

Drone Mission Planning Software

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Overview

The goal of this project is to design and develop a graphical user interface (GUI) for drone mission planning.

Requirements:

- A user-friendly interface
- Allow 3-dimensional mission planning
- Upload the flight plan using XAPI and XBee
- Allow manual override
- Implement drone hardware for flight control

Problem Definition

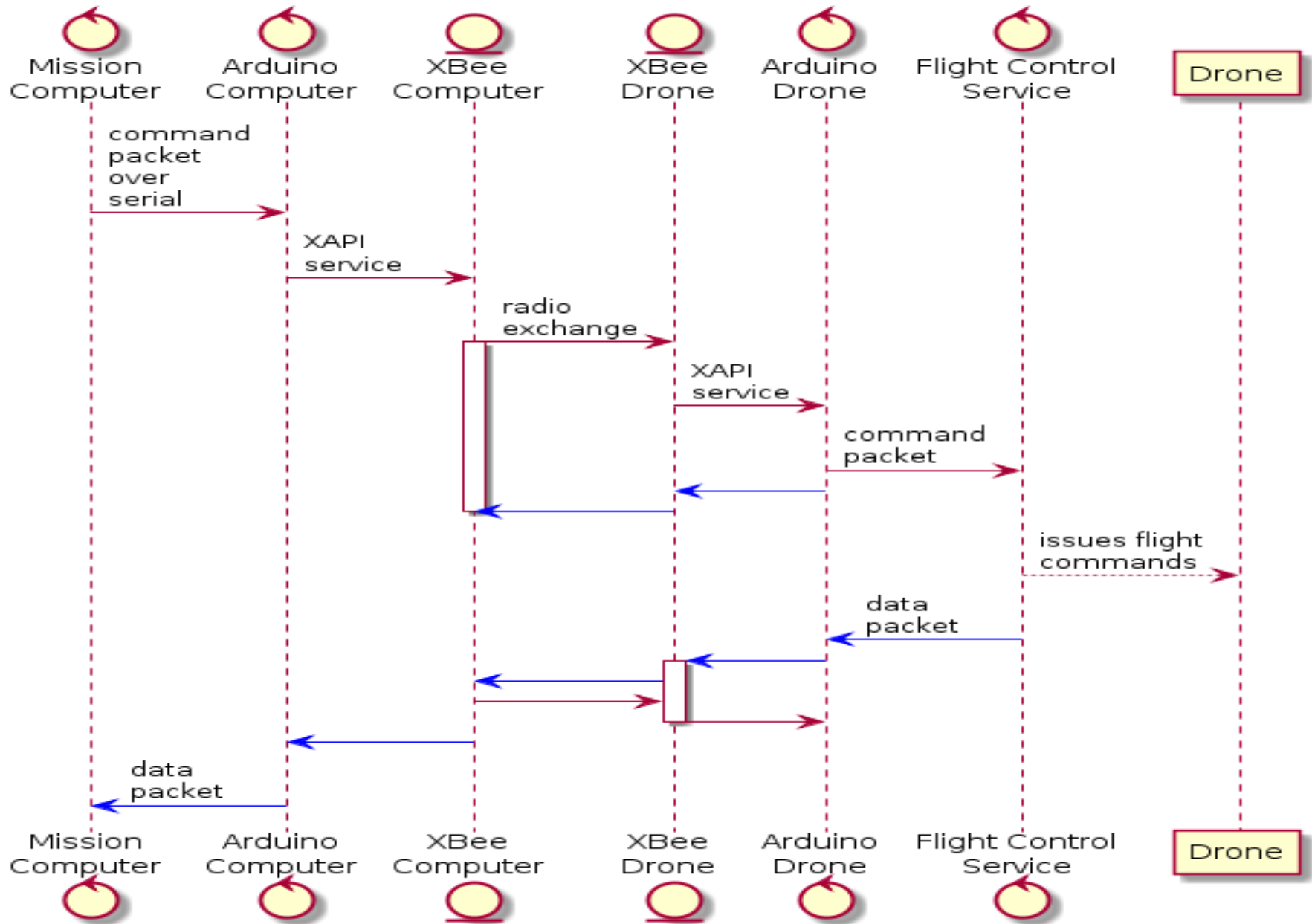
The communication system for this project must allow for commands to be sent from a computer to a drone.

