08	SYNC IN JBRX1	ı	Low frequency Synchronization signal input, UART B Receive
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12 GOIO 0 I Select KeyData or RawData  13 GND GROUND Digital ground  14 GPIO 1 I Reserved  15 DPO IO GPIO Pin  16 CS1 IO SPI Channel A - chip Select  17 DP1 IO GPIO Pin  18 3V3 O For meaurement only  19 GND GROUND Digital ground  20 MOSI 1 IO SPI Channel A - Master Out Slave In  21 BSS LOGGER IO BSS LOGGER  22 MISO 1 IO SPI Channel A - Master In Slave Out  23 MSS LOGGER JBTX1 O UART B Transmit  24 SPICLK 1 IO SPI Channel A - Clock  25 SOP2 I SOP2  26 GND GROUND Digital ground  27 SOP1 I SOP1  28 nERRIN I Failsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware.  29 GND GROUND Mistake Proofing Pin  O PMIC/Processor/MCU to indicate that some severe criticatlif fault has happened. Recovery would be through reset.  Open drain fail safe warm reset signal. Can be driven from	10	GND	GROUND	Digital ground
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17 DP1 IO GPIO Pin  18 3V3 O For meaurement only  19 GND GROUND Digital ground  20 MOSI 1 IO SPI Channel A - Master Out Slave In  21 BSS LOGGER IO BSS LOGGER  22 MISO 1 IO SPI Channel A - Master In Slave Out  23 MSS LOGGER JBTX1 O UART B Transmit  24 SPICLK 1 IO SPI Channel A - Clock  25 SOP2 I SOP2  26 GND GROUND Digital ground  27 SOP1 I SOP1  28 NERRIN I Failsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware.  29 GND GROUND Mistake Proofing Pin  O Open drain fail safe output signal. Connected to PMIC/Processor/MCU to indicate that some severe criticatlif fault has happened. Recovery would be through reset.  Open drain fail safe warm reset signal. Can be driven from	15	DP0	10	GPIO Pin
18 3V3 O For meaurement only  19 GND GROUND Digital ground  20 MOSI 1 IO SPI Channel A - Master Out Slave In  21 BSS LOGGER IO BSS LOGGER  22 MISO 1 IO SPI Channel A - Master In Slave Out  23 MSS LOGGER JBTX1 O UART B Transmit  24 SPICLK 1 IO SPI Channel A - Clock  25 SOP2 I SOP2  26 GND GROUND Digital ground  27 SOP1 I SOP1  28 NERRIN I Failsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware.  29 GND GROUND Mistake Proofing Pin  30 NERROUT O Open drain fail safe output signal. Connected to PMIC/Processor/MCU to indicate that some severe criticatlif fault has happened. Recovery would be through reset.  Open drain fail safe warm reset signal. Can be driven from	16	CS1	10	SPI Channel A - chip Select
19 GND GROUND Digital ground 20 MOSI 1 IO SPI Channel A - Master Out Slave In 21 BSS LOGGER IO BSS LOGGER 22 MISO 1 IO SPI Channel A - Master In Slave Out 23 MSS LOGGER JBTX1 O UART B Transmit 24 SPICLK 1 IO SPI Channel A - Clock 25 SOP2 I SOP2 26 GND GROUND Digital ground 27 SOP1 I SOP1 28 NERRIN I Failsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware. 29 GND GROUND Mistake Proofing Pin 30 NERROUT O Open drain fail safe output signal. Connected to PMIC/Processor/MCU to indicate that some severe criticatlif fault has happened. Recovery would be through reset. Open drain fail safe warm reset signal. Can be driven from	17	DP1	10	GPIO Pin
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21 BSS LOGGER  22 MISO 1 IO SPI Channel A - Master In Slave Out  23 MSS LOGGER JBTX1 O UART B Transmit  24 SPICLK 1 IO SPI Channel A - Clock  25 SOP2 I SOP2  26 GND GROUND Digital ground  27 SOP1 I SOP1  28 nERRIN I Failsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware.  29 GND GROUND Mistake Proofing Pin  30 nERROUT O Open drain fail safe output signal. Connected to PMIC/Processor/MCU to indicate that some severe criticatlif fault has happened. Recovery would be through reset.  Open drain fail safe warm reset signal. Can be driven from	19	GND	GROUND	Digital ground
22   MISO 1   IO   SPI Channel A - Master In Slave Out	20	MOSI 1	10	SPI Channel A - Master Out Slave In
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24 SPICLK 1  10 SPI Channel A - Clock  25 SOP2  1 SOP2  26 GND  27 SOP1  1 SOP1  28 nERRIN  1 Failsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware.  29 GND  30 nERROUT  O Open drain fail safe output signal. Connected to PMIC/Processor/MCU to indicate that some severe criticatling fault has happened. Recovery would be through reset.  Open drain fail safe warm reset signal. Can be driven from	22	MISO 1	10	SPI Channel A - Master In Slave Out
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26 GND GROUND Digital ground  27 SOP1 I SOP1  28 nERRIN I Failsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware.  29 GND GROUND Mistake Proofing Pin  30 nERROUT O Open drain fail safe output signal. Connected to PMIC/Processor/MCU to indicate that some severe criticatling fault has happened. Recovery would be through reset.  Open drain fail safe warm reset signal. Can be driven from	24	SPICLK 1	10	SPI Channel A - Clock
27 SOP1  1 SOP1  28 nERRIN  I Failsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware.  29 GND  GROUND  Mistake Proofing Pin  O Open drain fail safe output signal. Connected to PMIC/Processor/MCU to indicate that some severe criticatling fault has happened. Recovery would be through reset.  Open drain fail safe warm reset signal. Can be driven from	25	SOP2	1	SOP2
Pailsafe input to the device. Nerror output from any other device can be concentrated in the error signaling monitor module inside the device and appropriate action can be taken by Firmware.  GROUND Mistake Proofing Pin  Open drain fail safe output signal. Connected to PMIC/Processor/MCU to indicate that some severe criticatlif fault has happened. Recovery would be through reset.  Open drain fail safe warm reset signal. Can be driven from	26	GND	GROUND	Digital ground
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Open drain fail safe output signal. Connected to PMIC/Processor/MCU to indicate that some severe criticatlif fault has happened. Recovery would be through reset.  Open drain fail safe warm reset signal. Can be driven from	28	nERRIN	1	device can be concentrated in the error signaling monitor module inside the device and appropriate action can be
PMIC/Processor/MCU to indicate that some severe criticatlist fault has happened. Recovery would be through reset.  Open drain fail safe warm reset signal. Can be driven from	29	GND	GROUND	Mistake Proofing Pin
	30	nERROUT	0	PMIC/Processor/MCU to indicate that some severe criticatlity
device is going through reset.	31	WARMRST	Ю	PMIC for diagnostic or can be used as status signal that the
32 GPIO2 O LED Indicator	32	GPIO2	0	LED Indicator

