

# Gibbs Sampling

## Some Theory and Some Practice

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# Outline

- 1 Introduction to Markov Chain Methods
  - The Grasshopper's Problems

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  - Systematic Scan
  - Bivariate Normal

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  - Bivariate Normal
- 4 Application in Statistics
  - Known Marginal

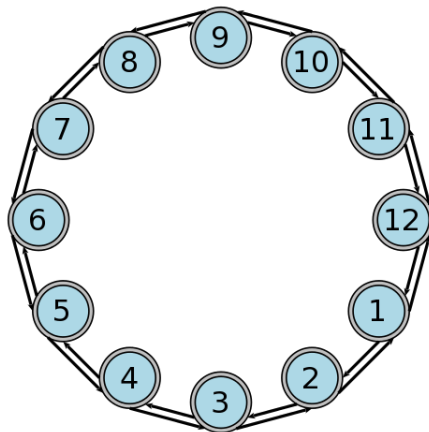
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- 5 The Ising Model
- 6 Appendices

# Visit Each Hour Equally





# Suppose Achieve Goal

$$\pi'(n) = p(n | n - 1)\pi(n - 1) + p(n | n + 1)\pi(n + 1)$$

## Suppose Achieve Goal

$$\pi'(n) = p(n | n-1)\pi(n-1) + p(n | n+1)\pi(n+1)$$

$$\pi'(n) = \frac{1}{2} \frac{1}{N} + \frac{1}{2} \frac{1}{N} = \frac{1}{N}$$

# Testing Convergence

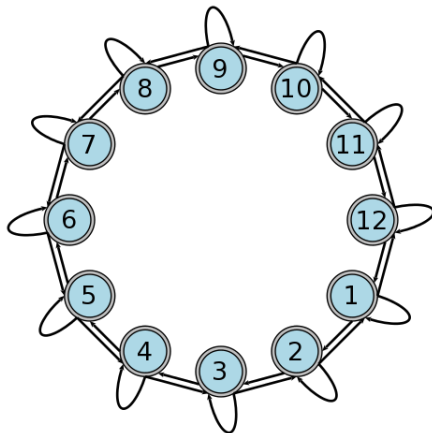
```
ghci> startOnOne  
(1<5)  
[ 1.0, 0.0, 0.0, 0.0, 0.0 ]
```

```
ghci> eqProbsMat  
(5<5)  
[ 0.0, 0.5, 0.0, 0.0, 0.5  
  , 0.5, 0.0, 0.5, 0.0, 0.0  
  , 0.0, 0.5, 0.0, 0.5, 0.0  
  , 0.0, 0.0, 0.5, 0.0, 0.5  
  , 0.5, 0.0, 0.0, 0.5, 0.0 ]
```

# Testing Convergence

```
ghci> take 1 $  
      drop 1000 $  
      iterate (<> eqProbsMat) startOnOne  
[(1><5)  
 [ 0.2, 0.2, 0.2, 0.2, 0.2 ]]
```

# Visit Each Hour Proportionally



## Suppose Achieve Goal

$$\pi'(n) = p(n | n-1)\pi(n-1) + p(n | n)\pi(n) + p(n | n+1)\pi(n+1)$$

## Suppose Achieve Goal

$$\pi'(n) = p(n | n-1)\pi(n-1) + p(n | n)\pi(n) + p(n | n+1)\pi(n+1)$$

$$\begin{aligned}\pi'(4) &= \frac{1}{2}\pi(3) + \frac{1}{2}\frac{1}{4}\pi(4) + \frac{1}{2}\frac{4}{5}\pi(5) \\ &= \frac{1}{2}\left(\frac{3}{N} + \frac{1}{4}\frac{4}{N} + \frac{4}{5}\frac{5}{N}\right) \\ &= \frac{1}{2}\frac{8}{N} \\ &= \frac{4}{N} \\ &= \pi(4)\end{aligned}$$

## Testing Convergence

```
ghci> incProbsMat
(5><5)
[ 0.00, 0.500, 0.000, 0.000, 0.5
, 0.25, 0.250, 0.500, 0.000, 0.0
, 0.00, 0.333, 0.167, 0.500, 0.0
, 0.00, 0.000, 0.375, 0.125, 0.5
, 0.10, 0.000, 0.000, 0.400, 0.5 ]

ghci> take 1 $
      drop 1000 $
      iterate (<> incProbsMat) startOnOne
[(1><5)
 [ 6.67e-2, 0.133, 0.199, 0.267, 0.333 ]]
```



