

**#` Economics of Production Function with Two Input and One Output- ( Quadratic and Cobb Douglas Production Function)**

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**# Input Side Economics: of Production Function with Two Input and One Output (Quadratic and Cobb Douglas Production Function)**

**# Profit Maximization, Cost Minimization Subejct to Output Constraints and Output Maximization Subject to Budget Constraints, Duality and Comprative Statics**

# Some terminologies to understand:  
# Orinary Input Demand Functions:  
# Constrained Input Demand Functions:  
# Expenditure Demand Functions:  
# Supply Function:  
# Profit Function:  
# Cost Function:  
# Conditional Production Function:

restart;

#Use this line to enter the value of variables as given in the exam.

$r1 := w; r2 := r; p := p; b := 0; Co := Co; yo := yo;$

**# Input 1 Cost, Input 2 Cost, Output Price, Fixed Cost, Constrained Investment or Budget, Constrained Output.**

$x1 := h; x2 := k; b1 := 80; b2 := 75; c1 := -4; c2 := -3; d1 := -4; a := 0;$

**#Change  $x1$  and  $x2$  and Coefficients  $x1, x2, x1^2, x2^2, x1 \cdot x2$ , Constant **for** quadratic function.**

$m := m; n := n; Z := Z;$  #Change m, n and Z to change Cobb Douglas production function.

**# Cobb Douglas Production Function:**

$Z := Z; m := m; n := n; cobb := Z \cdot x1^m x2^n;$

**# Quadratic Production function (Two Input One Output):**

$b1 := b1; b2 := b2; c1 := c1; c2 := c2; d1 := d1; a := a; x1 := x1; x2 := x2; quad := b1 \cdot x1 + b2 \cdot x2 + c1 \cdot x1^2 + c2 \cdot x2^2 + d1 \cdot x1 \cdot x2 + a;$

**#  $x1$  = Input 1,  $x2$  = Input 2.  $b1, b2, c1, c2, d1$ , are coefficients of inputs and their interactions,  $a$  is a constant.**

$y := quad;$  **#Change production function (quad or cobb).**

$VC := r1 \cdot x1 + r2 \cdot x2; FC := b; TotalCost := VC + FC;$

**# Cost Functions: Variable Cost (VC), Fixed Cost (FC), Total Cost (TC)**

$TVP := p \cdot y; Profit\_Function := TVP - TotalCost;$  **#  $TVP$  = Total Value Product,  $Profit\_fun$  = Profit.**

$TPP := y; APP1 := simplify\left(\frac{y}{x1}\right); APP2 := simplify\left(\frac{y}{x2}\right); AVP1 := simplify(APP1 \cdot p); AVP2 := simplify(APP2 \cdot p);$   
*# Total Physical Product, Average Physical Productivity of Factor x1, Average Physical Productivity of Factor x2, Average Value productivity of Factor x1, Average Value Productivity of Factor x2*

$f1 := \frac{\partial}{\partial x1}(y); f2 := \frac{\partial}{\partial x2}(y); MVP1 := p \cdot f1; MVP2 := p \cdot f2; MFC1 := MVP1; MFC2 := MVP2;$   
*# Marginal Physical Productivity (MPP) of Factor x1, Marginal Physical Productivity of Factor x2, Marginal Value Productivity (MVP) of Factor x1, Marginal Value Productivity of Factor x2, Marginal Factor Cost (MFC) of Factor x1, Marginal Factor Cost of Factor x2.*

$f11 := \frac{\partial}{\partial x1}(f1); f22 := \frac{\partial}{\partial x2}(f2); f12 := \frac{\partial^2}{\partial x1 \partial x2}(y); f21 := \frac{\partial^2}{\partial x2 \partial x1}(y);$

*# Second Order Conditions of f1, f2.*

*#f11 & f22 < 0 ⇒ Diminishing Marginal Physical Returns.*

*#f12 & f21 are Factor Inerdependence (f12 or f21 < 0 ⇒ competitive; f12 or f21 = 0 ⇒ independent; f12 or f21 > 0 ⇒ complementary).*

$MRTS := simplify\left(\left(\frac{f1}{f2}\right)\right);$

*# Marginal Rate of Technical Substitution (MRTS<sub>21</sub>) If MRTS is simplified*