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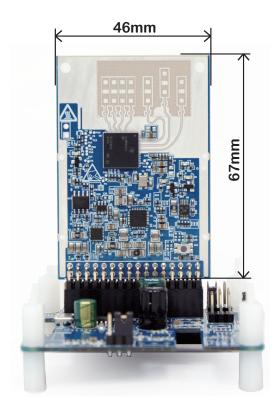
# mmWave Raspberry Pi Hat Pin Assignment



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#### **Product Dimensions**



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This EVM Kit does not include Raspberry Pi computer, nor NVIDIA Jetson Nano computer.



(BM101-VSD) Vital Signs Detection

For a contactless and wearableless human Vital Signs Detection (VSD) with real-time Heartbeat Rate & Respiration Rate data, for range of 30cm ~ 90cm (about 1~3 feet); along with Status Indicator for sensing the presence of a person, as well as the measurement stability, and whether the person is present but without Vital Signs.



(BM101-HAM) High Accuracy Measurement

For a wireless High Accuracy Measurement (HAM) of an object distance with range of 30cm ~ 3 meters (about 1~10 feet), having millimeter measurement resolution.



(BM101-PMB)
People Movement Behavior

For a wireless People Movement Behavior (PMB) detection in 4 x 4 meter or 16 meter square area (or about 172 square feet); and with software that could set virtual geo-fence(s) to trigger alert or action when People are moving into the geo-fence(s).



(BM101-SRR) Short Range Radar

For Short Range Radar (SRR) detection of human in 1 meter  $\sim$  20 meters (about 3  $\sim$  66 feet), or detection of vehicle in 1 meter  $\sim$  50 meters (about 3  $\sim$  164 feet), along with viewing angle of 120 degrees; along with Doppler Data to distinguish for whether the objects are moving-towards or moving-away from the mmWave sensor.



(BM101-ZOD)
Zone Occupancy Detection

For plotting a Range-Azimuth-Heatmap with a 64 x48 Grid Matrix covering: Range of 3meter/64row (approx. 0.047meter per row) x Azimuth of 120degree/48column (approx. 2.5degree/column). Subsequently a programmer may write a program to group the Grid(s) into Zone(s) for detecting whether the particular Zone(s) is occupied by Target(s).



(BM201-LPD)
Long-Range People Detection

For a contactless and wearableless Long-Range People Detection (LPD) of 1 meter ~ 50 meters (about 3 ~ 164 feet), for various applications that require people sensing or counting without privacy invasion.



(BM201-TMD)
Traffic Monitoring Detection

For detecting moving objects (such as vehicles) in 5m ~ 50m with FOV of approx. +/- 54 degrees with Position X&Y, Velocity X&Y info. And based on the detected data, a programmer may write a program to define virtual Zones, for mapping objects (vehicles) moving in and out of certain Zones for traffic monitoring applications.



(BM201-VSD)
Vital Signs Detection

For a contactless and wearableless human Vital Signs Detection (VSD) with real-time Heartbeat Rate & Respiration Rate data, for range of 30cm ~ 90cm (about 1~3 feet); along with Status Indicator for sensing the presence of a person, as well as the measurement stability, and whether the person is present but without Vital Signs.



(BM201-HAM) High Accuracy Measurement For a wireless High Accuracy Measurement (HAM) of an object distance with range of 30cm ~ 3 meters (about 1~10 feet), having millimeter measurement resolution.



(BM301-FDS)
Fall Detection Sensing

For the wireless detection of People in 3-Dimensional movement from -3 meter ~ +3 meter on one direction, and -3 meter ~ + 3 meter on the perpendicular/orthogonal direction, and +3 meter from ceiling to ground, all with the respect to the mmWave Sensor positioned in the center of the ceiling; and thus, the Sensor is capable to detect and track people movement along with standing, sitting, lying down positions