# Very Simple Markov Chain

$$q(i, j) = \begin{cases} \mathbb{P}(X_{n+1} = j \mid X_n = i) = \frac{1}{2} & \text{if } j = i + 1 \pmod{N} \\ \mathbb{P}(X_{n+1} = j \mid X_n = i) = \frac{1}{2} & \text{if } j = i - 1 \pmod{N} \\ \mathbb{P}(X_{n+1} = j \mid X_n = i) = 0 & \text{otherwise} \end{cases}$$

## Simple Markov Chain

The grasshopper knows that  $\pi(i) = i/N$  so it can calculate  $\pi(j)/\pi(i) = j/i$  without knowing  $N$ .

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$$p(i,j) = \begin{cases} q(i,j) \left[ \frac{\pi(j)q(j,i)}{\pi(i)q(i,j)} \wedge 1 \right] & \text{if } j \neq i \\ 1 - \sum_{k:k \neq i} q(i,k) \left[ \frac{\pi(k)q(k,i)}{\pi(i)q(i,k)} \wedge 1 \right] & \text{if } j = i \end{cases}$$

# Simple Markov Chain

$$q(i, j) = \begin{cases} \frac{1}{2}(\frac{j}{i} \wedge 1) & \text{if } j \text{ is 1 step clockwise} \\ \frac{1}{2}(\frac{j}{i} \wedge 1) & \text{if } j \text{ is 1 step anti-clockwise} \\ 1 - \frac{1}{2}(\frac{j^c}{i} \wedge 1) - \frac{1}{2}(\frac{j^a}{i} \wedge 1) & j = i \& j^a, j^c \text{ step (anti-)clockwise} \\ 0 & \text{otherwise} \end{cases}$$

# Orientation

- Markov chain theory normally interested in when chain has stationary distribution.

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- Here we have a distribution and want to create a Markov chain which has it as stationary distribution.

# Ergodic Theorem

An irreducible, aperiodic and positive recurrent Markov chain has a unique stationary distribution.

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# Ergodic Theorem

An irreducible, aperiodic and positive recurrent Markov chain has a unique stationary distribution.

Roughly speaking

- Irreducible means it is possible to get from any state to any other state.
- Aperiodic means that returning to a state having started at that state occurs at irregular times.
- Positive recurrent means that the expectation of first time to hit a state is finite (for every state and more pedantically except on sets of null measure).

## Detailed Balance

A Markov chain  $p(i, j)$  and a distribution  $\pi$  are said to be in **detailed balance** if

$$\pi(i)p(i, j) = \pi(j)p(j, i)$$

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$$\pi(i)p(i, j) = \pi(j)p(j, i)$$

Summing over  $i$

$$\pi P = \pi$$

So clearly stationary.

# Metropolis-Hastings

Let

- $\pi$  be a probability distribution on the state space  $\Omega$  with  $\pi(i) > 0$  for all  $i$
- $(Q, \pi_0)$  be an ergodic Markov chain on  $\Omega$  with transition probabilities  $q(i, j) > 0$

The latter condition is slightly stronger than it need be but we will not need fully general conditions.

# Metropolis-Hastings

Create a new (ergodic) Markov chain with transition probabilities

$$p_{ij} = \begin{cases} q(i, j) \left[ \frac{\pi(j)q(j, i)}{\pi(i)q(i, j)} \wedge 1 \right] & \text{if } j \neq i \\ 1 - \sum_{k: k \neq i} q(i, k) \left[ \frac{\pi(j)q(j, i)}{\pi(i)q(i, j)} \wedge 1 \right] & \text{if } j = i \end{cases}$$

# Metropolis-Hastings is Ergodic

$$\begin{aligned}\pi(i)q(i,j) \left[ \frac{\pi(j)q(j,i)}{\pi(i)q(i,j)} \wedge 1 \right] &= \pi(i)q(i,j) \wedge \pi(j)q(j,i) \\ &= \pi(j)q(j,i) \left[ \frac{\pi(i)q(i,j)}{\pi(j)q(j,i)} \wedge 1 \right]\end{aligned}$$

Secondly since we have specified that  $(Q, \pi_0)$  is ergodic then clearly  $(P, \pi_0)$  is also ergodic (all the transition probabilities are  $> 0$ ). So we know the algorithm will converge to the unique distribution we specified to provide estimates of values of interest.