*by equating with constant, k, that gives isolcline at MRTS = k.*

$MarginalRevenue := \frac{f1}{f2}; \# \left(\frac{r1}{r2} = \frac{f1}{f2}\right) Marginal Revenue (MR)$

*= Marginal Rate of Technical Substitution (MRTS<sub>21</sub>)*

$\left(\left(\frac{r1}{f1} = \frac{r2}{f2}\right)\right)$

*MarginalRevenue\_PerfectCompetition := p; #Only in perfectly competitive market.*

*Slope\_Of\_Isoquants\_at\_a\_Point := eval(MarginalRevenue, [x1 = x1, x2 = x2]);*

*# Slope of Isoquants at a Point. Replace x1 and x2 by given values of x1, and x2.*

$SOC := simplify(f2 \cdot f2 \cdot f11 - 2 \cdot f1 \cdot f2 \cdot f12 + f1 \cdot f1 \cdot f22);$

*# Second Order Conditions: Border Hessian Condition.*

$Curvature := simplify\left(\left(\frac{1}{f2^3}\right) \cdot SOC\right); \# Curvature. This curvature is derived from production function$

*. Gives change in slope of the isoquant and used to determine convexity of the isoquant.*

*# Also, if you know the equation of isoquant, then curvature is the second derivative of the equation for isoquant.*

$Curvature\_at\_a\_Point := eval(Curvature, [x1 = x1, x2 = x2]); \# Curvature at a Point. Replace x1 and x2 by given values of x1, and x2.$

$Elasticity\_of\_Factor\_Subsitution := \frac{f1 \cdot f2 \cdot (f2 \cdot x2 + f1 \cdot x1)}{(x1 \cdot x2) \cdot (2 \cdot f1 \cdot f2 \cdot f12 - f1 \cdot f1 \cdot f22 - f2 \cdot f2 \cdot f11)};$

*# Elasticity of Factor Subsitution (σ):*

$ElasticityOffS := eval(Elasticity\_of\_Factor\_Subsitution, [x1 = x1, x2 = x2]);$

*# Enter value of x1 and x2 as desired to calculate elasticity of factor subsitution.*

$Elasticity\_x1 := \frac{f1}{APP1}; \# Elasticity of Production for Factor x1. MPP1 divided by APP1.$

$Elasticity\_x2 := \frac{f2}{APP2}$ ; # Elasticity of Production for Factor x2. (MPP2 divided by APP2).

$Functional\_Coefficient := simplify(Elasticity\_x1 + Elasticity\_x2)$ ; #Elasticity of Production or Function Coefficient of Production Function.

# Elasticity of Production or Functional Coefficient ( $\epsilon$ ): Also gives Return to Scale ( = 1  $\Rightarrow$  Constant); ( > 1  $\Rightarrow$  Increasing); OR ( < 1  $\Rightarrow$  Decreasing).

$Functional\_Coefficient\_Alternative := simplify\left(\frac{f1 \cdot x1 + f2 \cdot x2}{y}\right)$ ;

#Functional\_Coefficient\_Alternative and Functional\_Coefficient are same, calculated differently

**# Isoquants:**

$Two\_Isoquants\_x1 := solve(y = v, x1)$ ; #v is constant.

$Two\_Isoquants\_x2 := solve(y = v, x2)$ ; #v is constant.

**# Stages of Productions for Two Inputs:**

$Stage\_I\_II\_Boundary\_Input\_x1 := solve(Elasticity\_x1 = 1, x1)$ ; #use positive value

$Stage\_II\_III\_Boundary\_Input\_x1 := solve(Elasticity\_x1 = 0, x1)$ ; #use positive value

$Stage\_I\_II\_Boundary\_Input\_x2 := solve(Elasticity\_x2 = 1, x2)$ ; #use positive value.

$Stage\_II\_III\_Boundary\_Input\_x2 := solve(Elasticity\_x2 = 0, x2)$ ; #use positive value.

$Inflection\_Point\_Input\_x1 := solve(f1 = APP1, x1)$ ; #Inflection Point for input X1

$Inflection\_Point\_Input\_x2 := solve(f2 = APP2, x2)$ ; #Inflection Point for input X2

**# Homogenous function:**

# if one common value in term of  $t$  is obtained for entire equation,

the function is homogenous of degree "r" and has constant proportion of return to scale of r

. The r value is also equal to functional coefficient ( $\epsilon$ ). The degree of homogeneity of MPPs and APPs of homogenous production functions are "r-1".

