PRML笔记

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1 Introduction

example: recognizing handwritten digits 手写识别

training set:

a large set of N digits {x1,...,xn}

To tune the parameters of an adaptive model 用来调节模型的参数 target vector t/y:

function y(x):

determined during the training/learning phase,

Preprocessed

transform them into some new space of variables speed up computation

- 1、supervised learning有监督学习 target vectors
 - 1. classification 分类

assign each input vector to one of a finite number of discrete categories,

2. regression. 回归

output consists of one or more continuous variables

- 2、unsupervised learning无监督学习 without target vectors
 - 1. clustering 聚类

similar examples within the data

2. density estimation 密度估计

determine the distribution of data within the input space 决定输入空间中数据的分布

3. Visualization 可视化

high-dimensional space down to two or three dimensions

3、reinforcement learning 反馈学习

finding suitable actions to take in a given situation in order to maximize a reward. 在给定的条件下,找到合适的动作,使回报达到最大值 feature:

trade-off between exploration and exploitation

- exploration: 探索
 - o system tries out new kinds of actions to see how effective they are,
- exploitation: 利用

o system makes use of actions that are known to yield a high reward

1.1 Example: Polynomial Curve Fitting 多项式曲线拟合

given a training set

$$\mathbf{x} \equiv (x_1,\ldots,x_N)^{\mathrm{T}}$$

observations of the values 观测值

$$\mathbf{t} \equiv (t_1, \dots, t_N)^{\mathrm{T}}$$

fit the data using a polynomial function of the form 多项式函数来拟合数据

$$y(x, \mathbf{w}) = w_0 + w_1 x + w_2 x^2 + \ldots + w_M x^M = \sum_{j=0}^M w_j x^j$$

y(x, w) is a linear function of the coefficients w. 线性模型

error function 误差函数

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \{y(x_n, \mathbf{w}) - t_n\}^2$$

choosing the order M

model comparison or model selection.

root-mean-square (RMS) error

$$E_{\rm RMS} = \sqrt{2E(\mathbf{w}^{\star})/N}$$

over-fitting problem 控制过拟合问题

Regularization 正则化

adding a penalty term to the error function 给误差函数增加一个惩罚项, 调节参数λ

$$\widetilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \{y(x_n, \mathbf{w}) - t_n\}^2 + \frac{\lambda}{2} ||\mathbf{w}||^2$$

1.2 Probability Theory 概率论

加法规则 乘法规则 贝叶斯定理 先验概率

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概率密度 probability density

$$p(x \in (a,b)) = \int_a^b p(x) dx$$

累积分布函数 cumulative distribution function

$$P(z) = \int_{-\infty}^{z} p(x) \, \mathrm{d}x$$

两者关系:

$$P'(x) = p(x)$$

推出新的加法规则和乘法规则

$$p(x) = \int p(x, y) \, \mathrm{d}y$$

$$p(x,y) = p(y \mid x)p(x)$$

期望

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$$\mathbb{E}[f] = \sum_{x} p(x) f(x)$$

连续

$$\mathbb{E}[f] = \int p(x)f(x) \, \mathrm{d}x$$

方差

$$var[f] = \mathbb{E}[(f(x) - \mathbb{E}[f(x)])^2]$$

1.2.3 Bayesian probabilities 贝叶斯定理

先验概率p(w) + 条件概率p(D | w)

$$p(\mathbf{w}|\mathcal{D}) = rac{p(\mathcal{D}|\mathbf{w})p(\mathbf{w})}{p(\mathcal{D})}$$

posterior ∝ likelihood × prior 频率学家

最大似然(maximum likelihood)估计自助法(bootstrap)

马尔科夫链蒙特卡罗 应用干小规模问题

1.2.4 The Gaussian distribution 高斯分布

$$\mathcal{N}\left(x|\mu,\sigma^2\right) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp\left\{-\frac{1}{2\sigma^2}(x-\mu)^2\right\}$$

μ均值(mean),

σ2方差(variance)

方差的倒数,记作精度 (precision)

$$\beta = \frac{1}{\sigma^2}$$