# Random Scan

Start with  $\pi(\theta_1, \theta_2)$ .

$$\begin{cases} \text{Sample } \theta_1^{(i+1)} \sim \pi(\theta_1 \mid \theta_2^{(i)}) & \text{with probability } \frac{1}{2} \\ \text{Sample } \theta_2^{(i+1)} \sim \pi(\theta_2 \mid \theta_1^{(i)}) & \text{with probability } \frac{1}{2} \end{cases}$$

The transition density kernel is then given by

$$\begin{aligned} q(\boldsymbol{\theta}^{(i+1)}, \boldsymbol{\theta}^{(i)}) &= \frac{1}{2} \pi(\theta_1^{(i+1)} \mid \theta_2^{(i)}) \delta(\theta_2^{(i)}, \theta_2^{(i+1)}) \\ &\quad + \frac{1}{2} \pi(\theta_2^{(i+1)} \mid \theta_1^{(i)}) \delta(\theta_1^{(i)}, \theta_1^{(i+1)}) \end{aligned}$$

where  $\delta$  is the Dirac delta function.



## Detailed Balance

$$\begin{aligned}
 &\pi(\theta_1, \theta_2) \left[ \frac{1}{2} \pi(\theta'_1 \mid \theta_2) \delta(\theta_2, \theta'_2) + \frac{1}{2} \pi(\theta'_2 \mid \theta_1) \delta(\theta_1, \theta'_1) \right] = \\
 &\frac{1}{2} \left[ \pi(\theta_1, \theta_2) \pi(\theta'_1 \mid \theta_2) \delta(\theta_2, \theta'_2) + \dots \right] = \\
 &\frac{1}{2} \left[ \pi(\theta_1, \theta'_2) \pi(\theta'_1 \mid \theta_2) \delta(\theta_2, \theta'_2) + \dots \right] = \\
 &\frac{1}{2} \left[ \pi(\theta'_2) \pi(\theta_1 \mid \theta'_2) \pi(\theta'_1 \mid \theta_2) \delta(\theta_2, \theta'_2) + \dots \right] = \\
 &\frac{1}{2} \left[ \pi(\theta'_1, \theta'_2) \pi(\theta_1 \mid \theta'_2) \delta(\theta'_2, \theta_2) + \dots \right] = \\
 &\pi(\theta'_1, \theta'_2) \left[ \frac{1}{2} \pi(\theta_1 \mid \theta'_2) \delta(\theta'_2, \theta_2) + \frac{1}{2} \pi(\theta_2 \mid \theta'_1) \delta(\theta'_1, \theta_1) \right]
 \end{aligned}$$

## Detailed Balance

$$\pi(\theta)q(\theta', \theta) = \pi(\theta')q(\theta, \theta')$$

Hand waving slightly, we can see that this scheme satisfies the premises of the ergodic theorem and so we can conclude that there is a unique stationary distribution and  $\pi$  must be that distribution.

## Systematic Scan

Most references on Gibbs sampling do not describe the random scan but instead something called a systematic scan.  
Again for simplicity let us consider a model with two parameters.  
In this sampler, we update the parameters in two steps.

$$\text{Sample } \theta_1^{(i+1)} \sim \pi(\theta_1 \mid \theta_2^{(i)})$$

$$\text{Sample } \theta_2^{(i+1)} \sim \pi(\theta_2 \mid \theta_1^{(i+1)})$$

# Systematic Scan

- **Not** time-homogeneous!!!