$Homogen := simplify(eval(y, [x1 = t \cdot x1, x2 = t \cdot x2]))$ ;

**# Ridgelines x1 and x2:**

$Ridgeline\_x1 := solve(f1 = 0, x1)$ ; # MPP1 = 0 and Stage III begins for input x2.

$Ridgeline\_x2 := solve(f2 = 0, x2)$ ; # MPP2 = 0 and stage III begins for input x1.

**# Profit Maximization (Without Any Constraints) and Duality with Hotellings Lemma:**

```
profit := Profit_Function;
pf1 := diff(profit, x1); pf11 := diff(pf1, x1); # pf11 < 0 for profit max.
pf2 := diff(profit, x2); pf22 := diff(pf2, x2); # pf22 < 0 for profit max.
pf12 := diff(pf1, x2); pf21 := diff(pf2, x1);
EP_p_x1 := solve(pf1=0, x1); # Expansion Path x1 Or Pseudo scale line x1.
EP_p_x2 := solve(pf2=0, x2); # Expansion Path x2 Or Pseudo scale line x2.
x2s_profit := simplify(solve( (eval(pf2, x1=EP_p_x1)) = 0, x2));
# X2Star: Profit Maximizing Level of Input x2 Or Ordinary Input Demand Function x2.
x1s_profit := simplify(eval(EP_p_x1, x2=x2s_profit));
# X1Star: Profit Maximizing Level of Input x1 Or Ordinary Input Demand Function x1.
MaxProfOut := simplify(eval(y, [x1=x1s_profit, x2=x2s_profit]));
# Profit Maximizing Level of Output.
ProfitStar := simplify(eval(profit, [x1=x1s_profit, x2=x2s_profit]));
# ProfitStar: Maximum Profit Function, Indirect Profit Function.

CostStar_MaxProfit := simplify(eval(TotalCost, [x1=x1s_profit, x2=x2s_profit]));
# CostStar: Cost at Maximum profit.

$$\frac{r1}{pf1} = \frac{r2}{pf2}, \frac{r1}{f1} = \frac{r2}{f2}, \frac{r1}{r2} = \frac{f1}{f2}, \frac{r1}{r2} = \frac{pf1}{pf2},$$

BHessian_Profit_Max := (pf11·pf22 - pf12·pf21);
#SOC Condition: Determinant of Boarder Hessian Matrix > 0 for maximization.
Curvature_ProfitMax := -  $\left( \frac{\text{abs}(pf11 \cdot pf22 - pf12 \cdot pf21)}{pf2^3} \right);$ 
#Strictly quasi concave in perfect competition.
Curvature_ProfitMax_Value := eval(Curvature_ProfitMax, [x1=x1s_profit, x2=x1s_profit]);
```

**# Duality: Production Function to Indirect Conditional Profit Function in Price Space and Back to Production Function.**

# Duality related to Hotllings Lemma follows same procedure of profit maximization without any constraints until we derive Indirect Profit Function (ProfitStar).

# So, this section is a contuination from profit maximization for duality. This section derive original production function from where we started using duality approach.

# To go back to production function we need to use **Hotllings Lemma** i.e. Partial derivative of indirect profit function with respect to  $p$  gives supply function.

Hotllings\_Lemma\_SupplyFunction := simplify(diff(ProfitStar, p));

**#Hotllings Lemma gives supply function.**

Ordinary\_Input\_Demand\_Function\_x1 := simplify(-diff(ProfitStar, r1));

**#This is same as X1Star from profit maximization.**

Ordinary\_Input\_Demand\_Function\_x2 := simplify(-diff(ProfitStar, r2));

**#This is same as X2Star from profit maximization.**

Duality\_Hotlling\_r1 := solve(Ordinary\_Input\_Demand\_Function\_x2 = x2, r1);

Duality\_Hotlling\_r2 := solve(Ordinary\_Input\_Demand\_Function\_x1 = x1, r2);

Duality\_Hotlling\_r2Star := simplify(solve(eval(Ordinary\_Input\_Demand\_Function\_x1, [r1 = Duality\_Hotlling\_r1]) = x1, r2));

Duality\_Hotlling\_r1Star := simplify(eval(Duality\_Hotlling\_r1, [r2 = Duality\_Hotlling\_r2Star]));

