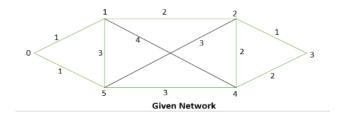
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DESTINATION SEQUENCED DISTANCE-VECTOR ROUTING PROTOCOL (DSDV)



Source Code

```
#include <stdio.h>
#include <stdlib.h>
#define INFINITY 999
#define MAX 10
int SeqNo =0;
int RT[MAX][4];
void FindPath(int G[MAX][MAX], int n, int start, int seqNo)
  int i,j,count,min,nextNode;
  int \ C[MAX][MAX], dist[MAX], path[MAX], v[MAX]; \\
  for(i=0;i < n;i++)
     for(j=0;j<n;j++)
        if(G[i][j]==0)
          C[i][j] = INFINITY;
          C[i][j] = G[i][j];
  for(i=0;i<n;i++)
     dist[i]=C[start][i];
     path[i]=start;
     v[i]=0;
     for(j=0;j<4;j++){
        RT[i][j]=0;
```

```
dist[start]=0;
  v[start]=1;
  count=1;
while(count < n-1)
  min = INFINITY;
  for(i=0;i< n;i++){
     if(dist[i] < min && !v[i]){
        min = dist[i];
        nextNode = i;
  v[nextNode] =1;
  for(i=0;i< n;i++){
     if(!v[i]){
        if(min+C[nextNode][i] < dist[i]){
           dist[i] = min+C[nextNode][i];
           path[i]= nextNode;
  count++;
int k=0; int prev = start;
for(i=0;i<n;i++){
     if(i != start){
        if(min+C[nextNode][i] < dist[i]) {</pre>
           dist[i] = min+C[nextNode][i];
           path[i]= nextNode;
     RT[k][0] = i;
     RT[k][1] = dist[i];
     j=i;
     while(j !=start){
        prev = j;
        j= path[j];
     RT[k][2] = prev; RT[k][3] = seqNo; seqNo++;
     k++;
```

```
printf("\n -----
                                                                                                                 ROUTING TABLE OF NODE %d \n",start);
                printf("\n
                printf(" Dest node
                                                                                                                                                           distance
                                                                                                                                                                                                                                                                                  nextHop
                                                                                                                                                                                                                                                                                                                                                                                        Seq No\t\n");
                for(i=0;i< n-1;i++){
                                 printf("\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}\t^{\prime\prime}
                                 printf("\n");
               }
 void UpdateTable(int dest, int dis , int next , int seq, int n) {
               for(i = 0; i < n-1; i++) {
                                 if(RT[i][0] == dest) {
                                                   if(RT[i][3] < seq){
                                                                    RT[i][1] = dis;
                                                                    RT[i][2] = next;
                                                                    RT[i][3] = seq;
                                                   printf("%d\n",RT[i][3]); }
int main()
                printf("\nStudent Name : BIJAY REGMI\nRoll number : 210913032\n\n");
               int i,j,n,s;
               // int C[MAX][MAX];
               // printf("Enter no. of vertices: ");
               // scanf("%d",&n);
               // printf("Enter the cost matrix<999 for infinity>:\n");
               // for(j=0;j<n;j++)
                                                            scanf("%d",&C[i][j]);
                n=6;
               int C[MAX][MAX] = {
                                 {0, 1, 999, 999, 999, 1},
                                {1, 0, 2, 999, 4, 3},
                                 {999, 2, 0, 1, 2, 3},
                                 {999, 999, 1, 0, 2, 999},
                                 {999, 4, 2, 2, 0, 3},
```

```
{1, 3, 3, 999, 3, 0}
  printf("\nInitial Cost matrix \n");
  for(i=0;i<n;i++)
      for(j=0;j< n;j++){}
         if(C[i][j] < 0) {
           printf(" \n\n ERROR..!! Negative Values are denied in the network\n");
           return 0;
       printf("\%d \ \ \ t" \ , \ C[i][j]);
    printf("\n");
  printf("\nEnter the Initial Sequence Number : ");
  scanf("%d",&SeqNo);
  for(;;)
    printf("\nEnter the node whose routing table required, -1 to exit : ");
    scanf("%d",&s);
    if((s == -1) || (s > n-1)) {
       printf("EXIT ..!!");
       break;
    FindPath(C,n,s,SeqNo);
    int uDest,uDist,uNext,uSeq;
    printf("\nEnter broken link information :(Destination node, Distance, NextHop, Sequence No.): "); scanf("%d %d %d %d",
&uDest, &uDist, &uNext, &uSeq);
    UpdateTable(uDest,uDist,uNext,uSeq,n);
    printf("\n -----
                             -----\n");
    printf("\n ----\n");
    printf(" Dest node distance
                                                    Seq No\t\n");
                                      nextHop
    for(i=0;i<n-1;i++)
       printf("\t%d\t\t %d\t\t%d\t\t%d\t\t%d\t\t,RT[i][0],RT[i][1],RT[i][2],RT[i][3]);
       printf("\n");
```

```
return 0;
}
```

INPUT/OUTPUT

```
Week3 — -zsh — 143×54
regmi@Bijays-MacBook-Air Week3 % gcc DSDVBrokenLink.c
regmi@Bijays-MacBook-Air Week3 % ./a.out
Student Name : BIJAY REGMI
Roll number : 210913032
Initial Cost matrix

0 1 999

1 0 2

999 2 0

999 999 1

999 4 2

1 3 3
                                                    1
3
3
999
                                999
999
                                999
Enter the Initial Sequence Number: 100
Enter the node whose routing table required, -1 to exit : 0
             ROUTING TABLE OF NODE 0
                                                                       Seq No
100
101
102
103
104
   Dest node
Enter broken link information :(Destination node, Distance, NextHop, Sequence No.) : 4 999 5 111 111
        UPDATED ROUTING TABLE OF NODE 0
                                                                       Seq No
100
   Dest node
                                                nextHop
                          distance
                                                                         101
102
111
104
                                 999
Enter the node whose routing table required, -1 to exit : -1
```