

# Big Red: A Development Environment for Bigraphs

Alexander Faithfull, Gian Perrone, and Thomas T. Hildebrandt

IT University of Copenhagen, Denmark  
{alef,gdpe,hilde}@itu.dk

**Abstract.** We present Big Red, a visual editor for bigraphs and bigraphical reactive systems, based upon Eclipse. The editor integrates with several existing bigraph tools to permit simulation and model-checking of bigraphical models. We give a brief introduction to the bigraphs formalism, and show how these concepts manifest within the tool. Finally, we detail the implementation and present a small motivating example bigraphical model developed using Big Red.

**Keywords:** bigraphs, editor, reactive systems

## 1 Introduction

Bigraphical reactive systems are a class of graph-rewriting systems designed to capture orthogonal notions of *connectivity* and *locality* through the use of a two-graph structure — a *place* graph, and a *link* graph. They were first proposed by Robin Milner [5] to address the challenges associated with modelling of ubiquitous computing applications. Bigraphs have been successful in capturing the syntax and semantics of a number of well-known formalisms and real-world applications<sup>1</sup>.

The Big Red tool is a prototype editor to support the development of bigraphs and bigraphical reactive systems in a visual manner. It interfaces with existing bigraph tools such as the BigMC bigraphical model checker [6] to permit the execution of models. Big Red aims to make bigraphs more accessible to novice users, as well as providing development support to more experienced bigraph users. Bigraphs have a visual presentation that is formal and unambiguous, and one of the major benefits is the ability to present a relatively complex bigraphical model in a way that is comprehensible by non-experts. This is the motivation for the development of Big Red: making it easier to create and interact with bigraphs increases the applicability and utility of the formalism in more diverse application areas.

### 1.1 Structure

The rest of this work is structured as follows: We describe a previous effort to construct a bigraph editor in Section 2. We give a brief introduction to the

---

<sup>1</sup> Some examples are available from <http://bigraph.org/papers/gcm2012/>.

bigraphs formalism in Section 3 and explain how these concepts are expressed in the syntax of Big Red. Section 4 describes the implementation of the tool, and suggests ways in which it may be extended using additional modules. We present a small example of using Big Red to model a building-wide printer system in bigraphs in Section 5. Finally in Section 6 we summarise the direction of future work on Big Red.

## 2 Related Work

One of the first attempts at creating a graphical editor for bigraphs was within the Bigraphspace [3] project in 2009, during which a prototype bigraph editor based upon eclipse was developed; however, this work was never completed, and no usable editor currently exists. Bigraphspace used the correspondence between the structure of bigraphs and XML documents [4] to provide a tuplespace-like API with which to manipulate bigraphs. Big Red differs from these efforts in that it implements editing of Milner’s bigraphs in such a way as to enable external tools to perform further analysis of these models, rather than imposing a particular (extra-bigraphical) semantics upon the models.

To date, bigraphical reactive systems have been largely implemented using term representations of bigraphs, such as that used in the BPLtool [2], or in the BigMC model checker [6]. While this is appropriate for bigraph experts, it presents a significant learning curve for novice users, and ignores the benefits provided by the formal graphical syntax provided by bigraphs.