Original\_Production\_Function := simplify(eval(Hotllings\_Lemma\_SupplyFunction, [r1 = Duality\_Hotlling\_r1Star, r2 = Duality\_Hotlling\_r2Star]));

### # Comparative Static of Profit Maximization Without Any Constraints:

$$\text{Own\_Price\_Effect\_X1Star\_Profit} := \left( \frac{f_{22}}{p \cdot (f_{11} \cdot f_{22} - f_{12} \cdot f_{12})} \right);$$

Own\_Price\_Effect\_X1S\_Profit\_Alternative := diff(x1s\_profit, r1); # Own Price Effect in x1.  
 # diff(x1s\_profit, r1) when dr2 = dp = 0; For maximum profit, Own Price Effect < 0.

$$\text{Output\_Price\_Effect\_X1Star\_Profit} := \text{simplify} \left( \frac{-f_1 \cdot f_{22} + f_2 \cdot f_{12}}{p \cdot (f_{11} \cdot f_{22} - f_{12} \cdot f_{12})} \right);$$

$$\text{Output\_Price\_Effect\_X1S\_Profit\_Alternative} := \text{simplify}(\text{diff}(x1s\_profit, p));$$

# Output Price Effect in x1

# diff(x1s\_profit, p) when dr1 = dr2 = 0. #I have to specify which x1, I want to use.

$$\text{Own\_Price\_Effect\_X2S\_profit} := \left( \frac{f_{11}}{p \cdot (f_{11} \cdot f_{22} - f_{12} \cdot f_{12})} \right);$$

Own\_Price\_Effect\_X2S\_Profit\_Alternative := diff(x2s\_profit, r2); # `Own Price Effect in x2.  
 # diff(x2s\_profit, r2) when dr1 = dp = 0.

$$\text{Output\_Price\_Effect\_X2Star\_Profit} := \text{simplify} \left( \frac{-f_2 \cdot f_{11} + f_1 \cdot f_{12}}{p \cdot (f_{11} \cdot f_{22} - f_{12} \cdot f_{12})} \right);$$

$$\text{Output\_Price\_Effect\_X2S\_Profit\_Alternative} := \text{simplify}(\text{diff}(x2s\_profit, p));$$

# Output Price Effect in x2 # diff(X2S\_profit, p) when dr1 = dr2 = 0.

# #I have to specify which x2, I want to use.

$$\text{Cross\_Price\_Effect\_X1S\_Profit} := \left( -\frac{f_{12}}{p \cdot (f_{11} \cdot f_{22} - f_{12} \cdot f_{12})} \right); \text{Cross\_Price\_Effect\_X2S\_Profit} := \left( -\frac{f_{21}}{p \cdot (f_{11} \cdot f_{22} - f_{12} \cdot f_{12})} \right);$$

$$\text{Cross\_Price\_Effect\_X1S\_Profit\_alternative} := \text{diff}(x2s\_profit, r1);$$

$$\text{Cross\_Price\_Effect\_X2S\_Profit\_Alternative} := \text{diff}(x1s\_profit, r2) \text{ #Cross Price Effect.}$$

# Cross Price Effect implies diff(x1s\_profit, r2) when dr1 = dp = 0 for X1S\_Profit & diff(x2s\_profit, r1) when dr2 = dp = 0 for X2S\_Profit. Both are same.

### # Economic Interdependence of Factors:

# If cross effects i.e. diff(x1s\_profit, r2) and diff(x1s\_profit, r2) are

# < 0 means two factors are complementary.

# = 0 means two factors are independent.

# > 0 means two factors are competitive.

## # Cost Minimization subject to Output Constraints (Min C st (y<sub>o</sub> - y)): Least Cost Combination of Two Factors of Production.

#**Conditional Factor Demands** is defined as relationship between quantity of factor used and factor price holding output constant. It reflects cost minimizing movements along with an isoquant as factor price changes.

Cost := TotalCost;

LC := Cost + λ · (y<sub>o</sub> - y); # **Lagrangean function**. λ is lagrangean multiplier.