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- At each step the transition matrix flips between the two transition matrices given by the individual steps.
- Cannot apply the ergodic theorem as it only applies to time-homogeneous processes.
- ... does not satisfy detailed balance

## An Example: The Bivariate Normal

$$\begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} \Big| y \sim N \left[ \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \quad \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \right]$$

The conditional distributions are easily calculated to be

$$\theta_1 \mid \theta_2, y \sim \mathcal{N}(y_1 + \rho(\theta_2 - y_2), 1 - \rho^2)$$

$$\theta_2 \mid \theta_1, y \sim \mathcal{N}(y_2 + \rho(\theta_1 - y_1), 1 - \rho^2)$$



# Haskell

*gibbsSampler* ::

*Double* →

*RVarT (W.Writer [(Double, Double)]) Double*

*gibbsSampler*  $\theta_2 = \mathbf{do}$

$\tilde{\theta}_1 \leftarrow \mathit{rvarT} \ (\mathit{Normal} \ (y_1 + \rho * (\theta_2 - y_2)) \ (1 - \rho^2))$

$\mathit{lift} \ \$ \ W.\mathit{tell} \ [(\tilde{\theta}_1, \theta_2)]$

$\tilde{\theta}_2 \leftarrow \mathit{rvarT} \ (\mathit{Normal} \ (y_2 + \rho * (\tilde{\theta}_1 - y_1)) \ (1 - \rho^2))$

$\mathit{lift} \ \$ \ W.\mathit{tell} \ [(\tilde{\theta}_1, \tilde{\theta}_2)]$

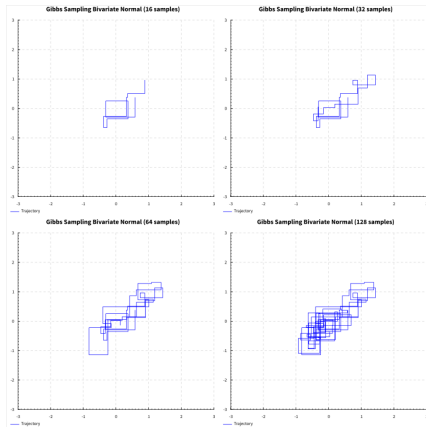
$\mathit{return} \ \$ \ \tilde{\theta}_2$

# Haskell

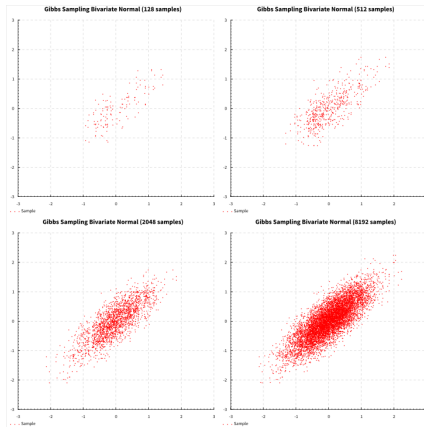
From which we can create an infinite stream of samples.

```
runMCMC :: [(Double, Double)]  
runMCMC =  
    drop burnIn $  
    snd $  
    runWriter $  
    evalStateT (sample (iterateM_ gibbsSampler 2.5))  
    (pureMT 2)
```

# Typical Paths



# Typical Samples



## Prior and Likelihood

$$\pi(\mu, \tau) \propto \frac{1}{\tau} \quad -\infty < \mu < \infty \text{ and } 0 < \tau < \infty$$

$$p(x | \mu, \sigma^2) = \prod_{i=1}^n \left( \frac{1}{\sigma \sqrt{2\pi}} \right) \exp \left( - \frac{(x_i - \mu)^2}{2\sigma^2} \right)$$

# Posterior

Re-writing in terms of precision

$$p(x | \mu, \tau) \propto \prod_{i=1}^n \sqrt{\tau} \exp \left( -\frac{\tau}{2} (x_i - \mu)^2 \right)$$

Thus the posterior is

$$p(\mu, \tau | x) \propto \tau^{n/2-1} \exp \left( -\frac{\tau}{2} \sum_{i=1}^n (x_i - \mu)^2 \right)$$

# Conditionals

We can re-write the sum in terms of

- Sample mean  $\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$
- Sample variance  $s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$

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$$\sum_{i=1}^n (x_i - \mu)^2 = (n-1)s^2 + n(\bar{x} - \mu)^2$$



# Conditionals

Thus the conditional posterior for  $\mu$  is

$$\begin{aligned} p(\mu | \tau, x) &\propto \exp \left( -\frac{\tau}{2} \left( \nu s^2 + n(\bar{x} - \mu)^2 \right) \right) \\ &\propto \exp \left( -\frac{n\tau}{2} (\mu - \bar{x})^2 \right) \end{aligned}$$

which we recognise as a normal distribution with mean of  $\bar{x}$  and a variance of  $(n\tau)^{-1}$ .