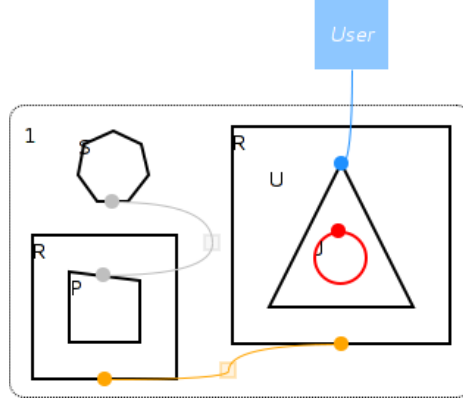
## 3 Bigraphs

A static bigraph is a forest of nodes with identities called the *place graph*, the roots of which are indexed by integers, and referred to as *regions*. The place graph parent relationship is usually drawn by nesting in the graphical syntax. To each place graph node is assigned a *control*, drawn from the bigraph *signature*. We will occasionally use “**X** node” to mean a node that is assigned the control **X**. A control also defines the number of *ports* of a node to which that control is assigned. The link graph is an undirected hypergraph over these ports and the *inner* and *outer* names of the bigraph, which are joined (inner-to-outer) by name agreement through bigraph composition to form (hypergraph) edges. By convention, outer names are drawn upward, while inner names are drawn downwards. Fig. 1 is an example bigraph in which **R**, **S**, **P**, **J**, and **U** are controls. Big Red permits users to specify custom shapes for nodes associated with each type of control. The shaded box **User** is an outer name that is linked to a port of the **U** node. We reiterate Milner’s bigraph definition [5] here:

$$(V, E, ctrl, prnt, link) : \langle n, X \rangle \rightarrow \langle m, Y \rangle$$

where  $V$  is the set of nodes,  $E$  is a set of edges,  $ctrl : V \rightarrow \Sigma$  assigns controls to nodes drawn from a signature  $\Sigma$ ,  $prnt : m \uplus V \rightarrow V \uplus m$  is the *parent map* that

gives the nested place graph structure, and  $link : X \uplus P \rightarrow E \uplus Y$  is the link map, where  $P = \{(v, i) : v \in V \wedge i \in 0 \dots ar(ctrl(v))\}$ , giving the set of ports for a given node.



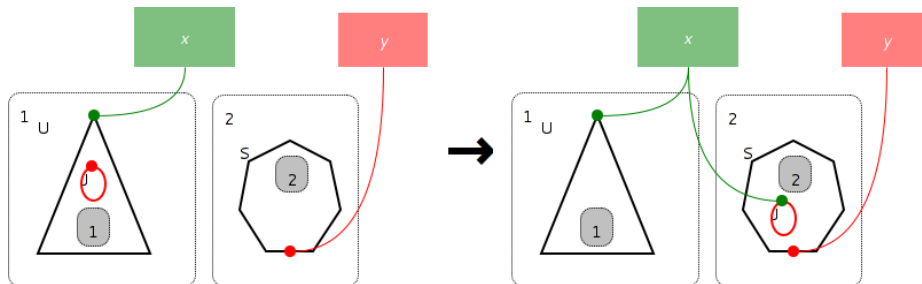
**Fig. 1.** A example bigraph expressed in the visual syntax of the Big Red tool

Dynamic behaviour is added to a bigraph model by adding a set of *reaction rules*. We give examples of reaction rules in Fig. 2 and 3. Bigraph reaction rules may be parametric, such that for a given reaction rule  $R \rightarrow R'$ , a bigraph  $G = C \circ R \circ D$  may be decomposed into a context  $C$ , an instance of the left-hand side of the rule  $R$ , and a set of parameters  $D$  — such parameters in the reaction rule are called *holes*, which Big Red represents as shaded place graph objects, indexed by integers. Through this explanation we obscure a number of technical details — interested readers are referred to [5] for detailed description of bigraphs and bigraphical reactive systems.

## 4 Implementation

Big Red is implemented as an Eclipse *plugin*, which extends the Eclipse platform with additional file formats representing the objects of a bigraphical reactive system, wizards to create model files, and editors to modify them. In turn, Big Red defines several Eclipse *extension points*: these allow other plugins to contribute extensions to Big Red, adding support for new external tools and export formats.

Big Red's implementation of the bigraphical model strikes a balance between theoretical purity and practicality. No extensions to the bigraphical model are implemented, but the classes have been designed with extensibility in mind; as a result, adding new concepts to the model is easy. Indeed, Big Red uses these mechanisms to implement some of its own functionality — the information used to draw and position objects, for example, has no specific support in the underlying model.



**Fig. 2.** The *JobToSpool* rule

The Eclipse platform includes comprehensive libraries to support the building of modelling tools. At the heart of these is the Graphical Editor Framework, a toolkit for implementing model-view-controller-based editors. Big Red’s bigraph and reaction rule editors are both built on this powerful and flexible component.