LCf1 := diff(LC, x1); LCf11 := diff(LCf1, x1); # **FOC and SOC of lagrangean function wrt x1**

LCf2 := diff(LC, x2); LCf22 := diff(LCf2, x2); # **FOC and SOC of lagrangean function wrt x2**

LCf12 := diff(LCf1, x2); LCf21 := diff(LCf2, x1);

# Cross differentiation of LCf1 and LCf2 wrt x2 and x1 respectively. **Gives interdependence of factors.**

LCFλ := diff(LC, λ); # **FOC of lagrangean function wrt λ**

LCf1λ := solve(LCf1, λ); # **λ from LCf1.**

LCf2λ := solve(LCf2, λ); # **λ from LCf2.**

$$\frac{r1}{LCf1} = \frac{r2}{LCf2}; \frac{r1}{f1} = \frac{r2}{f2}; \frac{r1}{r2} = \frac{f1}{f2}; \frac{r1}{r2} = \frac{LCf1}{LCf2};$$

EP\_C\_x1 := solve(LCf1λ = LCf2λ, x1); # **Expansion path X1**

EP\_C\_x2 := solve(LCf1λ = LCf2λ, x2); # **Expansion Path X2**

x2s\_cost := solve((eval(LCFλ, x1 = EP\_C\_x1)), x2);

# **X2Star: Cost Minimizing Input x2 Demand Function**, [Verify :

Constrained Input Demand Function x2.] #Use small positive value

x1s\_cost := eval(EP\_C\_x1, x2 = x2s\_cost); # **X1Star: Cost Minimizing Input x1 Demand Function**. [Verify : Constrained Input Demand Function x1.] #use small positive value.

CostStar := r1 · x1s\_cost + r2 · x2s\_cost + b; # **CostStar: Minimum Cost**

**for the production of given level of output. Indirect Conditional Cost Function.**

ystar\_cost := eval(y, [x1 = x1s\_cost, x2 = x2s\_cost]);

# **Ystar: Output level produced. This should be equal to given level of output.**

LCf1λStar := eval(LCf1λ, [x1 = x1s\_cost, x2 = x2s\_cost]); # **λ1Star Lagrangean Multiplier**

#Use positive value #Marginal Cost

LCf2λStar := eval(LCf2λ, [x1 = x1s\_cost, x2 = x2s\_cost]); # **λ2Star Lagrangean multiplier**

#Use positive value. Marginal Cost

BHessian\_Cost\_Min := simplify(λ · (LCf1 · LCf1 · LCf22 - 2 · LCf1 · LCf2 · LCf12 + LCf2 · LCf2 · LCf11)); # **SOC Condition**

# **SOC Condition: Minimum Cost = Determinant of Boarder Hessian Matrix < 0. If > 0, then cost is Maximum.**

# BHessian\_Cost\_Min\_Value := eval(BHessian\_Cost\_Min, [x1 = x1s\_cost, x2 = x2s\_cost, λ = LCf1λStar]);

Curvature\_CostMin := simplify(- ( (abs(BHessian\_Cost\_Min) ) ) ) / ( λ · LCf2<sup>3</sup> );

# **Curvature`** Strictly quasi-concave production function or Convex Isoquant; SOC always holds

# Corvature\_costMin\_Value := eval(Curvature\_CostMin, [x1 = x1s\_cost, x2 = x2s\_cost, λ = LCf1λStar]);

**# Duality: Production Function to Indirect Conditional Cost Function in Price Space and back to Production Function.**

# Duality related to Shephard Lemma follows same procedure of cost minimization until we derive Indirect Cost Function (CostStar).

# So, this section is a continuation from cost minimization for duality. This section derive original production function from where we started using duality approach.

# To go back to production function we need to use **Shepard Lemma**.

# Duality related to Shephard lemma follows same procedure of cost minimization until we derive indirect cost function (**CostStar**).

# So, this section is a continuation from cost—minimization for duality starting from original production function to indirect conditional cost function and back to original production function.

ConstantOutput\_Input\_Demand\_x1 := diff(CostStar, r1);

**# This should be equal to x1s\_cost. Constant-Output input Demand Function x1.**

ConstantOutput\_Input\_Demand\_x2 := diff(CostStar, r2);

**# This should be equal to x1s\_cost. Constant-Output input Demand Function x2.**

# Note: We have to use concept that price ratio is equal to some constant,  $m$ , i.e.  $m$  as ratio of constant output input demands  $r1$  and  $r2$ . Then we solve for  $r1$ , substitute resulting  $r1$  in both constant output input demand functions  $r1$  and  $r2$  and solve for  $m$  from  $r1$  and  $r2$ , then set them  $m$  equal to find original production function. ( $y0$  is the  $y$  function).