# Conditionals

The conditional posterior for  $\tau$  is

$$p(\tau \mid \mu, x) \propto \tau^{n/2-1} \exp \left( -\tau \frac{1}{2} \sum_{i=1}^n (x_i - \mu)^2 \right)$$

which we recognise as a gamma distribution with a shape of  $n/2$  and a scale of  $\frac{1}{2} \sum_{i=1}^n (x_i - \mu)^2$

# Marginal

In this particular case, we can calculate the marginal posterior of  $\mu$  analytically.

$$p(\mu | x) \propto \left( 1 + \frac{n(\mu - \bar{x})^2}{(n-1)s^2} \right)^{-n/2}$$

This is the non-standardized Student's t-distribution  $t_{n-1}(\bar{x}, s^2/n)$ .

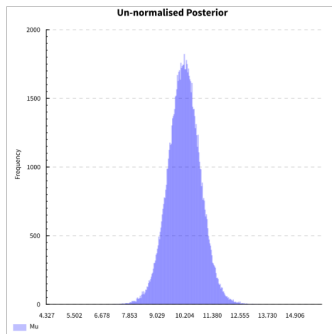
# Haskell

```
gibbsSampler :: MonadRandom m =>
    Double → m (Maybe ((Double, Double), Double))
gibbsSampler τ = do
     $\tilde{\mu} \leftarrow \text{sample } (\text{Normal } \bar{x} \text{ (recip (sqrt (n * \tau)))))$ 
    let shape = 0.5 * n
    scale = 0.5 * ( $\sum x_i^2 + n * \tilde{\mu} \uparrow 2 - 2 * n * \tilde{\mu} * \bar{x}$ )
     $\tilde{\tau} \leftarrow \text{sample } (\text{Gamma shape (recip scale)})$ 
    return $ Just (( $\tilde{\mu}$ ,  $\tilde{\tau}$ ),  $\tilde{\tau}$ )
```

From which we can create an infinite stream of samples.

```
gibbsSamples :: [(Double, Double)]
gibbsSamples = evalState (unfoldrM gibbsSampler τ0)
    (pureMT 1)
```

# Posterior for $\mu$



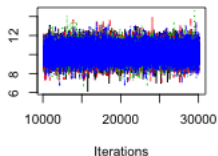
# JAGS

JAGS is a mature, DSL for building Bayesian statistical models using Gibbs(?) sampling.

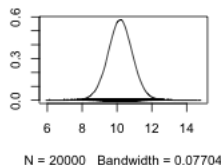
```
model {  
  for (i in 1:N) {  
    x[i] ~ dnorm(mu, tau)  
  }  
  mu ~ dnorm(0, 1.0E-6)  
  tau <- pow(sigma, -2)  
  sigma ~ dunif(0, 1000)  
}
```

# Output for JAGS

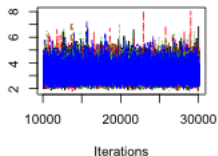
Trace of mu



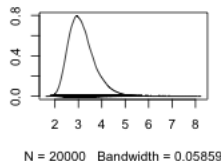
Density of mu



Trace of sigma



Density of sigma



# STAN

STAN: DSL similar to JAGS but newer, uses HMC, allows variable re-assignment, cannot really be described as declarative.

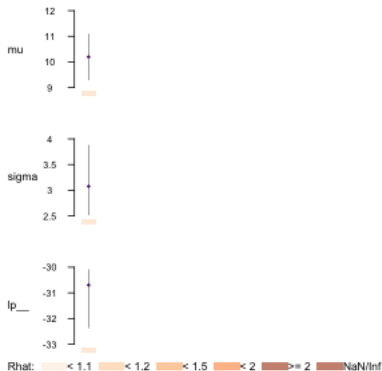
```
data {
  int<lower=0> N;
  real x[N];
}
parameters {
  real mu;
  real<lower=0,upper=1000> sigma;
}
model{
  x ~ normal(mu, sigma);
  mu ~ normal(0, 1000);
}
```



# Output for STAN

Stan model 'Stan' (3 chains: iter=30000; warmup=10000; thin=1) fitted at Wed Apr 9 12:30:01 2014