Quite apart from its specific support for modelling tools, Eclipse is a very portable and widely-used platform with a vibrant community and many pre-built features, which makes it an ideal choice for the rapid development of an editor.

#### 4.1 Interacting with External Tools

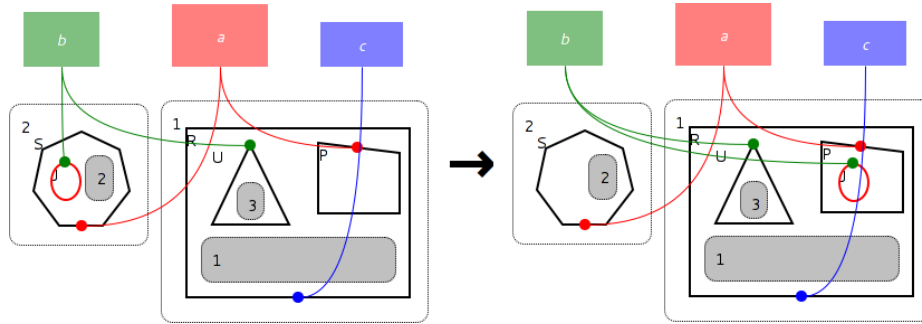
Big Red defines a special extension point for plugins that want to operate on a complete bigraphical reactive system. When an extension registered with this point is activated, Big Red’s user interface is suspended, and the extension takes over — essentially, this gives developers the ability to write subprograms that work with Big Red’s model objects without having to delve too deeply into the workings of Eclipse.

The integration between Big Red and BigMC is implemented in this way — as an external plugin which converts a Big Red model into its BigMC term language representation, executes BigMC as a subprocess, and parses the results back into Big Red model objects so that they can be visualised.

## 5 Example

Fig. 2 and 3 exemplify the kinds of reaction rules that could be constructed within Big Red for a context-aware printing system, inspired by that given in [1]. The example scenario involves a building in which users can submit print jobs to a central print spool, and then move into a room with any printer connected to that print spool, at which point the printer will complete the job. Fig. 1 gives an example building configuration to which these rules could be applied.

The *JobToSpool* rule allows a print job (represented by a *J* control) to be transferred from a user (represented by a *U* control) to a spool (represented by an *S* control), adding an identifying link to connect users to their submitted print



**Fig. 3.** The *JobToPrinter* rule

jobs. *JobToPrinter* will transfer a job from the spool to a printer (represented by a P control) that is co-located with the user associated with that job. For brevity, we have omitted the rules for removing completed jobs and allowing users to move between rooms. The full example model is available from <http://bigraph.org/papers/gcm2012>.

## 6 Conclusion

We have presented a brief introduction to the Big Red tool, and described the motivation for developing such a tool. Big Red and accompanying user documentation are available under the Eclipse Public License from <http://bigraph.org>.

Big Red is still under active development. We intend to integrate support for other bigraph tools, and — together with the University of Udine — we are working on developing Big Red into a generally-useful platform for building and hosting new tools for bigraphs.

## References

1. L. Birkedal, S. Debois, E. Elsborg, T.T. Hildebrandt, and H. Niss. Bigraphical models of context-aware systems. In *Foundations of Software Science and Computation Structures*, pages 187–201. Springer, 2006.
2. A.J. Glenstrup, T.C. Damgaard, L. Birkedal, and E. Højsgaard. An implementation of bigraph matching. 2007.
3. C. Greenhalgh. bigraphspace, 2009.
4. T.T. Hildebrandt, H. Niss, and M. Olsen. Formalising Business Process Execution with Bigraphs and Reactive XML. In *COORDINATION’06*, volume 4038 of *Lecture Notes in Computer Science*, pages 113–129. Springer-Verlag, January 2006.
5. R. Milner. *The Space and Motion of Communicating Agents*. Cambridge University Press, 2009.
6. G. Perrone, S. Debois, and T.T. Hildebrandt. A Model Checker for Bigraphs. In *ACM Symposium on Applied Computing 2012 – Software Verification and Testing Track*. ACM, 2012.