$sr1 := m \cdot r2$ ;

$m1 := \text{solve}(\text{eval}(\text{ConstantOutput\_Input\_Demand\_x1}, [r1 = sr1]) = x1, m)$ ; # $m1 := \text{eval}(m1\text{Init}, n = 1)$ ;

$m2 := \text{solve}(\text{eval}(\text{ConstantOutput\_Input\_Demand\_x2}, [r1 = sr1]) = x2, m)$ ; # $m2 := \text{eval}(m2\text{Init}, n = 1)$ ;

Original\_Production\_Function\_ShephardLemma := simplify(solve( $m1[1] = m2[1]$ ,  $y0$ ));



**# Comparative Statics of Cost Minimization Model Or Conditional Factor Demands:** What is the relationship between quantities of factors used **and** factors prices when output is constant?

$$\text{Own\_Price\_Effect\_X1S\_Cost} := \frac{-f2 \cdot f2}{LCf1\lambda\text{Star} \cdot (2 \cdot f1 \cdot f2 \cdot f12 - f1 \cdot f1 \cdot f22 - f2 \cdot f2 \cdot f11)};$$

$$\text{Own\_Price\_Effect\_X1S\_Cost\_Alternative} = \text{diff}(x1s\_cost, r1);$$

# This is equivalent to  $\text{diff}(x1s\_cost, r1)$  when  $dr2 = dy = 0$  This value is negative • after

$$\text{Output\_Effect\_X1S\_Cost} := \frac{f2 \cdot f12 - f1 \cdot f22}{LCf1\lambda\text{Star} \cdot (2 \cdot f1 \cdot f2 \cdot f12 - f1 \cdot f1 \cdot f22 - f2 \cdot f2 \cdot f11)};$$

# This is equivalent to  $\text{diff}(x1s\_cost, y)$  when  $dr1 = dr2 = 0$ .

# If this value  $> 0$ , then we have normal factor. And, if this value  $< 0$ , we have inferior factor.

Verify Formula

$$\text{Output\_Effect\_X1S\_Cost\_Alternative} := \text{diff}(x1s\_cost, y);$$

$$\text{Own\_Price\_Effect\_X2S\_Cost} := \frac{-f1 \cdot f1}{LCf2\lambda\text{Star} \cdot (2 \cdot f1 \cdot f2 \cdot f12 - f1 \cdot f1 \cdot f22 - f2 \cdot f2 \cdot f11)};$$

$$\text{Own\_Price\_Effect\_X2S\_Cost\_Alternative} := \text{diff}(x2s\_cost, r2);$$

# This is equivalent to  $\text{diff}(x2s\_cost, r2)$  when  $dr1 = dy = 0$ .

$$\text{Output\_Effect\_X2S\_Cost} := \frac{f1 \cdot f21 - f2 \cdot f11}{LCf2\lambda\text{Star} \cdot (2 \cdot f1 \cdot f2 \cdot f12 - f1 \cdot f1 \cdot f22 - f2 \cdot f2 \cdot f11)};$$

# This is equivalent to  $\text{diff}(x2s\_cost, y)$  when  $dr1 = dr2 = 0$ .

# If this value  $> 0$ , then we have normal factor. And, if this value  $< 0$ , we have inferior factor. Verify Formula.

$$\text{Output\_Effect\_X2S\_Cost\_Alternative} := \text{diff}(x2s\_cost, y);$$

$$\text{Cross\_Price\_Effect\_X1S\_Cost} := \frac{f1 \cdot f2}{LCf1\lambda\text{Star} \cdot (2 \cdot f1 \cdot f2 \cdot f12 - f1 \cdot f1 \cdot f22 - f2 \cdot f2 \cdot f11)};$$

$$\text{Cross\_Price\_Effect\_X1S\_Cost\_Alternative} := \text{diff}(x1s\_cost, r2);$$

