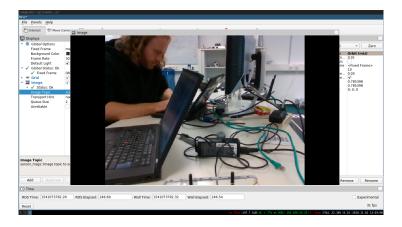
1 Aufabe 1



2 Aufgabe 2

```
data: "I heard: -0.148836001754"
     "I heard: -0.149436056614"
     "I heard: -0.149948328733"
     "I heard: -0.149829342961"
               -0.148600012064"
data: "I heard: -0.14835575223"
     "I heard: -0.148839324713"
     "I heard: -0.148477122188"
     "I heard: -0.148836001754"
     "I heard: -0.149831831455"
     "I heard: -0.149200543761"
     "I heard: -0.149949297309"
     "I heard: -0.148478612304"
     "I heard: -0.149314209819"
                   :Local: 192.168.43.24 Public: 160.45.112.201 1:editor*Z | 2 nvim-
```

Den Quellcode finden sie hier https://github.com/bigzed/model_car/blob/version-4.0/catkin_ws/src/assignment1_publisher_subscriber/src/publisher_subscriber.py oder auf der nächsten Seite.

```
1 #!/usr/bin/env python
2 import rospy
_{\rm 3} from std_msgs.msg import String
_4\ \text{from std\_msgs.msg} import Float32
6 def callback(data):
      publisher.publish(String('I heard: {}'.format(data.data)))
9 def listener():
      global publisher
10
      # init node
11
      rospy.init_node('assignment1_publisher_subscriber', anonymous=True)
12
      # create publisher
13
      publisher = rospy.Publisher('/assignment1_publisher_subscriber', String,
14
      \rightarrow queue_size = 10)
      # subscribe with callback
      rospy.Subscriber('/yaw', Float32, callback)
17
      rospy.spin()
18
19
20 if __name__ == '__main__':
      listener()
```