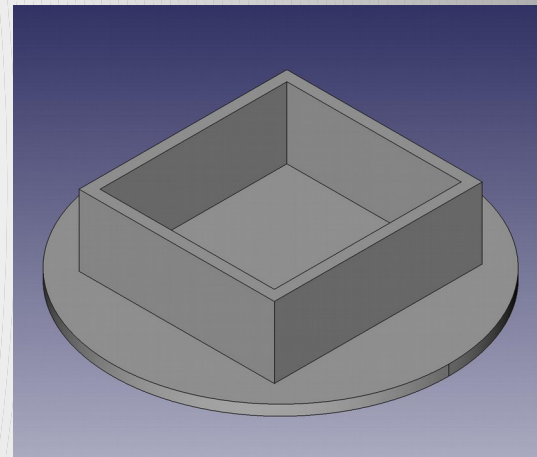
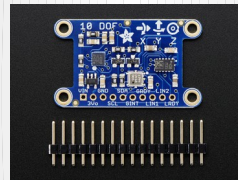
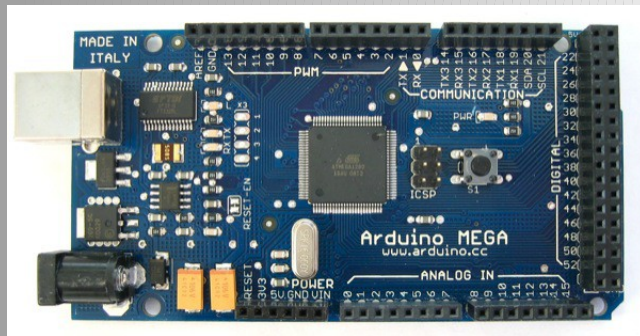
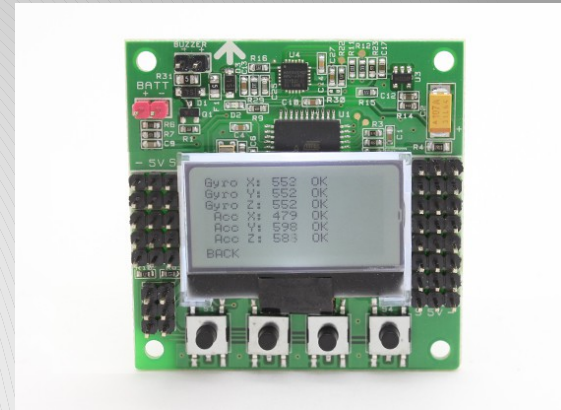
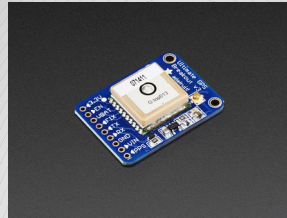
Requirements:

- XAPI and XBee hardware
- Specific TUN packets:
 - Manual drone instructions (altitude, direction, takeoff, etc..)
 - Settings
 - Acknowledgement of packet received
 - Heartbeat/status updates
 - Override (manual, land)
 - Flight plan protocol
 - ✿ Initialize for upload
 - ✿ Get instructions
 - ✿ Echo instructions
 - ✿ Terminate upload

Communication Design

Simplified Drone Communication Sequence





Drone Design

Flight Planning
System

Communications
Terminal

Status Info

Speed

Text Box

Altitude

Text Box

Elevator

Aileron

Throttle

Manual
Override

Reset

Rudder

Graphical User Interface Design

Re-design drone for reliable flight

Finish implementing communications between two Arduino boards over XBee using XAPI

Finish designing all needed packet types for drone control, status, ACK, and response.

Implement service on Arduino to send commands to flight computer

Finalize UI design, implement communications system, design mission planning sub-system

Timeline

Questions or concerns?

Thank You