# This is equivalent to  $\text{diff}(x1s\_cost, r2)$  when  $dr1 = dy = 0$ .

$$\text{Cross\_Price\_Effect\_X2S\_Cost} := \frac{f2 \cdot f1}{LCf2\lambda\text{Star} \cdot (2 \cdot f1 \cdot f2 \cdot f12 - f1 \cdot f1 \cdot f22 - f2 \cdot f2 \cdot f11)};$$

$$\text{Cross\_Price\_Effect\_X2S\_Cost\_Alternative} := \text{diff}(x2s\_cost, r1);$$

# This is equivalent to  $\text{diff}(x2s\_cost, r1)$  when  $dr2 = dy = 0$ .

**# Maximize Output subect to Budget Constraints (Max y st (Co - C)): (Should gives same result as before)**

```

Ly := y + μ · (Co - Cost); # Lagrangean function.
Lyf1 := diff(Ly, x1); Lyf11 := diff(Lyf1, x1); #FOC and SOC of Lagrangean function wrt x1.
Lyf2 := diff(Ly, x2); Lyf22 := diff(Lyf2, x2); #FOC and SOC of Lagrangean function wrt x2.
Lyf12 := diff(Lyf1, x2); Lyf21 := diff(Lyf2, x1);
#Cross SOC of Lyf1 and Lyf2 wrt x2 and x1 respectively.
Lyμ := diff(Ly, μ); # FOC of Lagrangean function wrt μ.
Lyf1μ := solve(Lyf1 = 0, μ); #Solve for μ using Lyf1μ
Lyf2μ := solve(Lyf2 = 0, μ); #Solve for μ using Lyf1μ
EP_Ly_x1 := solve(Lyf1μ = Lyf2μ, x1);
#Equate μ from above two equations and solve for x1. Expansion path x1.
EP_Ly_x2 := solve(Lyf1μ = Lyf2μ, x2);
#Equate μ from above two equations and solve for x2. Expansion path x2.
x2s_expd := solve(eval(Lyμ, x1 = EP_Ly_x1), x2);
#X2Star: Demand function of input x2 to maximize the output subject to budget constraints.
Ordinary Input Demand Function x2.
x1s_expd := eval(EP_Ly_x1, x2 = x2s_expd);
#X1Star: Demand function of input x1 to maximize the output subject to budget constraints.
Ordinary Input Demand Function x1.
ystar_expd := eval(y, [x1 = x1s_expd, x2 = x2s_expd]);
#YStar: Supply function. Total output produced under constrained budget.
CostStar_expd := eval(Cost, [x1 = x1s_expd, x2 = x2s_expd]);
#CostStar: Total cost to produce given amount of output.
LyμStar_Lyf1μ := eval(Lyf1μ, [x1 = x1s_expd, x2 = x2s_expd]);
#Lagrangean Multiplier Star (LyμStar_Lyf1μ = LyμStar_Lyf2μ)
#Lagrangean Multiplier Star is Marginal product (increase in output per unit cost) under
constrained budget condition. LyμStar_Lyf1μ = LyμStar_Lyf2μ.
LyμStar_Lyf1μ := eval(Lyf2μ, [x1 = x1s_expd, x2 = x2s_expd]);
#Lagrangean Multiplier Star (LyμStar_Lyf1μ = LyμStar_Lyf2μ)`.
BHessian_Output_Max := simplify(μ · (Lyf1 · Lyf1 · Lyf22 - 2 · Lyf1 · Lyf2 · Lyf12 + Lyf2 · Lyf2 · Lyf11));
#SOC Conditions
#SOC Condition: Determinant of Boarder Hessian Matrix > 0 for Output Maximization.
BHessian_Output_Max_Value := simplify(eval(BHessian_Output_Max, [x1 = x1s_expd, x2
= x2s_expd, λ = Lyf1μStar]));
Curvature_Output_Max := simplify(- (abs(BHessian_Output_Max) / (μ · Lyf23))); #Curvature
Corvature_Output_Max_Value := eval(Curvature_Output_Max, [x1 = x1s_expd, x2 = x2s_expd, λ
= Lyf1μStar]);
# Homogeneity of Demand Functions: Factor demand functions are homogenous of degree zero.
# Comparative Statisc of Output Maximization: # Not Demonstrated in Note and not in book as well.

```

- # *Output Side Economics: of Production Function with Two Input and One Output (Quadratic and Cobb Douglas Production Function)*
- # *Cost Minimization subject to Output Constraints (Min  $C$  st  $(y_0 - y)$ ): Least Cost Combination of Two Factors of Production. Necessary for output side economics.*