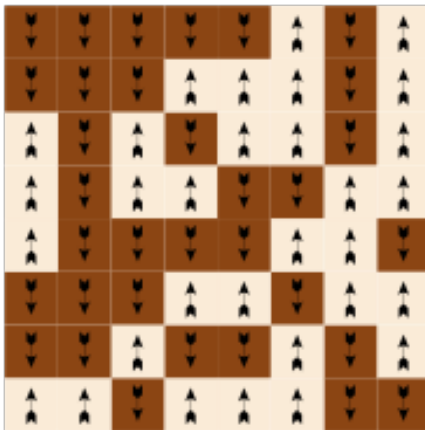
medians and 80% intervals



# Curie Temperature

[https://www.youtube.com/watch?v=YzwGzJm41\\_o](https://www.youtube.com/watch?v=YzwGzJm41_o)

# Ising in a Nutshell



# Boltzmann Distribution

To calculate the total magnetization, pick random configurations according to the Boltzmann distribution.

$$\mathbb{P}(\sigma) = \frac{\exp(-E(\sigma)/k_B T)}{Z(T)}$$

$T$  temperature,  $k_B$  Boltzmann's constant,  $E$  energy.

$$E(\sigma) = -J \sum_{\langle i,j \rangle} \sigma_i \sigma_j$$

$Z(T)$  normalizing constant,  $J$  a constant.

$$Z(T) = \sum_{\sigma} \exp(-E(\sigma)/k_B T)$$

# Uniform Sampling

But what about the normalizing constant  $Z$ ? Even for a modest grid size say  $10 \times 10$ , the number of states that needs to be summed over is extremely large  $2^{10 \times 10}$ .

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Idea: could draw  $R$  random samples  $(\sigma^{(i)})_{0 \leq i < R}$  uniformly then use

$$Z_R \triangleq \sum_0^{R-1} \exp(-\beta \sigma_i)$$

# Uniform Sampling

Now can estimate e.g. the magnetization

$$\langle M \rangle = \sum_{\sigma} M(\sigma) \frac{\exp(-\beta E(\sigma))}{Z(T)}$$

by

$$\widehat{\langle M \rangle} = \sum_{i=0}^{R-1} M(\sigma) \frac{\exp(-\beta E(\sigma(i)))}{Z_R}$$

# Problem

Statistical physics tells us that systems with large numbers of particles will occupy a small portion of the state space with any significant probability.



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High dimensional distribution concentrated on small region of the state space: typical set  $T$  volume is given by  $|T| \approx 2^H$  where  $H$  is the (Shannon) entropy.

$$H = - \sum_{\sigma} P(\sigma) \log_2(P(\sigma))$$

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$$H = - \sum_{\sigma} P(\sigma) \log_2(P(\sigma))$$

Actual value of the (mean) magnetization will be determined by the values that  $M$  takes on  $T$ .

# Problem

Uniform sampling will only give a good estimate if we make  $R$  large enough that we hit  $T$  at least a small number of times.

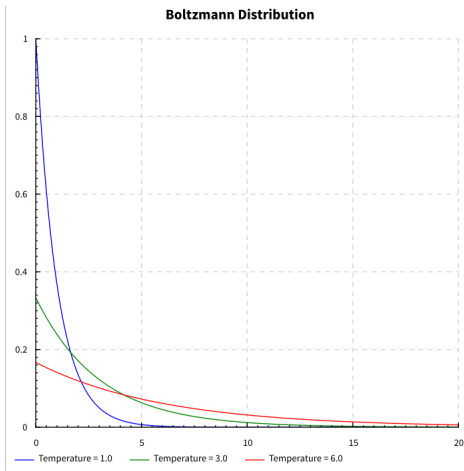
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# Boltzmann Distribution



# High Temperature

At high temperatures, the Boltzmann distribution flattens out so roughly all of the states have an equal likelihood of being occupied. We can calculate the (Shannon) entropy for this.

$$H \approx \sum_{\sigma} \frac{1}{2^N} \log_2 2^N = N$$

## Low Temperature

- At "low" temperatures e.g. the temperature at which the phase transition occurs,  $T = 2.269$ , the entropy is approximately  $0.13N$ .



## Low Temperature

- At "low" temperatures e.g. the temperature at which the phase transition occurs,  $T = 2.269$ , the entropy is approximately  $0.13N$ .
- So uniform sampling would require  $\sim 2^{(N-N)}$  samples at high temperatures but  $\sim 2^{(N-0.13N)} \approx 2^{N/2}$  at temperatures of interest. Even for our modest  $10 \times 10$  grid this is  $2^{50} \approx 10^{17}$  samples!

