

# MARCO CASAGRANDE

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# **EXPERIENCE**

SEP 2021- ONGOING

## **ALGORITHM DEVELOPER** - IBEO AUTOMOTIVE SYSTEMS GMBH, GERMANY

Development of automotive perception algorithms to estimate the position and orientation of the Ego vehicle.

Implemented estimation of the relative localization of the Ego vehicle with respect to an airplane based on LiDAR data and showcased in *AirPortMover* project.

Working on lane marking extraction and tracking through camera- and LiDAR data.

Integrating and testing software with unit tests as well as in the vehicle platform.

OCT 2019 - AUG 2021

## **WORKING STUDENT** - IBEO AUTOMOTIVE SYSTEMS GMBH, GERMANY

Creation of simulation scenarios in CarMaker for testing autonomous driving functions.

MAY 2018 - SEP 2019

## PROJECT ENGINEER - IBEO AUTOMOTIVE SYSTEMS GMBH, GERMANY

Validation of customer perception stack via a proprietary reference system, providing ground truth and related KPIs.

Offering remote and on-site technical support and trainings to customers and partners.

AUGUST 2016 – JANUARY 2017

**ENGINEERING INTERN** – ROBERT BOSCH GMBH, GERMANY

Characterization and validation of inertial MEMS sensor samples.

MAY 2011 - MAY 2014

JR. FULL-STACK DEVELOPER – FB SERVICES SRL, ITALY

Development of web applications for infotainment systems.

# **EDUCATION**

#### **OCTOBER 2019 – AUGUST 2021**

# M. SC. ICT INNOVATION, KTH STOCKHOLM, TU BERLIN

Degree project: "Relative pose estimation of a plane on an airfield with automotive-class solid-state LiDAR sensors", GPA: 1.0

#### **RELEVANT COURSES:**

- Robotics
- Laser Scanning Technologies

- Event-based robot vision
- Reinforcement Learning

#### SEPTEMBER 2014 - APRIL 2018

## B. SC. INFORMATION ENGINEERING, HAW HAMBURG

Degree project: "Robust setup of an Autonomous Mobile Robot research platform with multisensor integration in ROS", GPA: 0.9, HAW Best Graduate Award 2018

#### **RELEVANT COURSES:**

- Software Engineering
- Algorithms and Data Structures
- Introduction to Computer Graphics
- Electronics
- Microcontrollers
- Digital Signal Processing

# SKILLS

- Algorithms development
- LiDAR sensor data processing
- Agile development with SCRUM

- Proficient: C++ 14, ROS, Git, Linux
- Familiar: C, C#, Python, Java, PHP, CarMaker
- German B2, English C1, Italian

## **EXPECTATIONS**

- Challenging and interesting tasks
- Career opportunities
- Working occasionally from abroad
- Flexible working time preferred

- Training opportunities
- Hybrid work at home and office
- Transparent communication between management and employees

## **AVAILABILITY**

• Can start working after three months' notice

# REFERENCES

More information on my work as well as certificates and letters of recommendation can be found on my portfolio page [1].

[1] M. Casagrande. [Online]. Available: https://github.com/bighouwski/portfolio.