## Low Temperature

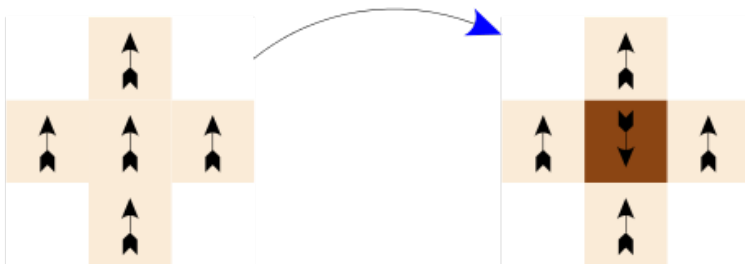
- At "low" temperatures e.g. the temperature at which the phase transition occurs,  $T = 2.269$ , the entropy is approximately  $0.13N$ .
- So uniform sampling would require  $\sim 2^{(N-N)}$  samples at high temperatures but  $\sim 2^{(N-0.13N)} \approx 2^{N/2}$  at temperatures of interest. Even for our modest  $10 \times 10$  grid this is  $2^{50} \approx 10^{17}$  samples!
- Enter Metropolis and his team: construct a Markov chain with a limiting distribution of the distribution required — does not require the evaluation of the partition function — samples high density areas with high probability (although theoretical results substantiating this latter point seem to be hard to come by).

# Gibbs

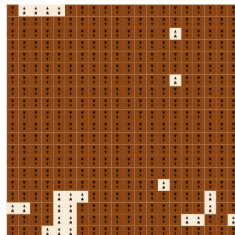
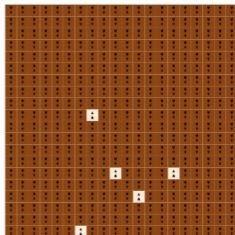
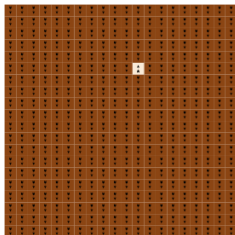
Use random scan and

$$p(\sigma_i = +1 \mid \sigma_{-i}) = \frac{\exp \left( J/k_b T \sum_{\langle i,j \rangle} \sigma_j \right)}{\exp \left( J/k_b T \sum_{\langle i,j \rangle} \sigma_j \right) + \exp \left( - J/k_b T \sum_{\langle i,j \rangle} \sigma_j \right)}$$

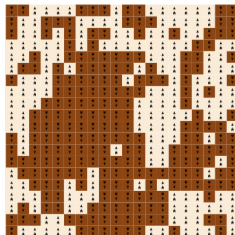
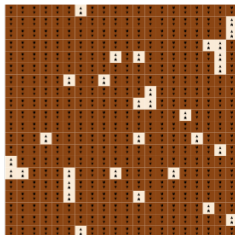
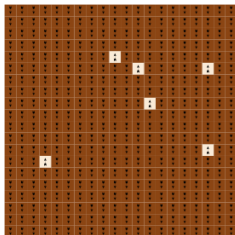
## An Possible Flip



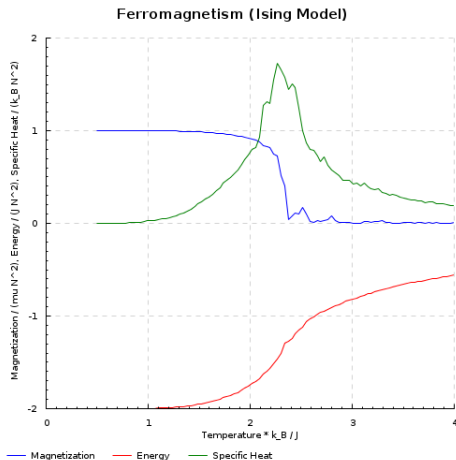
## Evolution at $T = 2$ , steps = 100, 1000, 10,000



## Evolution at $T = 3$ , steps = 100, 1000, 10,000



# The Phase Transition Revealed



# Acknowledgements

- <http://education.mrsec.wisc.edu/463.htm>
- <http://www.inference.phy.cam.ac.uk/itila/book.html>
- <http://idontgetoutmuch.wordpress.com>